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Minimal vertex covers of random trees

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Abstract

We study minimal vertex covers of trees. Contrarily to the number $N_{vc}(A)$ of minimal vertex covers of the tree A , $\log N_{vc}(A)$ is a self-averaging quantity. We show that, for large sizes n , $\lim_{n \rightarrow +\infty} \langle \log N_{vc}(A) \rangle_n / n = 0.1033252 \pm 10^{-7}$. The basic idea is, given a tree, to concentrate on its degenerate vertices, that is those vertices which belong to some minimal vertex cover but not to all of them. Deletion of the other vertices induces a forest of totally degenerate trees. We show that the problem reduces to the computation of the size distribution of this forest, which we perform analytically, and of the average $\langle \log N_{vc} \rangle$ over totally degenerate trees of given size, which we perform numerically.

1 Introduction

The vertex-cover problem, as other combinatorial problems, is arousing growing interest in the fields of statistical physics and disordered systems. In particular, it helps to understand, and the machinery of optimization algorithms helps to solve, spin-glasses and random hamiltonian models (see [1] for a recent review of the problem, [2] for a critical analysis point of view). A possible question is : given a graph, what can be said about the size and number of its minimum vertex covers ? Another approach consists in answering this question *on average*, for a given statistical ensemble of graphs.

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In this paper, we are concerned with average behaviour, and focus on the simple situation of trees. In this case, good algorithms are known, for instance based on the so-called b-colorings (see [3] and sect.2), to find the number $N_{vc}(A)$ or size of minimal vertex covers of a given tree A . In fact, if each tree of given size n has the same probability, then the average number of vertex covers can also be retrieved analytically by means of these b-colorings. However, this is not a self-averaging quantity for large n , and it would be desirable to find a thermodynamically extensive quantity giving a somewhat more physical insight into the number of minimal configurations of a random tree.

We claim that $\langle \log N_{vc}(A) \rangle_n$ is indeed self-averaging, and the reason is as follows. Suppose that we delete from A all the vertices which are not degenerate (that is, those which belong either to all the minimal vertex covers of A or to none of them). Then we obtain (see sect.3) a forest with the same number of minimal vertex covers as A and whose vertices are all degenerate. Moreover, in this forest, the number of trees of given size scales thermodynamically with the size of A (see sect.4), and the probability of appearance of a given tree depends only on its size. In other words, as far as we are concerned with the number of minimal vertex covers, picking at random a tree on $n \gg 1$ vertices amounts for each $i \geq 1$ to picking with uniform law $c_i n$ totally degenerate trees on i vertices. And, in turn, it is expected that such a typical tree A verifies $\log N_{vc}(A) \approx n \sum_i c_i \langle \log N_{vc} \rangle_i^R$, where $\langle \log N_{vc} \rangle_i^R$ is the average of $\log N_{vc}$ over totally degenerate trees on i vertices.

The computation thus reduces to that of the scaling parameters c_i for the size distribution, and to the evaluation of the average of $\log N_{vc}$ over totally degenerate trees with given size (see sect.5).

But let us begin with a reminder of some basic facts and the crucial theorem on b-colorings.

2 Preliminary observations

2.1 Basic definitions

A *graph* is a pair $A = (V, \mathcal{E})$ where V is a set with $n \geq 1$ elements (written $|V| = n$ in the sequel) and \mathcal{E} is a subset of $\{\{x, y\} \subset V; x \neq y\}$. V is the set of *vertices* of A and \mathcal{E} the set of *edges* of A , n is the *size* of A , denoted by $|A|$. In this paper A is called a *labeled graph* if V consists of positive integers.

Given two distinct vertices x, y of the graph $A = (V, \mathcal{E})$, a path from x to y in A is a sequence $\{v_0, v_1\}, \{v_1, v_2\}, \dots, \{v_{p-1}, v_p\}$ of edges of A such

that $v_0 = x, v_p = y$ and $v_i \neq v_j$ if $i \neq j$. A graph is called a *tree* if any two distinct vertices are connected by a unique path, and a *forest* if any two distinct vertices are connected by at most one path.

A *rooted tree* is a triple (V, \mathcal{E}, r) , such that (V, \mathcal{E}) is a tree and $r \in V$.

A *vertex cover* of the graph $A = (V, \mathcal{E})$ is a subset of V containing at least one end of each edge of A . A vertex cover of A is *minimal* if there does not exist any other vertex cover with less elements. In the sequel, the number of minimal vertex covers of A is denoted $N_{vc}(A)$.

2.2 Some useful results

The exponential generating function of rooted trees It is defined as $T(x) = \sum_A \frac{x^{|A|}}{|A|!}$, where the sum runs over all rooted trees. Cayley's formula states that the number of rooted trees on n vertices is n^{n-1} , hence $T(x) = \sum_{n \geq 1} \frac{n^{n-1}}{n!} x^n$ and this implies that $T(x) = xe^{T(x)}$ as can be deduced by a direct combinatorial argument relying on the recursive nature of rooted trees.

A theorem on minimal vertex covers of trees It has been shown in [3] that, for any tree $A = (V, \mathcal{E})$, there exists a unique triple $(B, \mathcal{R}, G) \subset V \times \mathcal{E} \times V$, called the *b-coloring* of A , such that

- B, G and the set of end-vertices of \mathcal{R} form a partition of V .
- The edges in \mathcal{R} are non-adjacent; the edges with one end-vertex in G have the other end-vertex in B ; each vertex in B is connected to G by at least two edges.

Moreover, the b-coloring of A has the following connection with its minimal vertex covers : B (resp. G) is the set of vertices contained in all (resp. none) of the minimal vertex covers of A . Consequently, any end-vertex of \mathcal{R} is contained in some minimal vertex cover of A but not in all of them : these vertices are called *degenerate*.

An additional result is that any minimal vertex cover of A contains exactly one end-vertex of each edge in \mathcal{R} . Consequently, a vertex cover of A is minimal if and only if it contains $|B| + |\mathcal{R}|$ vertices.

In the sequel, vertices in B and G and end-vertices of \mathcal{R} will be called respectively *brown*, *green* and *red* vertices, while edges in \mathcal{R} will be called red edges. A tree with no brown or green vertices is said to be red.

3 Red forest of a tree

Given a tree $A = (V, \mathcal{E})$ and a non-empty set $S \subset V$ of vertices, the forest induced by A on S is defined as (S, \mathcal{E}') , where \mathcal{E}' consists of those edges in \mathcal{E} with both ends in S . If A is a tree with b-coloring (B, \mathcal{R}, G) , and such that $\mathcal{R} \neq \emptyset$, define the *red forest* of A to be the forest induced by A on the set of red vertices. Denote $A_1 = (V_1, \mathcal{E}_1), \dots, A_p = (V_p, \mathcal{E}_p)$ the trees of that forest. Then it follows at once from the definitions that A_i has b-coloring $(\emptyset, \mathcal{R} \cap \mathcal{E}_i, \emptyset)$, hence is red. But if C is a minimal vertex cover of A , $C \cap V_i$ is a vertex cover of A_i . Since C contains exactly one end of each red edge of A , $C \cap V_i$ contains $|\mathcal{R} \cap \mathcal{E}_i|$ vertices of A_i : it is a minimal vertex cover of A_i . Now, given minimal vertex covers C_1, \dots, C_p of the A_i 's, $B \cup C_1 \cup \dots \cup C_p$ is a vertex cover of A (because an edge of A either is an edge of some A_i or has at least one end in B), which is minimal since it contains $|B| + |\mathcal{R}|$ vertices. It is in fact the only minimal vertex cover of A which coincides with C_i on each A_i , and this proves that :

$$N_{vc}(A) = \prod_{i=1}^p N_{vc}(A_i).$$

Let us define the *size distribution* of a forest F as the sequence $D = (D_i)_{i \geq 1}$, where D_i is the number of components of size i in F . Given two forests F_1, F_2 of red trees, with same size distribution D , there is no difficulty in proving that the numbers of trees with red forests respectively F_1 and F_2 are equal. In other words the number of trees on n vertices with given red forest F depends on F only via its size distribution D : this number shall be denoted $\nu_D(n)$ in the sequel. Note that $\nu_D(n) = 0$ if $D_i \neq 0$ for some $i > n$.

If we denote by λ_i the sum over red trees R on i vertices of $\log N_{vc}(R)$, the preceding remarks allow to write our sum over trees of size n as

$$\sum_A \log N_{vc}(A) = \sum_D \nu_D(n) (D_1 \lambda_1 + D_2 \lambda_2 + \dots + D_n \lambda_n).$$

We are thus led to the computation of the ν_D 's and λ_i 's. Note already that a red tree has even size, whence $\nu_D(n) = 0$ if $D_{2i+1} \neq 0$ for some i . We now come to the analytic computation of $\nu_D(n)$.

4 Size distribution

Denote by G, B, R respectively the exponential generating functions for the number of rooted trees with root of color green, brown and red. For instance,

$G(x) \equiv \sum_A \frac{1}{|A|!} x^{|A|}$, where the sum runs over all rooted trees with green root. The following relations hold between these generating functions (see [3] for details and the combinatorial meaning of U, Q)

$$\begin{aligned} G &= xe^U \\ U &= xe^{B+R}(e^G - 1) \\ B &= xe^{B+R}(e^G - 1 - G) \\ R &= xQe^{B+R} \\ Q &= xe^{B+R}, \end{aligned}$$

leading in particular to $B(x) = T(x) + T(-T(x)) - T(-T(x))^2$. Now, let us look more closely at those trees with red root. The red forest of such a tree A has exactly one component containing the root, and the size $s(A)$ of this component can be encoded in the following generating function, where the sum runs over rooted trees with red root

$$R_0(x, y) \equiv \sum_A \frac{1}{|A|!} x^{|A|} y^{s(A)}.$$

Since $R_0 = xyQ_0e^{B+R_0}$ with $Q_0 = xye^{B+R_0}$, it follows that $R_0 = T(2x^2y^2e^{2B(x)})/2$, and the total number of red components of size $2p$ among labeled trees of size n is

$$\frac{1}{2p} n! [x]_n [y]_{2p} R_0(x, y) = \frac{(2p)^{p-2}}{p!} n! [x]_{n-2p} e^{2pB(x)}$$

A straightforward application of the saddle-point method then shows that, for large n , the average number of red components of size $2p$ scales thermodynamically with n : $C_{2p}(n) \sim c_{2p}n$ and

$$c_{2p} = \frac{(2p)^{p-1}}{p!} T' T^{2p-1} e^{-2pT^2} (2T^2 - 1), \quad (1)$$

where, in the above formula, $T(x)$ and its derivative are taken at the saddle-point $x = -1$. For large p , we get that $\frac{\log c_{2p}}{p}$ tends to $\log(2eT^2 \exp(-2T^2)) \approx -0.0844424236$, showing that c_{2p} decays exponentially.

Now, we make the ‘‘thermodynamic limit’’ assumption that the number of trees with given size in the red forest of some random large tree is a self-averaging quantity. That is, we suppose that, for large n , the trees which contribute significantly to $\langle \log N_{vc} \rangle_n$ have indeed C_2 trees of size 2, C_4 trees of size 4, \dots . The distribution ν_D hence becomes irrelevant, since it concentrates on one particular value, and the average becomes

$$\lim_{n \rightarrow +\infty} \langle \log N_{vc} \rangle_n / n = \sum_i c_{2i} \frac{\lambda_{2i}}{N_{2i}},$$

where N_{2i} denotes the number of red trees of size $2i$.

5 Minimal vertex covers of the red trees

In this section, we compute analytically the number N_{2p} of red trees on $2p$ vertices and give a numeric estimate of the λ_{2i} 's. In fact, one could deduce directly $R(x)$, whence the N_{2p} 's, from the set of equations on B, G, R, Q, U stated in the preceding section. But we prefer to give a direct combinatorial derivation which, after slight adaptations, shall give also the total number of minimal vertex covers among red trees of size $2p$.

5.1 Overview

As was already emphasized, a red tree A has an even number of vertices, say $2p$, and we associate to A its *shrunked tree* \tilde{A} as follows

- The vertices of \tilde{A} are the red edges of A , so \tilde{A} has size p ;
- Two vertices of \tilde{A} are connected in \tilde{A} if and only if the corresponding two red edges of A are connected by some other edge in A .

This procedure is uniquely defined and, if the set of vertices of A is V , that of its shrunked tree is a partition of V into sets of 2 elements. Such a partition will be called a *pairing* of V : note that it consists of the red edges of A .

Conversely, let V be a set ($|V| = 2p$). There are $\frac{(2p)!}{2^p p!}$ pairings of V , and p^{p-2} trees with set of vertices equal to one of these pairings. Given such a tree B , the number of red trees on V with shrunked tree B is 4^{p-1} , because each of the $p - 1$ edges of B leaves 4 possibilities for the corresponding edge of the red tree. Hence, the number of red trees on $2p$ vertices is

$$N_{2p} = \frac{(2p)!}{p!} (2p)^{p-2},$$

so the number $2pN_{2p}$ of rooted trees has exponential generating function $R(x) = T(2x^2)/2$.

Let us now enumerate the total number of minimal vertex covers among the red trees of size $2p$. Consider a minimal vertex cover on a labeled tree A of size $2p$. To encode this vertex cover, add an arrow at each covered end of each black edge (that is, each edge which is not red). By definition of vertex covers a black edge is either oriented (one arrow) or bi-oriented (two arrows).

Now, we apply the shrinking procedure as defined above, but we keep track of the orientations : this leads to a tree on p vertices, each edge being either oriented or bi-oriented.

Again this procedure is uniquely defined. If V is a set on $2p$ vertices, the number of trees with set of vertices a pairing of V and with edges either

oriented or bi-oriented is $\frac{(2p)!}{2^p p!} p^{p-2} 3^{p-1}$. Given one such tree B , the number of covered red trees A with shrunked tree B is 2^p . Indeed, each of the p vertices of B corresponds to a red edge of A , which may be covered in two ways. Once this choice has been made, the way the black edges connect the red edges with each other is completely constrained by their (bi-)orientation.

Hence, the total number of minimal vertex covers over red trees of size $2p$ is $3 \frac{(2p)!}{p!} (3p)^{p-2}$, and the average number of minimal vertex covers among red trees on $2p$ vertices is $< N_{vc} >_{2p}^R = 2(3/2)^{p-1}$.

5.2 Theoretical viewpoint

Both for theoretical understanding and for numerical purpose, it proves useful to focus on rooted trees, and we denote by $n_+(A)$ (resp. $n_-(A)$) the number of minimal vertex covers which contain (resp. do not contain) the root of the rooted red tree A .

A red tree with root r may be seen recursively as an edge $\{r, r'\}$, with both ends connected to the root of arbitrarily many red rooted trees. And it is clear (see [3] for details) that a set S of vertices of A is a minimal vertex cover of A if and only if : (i) it induces a minimal vertex cover on each of these attached subtrees (ii) exactly one end of $\{r, r'\}$ is not in S (iii) the edges incident at this vertex have the other end in S . Consequently, denoting by A_i the red trees attached to r and by A'_j those attached to r' :

$$n_+(A) = \prod (n_+(A_i) + n_-(A_i)) \prod n_+(A'_j) \quad (2)$$

$$n_-(A) = \prod n_+(A_i) \prod (n_+(A'_j) + n_-(A'_j)) \quad (3)$$

Now, let us have a closer look at the generating function for rooted red trees $R(x) = T(2x^2)/2$. As follows from the equation for T , R should be such that $R(x) = x^2 e^{2R(x)}$. Combinatorially, this means that the number of rooted red trees on $2p$ vertices is

$$(2p)! [x^{2p-2}] \left(\sum_{k \geq 0} \frac{1}{k!} \left[\sum_A \frac{x^{|A|}}{|A|!} \right]^k \right) \left(\sum_{k' \geq 0} \frac{1}{k'!} \left[\sum_A \frac{x^{|A|}}{|A|!} \right]^{k'} \right), \quad (4)$$

where A ranges over rooted red trees. But building a rooted tree on n vertices amounts to choosing (i) the root r and the vertex r' with whom r shares its red edges ($2p(2p-1)$ ways) (ii) the numbers k and k' of rooted trees attached respectively to those vertices (iii) those trees themselves A_1, \dots, A_k and $A'_1, \dots, A'_{k'}$, in such a way that their total number of vertices is $2p - 2$ (iv) finally, a relabeling of those trees which exhausts the labels $\neq r, r'$

$((2p-2)!/(\prod |A_i|! \prod |A'_j|!))$ ways). Each term of the expansion of $\left[\sum_A \frac{x^{|A|}}{|A|!}\right]^k$ corresponds to a particular *ordered* choice in (iii), and the $1/k!$ factor just gets rid of this ordering. This is true also for the primed term, hence the combinatorial meaning of the equation for R is clear and we now apply it to our vertex covers problem.

The set S of functions $\mathbb{N}^2 \rightarrow \mathbb{R}$ is a vector space. If ϕ is such a function, and $\phi(a,b) = x_{ab}$, $a, b \in \mathbb{N}$, we write $\phi = \sum_{a,b} x_{ab}(a,b)$. If $\psi = \sum_{a,b} x'_{ab}(a,b)$ is another function, let their product be $\phi * \psi = \sum_{a,b,a',b'} x_{ab} x'_{a'b'}(aa', bb')$. S is then an algebra, generated by the (a,b) , $a, b \in \mathbb{N}$. Let σ be the (algebra) morphism such that $\sigma(a,b) = (b,a)$ for all a, b and ρ the (vector space) morphism such that $\rho(a,b) = (a+b, a)$. Then eqs.(2,3) rewrite $(n_+(A), n_-(A)) = \prod \rho(n_+(A_i), n_-(A_i)) * \prod \sigma \rho(n_+(A'_j), n_-(A'_j))$. Hence, our remarks on the combinatorial meaning of eq.(4) show that the formal power series $R_{+-}(x) \equiv \sum_A (n_+(A), n_-(A)) \frac{x^{|A|}}{|A|!}$ obeys the equation

$$R_{+-}(x) = x^2 e^{\rho R_{+-}(x) + \sigma \rho R_{+-}(x)}.$$

Of course, in this equation, the exponential is defined by its power series, the product being as defined above.

Let f_{lm} be the (algebra) morphism such that $f_{lm}(a,b) = a^l b^m$ for all a, b . Then $f R_{+-}(x) = x^2 e^{f \rho R_{+-}(x) + f \sigma \rho R_{+-}(x)}$, so we have the following generating functions for rooted trees:

$$\begin{aligned} R_{lm}(x) &\equiv \sum_A n_+(A)^l n_-(A)^m \frac{x^{|A|}}{|A|!} \\ &= x^2 \exp \left(\sum_{k=0}^l \binom{l}{k} R_{k, l+m-k} + \sum_{k=0}^m \binom{m}{k} R_{k, l+m-k} \right) \end{aligned} \quad (5)$$

For the first two values of n , the resulting system of equations is easily solved. For instance :

For $l = m = 0$: $R_{0,0}(x) = x^2 e^{2R_{0,0}(x)}$, so $R_{0,0}(x) = T(2x^2)/2$ as expected.

For $l = 1, m = 0$ or $l = 0, m = 1$: $R_{1,0}(x) = R_{0,1}(x) = x^2 e^{3R_{1,0}(x)}$, so $R_{1,0}(x) = T(3x^2)/3$, again in agreement with the formula above.

And this seems to be the largest value of n for which the exact solution functions are retrievable. In the case where $l + m = 2$, the system reduces to an implicit expression for $R_{2,0}$: $R_{2,0} = x^2 \exp(3R_{2,0} + 2R_{2,0}e^{-R_{2,0}})$, still allowing asymptotic computations. However, we have not found a systematic

k	1	2	3
M_k	0.20273	0.41576	0.63658

Table 1: Moments $M_k = \lim_{p \rightarrow +\infty} \frac{1}{2p} \log \langle N_{vc}^k \rangle_{2p}^R$ of the number of minimal vertex covers of red trees, as obtained from eq.(5).

treatment for the study of eq.(5) which would have been a possible starting point for the replica method.

We now come to the numerical evaluation of the λ_{2p} 's.

5.3 Numerical computations

Given a red tree A on $2p$ vertices, one can choose any of its vertices as a root and apply recursively equations (2,3) to compute $n_+(A), n_-(A)$ in $O(p)$ time. However, the number of such trees increases exponentially with p , and systematic enumeration soon becomes a challenge.

For small trees ($p \leq 16$), we compute the exact distribution of the number of minimal vertex covers. The algorithm is based on an exhaustive recursive enumeration of rooted trees [4], followed by systematic unshrinking.

For larger trees, we proceed as follows. The number of red trees with given shrunked tree A depends only on $|A|$, and every red tree on $2p$ vertices has a unique shrunked tree, which is of size p . Hence, to pick randomly a red tree on $2p$ vertices with uniform law, it suffices to : (i) Pick randomly a tree A on p vertices, with uniform law (this is conveniently done by means of the Prüfer bijection between those trees and sequences of $\{1, \dots, p\}^{\{1, \dots, p-2\}}$) (ii) Choose, again with uniform probability, one of the red trees with shrunked tree A .

The number of samples picked for each size was chosen so as to ensure a precision of 10^{-7} on $\langle \log N_{vc} \rangle / n$. From the fact that $\langle \log N_{vc} \rangle / n = \sum_i c_{2i} \lambda_{2i} / N_{2i}$, it follows that an error δ_{2i} on $\frac{1}{2i} \frac{\lambda_{2i}}{N_{2i}}$ leads to a maximum error $\sum_i c_{2i} 2i \delta_{2i}$ on $\langle \log N_{vc} \rangle / n$. From eq.(1) we see that c_{2i} decays exponentially fast with i : in practice, we took $8 \cdot 10^9$ samples for each size $17 \leq p \leq 45$ and $1.5 \cdot 10^8$ samples for sizes $46 \leq p \leq 189$. And this leads to

$$\lim_{n \rightarrow +\infty} \langle \log N_{vc}(A) \rangle_n / n = \sum_{p>0} c_{2p} \langle \log N_{vc} \rangle_{2p}^R = 0.1033252 \pm 10^{-7}$$

Those numerical simulations also give evidence that, for red trees of large size $2p$, the random variable $X_p = (\log N_{vc}) / (2p)$ is self-averaging. Indeed, for each of the sizes considered in the previous paragraph, it is possible to get the approximate distribution of X_p , and it appears that $(X_p - \langle X_p \rangle) \sqrt{p}$

approaches a fixed gaussian distribution for large p . Numerically, we find $\lim_{p \rightarrow +\infty} \langle X_p \rangle = \lim_{p \rightarrow +\infty} \langle \log N_{vc} \rangle_{2p}^R / 2p = 0.1963 \pm 10^{-4}$, to be compared with the first few moments of table [1]. In fact, approximating the first few M_k 's by a rational function leads to estimate $\lim_{p \rightarrow \infty} \langle X_p \rangle = \frac{dM_k}{dk} \Big|_{k=0} \approx 0.196$, a result remarkably close to the expected limit. Good understanding of this self-averaging feature would certainly be a crucial issue in the exact derivation of $\lim_{p \rightarrow +\infty} \langle X_p \rangle$, and presumably also of the corresponding limit for general trees.

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