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# The asymptotic value in finite stochastic games

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We provide a direct, self-contained proof for the existence of  $\lim_{\lambda \rightarrow 0} v_\lambda$ , where  $v_\lambda$  is the value of  $\lambda$ -discounted finite two-person zero-sum stochastic game.

*Key words:* Stochastic game; Asymptotic value; Shapley operator  
*MSC2000 subject classification:* 91A06, 91A15

**1. Introduction.** Two-person zero-sum stochastic games were introduced by Shapley [4]. They are described by a 5-tuple  $(\Omega, \mathcal{I}, \mathcal{J}, q, g)$ , where  $\Omega$  is a finite set of states,  $\mathcal{I}$  and  $\mathcal{J}$  are finite sets of actions,  $g : \Omega \times \mathcal{I} \times \mathcal{J} \rightarrow [0, 1]$  is the payoff,  $q : \Omega \times \mathcal{I} \times \mathcal{J} \rightarrow \Delta(\Omega)$  the transition and, for any finite set  $X$ ,  $\Delta(X)$  denotes the set of probability distributions over  $X$ . The functions  $g$  and  $q$  are bilinearly extended to  $\Omega \times \Delta(\mathcal{I}) \times \Delta(\mathcal{J})$ . The stochastic game with initial state  $\omega \in \Omega$  and discount factor  $\lambda \in (0, 1]$  is denoted by  $\Gamma_\lambda(\omega)$  and is played as follows: at stage  $m \geq 1$ , knowing the current state  $\omega_m$ , the players choose actions  $(i_m, j_m) \in \mathcal{I} \times \mathcal{J}$ ; their choice produces a stage payoff  $g(\omega_m, i_m, j_m)$  and influences the transition: a new state  $\omega_{m+1}$  is chosen according to the probability distribution  $q(\cdot | \omega_m, i_m, j_m)$ . At the end of the game, player 1 receives  $\sum_{m \geq 1} \lambda(1-\lambda)^{m-1} g(\omega_m, i_m, j_m)$  from player 2. The game  $\Gamma_\lambda(\omega)$  has a value  $v_\lambda(\omega)$ , and  $v_\lambda = (v_\lambda(\omega))_{\omega \in \Omega}$  is the unique fixed point of the so-called Shapley operator [4], i.e.  $v_\lambda = \Phi(\lambda, v_\lambda)$ , where for all  $f \in \mathbb{R}^\Omega$ :

$$\Phi(\lambda, f)(\omega) = \text{val}_{(s,t) \in \Delta(\mathcal{I}) \times \Delta(\mathcal{J})} \{ \lambda g(\omega, s, t) + (1-\lambda) \mathbb{E}_{q(\cdot | \omega, s, t)} [f(\tilde{\omega})] \}. \quad (1)$$

The Shapley operator provides optimal stationary strategies for both players. In particular, the result holds for any signalling structure on past actions. The existence of  $\lim_{\lambda \rightarrow 0} v_\lambda$  was established by Bewley and Kohlberg [1], using Tarski-Seidenberg elimination theorem.

The purpose of this note is to provide a direct, self-contained proof for the existence of  $\lim_{\lambda \rightarrow 0} v_\lambda$ .

**1.1. The payoff induced by a couple of stationary strategies.** Let  $(x, y) \in \Delta(\mathcal{I})^\Omega \times \Delta(\mathcal{J})^\Omega$  be a pair of stationary strategies. Every time the state  $\omega \in \Omega$  is reached the next state is distributed according to  $q(\cdot | \omega, x(\omega), y(\omega))$  and the stage payoff is  $g(\omega, x(\omega), y(\omega))$ . Thus, the sequence of states  $(\omega_m)_m$  is a Markov chain with transition  $Q = (q(\omega' | \omega, x(\omega), y(\omega)))_{(\omega, \omega') \in \Omega^2}$  and the stage payoffs can be described by a vector  $g = (g(\omega, x(\omega), y(\omega)))_{\omega \in \Omega}$ . Let  $\gamma_\lambda(\omega, x, y)$  be the expected payoff induced by  $(x, y)$  in  $\Gamma_\lambda(\omega)$ . Then  $\gamma_\lambda = (\gamma_\lambda(\omega, x, y))_{\omega \in \Omega}$  is the unique solution of  $\gamma_\lambda = \lambda g + (1-\lambda)Q\gamma_\lambda$ . From Cramer's rule – the matrix  $\text{Id} - (1-\lambda)Q$  is invertible – one deduces that

$\gamma_\lambda(\omega, x, y)$  is a rational fraction in  $\lambda$  and in the variables  $(Q(\omega', \omega))_{(\omega, \omega') \in \Omega^2}$  and  $(g(\omega))_{\omega \in \Omega}$ . Suppose now that  $y \in \Delta(\mathcal{J})^\Omega$  is fixed. Then, for any pair  $(\omega, \omega') \in \Omega^2$ ,  $Q(\omega, \omega') = \sum_{i \in \mathcal{I}} x^i(\omega) q(\omega' | \omega, i, y)$  and  $g(\omega) = \sum_{i \in \mathcal{I}} x^i(\omega) g(\omega, i, y)$ . Thus,  $\gamma_\lambda(\omega, x, y)$  is a rational fraction in  $\lambda$  and in the variables  $(x^i(\omega))_{(\omega, i) \in \Omega \times \mathcal{I}}$ . Moreover, the monomials both in the numerator and in the denominator can all be written in the following form:

$$c\lambda^a \prod_{(\omega, i) \in \Omega \times \mathcal{I}} (x^i(\omega))^{A(\omega, i)}, \quad (2)$$

where  $c \in \mathbb{R}$  is some constant depending on the pair  $(\omega, y)$ ,  $a \in \{0, \dots, |\Omega|\}$  and  $A(\omega, i) \in \{0, 1\}$  for all  $(\omega, i) \in \Omega \times \mathcal{I}$ . Hence, by setting

$$\mathcal{M}^+ = \{(A, a) \mid A \in \{0, 1\}^{\Omega \times \mathcal{I}}, a \in \{0, \dots, |\Omega|\}\},$$

one can express the expected payoff as:

$$\gamma_\lambda(\omega, x, y) = \frac{\sum_{(A, a) \in \mathcal{M}^+} c(A, a) \lambda^a \prod_{(\omega, i) \in \Omega \times \mathcal{I}} (x^i(\omega))^{A(\omega, i)}}{\sum_{(A, a) \in \mathcal{M}^+} c'(A, a) \lambda^a \prod_{(\omega, i) \in \Omega \times \mathcal{I}} (x^i(\omega))^{A(\omega, i)}}, \quad (3)$$

where the real constants  $(c(A, a), c'(A, a))_{(A, a) \in \mathcal{M}^+}$  depend on  $(\omega, y)$  but not on  $(\lambda, x)$ .

**1.2. The asymptotic payoff induced by a sequence of stationary strategies.** Consider now a sequence  $(\lambda_n, x_n)_n$ , where  $\lambda_n \in (0, 1]$  is a discount factor and  $x_n \in \Delta(\mathcal{I})^\Omega$  is a stationary strategy, for all  $n \in \mathbb{N}$ . The aim of this section is to construct a vector which summarizes all relevant information for computing the limit of  $\gamma_{\lambda_n}(\omega, x_n, y)$ , as  $n$  tends to infinity, for a fixed stationary strategy  $y \in \Delta(\mathcal{J})^\Omega$ .

**DEFINITION 1.** A sequence  $(\lambda_n, x_n)_n$  in  $(0, 1] \times \Delta(\mathcal{I})^\Omega$  is *regular* if  $\lim_{n \rightarrow \infty} \lambda_n = 0$  and if for any two monomials of the form (2) their ratio converges in  $[0, +\infty]$  as  $n$  tends to infinity.<sup>1</sup>

Regular sequences can be characterized by a vector. Indeed, introduce the following set:

$$\mathcal{M} := \mathcal{M}^+ - \mathcal{M}^+ = \{(A, a) \mid A \in \{-1, 0, 1\}^{\Omega \times \mathcal{I}}, a \in \{-|\Omega|, \dots, 0, \dots, |\Omega|\}\}.$$

The sequence  $(\lambda_n, x_n)_n$  is regular if for all  $(A, a) \in \mathcal{M}$  the following limit exists in  $[0, +\infty]$ :

$$L[(\lambda_n, x_n)_n](A, a) := \lim_{n \rightarrow \infty} \lambda_n^a \prod_{(\omega, i) \in \Omega \times \mathcal{I}} (x_n^i(\omega))^{A(\omega, i)}. \quad (4)$$

The regularity of a sequence depends on the existence of finitely many limits. Thus, for any family  $(x_\lambda)_{\lambda \in (0, 1]}$  of stationary strategies there exists  $(\lambda_n)_n$  such that  $(\lambda_n, x_{\lambda_n})_n$  is regular.

**PROPOSITION 1.** Let  $y \in \Delta(\mathcal{J})^\Omega$  and  $\omega \in \Omega$  be fixed. For any regular sequence  $(\lambda_n, x_n)_n$ ,  $\lim_{n \rightarrow \infty} \gamma_{\lambda_n}(\omega, x_n, y)$  exists and depends only on the vector  $L[(\lambda_n, x_n)_n]$ .

*Proof.* Let  $(\lambda_n, x_n)_n$  be regular and let  $L = L[(\lambda_n, x_n)_n]$ . We have already seen in Section 1.1 that the expected payoff induced by  $(x_n, y)$  in  $\Gamma_{\lambda_n}(\omega)$  can be written as a rational fraction whose monomials are all of the form (2). A sharper result can be derived from [5, Proposition 3]. The key observation is that, for any  $\omega'$ , the mean  $\lambda$ -discounted time  $t_\lambda(\omega, \omega') = \sum_{m \geq 1} \lambda(1 - \lambda)^{m-1} Q^{m-1}(\omega, \omega')$  can be written as a hitting time of an auxiliary Markov chain whose transitions are in the set  $\{0, \lambda, ((1 - \lambda)Q(\omega, \omega'))_{(\omega, \omega') \in \Omega^2}\}$ . Thus, using a classical result from Friedlin and Wentzell for finite

<sup>1</sup> We use here the natural convention that  $\frac{0}{0} = 0^0 = 1$  and  $0^\beta = 0$ ,  $0^{-\beta} = \frac{\beta}{0} = +\infty$ , for all  $\beta > 0$ .

Markov chains, one deduces that the monomials in  $\gamma_{\lambda_n}(\omega, x_n, y)$  have *nonnegative* coefficients. The monomials are no longer as in (2), but rather of the form:

$$m_n := c(1 - \lambda_n)^b \lambda_n^a \prod_{(\omega, i) \in \Omega \times \mathcal{I}} (x_n^i(\omega))^{A(\omega, i)}, \quad (5)$$

where  $c > 0$  (and does not depend on  $(\lambda_n, x_n)$ ),  $b \in \{0, \dots, |\Omega|\}$  and  $(A, a) \in \mathcal{M}^+$ . Note that the regularity of  $(\lambda_n, x_n)_n$  ensures that, for any two monomials  $m_n$  and  $m'_n$  of the form (5), their ratio converges and is determined by  $L$ , and the constants  $c, c' > 0$ . Use the vector  $L$  to define an order relation in the set of the monomials in  $\gamma_{\lambda_n}(\omega, x_n, y)$ :  $m_n \preceq m'_n$  if and only if  $\lim_{n \rightarrow \infty} m_n/m'_n \in [0, +\infty)$ . The set is totally ordered. Dividing numerator and denominator by some maximal element  $m_n^*$ , and taking  $n \rightarrow \infty$  we obtain that:

$$\lim_{n \rightarrow \infty} \gamma_{\lambda_n}(\omega, x_n, y) = \frac{\sum_{(A, a) \in \mathcal{M}^+} c(A, a) L(A - A^*, a - a^*)}{\sum_{(A, a) \in \mathcal{M}^+} c'(A, a) L(A - A^*, a - a^*)}, \quad (6)$$

for some *nonnegative* constants  $(c(A, a), c'(A, a))_{(A, a) \in \mathcal{M}^+}$ . The maximality of  $m^*$  ensures that  $L(A - A^*, a - a^*) \in [0, +\infty)$ , for all  $(A, a) \in \mathcal{M}^+$  and that not all are 0. The result follows.  $\square$

**1.3. Canonical strategies.** For any  $\mathbf{c} = (\mathbf{c}(\omega, i))$  and  $\mathbf{e} = (\mathbf{e}(\omega, i))$  in  $\mathbb{R}_+^{\Omega \times \mathcal{I}}$ , we define a family of stationary strategies  $(\mathbf{x}_\lambda)_\lambda$  as follows:

$$\mathbf{x}_\lambda^i(\omega) := \frac{\mathbf{c}(\omega, i) \lambda^{\mathbf{e}(\omega, i)}}{\sum_{i' \in \mathcal{I}} \mathbf{c}(\omega, i') \lambda^{\mathbf{e}(\omega, i')}}, \quad \forall (\omega, i) \in \Omega \times \mathcal{I}, \quad \forall \lambda \in (0, 1]. \quad (7)$$

Assume, in addition, that  $\sum_{i \in \mathcal{I}, \mathbf{e}(\omega, i)=0} \mathbf{c}(\omega, i) = 1$  for all  $\omega$ , so that

$$\mathbf{x}_\lambda^i(\omega) \sim_{\lambda \rightarrow 0} \mathbf{c}(\omega, i) \lambda^{\mathbf{e}(\omega, i)}, \quad \forall (\omega, i) \in \Omega \times \mathcal{I}. \quad (8)$$

The exponent determines the order of magnitude of the probability of playing the action  $i$  at state  $\omega$  asymptotically; the coefficient  $\mathbf{c}(\omega, i)$  its intensity.

**DEFINITION 2.** A family of strategies  $(\mathbf{x}_\lambda)_{\lambda \in (0, 1]}$  is *canonical* if it is induced by some  $\mathbf{x} = (\mathbf{c}, \mathbf{e})$  in the following set:

$$\mathbf{X} = \{(\mathbf{c}, \mathbf{e}) \in (\mathbb{R}_+^* \times \mathbb{R}_+)^{\Omega \times \mathcal{I}} \mid \forall \omega \in \Omega, \sum_{i \in \mathcal{I}, \mathbf{e}(\omega, i)=0} \mathbf{c}(\omega, i) = 1\}.$$

Note that the coefficients are taken strictly positive.

For all  $(A, a) \in \mathcal{M}$  and  $\mathbf{x} = (\mathbf{c}, \mathbf{e}) \in \mathbf{X}$  the following limit exists:

$$L_{\mathbf{x}}(A, a) := \lim_{\lambda \rightarrow 0} \lambda^a \prod_{(\omega, i)} (\mathbf{x}_\lambda^i(\omega))^{A(\omega, i)}. \quad (9)$$

Indeed, a direct consequence of (8) is that:

$$L_{\mathbf{x}}(A, a) = \lim_{\lambda \rightarrow 0} \lambda^{a + \sum_{(\omega, i)} A(\omega, i) \mathbf{e}(\omega, i)} \prod_{(\omega, i)} \mathbf{c}(\omega, i)^{A(\omega, i)},$$

where  $\prod_{(\omega, i)} \mathbf{c}(\omega, i)^{A(\omega, i)} > 0$ . Thus:

$$L_{\mathbf{x}}(A, a) \in \begin{cases} \{0\}, & \text{iff } a + \sum_{(\omega, i)} A(\omega, i) \mathbf{e}(\omega, i) > 0, \\ \{+\infty\}, & \text{iff } a + \sum_{(\omega, i)} A(\omega, i) \mathbf{e}(\omega, i) < 0, \\ (0, +\infty), & \text{iff } a + \sum_{(\omega, i)} A(\omega, i) \mathbf{e}(\omega, i) = 0. \end{cases} \quad (10)$$

Thus, for any  $\mathbf{x} \in \mathbf{X}$  and any vanishing sequence  $(\lambda_n)_n$  of discount factors, the sequence  $(\lambda_n, \mathbf{x}_{\lambda_n})_n$  is regular. Moreover,  $L_{\mathbf{x}} = L[(\lambda_n, \mathbf{x}_{\lambda_n})_n]$  for any such sequence.

## 2. Main results.

**2.1. Representation of a regular  $(\lambda_n, x_n)_n$  by a canonical strategy.** Fix some regular sequence  $(\lambda_n, x_n)_n$  throughout this section and let  $L = L[(\lambda_n, x_n)_n] \in [0, +\infty]^{\mathcal{M}}$  the vector defined in (4). Notice that  $L$  has many elementary properties:

(P1)  $L(0, 0) = 1$  and, for all  $(A, a) \neq 0$ ,  $L(A, a) = +\infty$  if and only if  $L(-A, -a) = 0$ ;

(P2) For all  $\mu \in \mathbb{R}$ ,  $L(0, \mu) := \lim_{n \rightarrow \infty} \lambda_n^\mu = 0 \Leftrightarrow \mu > 0$  and  $L(0, \mu) \in (0, +\infty) \Leftrightarrow \mu = 0$ . In particular,  $L(0, \mu) \in \{0, 1, +\infty\}$  for all  $\mu \in \mathbb{R}$ ;

(P3) For all  $(\omega, i) \in \Omega \times \mathcal{I}$ ,  $L((0, \dots, 1^{(\omega, i)}, \dots, 0), 0) := \lim_{n \rightarrow \infty} x_n^i(\omega) \in [0, 1]$ ;

(P4) If  $L(A, a) < +\infty$ , then  $L(\mu A, \mu a) := \lim_{n \rightarrow \infty} \lambda_n^{\mu a} \prod_{(\omega, i)} (x_n^i(\omega))^{\mu A(\omega, i)} = L(A, a)^\mu$ ;

(P5) If  $L(A, a) < +\infty$  and  $L(B, b) < +\infty$ , then  $L(A + B, a + b) = L(A, a)L(B, b)$ .

**PROPOSITION 2.** *There exists  $\mathbf{x} \in \mathbf{X}$  such that  $L_{\mathbf{x}} = L$ .*

*Proof.* Note that  $\prod_{(\omega, i)} \mathbf{c}(\omega, i)^{A(\omega, i)} > 0$  for any  $A \in \{-1, 0, 1\}^{\Omega \times \mathcal{I}}$ . Thus, from (10) and (P1) one deduces the following necessary and sufficient conditions on the coefficients and the exponents  $(\mathbf{c}, \mathbf{e})$  of  $\mathbf{x}$  for having  $L_{\mathbf{x}} = L$ :

$$\sum_{(\omega, i)} A(\omega, i) \mathbf{e}(\omega, i) + a > 0, \quad \forall (A, a) \in \mathcal{M} \text{ s.t. } L(A, a) = 0, \quad (11)$$

$$\sum_{(\omega, i)} A(\omega, i) \mathbf{e}(\omega, i) + a = 0, \quad \forall (A, a) \in \mathcal{M} \text{ s.t. } L(A, a) \in (0, +\infty), \quad (12)$$

$$\prod_{(\omega, i)} \mathbf{c}(\omega, i)^{A(\omega, i)} = L(A, a), \quad \forall (A, a) \in \mathcal{M} \text{ s.t. } L(A, a) \in (0, +\infty). \quad (13)$$

**Notation:** Let  $\mathcal{L}_0 := \{(A, a) \in \mathcal{M} \mid L(A, a) = 0\}$  and  $\mathcal{L}_+ := \{(A, a) \in \mathcal{M} \mid L(A, a) \in (0, +\infty)\}$ . Put  $\mathcal{L} := \mathcal{L}_0 \cup \mathcal{L}_+$ .

**Solving for the exponents.** Let us prove that the system (11)-(12) has a solution. One and only one of the systems (11)-(12) and (14)-(15)-(16) is consistent (see Mertens, Sorin and Zamir [3], part A, page 28):

$$\sum_{(A, a) \in \mathcal{L}} \mu(A, a) A = 0, \quad \mu|_{\mathcal{L}_0} \geq 0, \quad (14)$$

$$-\sum_{(A, a) \in \mathcal{L}} \mu(A, a) a \geq 0, \quad (15)$$

$$-\sum_{(A, a) \in \mathcal{L}} \mu(A, a) a + \sum_{(A, a) \in \mathcal{L}_0} \mu(A, a) > 0, \quad (16)$$

Let us prove that the system (14)-(15)-(16), with unknowns  $\mu = (\mu(A, a))_{(A, a) \in \mathcal{L}} \in \mathbb{R}^{\mathcal{L}}$ , is inconsistent. In (14),  $\mu|_{\mathcal{L}_0} := (\mu(A, a))_{(A, a) \in \mathcal{L}_0}$  denotes the restriction of  $\mu$  to  $\mathcal{L}_0$ . Assume (14). On the one hand, by (P4)-(P5), for all  $\mu \in \mathbb{R}^{\mathcal{L}}$ :

$$\prod_{(A, a) \in \mathcal{L}_+} L(A, a)^{\mu(A, a)} = L\left(\sum_{(A, a) \in \mathcal{L}_+} \mu(A, a) A, \sum_{(A, a) \in \mathcal{L}_+} \mu(A, a) a\right) \in (0, +\infty). \quad (17)$$

On the other hand, by (P4)-(P5), for all  $\mu \in \mathbb{R}^{\mathcal{L}}$  such that  $\mu|_{\mathcal{L}_0} \geq 0$  one has:

$$\prod_{(A, a) \in \mathcal{L}_0} L(A, a)^{\mu(A, a)} = L\left(\sum_{(A, a) \in \mathcal{L}_0} \mu(A, a) A, \sum_{(A, a) \in \mathcal{L}_0} \mu(A, a) a\right) = \begin{cases} 1 & \text{if } \mu|_{\mathcal{L}_0} = 0, \\ 0 & \text{otherwise.} \end{cases} \quad (18)$$

Multiplying (17) and (18) yields, by assumption (14) :

$$L\left(0, \sum_{(A, a) \in \mathcal{L}} \mu(A, a) a\right) \in \begin{cases} (0, +\infty) & \text{if } \mu|_{\mathcal{L}_0} = 0, \\ \{0\} & \text{otherwise.} \end{cases} \quad (19)$$

By (P2), the first case implies  $\sum_{(A,a) \in \mathcal{L}} \mu(A,a)a = 0$ , which contradicts (16), and the second case implies  $\sum_{(A,a) \in \mathcal{L}} \mu(A,a)a = 0$ , which contradicts (15). The system (14)-(15)-(16) being inconsistent, the existence of a solution to (11)-(12) in  $\mathbb{R}^{\Omega \times \mathcal{I}}$  follows. By (P3),  $((0, \dots, 1^{(\omega,i)}, \dots, 0), 0) \in \mathcal{L}_0 \cup \mathcal{L}_+$ . Thus,  $\mathbf{e}(\omega, i) = (0, \dots, 1^{(\omega,i)}, \dots, 0)\mathbf{e} \geq 0$ , by (11) and (12).

**Solving for the coefficients.** Taking the logarithm in (13) yields:

$$\sum_{(\omega,i)} A(\omega, i) \ln \mathbf{c}(\omega, i) = \ln(L(A, a)), \quad \forall (A, a) \in \mathcal{L}_+, \quad (20)$$

which is a linear system in  $\mathbf{d} = (\ln \mathbf{c}(\omega, i))_{(\omega,i)} \in \mathbb{R}^{\Omega \times \mathcal{I}}$ . As before, one and only one of the systems (20) and (21) is consistent:

$$\sum_{(A,a) \in \mathcal{L}_+} \mu(A, a)A = 0, \quad \sum_{(A,a) \in \mathcal{L}_+} \mu(A, a) \ln(L(A, a)) > 0. \quad (21)$$

Let us prove that the system (21), with unknowns  $\mu = (\mu(A, a))_{(A,a)} \in \mathbb{R}^{\mathcal{L}_+}$ , is inconsistent. Suppose that  $\sum_{(A,a) \in \mathcal{L}_+} \mu(A, a)A = 0$ . Then, by (P4)-(P5):

$$\prod_{(A,a) \in \mathcal{L}_+} L(A, a)^{\mu(A,a)} = L\left(0, \sum_{(A,a) \in \mathcal{L}_+} \mu(A, a)a\right) \in (0, +\infty).$$

By (P2), this implies  $\sum_{(A,a) \in \mathcal{L}_+} \mu(A, a)a = 0$  and, a fortiori,  $\prod_{(A,a) \in \mathcal{L}_+} L(A, a)^{\mu(A,a)} = 1$ , so that (21) fails. Consequently, there exists  $\mathbf{c} = (\exp(\mathbf{d}(\omega, i))) \in (\mathbb{R}_+)^{\Omega \times \mathcal{I}}$  satisfying (13).  $\square$

## 2.2. Existence of $\lim_{\lambda \rightarrow 0} v_\lambda$ .

**THEOREM 1.** *The limit of  $(v_\lambda)_\lambda$ , as  $\lambda$  tends to 0, exists. Moreover, there exists  $\mathbf{x} \in \mathbf{X}$  such that  $(\mathbf{x}_\lambda)_\lambda$  is asymptotically optimal, i.e. for all  $\varepsilon > 0$ , there exists  $\lambda_0 \in (0, 1]$  such that:*

$$\gamma_\lambda(\omega, \mathbf{x}_\lambda, j) \geq \lim_{\lambda \rightarrow 0} v_\lambda(\omega) - \varepsilon, \quad \forall \omega \in \Omega, \quad \forall j \in \Delta(\mathcal{J})^\Omega, \quad \forall \lambda \in (0, \lambda_0).$$

*Proof.* Let  $\omega \in \Omega$  be fixed. Let  $(x_\lambda)_{\lambda > 0}$  be a family of optimal stationary strategies in  $(\Gamma_\lambda(\omega))_{\lambda > 0}$  and let  $(\lambda_n)_n$  be a sequence of discount factors such that  $\lim_{n \rightarrow \infty} v_{\lambda_n}(\omega) = \limsup_{\lambda \rightarrow 0} v_\lambda(\omega)$ . The optimality of  $x_{\lambda_n}$  implies that  $\gamma_{\lambda_n}(\omega, x_{\lambda_n}, j) \geq v_{\lambda_n}(\omega)$ , for all  $j \in \mathcal{J}^\Omega$ . Indeed, against a stationary strategy of player 1, player 2 faces a Markov decision process. Thus, player 2 has a pure stationary best reply. Up to some subsequence,  $(\lambda_n, x_{\lambda_n})_n$  is regular. By Proposition 2, there exists  $\mathbf{x} \in \mathbf{X}$  such that  $L_{\mathbf{x}} = L[(\lambda_n, x_{\lambda_n})_n]$ . Thus, by Proposition 1,

$$\lim_{n \rightarrow \infty} \gamma_{\lambda_n}(\omega, x_{\lambda_n}, j) = \lim_{n \rightarrow \infty} \gamma_{\lambda_n}(\omega, \mathbf{x}_{\lambda_n}, j), \quad \forall j \in \mathcal{J}^\Omega.$$

On the other hand, the limit  $\lim_{\lambda \rightarrow 0} \gamma_\lambda(\omega, \mathbf{x}_\lambda, j)$  exists. Consequently:

$$\lim_{\lambda \rightarrow 0} \gamma_\lambda(\omega, \mathbf{x}_\lambda, j) = \lim_{n \rightarrow \infty} \gamma_{\lambda_n}(\omega, x_{\lambda_n}, j) \geq \limsup_{\lambda \rightarrow 0} v_\lambda(\omega), \quad \forall j \in \mathcal{J}^\Omega. \quad (22)$$

It follows that for all  $\varepsilon > 0$  there exists  $\lambda_0 \in (0, 1]$  such that:

$$\min_{j \in \mathcal{J}^\Omega} \gamma_\lambda(\omega, \mathbf{x}_\lambda, j) \geq \limsup_{\lambda \rightarrow 0} v_\lambda(\omega) - \varepsilon, \quad \forall \lambda \in (0, \lambda_0). \quad (23)$$

The latter implies that  $v_\lambda(\omega) \geq \limsup_{\lambda \rightarrow 0} v_\lambda(\omega) - \varepsilon$ , for all  $\lambda \in (0, \lambda_0)$ , and the existence of  $\lim_{\lambda \rightarrow 0} v_\lambda$  follows by taking the  $\liminf$ . The canonical strategy  $\mathbf{x}$  has the desired property.  $\square$

### 2.3. Concluding remarks.

(1) Consider an infinitely repeated stochastic game where the past actions are observed. The existence of the uniform value is due to Mertens and Neyman [2] and relies on the following result:

**THEOREM 2.** *Let  $f : (0, 1) \rightarrow \mathbb{R}^\Omega$  be a function such that:*

- (a)  $\|f_\lambda - f_{\lambda'}\| \leq \int_\lambda^{\lambda'} \varphi(x) dx$ , for all  $0 < \lambda < \lambda' < 1$  and for some  $\varphi \in L^1((0, 1], \mathbb{R}_+)$ ;
- (b) There exists  $\lambda_0 > 0$  such that  $\Phi(\lambda, f_\lambda) \geq f_\lambda$ , for all  $\lambda \in (0, \lambda_0)$ .<sup>2</sup>

Then, player 1 can guarantee  $\lim_{\lambda \rightarrow 0} f_\lambda$  in  $\Gamma_\infty$ .

One can use Theorem 1 to prove the existence of the uniform value. Indeed, for any  $x \in \Delta(\mathcal{I})^\Omega$ ,  $\omega \in \Omega$  and  $\lambda \in (0, 1]$ , let  $w_\lambda^x(\omega) := \min_{j \in \mathcal{J}^\Omega} \gamma_\lambda(\omega, x, j)$  be the payoff guaranteed by  $x$  in  $\Gamma_\lambda(\omega)$ . One can check that  $w_\lambda^x \leq \Phi(\lambda, w_\lambda^x)$ , for all  $\lambda \in (0, 1]$ . Besides, for any  $\mathbf{x} \in \mathbf{X}$ , the functions  $(\lambda \mapsto w_\lambda^{\mathbf{x}}(\omega))_{\omega \in \Omega}$  are of bounded variation, so that player 1 can guarantee  $\lim_{\lambda \rightarrow 0} w_\lambda^{\mathbf{x}}$ , for any  $\mathbf{x} \in \mathbf{X}$ . In particular, if  $(\mathbf{x}_\lambda)_\lambda$  is asymptotically optimal, player 1 can guarantee  $\lim_{\lambda \rightarrow 0} v_\lambda$ .

(2) The existence of an  $\mathbf{x} \in \mathbf{X}$  such that  $(\mathbf{x}_\lambda)_\lambda$  is asymptotically optimal was already noticed by Solan and Vieille [6]. The result was deduced from the semi-algebraicity of  $\lambda \mapsto v_\lambda$ , obtained in [1] using Tarski-Seidenberg elimination theorem.

(3) In the system (11)-(12) for the exponents (first part of the proof of Proposition 2) note that all the entries of  $A$  are in  $\{-1, 0, 1\}$ . This implies the existence of a solution having all its coordinates in  $\{0, 1/N, 2/N, \dots\}$ , for some  $N \leq |\Omega| |\mathcal{I}|^{\sqrt{|\Omega| |\mathcal{I}|}}$ .

(4) Our approach fails without the finiteness assumption on  $\mathcal{I}$ ,  $\mathcal{J}$  and  $\Omega$ . An example where  $\mathcal{I}$  and  $\mathcal{J}$  are compact,  $q$  is continuous,  $g$  is independent of the actions and the family  $(v_\lambda)_\lambda$  does not converge is due to Vigerál [7].

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<sup>2</sup>  $\Phi$  is the Shapley operator, defined in (1).