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M. A. Garcia, M. L. Sánchez, B. de Torre, I. A. Pérez. Characterisation of the mixing height temporal evolution by means of a laser dial system in an urban area? intercomparison results with a model application. *Annales Geophysicae*, 2007, 25 (10), pp.2119-2124. hal-00318394

HAL Id: hal-00318394

<https://hal.science/hal-00318394>

Submitted on 18 Jun 2008

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Characterisation of the mixing height temporal evolution by means of a laser dial system in an urban area – intercomparison results with a model application

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Received: 9 May 2006 – Revised: 29 May 2007 – Accepted: 15 October 2007 – Published: 6 November 2007

Abstract. Measurements of vertical and temporal variations in ozone and aerosol as extinction over an urban area in Segovia, central Spain, were performed during two summer months in 2004 by means of a commercial Nd:YAG laser DIAL remote sensing system. The Differential Absorption Lidar (DIAL) technique was applied and its description is given. From the profile data, a practical determination of mixing height may be derived. A diurnal evolution for the whole dataset is observed, the highest mean mixing height being reached at 16:00 GMT, 2150 m. The presence of a double-layer structure at night was observed and the layers can be considered residual. On average, the lower layer is formed at 670 m and the upper layer yielded mean heights ranging between 1270 and 1390 m. The estimated mixing heights during the day are also compared with those obtained from the Lagrangian HYSPLIT model. The results show good statistical agreement between both approaches, mainly in the early afternoon, with correlation coefficients around 0.7.

Keywords. Atmospheric composition and structure (Evolution of the atmosphere; Instruments and techniques) – Radio science (Remote sensing)

1 Introduction

The height of the atmospheric boundary layer or mixing height is a fundamental parameter characterising the structure of the lower atmosphere. Mixing height determines the volume available for the dispersion of pollutants by convection or mechanical turbulence and understanding it is of particular importance for various applications such as environmental monitoring and the prediction of air pollution, weather forecasting or as a scaling parameter for the description of vertical profiles (Beyrich, 1997). Thus, an accurate

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representation of the mixing depth plays an essential role in the ability of models to calculate pollutant concentrations (Ulke and Mazzeo, 1998). Since the mixing height is not measured by standard meteorological practices, much effort is being invested in improving its estimation. Although there are several definitions and methods for determining the mixing height (Stull, 1988; Seibert et al., 1998, 2000; Karppinen et al., 2001; Sicard et al., 2006), it often proves a somewhat unspecific parameter whose definition and estimation is not precise.

Two general approaches are used to determine mixing heights; on the one hand the analysis of profile measurements from remote sensing and on the other the application of parameterisations or models based on operationally available data. The former has the advantage of providing high temporal and spatial resolution information for the mixing height (He et al., 2006). Although widely used, the second method may entail uncertainties in the specification of the mixing height evolution as discussed by certain authors (Berman et al., 1997; Scaudt and Dickinson, 2000; Nitis et al., 2004).

In recent decades experimental studies of the atmospheric boundary layer have been performed for several types of urban areas. Many of these studies have been summarised by Baklanov (2002), and have enabled analysis of the effects of urban peculiarities and verification of different methods of mixing height estimation versus measurement data sets.

To enhance knowledge of this critical parameter for air pollution applications, we performed an intensive campaign in an urban area, Segovia (Spain). The location chosen is a small city in the upper plateau located close on the foothills of the Guadarrama Mountain Range in the Central Massif. The area is featured by complex topography, with mountains up 2540 m, contributing significantly to the development of convective cells that can inject pollutants from the boundary layer to the free troposphere and mid-troposphere where they can participate in long-range transport processes as has been documented by Millán et al. (1996).

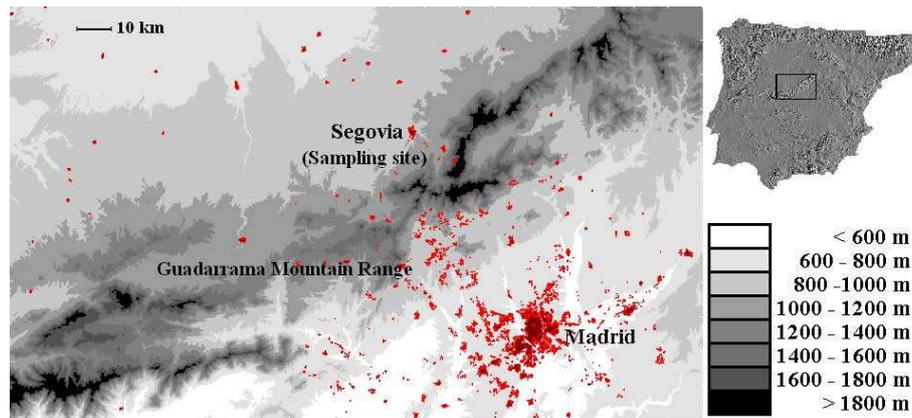


Fig. 1. Topographic map of the sampling site close to the Guadarrama Mountain Range. The domain corresponds to the rectangular area drawn on the Iberian Peninsula.

Continuous measurements of ozone and aerosols (as extinction) were conducted over almost 37 complete days in June and July 2004. The description of the ozone vertical exchange processes in the low troposphere by means of the long temporal series obtained is reported in Sánchez et al. (2007a). This paper focuses on the vertical distribution of aerosols and specifically deals with the following objectives: 1) To present the experimental results obtained and discuss the daily course of the mixing height evolution at the measuring site and b) To analyse the reliability of the day-to-day experimental results with those computed by means of the HYSPLIT model.

2 Sampling site

Continuous measurements of aerosol vertical profiles were performed in the summer of 2004 in an urban area located in Segovia (Spain), a small city close to the Guadarrama Mountain Range (lat. $4^{\circ}4'32''$ N, long. $40^{\circ}56'49''$ W, alt: 1100 m above m.s.l.), some 65 km from Madrid. The site is shown in a topographic map in Fig. 1.

Concurrent meteorological variables were available from the routine measurements carried out by the Territorial Meteorological Centre of Castile and Leon in Segovia. During the measurement period, the site was characterized by slow winds, with a mean value of 2.8 m s^{-1} and extreme values ranging from 0.1 to 11.0 m s^{-1} . The daily cycle of this meteorological variable was consistent with the effects thermally-induced by the mountains, characterised by high values during the period of convective activity whereas light winds were dominant overnight. Hourly temperature values range from 6.8 to 35.7°C , the mean value registered being 21.7°C . During the day, the most frequent wind directions are W and NW accounting for a frequency of 33.6 and 18.3%, respectively. However, E and SE are the main directions at night, 38.9 and 17.0%, respectively. The prevailing wind directions might be attributed to the topographical channelling

effects produced by the Guadarrama Mountains on the general regional winds.

3 Description of the laser remote sensing system

The laser remote sensing device is a commercial compact Lidar system, manufactured by Elight Laser System GmbH, (size: $1.2 \text{ m} \times 0.85 \text{ m} \times 1.45 \text{ m}$) weighing approximately 450 kg. It has low maintenance and operational costs. The system allows monitoring of vertical aerosol distribution (as extinction) from about 400 to 3800 m, depending on the meteorological conditions and the alignment of the equipment.

The profiles were obtained using a Differential Absorption Lidar (DIAL) system based on specific light absorption by molecules, which depends on the wavelength of the incident light. The system uses a Nd:YAG laser that emits pulses at 1064 nm with a repetition rate of 20 Hz. Laser light is converted to 532 nm in the second harmonic generator module and the rest of the 1064 nm pulse is sent into a beam trap. The fourth harmonic generator module converts 532 nm to 266 nm. The rest of 532 nm is sent into a trap, where its energy is measured. 266 nm laser pulses are directed and focused inside the Raman cell, which is 1 m long and filled with Nitrogen at 38 hPa. Inside the Raman cell the 266 nm laser light is partly converted into its first and second Stokes wavelengths. As a result three wavelengths pass the shutter. Backscattered light is collected in a double-coaxial 30 cm diameter telescope and redirected by the Newtonian mirror in the spectrometer, where the signals are transmitted to the photomultipliers. The equipment uses three pairs of wavelengths: 266–284, 284–304 and 266–304 nm. In each pair, one of the wavelengths refers to high selective absorption and the other to no absorption. The difference of the acquired signals allows us to calculate vertical ozone and aerosol distribution as a function of the distance along the beam (Elight

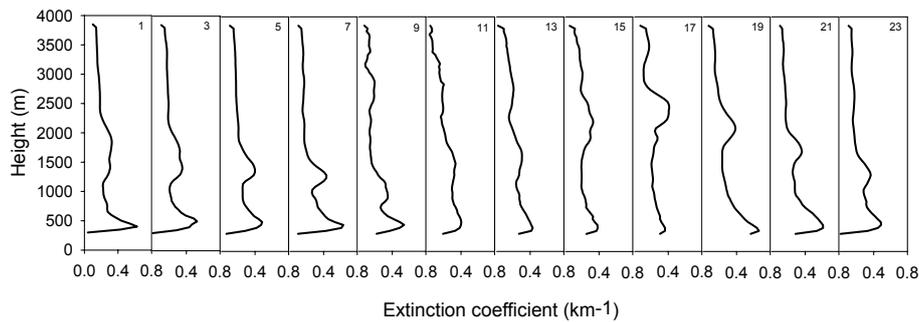


Fig. 2. Vertical profiles of the extinction coefficients corresponding to 16 June 2004 for specific hours of the day.

Laser Systems, 2003). The 284–304 pair was selected for data processing due to its long-range and lower atmospheric absorption. The default temporal resolution of the evaluation software is 10-min. From these data, hourly means were computed. The vertical resolution can be selected by the user and in this paper the default value, 50 m, was selected. The system has been used in an unattended and fully remote controlled operation. This option has allowed us to transfer the data in almost real time as well as to perform routine operations for optical system alignment.

4 Results

4.1 Estimating mixing height from extinction coefficient profiles

During the campaign, extinction coefficients vertical profiles were continuously measured over 16 days in June and 21 in July, covering contrasting scenarios characterised by low and high convective activity. The profile measurements of the extinction coefficients were used for operational estimation of mixing height. Several approaches have been used to estimate this parameter from the Lidar. Sicard et al. (2006) summarise some of these and evaluate three derivative methods. In this paper, a visual inspection method based on a qualitative analysis of the extinction coefficient is considered in a similar way to that provided by Mok and Rudowicz (2004). The profiler mixing depths are determined to be at the transition point where the aerosol amount or the extinction coefficient values under free conditions are lower. Mixing height is assumed to be located at the same height as the maximum extinction coefficient values recorded. Although this method presents a certain weakness, it may be considered an easy to use and straightforward procedure for an approximate initial analysis of data.

Figure 2 shows the development of the mixing layer along a typical day using the extinction coefficient profiles. In this example, mixing height values are lower than those of days with strong convective activity when they may even reach up to 3500 m caused by the slopes heating at the early stage

of convective activity development (Sánchez et al., 2007a, b). The most prominent feature at night is the presence of a double-layer structure clearly visible in the profiles, formed due to katabatic winds during the radiative cooling period as reported in Sánchez et al. (2005). For the time of measurements, mean heights of the lower layer above the ground for each hour vary between 620 to 710 m. We cannot be sure that this is the lowest layer generally formed at a few meters when the earth cools due to equipment restrictions in vertical measurements below the first 400 m since data are not registered. The second layer is characterised by mean heights ranging from 1270 to 1390 m. One possible explanation for this elevated layer is that it might be a residual layer from the day before since it remains during the night when the lower layer also begins to be observed. Moreover, it is interesting to note that after the peak at 16:00 GMT, the elevated layer decreases in height with time while the lowest layer becomes more pronounced. It could be assumed that with the cooling and decrease in mixing, aerosols are no longer being injected to those heights and the apparent decrease in height of the mixed layer is consistent with the development of down-slope mountain breezes.

During the daylight period under unstable atmospheric conditions, the mixing layer height exhibits a well-defined evolution over the sampling location. Figure 3 depicts the variation of the mean mixing heights obtained for June and July 2004 from 09:00 GMT when the mixing layer commences its development to 20:00 GMT, when it collapses. Due to the radiative heating of the ground the morning ascent of the mixing layer culminates at 16:00 GMT with a mean depth of 2150 m. These results agree with other values reported in the literature for continental regions (Bösenberg and Mattias, 2003), but are higher than those obtained for other locations, such as coastal areas (Pérez et al., 2004). Then, a slow decrease is observed towards sunset. The standard deviations of the mixing depths are between 200 and 370 m with the lowest values in the morning and the highest in the late afternoon. However, from 18:00 to 20:00 GMT the data present a slightly greater variability of around 400 m. The linear increase of mixing height observed during the morning hours is quite pronounced with the average mixing

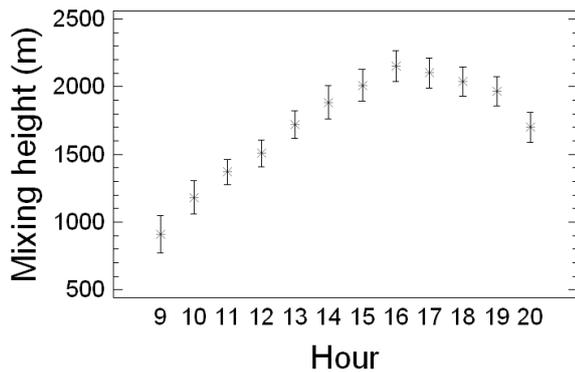


Fig. 3. Hourly evolution of the mean mixing heights at the sampling site in June and July 2004 for specific hours of the day. The bars show the uncertainty intervals of least significant differences at 95% confidence level.

height values. Mixing height peaks at approximately the same time as temperature. The high values obtained are influenced by the strong convection generated in the mountains nearby, mainly with high temperatures. These values frequently occurred when the return signal from aerosols suspended aloft during the previous day's mixing exceeded that from new aerosols being mixed into the developing convective boundary layer as has been commented above (Marsik et al., 1995).

4.2 Determination of the mixing heights from a model – comparison

Among the approaches for the practical estimation of the mixing height, we have used the Lagrangian HYSPLIT 4 model (Draxler and Rolph, 2003) for the same period of time. This model is widely applied in many studies and assumes that there is a well-mixed layer in which pollutant transport and dispersion take place. The model interpolates the mixing depths at the required times from the synoptic times available in the meteorological data with 6 h resolution. It might be worth noting that the interpolated model values between 12:00 and 18:00 GMT are both in the daytime, while interpolations between 06:00–12:00 and 18:00–00:00 GMT might have the influence of the day/night transition. The vertical extent of the mixing layer is calculated within the model from potential temperature data by finding the height of an elevated inversion at each grid point. The model assumes the boundary layer depth to be equal to the height at which the potential temperature first exceeds the value at the ground by 2 K. The temperature profile is analyzed from the top down to determine the boundary layer depth. The top-down approach reduces the influence of shallow stable layers near the ground. In addition, a minimum depth of 250 m is assumed for all hours. The height was chosen to correspond to the minimum height resolution, typical of the meteorological input data (Draxler and Hess, 2004).

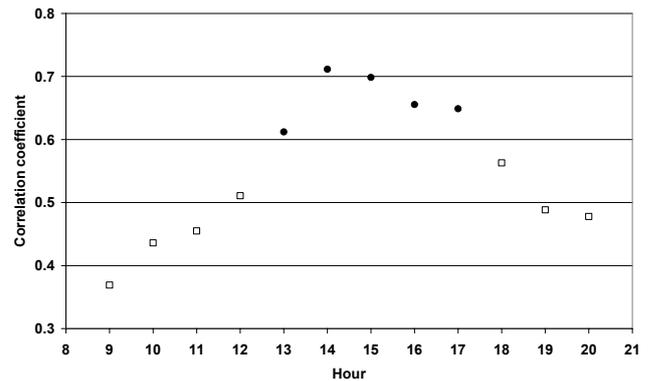


Fig. 4. Correlation coefficients for the linear regression between mixing heights from the profiler measurements and those from the model at specific hours of the day. Black circles correspond to a p-value below 0.01 indicating the statistically significant relationship at a 99% confidence level. White squares correspond to a p-value greater or equal to 0.01 at a 90% or higher confidence level.

The estimated mixing heights obtained directly from the model were compared to those from the profile measurements presented in the previous section. The mean of the percentage differences between the experimental and modelled mixing height values with regard to experimental data were lower than 30%. The intercomparison based on a linear regression was performed for each hour of the day. The results obtained at night for low heights do not allow any definite conclusions to be drawn due to the previously mentioned threshold considered by the model and the limitations of the profiler. Heights might be less reliable and representative to establish a relationship between both approaches. The correlation coefficients vary along the day. The correlation values obtained for certain hours of the day are represented in Fig. 4 and a few important observations can be made. They range between 0.369 and 0.511 in the morning showing a relatively weak relationship between both variables. Similar results are obtained at the end of the day as can be seen. In early afternoon, from 13:00 to 17:00 GMT, the coefficients range between 0.612 and 0.712. The p-value of below 0.01 indicates the statistically significant correlation at a 99% confidence level. Consequently, the better agreement found after noon suggests that the model might prove satisfactory to estimate the mixing height when it is developed. However, experimental measurements in the sampling site are required outside this period. The overall results of this study are in accordance with the conclusions presented by Marsik et al. (1995) regarding mixing height estimates using various systems: rawinsonde system, radar wind profiler-RASS system and also the Lidar system.

5 Conclusions

This paper has described the ability of a commercial laser remote sensing system designed to run autonomously to determine the evolution of the mixing layer over an urban area located in the foothills of the Guadarrama Mountain range over 37 days in summer 2004. The device provides continuous data of vertical aerosol distribution as extinction based on the DIAL technique. When examining the results of the extinction coefficients, an extremely well-defined layer with the highest coefficients is observed and the height corresponding to the transition to lower values is assigned to the mixing layer height. A daily evolution is distinguished and the maximum mean values are obtained in the afternoon when the mixing layer expands, reaching a mean depth of 2150 m. Two residual layers are identified at night. The mean mixing heights of the lower one is not below 600 m justified by the limitation of the equipment in the lower range of 400 m. The higher layer is clearly observed at around an average 1330 m as a residual layer remaining from the day before.

The reliability of the experimental results was tested using the mixing heights computed by the HYSPLIT model, which calculates the vertical extent of the mixing layer from potential temperature. The mean of the percentage differences between the experimental and modelled mixing height values with regard to experimental data were lower than 30%. Intercomparison based on a linear regression was performed for each hour of the day. This approach provides the best fits in the early afternoon with correlation coefficients up to 0.712 ($p < 0.01$) mainly when the mixing height is fully developed. Profiler restrictions and the minimum depth (250 m) assumed by the model make an accurate estimation of the mixing height more difficult during night time. Finally, the resolution of the meteorological data file might also have some influence to interpolate the mixing depths in the morning and in the afternoon due to the day/night transition.

Acknowledgements. This research was funded by the Interministerial Commission of Science and Technology, CICYT, and the Government of Castile and Leon. Special thanks are due to the NOAA Air Resources Laboratory (ARL) for the provision of the HYSPLIT transport and dispersion model and the READY website (<http://www.arl.noaa.gov/ready.html>) used in this publication.

Topical Editor F. D'Andrea thanks two anonymous referees for their help in evaluating this paper.

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