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autoconversion**

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Does the threshold representation associated with the autoconversion process matter?

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Abstract

Different ad hoc threshold functions associated with the autoconversion process have been arbitrarily used in atmospheric models. However, it is unclear how these ad hoc functions impact model results. Here systematic investigations of the sensitivities of climatically-important properties: CF (cloud fraction), LWP (liquid water path), and AIE (aerosol indirect effect) to threshold functions have been performed using a 3-D cloud-resolving model. It is found that the effect of threshold representations is larger on instantaneous values than on daily averages; and the effect depends on the percentage of clouds in their transitional stages of converting cloud water to rain water. For both the instantaneous values and daily averages, the sensitivity to the specification of critical radius is more significant than the sensitivity to the “smoothness” of the threshold representation (as embodied in the relative dispersion of droplet size distribution) for drizzling clouds. Moreover, the impact of threshold representations on the AIE is stronger than that on CF and LWP.

1 Introduction

The autoconversion process generally refers to the process whereby droplets grow into embryonic raindrops. It determines the onset of precipitation of warm clouds, influences the precipitation amount, and thereby the global hydrological cycle. Furthermore, the autoconversion process is an important bridge between aerosols, clouds, and precipitation, in that the suppression of precipitation by aerosols could increase cloud spatial and temporal extent (Albrecht, 1989; Pincus and Baker, 1994). Therefore, an appropriate representation of the autoconversion process is critical for advancing our scientific understanding of cloud micro- and macro-properties, as well as cloud and/or aerosol effects on climate (Boucher et al., 1995; Rotstayn and Liu, 2005).

All the autoconversion parameterizations that have been developed so far can be

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generically written as

$$P = P_0 T, \quad (1)$$

where P is the autoconversion rate ($\text{g cm}^{-3} \text{s}^{-1}$), P_0 is the rate function describing the conversion rate after the onset of the autoconversion process, and T ($0 \leq T \leq 1$) is the threshold function describing the threshold behavior of the autoconversion process. To date, the primary foci of both parameterization development (Kessler, 1969; Manton and Cotton, 1977; Liu and Daum, 2004) and sensitivity investigations (Iacobellis and Somerville, 2006) have been on the rate function P_0 .

The threshold function has received little attention. In most global climate models (GCMs) and/or cloud resolving models (CRMs), the threshold behavior has been represented by an ad hoc function of liquid water content or droplet size. It ranges from an all-or-nothing Kessler-type ($T = \text{Heaviside function}$, Kessler, 1969) to a smoother Sundqvist-type ($T = \text{exponential function}$, Sundqvist, 1978; Del Genio et al., 1996) and to a constant Berry-type ($T=1$, Berry 1968; Beheng 1994). Despite their dramatic differences, these functions have been used arbitrarily, and no systematic investigation has been performed to examine whether or not these different representations exert significant effects on model results.

To fill this gap, this study explores how the climatically important properties, i.e., cloud fraction (CF), liquid water path (LWP), and aerosol indirect effect (AIE) respond to different threshold representations by applying a theoretical threshold function to a 3-D cloud-resolving model, ATHAM (Active Tracer High-resolution Atmospheric Model) (Herzog et al., 1998, 2003; Guo et al., 2007a).

2 Threshold representation

Liu et al. (2006a) derived a theoretical threshold function (T_ε) that covers all the existing types of threshold representations. Briefly, T_ε is described by

$$T_\varepsilon = \gamma(6\varepsilon + 1, [\Gamma(3\varepsilon + 1)]^{1/(3\varepsilon)} x_c^{1/(3\varepsilon)}) \times \gamma(3\varepsilon + 1, [\Gamma(3\varepsilon + 1)]^{1/(3\varepsilon)} x_c^{1/(3\varepsilon)}), \quad (2)$$

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where $\Gamma(a) = \int_0^{\infty} t^{a-1} e^{-t} dt$ is the Gamma function; $\gamma(a, x) = \int_x^{\infty} t^{a-1} e^{-t} dt / \int_0^{\infty} t^{a-1} e^{-t} dt$

the normalized incomplete Gamma function; ε the relative dispersion (the ratio of the standard deviation to the mean radius of the cloud droplet size distribution); and x_c the ratio of the critical to the mean mass of cloud water (Liu et al., 2006a). Equation (2) indicates that T_ε depends on two dimensionless variables: ε and x_c , as compared to ad hoc threshold functions which depend only on x_c . It should be emphasized that ε controls the “type” of T_ε , changing from the Kessler-type to the Berry-type as ε increases from 0 to infinity. This dependence of T_ε on ε allows us to systematically examine the effect of the “smoothness” of the threshold function, which has been unknowingly buried in arbitrary uses of ad hoc threshold functions in previous studies (Liu et al., 2006a).

3 Model and case descriptions

ATHAM is a non-hydrostatic, fully compressible atmospheric model. In this study, the 3-D version is adopted. The horizontal domain is $6.4 \times 6.4 \text{ km}^2$ with a uniform horizontal spacing of 100 m. The vertical spacing is 30 m within the boundary layer (below 2 km). The time step is 2 s, and model results have been archived every 5 (model) min. The entire simulation period is 30 h, but we mainly examined the model results in the daytime from 06:00 to 18:00 LT (local time) when the AIE is significant. A double-moment cloud microphysical parameterization is employed, e.g., cloud droplet number concentration is predicted following Lohmann et al. (1999). Both the shortwave and longwave radiative heating/cooling rates are computed interactively. The model is initialized and driven by the re-analysis data from European Centre for Medium-Range Weather Forecast (ECMWF).

We investigated two contrasting clean and polluted cases observed during the second Aerosol Characterization Experiment (ACE-2) over Portugal, the Azores, and the

Canary Islands. The clean case (denoted as “CLEAN”) occurred on 26 June 1997, when the ACE-2 area was under the control of a cyclone that brought in pristine maritime air. The polluted case (denoted as “POLL”) occurred on 9 July 1997, when the ACE-2 area was under the influence of the Azores High that brought in anthropogenic pollution from Europe (Verver et al., 2000). For the “CLEAN” and “POLL” cases, the total aerosol number concentrations were 218 cm^{-3} and 636 cm^{-3} , respectively (Snider and Brenguier, 2000); and the non sea-salt (nss) sulfate mass concentrations were $0.30 \mu\text{g m}^{-3}$ and $2.8 \mu\text{g m}^{-3}$, respectively (Guibert et al., 2003). Note that the detailed model set-up and case descriptions were available in Guo et al. (2007a,b).

In addition to the contrasting aerosol and meteorological conditions, significant proportions of these clouds were in their transitional stages where precipitation depended critically on the threshold representation, providing a good opportunity to explore the effects of different threshold representations on clouds.

4 Sensitivity studies

4.1 Sensitivity to the relative dispersion (ϵ)

To explore all the existing threshold functions, we performed simulations with $\epsilon=0, 0.1, 0.2, 0.4, 0.6, 0.8, 1.0, 10.0,$ and 300 in Eq. (2). [Note: $\epsilon=0, 0.4,$ and 300 approximately represent the Kessler-type, the Sundqvist-type, and the Berry-type threshold functions, respectively]. The results are shown in Fig. 1, where the results for $\epsilon=0$ are used as the base cases (black) and the results of sensitivity tests for $\epsilon=0.4$ and 300 are shown as percentage differences relative to the base cases. For the “CLEAN” case, both CF and LWP reach their maxima in the local early morning and their minima in the local afternoon (Fig. 1a and 1c). But for the “POLL” case, neither CF nor LWP exhibits a significant diurnal cycle due to a strong large-scale subsidence associated with the Azores High (Fig. 1b and 1d). The magnitude of the AIE is the largest near local noon for both the “CLEAN” and “POLL” cases due to the peak insolation (Fig. 1e and 1f). The

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“CLEAN” case has a larger AIE than the “POLL” case because the “CLEAN” clouds are deeper and moister (Pawlowska and Brenguier, 2003). Note that CF here is defined as the fraction of cloudy columns, and a cloudy column is a column containing one or more cloudy cells with liquid water mixing ratio >0.01 g/kg. The AIE (shortwave plus longwave) at the top-of-the-atmosphere is estimated by swapping the aerosol and meteorological conditions between the “CLEAN” and “POLL” cases and then calculating the radiative flux difference between the clean and polluted aerosol conditions under the same meteorological background (Guo et al., 2007b).

The relative differences in the instantaneous CF, LWP, and AIE between the base cases ($\varepsilon=0$) and the sensitivity tests ($\varepsilon=300$) vary significantly, and can reach up to $\sim 20\%$, $\sim 40\%$, and $\sim 60\%$, respectively (Fig. 1). The maximum of the AIE difference can reach 100%. As expected, the difference between $\varepsilon=0$ and 300 is generally larger than that between $\varepsilon=0$ and 0.4. The effect of ε is stronger for the “POLL” case than that for the “CLEAN” case.

To further explore the underlying physics, Fig. 2 shows the relationship of the relative differences in CF, LWP, and AIE (for $\varepsilon=0$ and 300) as a function of x_c . It is clear that larger differences in these three quantities are generally associated with larger values of x_c , suggesting that an exact representation of the threshold behavior becomes more important as the autoconversion becomes less efficient. This is expected because all threshold functions gradually approach 1 as x_c decreases to 0. The association of a larger difference with a larger x_c explains why the effect of ε is stronger for the “POLL” case than for the “CLEAN” case as shown in Fig. 1.

For the “CLEAN” case, as daytime heating progresses, the cloud water is depleted so quickly (Fig. 1a and 1c) that the magnitude of x_c jumps from $\ll 1$ to ~ 1 . Consequently, the “CLEAN” clouds transform quickly from one stage (with efficient drizzle production) to another stage (between drizzling and non-drizzling). But for the “POLL” case, due to their continental origins and the strong large-scale subsidence (Guo et al., 2007b), these “POLL” clouds tend to precipitate less efficiently. As shown in Fig. 2, the “CLEAN” and “POLL” cases span a wide range of x_c from 0.1 to 40, covering con-

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ditions of efficient ($x_c \ll 1$), inefficient ($x_c \gg 1$), and intermediate ($x_c \sim 1$) precipitation production via the autoconversion process. So these two cases include clouds with different precipitation efficiencies.

Compared to the significant differences in the instantaneous CF, LWP, and AIE, the differences in the corresponding daily averages are less noticeable. For various ε from 0 to 300, the daily averaged CF and LWP differ by <3%, whereas the daily averaged AIE differs by up to 15%. The larger difference in the AIE is due to the magnification of the differences in CF and LWP by the stronger insolation in the afternoon.

These differences in the instantaneous and averaged values imply that the influence of the “smoothness” of threshold representations (determined by ε) is scale-dependent: more significant for the instantaneous values than for the daily averages. Furthermore, the effect of ε strongly depends on x_c or the percentage of clouds in the transitional stage (with weak drizzle or between drizzling and non-drizzling); and the same is expected to hold true for global averages.

4.2 Sensitivity to the critical radius (r_c)

As discussed in Sect. 2, in addition to ε , the theoretical threshold function also depends on x_c . Since x_c is a function of critical radius (r_c) and r_c is a parameter widely used in existing autoconversion parameterizations, the sensitivity to x_c can be replaced by the sensitivity to r_c .

The critical radius r_c has often been prescribed and/or “tuned” to achieve satisfactory agreement with observations of cloud water, albeit without a sound physical basis (Rotstajn, 2000). Recently Liu et al. (2004) derived an analytical expression for r_c based on the kinetic potential theory (McGraw and Liu, 2003, 2004):

$$r_c = 2.8522 \times N^{1/6} / L^{1/3} \quad (3)$$

where r_c is in μm , N is the cloud droplet number concentration in cm^{-3} , and L is the liquid water content in g cm^{-3} . Rotstajn and Liu (2005) found that replacing the

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prescribed r_c with the analytical r_c reduced the second AIE by $\sim 27\%$ using the CSIRO (Commonwealth Scientific and Industrial Research Organisation) GCM.

To better understand the effect of r_c and compare it to the effect of ε , we have performed sensitivity tests on r_c by applying the analytical r_c and by prescribing r_c to be 10, 15, 20, and 25 μm .

Figure 3 shows the results for the “CLEAN” case with $\varepsilon=0$ (i.e., the Kessler-type threshold function). The results with the analytical r_c are shown as the base case (black), and the results with $r_c=10, 15, 20 \mu\text{m}$ are shown in percentage differences relative to this base case. Evidently, a larger prescribed r_c is associated with smaller CF and LWP. At first glance, this association seems contradictory to the hypothesis that decreased precipitation leads to larger CF and LWP (Albrecht, 1989). Deeper analysis reveals that the smaller CF and LWP are due to the stabilization of boundary layer by precipitation formation. Smaller precipitation with increasing r_c results in higher entrainment drying and thereby more efficient depletion of cloud water (Guo et al., 2007b). In the afternoon, the instantaneous CF and LWP (with $r_c=20 \mu\text{m}$) are reduced as much as 60% and 50%, respectively. Consequently, clouds exhibit a more significant diurnal change. This is due to a positive feedback between the cloud geometric radius and entrainment. A smaller cloud radius allows cloudy air to have a larger surface area to mix with drier ambient air, and thus enhances entrainment drying (Blyth et al., 1988).

The relative difference in the instantaneous AIE is even more striking and varies by up to $\sim 80\%$ in the daytime (Fig. 3c). The magnitude of the AIE tends to decrease with a larger r_c , corresponding to the decreased CF and LWP. The variation in the AIE tends to be larger than that in CF or in LWP.

The difference between the base case and the sensitivity test with $r_c=10 \mu\text{m}$ as was suggested by an observational study (Pawlowska and Brenguier, 2003) is minimal, because the averaged analytical r_c is $\sim 10 \mu\text{m}$ although it varies from 7 to 16 μm . This good agreement provides observational support for using the analytical r_c .

The daily averaged CF, LWP, and AIE are reduced by 20%, 20%, and 40%, respectively, when the prescribed $r_c=20 \mu\text{m}$ is used (as compared to the analytical r_c); and

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they are reduced by 6%, 6%, and 20%, respectively, when the prescribed $r_c=15\ \mu\text{m}$ is used as was suggested for heavily drizzling clouds (Gerber, 1996). These results highlight the high sensitivities of the simulated cloud properties and the estimated aerosol forcing to r_c for drizzling clouds.

5 Discussion and concluding remarks

The sensitivities of the cloud fraction (CF), liquid water path (LWP), and aerosol indirect effect (AIE) to different threshold representations associated with the autoconversion process were systematically examined by applying a theoretical threshold function to a 3-D cloud-resolving model. We have found that

1. the sensitivity to threshold representations is larger for the instantaneous CF, LWP, and AIE than for the corresponding daily averages;
2. the sensitivity depends critically on the critical-to-mean mass ratio of cloud water (x_c), or the percentage of transitional clouds with weak drizzle or between drizzling and non-drizzling;
3. the sensitivity to critical radius (r_c) is more significant than the sensitivity to the “smoothness” of threshold representations as embodied in the relative dispersion of droplet size distribution (ε) for drizzling clouds;
4. the relative differences in the instantaneous CF, LWP, and AIE (for $\varepsilon=0$ and 300) are as large as 20%, 40%, and 100%, respectively. But the daily averages are less sensitive to ε ;
5. both CF and LWP tend to vary most significantly during the local afternoon when different values of ε and r_c are used. The magnification of the variations in CF and LWP by the stronger insolation near local noon leads to a larger variation in the AIE. Therefore, the relative differences in the AIE are larger than those in CF or in LWP.

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The theoretical threshold function in Eq. (2) is derived from first principles, so its use would be desirable in modeling studies (Lohmann et al., 2007); but it may be more complex than is warranted in current GCMs especially when the complicated subgrid cloud variation is involved (personal communications with L. Rotstajn and A. Chen, 2007). In order to explore whether the above differences also exist in the threshold functions generally used in GCMs, we have conducted similar sensitivity tests using the generalized Sundqvist threshold function (Liu et al., 2006b), and have obtained similar results (not shown here).

Although this study covers all existing types of ad hoc threshold functions, the effect of ε here should not be considered to be the total effect of ε on clouds and/or aerosol forcing, because the current expression for r_c (and thus x_c) does not account for ε (Liu et al., 2004).

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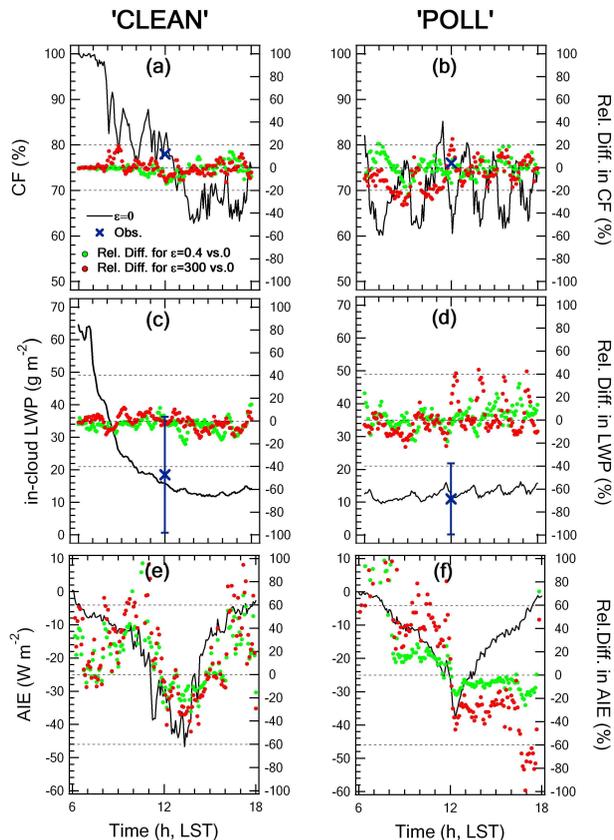


Fig. 1. Time series of cloud fraction (CF, **a**, **b**), in-cloud liquid water path (LWP, **c**, **d**), and aerosol indirect effect (AIE, **e**, **f**) at the top-of-the-atmosphere for the base cases ($\varepsilon=0$, black); and the corresponding relative differences (Rel. Diff.) between the base cases and the sensitivity tests ($\varepsilon=0.4$, green; $\varepsilon=300$, red). The left and right panels are for the “CLEAN” (**a**, **c**, **e**) and “POLL” (**b**, **d**, **f**) cases, respectively. The observed values and their uncertainties are indicated with “x” and vertical bars if available.

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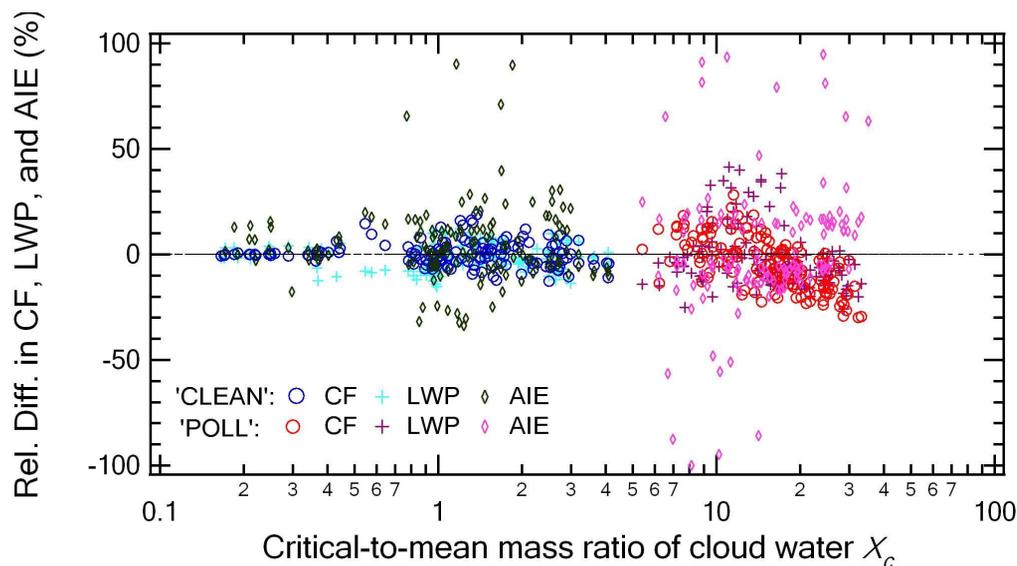


Fig. 2. The relative differences (Rel. Diff.) between the base cases ($\varepsilon=0$) and the sensitivity tests ($\varepsilon=300$) vs. the critical-to-mean mass ration of cloud water (x_c) averaged over all cloudy cells at the same model time for the “CLEAN” and “POLL” cases. The circle, plus, and diamond denote the instantaneous cloud fraction (CF), liquid water path (LWP), and aerosol indirect effect (AIE), respectively.

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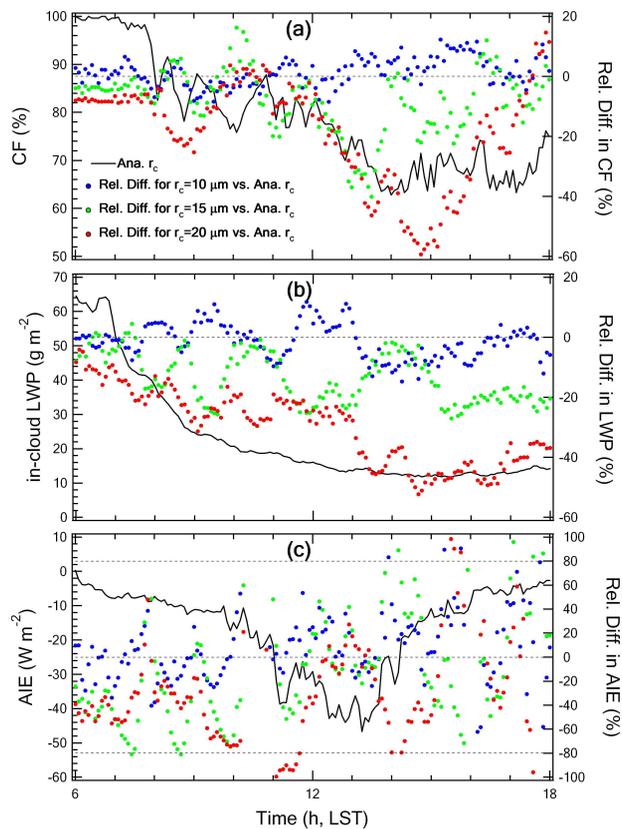


Fig. 3. Similar to Fig. 1, but for the relative differences (Rel. Diff.) between the base case with the analytical critical radius r_c (Ana. r_c) and the sensitivity tests with the prescribed r_c of $10\ \mu\text{m}$ (blue), $15\ \mu\text{m}$ (green), $20\ \mu\text{m}$ (red) for the “CLEAN” case.

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