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A non-topological proof for the impossibility of k -set agreement

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Abstract. In the k -set agreement task each process proposes a value, and it is required that each correct process has to decide a value which was proposed and at most k distinct values must be decided. Using topological arguments it has been proved that k -set agreement is unsolvable in the asynchronous *wait-free* read/write shared memory model, when $k < n$, the number of processes.

This paper presents a simple, non-topological impossibility proof of k -set agreement. The proof depends on two simple properties of the *immediate snapshot executions*, a subset of all possible executions, and on the well known graph theory result stating that every graph has an even number of vertices with odd degree (the *handshaking lemma*).

Keywords: Set agreement, Shared memory, Wait-freedom.

1 Introduction

In a breakthrough result, Fischer, Lynch and Paterson proved [7] that it is impossible to solve consensus in the asynchronous message passing system in which at most one process, which is unknown in advance, can crash. Herlihy [11] and Loui and Abu-Amara [17] extended this impossibility result to the asynchronous wait-free read/write shared memory model, where *wait-free* means that in each execution all processes but one can fail by crashing. Recall that in the *consensus* task, each process proposes a value, and it is required that every correct process decides on a value proposed by some process and no two correct processes decide distinct values.

Later, in order to study the border between solvable and unsolvable tasks in presence of asynchrony and failures, Chaudhuri [6] introduced a natural generalization of consensus, called k -set agreement; in this task, each process proposes a value and it is required that each correct process decides on a value proposed by a process and at most $k \geq 1$ distinct values are decided. For $k = 1$, k -set agreement is exactly consensus, and for $k = n$, the number of processes in the system, k -set agreement is trivial, since every process can decide on its proposal. The paper shows that k -set agreement can be solved by a t -resilient asynchronous algorithm, when $t < k$. An algorithm is t -resilient, $1 \leq t \leq n - 1$, if it solves the problem even in executions where up to t processes crash. This means that

if the number of failures is strictly smaller than the number of possible decision values, then k -set agreement is solvable. Chaudhuri [6] also conjectured that k -set agreement is unsolvable if $t \geq k$. For the case $k = 1$, this conjecture matches the impossibility of solving consensus, namely, 1-set agreement, with a single crash failure [11, 17]. Notice that for the wait-free case, i.e., $t = n - 1$, this conjecture says that only the trivial n -set agreement task has a wait-free solution.

Chaudhuri’s conjecture was proved by Borowsky and Gafni [3], Herlihy and Shavit [15] and Saks and Zaharoglou [18]. Indeed, these three papers discovered a strong relationship between distributed computing and topology and used this topological approach for proving the conjecture of Chaudhuri. Later, Attiya and Rajsbaum [1] and Herlihy and Rajsbaum [13] presented two other topological impossibility proofs of k -set agreement. Although these proofs are not extremely complicated, they use concepts and results that are not widely known by the distributed computing community; the kind of arguments they use vary from combinatorial and algebraic to continuous arguments.

This paper presents a simple, non-topological impossibility proof for k -set agreement. This proof does not demand from the reader any previous knowledge of topology at all. Very roughly, the proof considers the *immediate snapshot (IS) executions* [1, 3, 4, 18] of an algorithm, a subset of all possible executions, and constructs a graph, whose vertices are the IS executions, and whose edges connect two IS executions (vertices) only if they satisfy certain indistinguishability conditions. Then, using the well known *handshaking lemma*, stating that every graph has an even number of vertices with odd degree, the proof concludes that there must be at least one execution in which at least $k + 1$ values are decided.

We believe that it is valuable to have several proofs of this important result, since they provide different perspectives on it. In particular, the proof we present in this paper gives an operational insight into the impossibility of set agreement. Such a perspective cannot be easily obtained from the known topological impossibility proofs for k -set agreement.

We stress that this paper does not argue that the use of topology for proving the impossibility of k -set agreement is “artificial”, namely, that topology has been used before as a “trick” for proving the result. The reader has not to understand this paper in that way. The fundamental reason why k -set agreement is not solvable is topological, and more precisely, it has to do with Sperner’s lemma [10, p. 36]. We strongly encourage the reader to see the connections between the proof we present here and Sperner’s lemma. Moreover, we believe that the topological approach to distributed computing must be studied and extended, since it has been extensively and successfully used in the past for proving a variety of results (see, for example, [5, 8, 9, 12, 14, 16]), and it is unlikely that all these results have non-topological proofs.

The paper is organized as follows. Section 2 describes the asynchronous wait-free read/write shared memory model. Section 3 presents the subset of IS executions, which is used for proving the impossibility of k -set agreement in Section 4. Finally, Section 5 provides an operational perspective of this proof.

2 Model of computation

This section describes the standard asynchronous wait-free read/write shared memory model, considered in this paper, following [1, 2].

System and executions. A *system* consists of n asynchronous sequential processes p_1, \dots, p_n . Each process is a deterministic state machine with a (possibly infinite) set of *local states* S and two subsets of S called *initial states* and *output states*, respectively. The processes communicate by using a shared memory with a finite number of *single-writer multi-reader atomic registers*. No assumption is made regarding the size of the registers, thus we can assume that process p_i has a single register r_i to which it can write its entire state. Process p_i has two atomic operations available to it: $write_i(v)$ that writes the value v into r_i , and $read_i(j)$ that returns the current value in r_j . A *step* is performed by a single process p_i , which executes one of its two available operations, $read_i$ or $write_i$, performs some local computation and then changes its local state.

A *configuration* of the system consists of the local states of the processes and the content of the registers. An *initial configuration* is a configuration in which all local states are initial states and all registers are set to a distinguished value \perp . An *output configuration* is a configuration in which all local states are output states.

An *execution* of the system is a, possibly infinite, alternating sequence of configurations and steps $\alpha = C_0, s_0, C_1, s_1, C_2, \dots$, where C_0 is an initial configuration and $C_{\ell+1}$ is the result of applying the step s_ℓ to C_ℓ , for $\ell \geq 0$. The *view* of a process p_i in α , denoted $\alpha|p_i$, is the sequence of p_i 's local states in configurations C_0, C_1, \dots . The *participating set* of an execution α , denoted $ps(\alpha)$, is the set of processes that take at least one step in the execution.

Two executions α and α' are *indistinguishable* for a set of processes P , denoted $\alpha \sim^P \alpha'$, if all processes in P have the same view in both executions, namely, $\forall p_i \in P, \alpha|p_i = \alpha'|p_i$. In the following section we are interested in pairs of executions α and α' that are distinguishable to exactly one process, that is, there is a process p_i such that $\alpha|p_i \neq \alpha'|p_i$ and $\alpha \sim^P \alpha'$, where $P = \{p_1, \dots, p_n\} \setminus \{p_i\}$. In this case, we write $\alpha \overset{p_i}{\sim} \alpha'$.

Algorithms. The state machine of a process p_i models a *local algorithm* A_i that determines p_i 's next step. An *algorithm* A is a collection of local algorithms A_1, \dots, A_n .

Each process has two distinguished components, *input* and *output*, that allow the system to model decision tasks. The input component never changes and cannot contain the distinguished value \perp . The output component contains initially \perp , and once a process reaches a local state in which a non- \perp value is written in it, the output component never changes. When that happens, we say that the process *decides*. The output states are the states with non- \perp output values. If a process decides v in an execution α , we say v is *decided* in α .

A view of a process p_i in a finite execution α is *final*, if p_i decides in α . A final view of p_i in α is *minimal* if none of its prefixes is final. In other words, the minimal final view of p_i in α is the prefix of the view of p_i up to the first configuration in which p_i decides. A finite execution α is *minimal final* if the view of each process in $\text{ps}(\alpha)$ is a minimal final; in particular, each participating process decides in α . For a minimal final execution α , $\text{dec}(\alpha)$ is the set of all the values that are decided in α , and for a process $p_i \in \text{ps}(\alpha)$, $\text{dec}(\alpha, \neg p_i)$ is the set $\text{dec}(\alpha) \setminus \{v\}$, where v is the value that p_i decides in α . Note that if two distinct processes p_i and p_j decide on the same value v , then $\text{dec}(\alpha, \neg p_i) = \text{dec}(\alpha, \neg p_j)$.

An algorithm A is *wait-free* if in each execution of A , every process executes a finite number of steps or decides. Therefore, a process must decide if it executes an infinite number of steps. We only consider wait-free algorithms.

An algorithm is *full-information* if a process writes its entire local state in every write operation. We say that an algorithm is in *standard-form* if processes proceed in a sequence of asynchronous rounds. In a round, every process first executes a write operation and then asynchronously reads all registers. Note that if there is a wait-free algorithm solving some task, then there is a, possibly inefficient, full-information and standard-form wait-free algorithm solving this task. Since efficiency is not an issue in this paper, we only consider full-information and standard-form algorithms.

k-set agreement. In *k-set agreement* [6], $1 \leq k \leq n$, each process p_i proposes a value and has to decide on a value, such that the following properties hold.

Termination: Each process executes a finite number of steps or decides.

Validity: A decided value is a proposed value.

k-Agreement: At most k different values are decided.

We now define a trivial task \mathcal{T} that will be used in the impossibility proof of k -set agreement. Indeed, in Section 4 we shall see that every wait-free algorithm that solves \mathcal{T} possesses a property which implies that there is no algorithm that solves k -set agreement for $k < n$.

In the task \mathcal{T} each process p_i proposes a value and each process has to decide a value such that the termination and validity properties of k -set agreement are satisfied. Obviously, \mathcal{T} is wait-free solvable: Each process can just decide its proposal, or each process can decide the smallest proposed value it sees in the shared memory. The following lemma is immediate from the definition of k -set agreement and \mathcal{T} .

Lemma 1. *Any wait-free algorithm that solves k -set agreement for some k , $1 \leq k \leq n$, also solves \mathcal{T} .*

3 Immediate snapshot executions

Consider a full-information and standard-form wait-free algorithm. The immediate snapshot executions of this algorithm form a subset of all its possible

executions. The executions in this set have a structure that makes them easier to analyze.

An *immediate snapshot* (IS) execution [1, 3, 4, 18] is modeled by a sequence of non-empty sets of processes $\alpha = s_1, \dots, s_l, \dots$. Processes in s_l first perform, one by one, a write operation and then read all registers. Intuitively, the processes execute a concurrent write followed by a concurrent atomic snapshot of the shared memory. If $p_i \in s_l$, then we say that p_i is *active* in the l -th set of α .

Since we only consider wait-free algorithms, we can restrict our attention to minimal final IS executions, namely, each process executes computation steps until it decides. Indeed, each process decides in the last round in which it is active. We sometimes write α as a concatenation of sequences of sets, i.e., $\alpha = \alpha_1 \alpha_2$, where $\alpha_1 = s_1 s_2 \dots s_\ell$ and $\alpha_2 = s_{\ell+1} s_{\ell+2} \dots s_t$.

For example, $\alpha = \{p, q\} \{r\}$ denotes an IS execution made of 2 sets. Processes p and q are active in the first set and r is active in the second one. Observe that p and q see each other, but do not see r because it executes steps of computation after p and q read the whole memory.

Although IS execution are well-structured they still have uncertainty, as the following example shows. In addition to the execution α described in the previous paragraph, consider the IS execution $\alpha' = \{p\} \{q\} \{r\}$. Note that p only sees itself in α' while sees itself and q in α . The reader can verify that the views of q and r are the same in α and α' . Therefore, $\alpha \stackrel{\neg p}{\sim} \alpha'$.

For a sequence $\alpha = s_1 s_2 \dots s_t$ of sets of processes and a process p_i , we write $p_i \notin \alpha$ if $p_i \notin s_\ell$ for every ℓ , $1 \leq \ell \leq t$. Alternatively, we say that p_i *does not appear* in α . Also, for p_i and $r \geq 1$, we let $\{p_i\}^r$ denote the sequence containing r times the set $\{p_i\}$.

Formally, we say that a process p_i is *unseen* in an IS execution $\alpha = s_1 s_2 \dots s_t$ if and only if there exists ℓ , $1 \leq \ell \leq t - 1$, such that $p_i \notin s_x$, $1 \leq x \leq \ell$ and $s_y = \{p_i\}$, $\ell < y \leq t$. Therefore, if p_i is unseen in α , then $\alpha = \alpha' \{p_i\}^r$, for some $r \geq 1$ and α' , such that $p_i \notin \alpha'$. Intuitively, p_i is unseen in α since every step of p_i occurs after all other processes decided. A process p_i is *seen* in an IS execution α if it is not unseen in α .

Lemmas 2 and 3 below are from [1]. They capture two properties about the uncertainty in minimal final IS executions. They will be used in the impossibility proof of k -set agreement presented in the following section. Lemma 2 is Lemma 3.3 in [1] and Lemma 3 is a restatement of Lemma 3.4 in [1].

Lemma 2. *If a process p_i is unseen in a minimal final IS execution α , then there is no minimal final IS execution α' such that $\alpha \stackrel{\neg p_i}{\sim} \alpha'$.*

Lemma 3. *Let α be a minimal final IS execution in which a process p_i is seen. Then there is a unique minimal final IS execution α' such that $\alpha \stackrel{\neg p_i}{\sim} \alpha'$.*

Let A be a wait-free algorithm. For any given collection C of inputs to the processes, let S be the set containing all minimal final IS executions of A in which the processes start with inputs C . For a subset P of processes, let $PS_P(S)$ be the set containing all executions in S with participating set P . If there is no ambiguity, we write PS_P instead of $PS_P(S)$.

For a proper subset of processes P and a process $p \notin P$, the next lemma shows that there is a one-to-one correspondence between the executions in PS_P and the executions in $PS_{P \cup \{p\}}$ in which p is unseen.

Lemma 4. *For every proper subset of processes P and a process $p_i \notin P$, the following properties hold:*

1. *For every execution $\alpha \in PS_P$ there is a unique execution $\alpha' \in PS_{P \cup \{p_i\}}$ such that p_i is unseen in α' and α is equal to the maximal prefix of α' in which p_i does not appear.*
2. *For every execution $\alpha \in PS_{P \cup \{p_i\}}$ such that p_i is unseen in α , PS_P contains the maximal prefix α' of α in which p_i does not appear.*

Proof. First let us consider an execution $\alpha \in PS_P$. Since A is asynchronous wait-free, α can be extended to a minimal final execution α' with $\text{ps}(\alpha') = P \cup \{p_i\}$, namely, $\alpha' = \alpha \{p_i\}^r$, for some $r \geq 1$. Thus $\alpha' \in PS_{P \cup \{p_i\}}$. Note that p_i is unseen in α' because by hypothesis $p_i \notin \alpha$. In addition, α is the maximal prefix of α' in which p_i does not appear. Moreover, α' is unique because A is deterministic.

Now let us consider an execution $\alpha \in PS_{P \cup \{p_i\}}$ such that p_i is unseen in α . We have that $\alpha = \alpha' \{p_i\}^r$, for some $r \geq 1$ and $p_i \notin \alpha'$. Note that α' is the maximal prefix of α in which p_i does not appear. Moreover, $\alpha' \in PS_P$ because, by hypothesis, each process that appears in α' executes steps of computation until it decides, namely, it is a minimal final IS execution with $\text{ps}(\alpha') = P$. \square

4 Impossibility of k -set agreement

This section is devoted to proving the impossibility of the k -set agreement task in the asynchronous wait-free read/write shared memory model (Theorem 1). The core of the proof is Lemma 6, roughly showing that every wait-free algorithm solving the task \mathcal{T} (defined in Section 2) maintains an invariant concerning the number of its executions in which ℓ distinct processes decide ℓ distinct values. Indeed this lemma can be regarded as the operational counterpart of the Sperner's lemma [10, p. 36]. Then, using Lemma 1 and the invariant in Lemma 6, we conclude that k -set agreement is not wait-free solvable.

Let A be a wait-free algorithm that solves \mathcal{T} . Consider n distinct input values v_1, \dots, v_n and let S be the set containing all minimal final IS executions of A in which process p_i has input v_i , $1 \leq i \leq n$.

Recall that PS_P is the set of all executions in S with participating set P . The next simple lemma directly follows from the validity property of \mathcal{T} , and it is used in the proof of Lemma 6 below.

Lemma 5. *For every subset of processes P and for every execution $\alpha \in PS_P$, $\text{dec}(\alpha)$ contains only the inputs of processes in P .*

When $P = \{p_1, \dots, p_t\}$, $1 \leq t \leq n$, we write PS_t instead of PS_P .

Lemma 6. *For all t , $1 \leq t \leq n$, PS_t contains exactly an odd number of executions $\alpha_1, \dots, \alpha_{2q+1}$, $q \geq 0$, such that $\text{dec}(\alpha_j) = \{v_1, \dots, v_t\}$, $1 \leq j \leq 2q+1$.*

Intuitively, the proof of Lemma 6 proceeds by constructing a graph G using the executions in PS_t as vertices and putting an edge between two executions $\alpha, \alpha' \in PS_t$ if and only if at most one process distinguishes between them and at least $t - 1$ distinct values are decided in α and α' . The graph G also contains an “imaginary” vertex v^* , which is defined in such a way that it has odd degree. This guarantees that G contains at least one vertex with odd degree. All other vertices of G with odd degree, if they exist, correspond to the executions of PS_t in which the values v_1, \dots, v_t are decided. Let M be the set containing all vertices of G with odd degree except v^* . Using the well known handshaking lemma, stating that every graph has an even number of vertices with odd degree,³ the proof finally concludes $|M \cup \{v^*\}|$ is even, hence $|M|$ is odd, which proves the lemma.

Proof (of Lemma 6). We proceed by induction on t . For $t = 1$, PS_1 only contains p_1 's solo execution, that is, PS_1 only contains $\alpha = \{p_1\}^r$, for some $r \geq 1$. Obviously, p_1 must decide v_1 in α , which proves the base of the induction. Now suppose that the lemma holds for $t, 1 \leq t \leq n - 1$. We prove it holds for $t + 1$.

We define a graph $G = (V, E)$ whose vertices are the executions in PS_{t+1} , plus an additional vertex v^* , that is, $V = PS_{t+1} \cup \{v^*\}$. The edges of G are defined as follows (recall that v_i is the input of process p_i).

- For every pair of executions $\alpha, \alpha' \in PS_{t+1}$, $(\alpha, \alpha') \in E$ if and only if there is a process p_i such that $\alpha \stackrel{\neg p_i}{\sim} \alpha'$ and $\text{dec}(\alpha, \neg p_i) = \{v_1, \dots, v_t\}$; hence, $\text{dec}(\alpha', \neg p_i) = \{v_1, \dots, v_t\}$.
- For every execution $\alpha \in PS_{t+1}$, $(v^*, \alpha) \in E$ if and only if p_{t+1} is unseen in α and $\text{dec}(\alpha, \neg p_{t+1}) = \{v_1, \dots, v_t\}$.

Fig. 1 depicts an example of the graph G constructed in the inductive step $t = 2$ for a one-round algorithm for three processes p, q and r . In the algorithm, a process decides its proposal if it sees less than 2 processes. Otherwise, if it sees that its proposal is not the largest one, then decides the smallest proposal, and it decides the second smallest proposal in any other case. In Fig. 1 the inputs for p, q and r are 1, 2 and 3, respectively, and process r corresponds to p_{t+1} . In each execution, above each process it appears the value that the process decides in that execution. Observe that there is an edge between executions $\alpha = \{p\} \{q, r\}$ and $\alpha' = \{p, q, r\}$ because, first, $\alpha \stackrel{\neg p}{\sim} \alpha'$ (p sees no other process than itself in α while it sees q and r in α'), and second, q and r decide 1 and 2, respectively, in α . Also there is an edge between v^* and $\alpha = \{p, q\} \{r\}$ because r is unseen in α and p and q decide 1 and 2. Finally, note that there is no edge between $\alpha = \{p, q, r\}$ and $\alpha' = \{r\} \{p, q\}$ because although $\alpha \stackrel{\neg r}{\sim} \alpha'$, both p and q decide 1 in α .

For the rest of the proof, let $\text{deg}(v)$ denote the degree of a vertex v of G . Below, we prove the following properties about the degrees of the vertices in G .

1. $\text{deg}(v^*)$ is odd.

³ This result is a consequence of Euler's observation that for every graph $G = (V, E)$, $\sum_{v \in V} \text{deg}(v) = 2|E|$.

2. For all $\alpha \in PS_{t+1} = V \setminus \{v^*\}$:
- (a) If $\text{dec}(\alpha) = \{v_1, \dots, v_{t+1}\}$, then $\text{deg}(\alpha) = 1$.
 - (b) If $\text{dec}(\alpha) = \{v_1, \dots, v_t\}$, then $\text{deg}(\alpha) = 2$.
 - (c) Otherwise, $\text{deg}(\alpha) = 0$.

These properties, can be use to derive the induction step, together with the next well-known result of graph theory.

Handshaking Lemma. *Every graph has an even number of vertices with odd degree.*

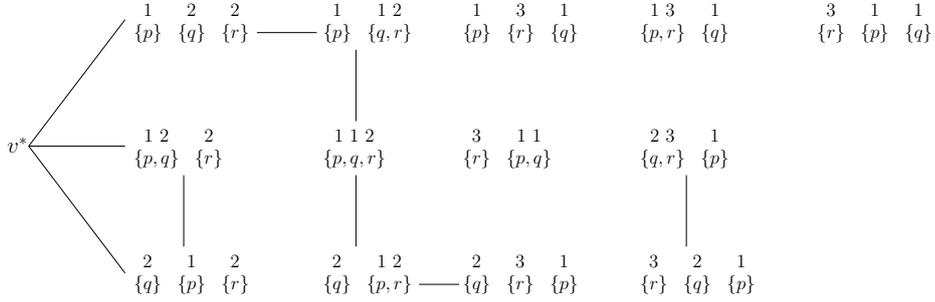


Fig. 1. Graph associated with a 3-process 1-round algorithm.

The vertices of G with odd degree are exactly $M \cup \{v^*\}$, where M is the set that contains every execution $\alpha \in PS_{t+1}$ such that $\text{dec}(\alpha) = \{v_1, \dots, v_{t+1}\}$. Thus, by the Handshaking Lemma, $|M \cup \{v^*\}|$ is even, hence $|M|$ is odd. We now prove the properties of the degrees.

$\text{deg}(v^*)$ is odd. Consider an execution $\alpha \in PS_t$. By Lemma 4(1), there is a unique execution $\alpha' \in PS_{t+1}$ such that p_{t+1} is unseen in α' and α is equal to the maximal prefix of α' in which p_{t+1} does not appear. Conversely, by Lemma 4(2), for every execution $\alpha \in PS_{t+1}$ such that p_{t+1} is unseen in α , PS_t contains the maximal prefix α' of α in which p_{t+1} does not appear.

By the induction hypothesis, we have that PS_t contains exactly an odd number of executions $\alpha_1, \dots, \alpha_{2q+1}$, $q \geq 0$, such that $\text{dec}(\alpha_j) = \{v_1, \dots, v_t\}$, $1 \leq j \leq 2q+1$. Thus for every α_j , $1 \leq j \leq 2q+1$, there is a unique execution $\alpha'_j \in PS_{t+1}$ such that p_{t+1} is unseen in α'_j and α_j is a prefix of α'_j . Hence, $(v^*, \alpha'_j) \in E$, since $\text{dec}(\alpha'_j, \neg p_{t+1}) = \{v_1, \dots, v_t\}$ because $\text{dec}(\alpha_j) = \{v_1, \dots, v_t\}$. Moreover, these are all the edges adjacent to v^* because, as explained above, there is a one-to-one correspondence between the executions of PS_t and the executions of PS_{t+1} in which p_{t+1} is unseen. Therefore, $\text{deg}(v^*)$ is odd.

For every execution $\alpha \in PS_{t+1}$, if $\text{dec}(\alpha) = \{v_1, \dots, v_{t+1}\}$, then $\text{deg}(\alpha) = 1$.

Since $|\text{dec}(\alpha)| = |\{v_1, \dots, v_{t+1}\}| = t + 1$ and $|\text{ps}(\alpha)| = |\{p_1, \dots, p_{t+1}\}| = t + 1$, it follows that for every $v \in \{v_1, \dots, v_{t+1}\}$, there is exactly one process in α that decides v . Let p denote the process that decides v_{t+1} in α . Thus, $\text{dec}(\alpha, \neg p) = \{v_1, \dots, v_t\}$. We identify two subcases: p is unseen in α or p is seen in α .

If p is unseen in α , then, by Lemma 4(2), PS_P contains the maximal prefix α' of α in which p does not appear, where $P = \{p_1, \dots, p_{t+1}\} \setminus \{p\}$. Observe that $\text{dec}(\alpha') = \{v_1, \dots, v_t\}$. Lemma 5 and the assumption that each p_i has a distinct input v_i , imply that $P = \{p_1, \dots, p_{t+1}\} \setminus \{p\} = \{p_1, \dots, p_t\}$, hence $p = p_{t+1}$. Therefore, p_{t+1} is unseen in α and $\text{dec}(\alpha, \neg p_{t+1}) = \{v_1, \dots, v_t\}$, because as explained above $\text{dec}(\alpha, \neg p) = \{v_1, \dots, v_t\}$. By definition of G , $(v^*, \alpha) \in E$.

We claim that (v^*, α) is the only edge that is adjacent to α . First, there is no execution $\alpha' \in PS_{t+1}$ such that $\alpha \stackrel{q}{\sim} \alpha'$ with $q = p_{t+1}$, by Lemma 2. Second, for every process $q \in \{p_1, \dots, p_t\}$, $\text{dec}(\alpha, \neg q) \neq \{v_1, \dots, v_t\}$ because for each $v \in \{v_1, \dots, v_{t+1}\}$ there is exactly one process in α that decides v , and q decides on a value in $\{v_1, \dots, v_t\}$. These two observations imply that there is no $\alpha' \in PS_{t+1}$ such that $(\alpha, \alpha') \in E$, and hence $\text{deg}(\alpha) = 1$.

For the second subcase, namely, p is seen in α , there is only one execution $\alpha' \in PS_{t+1}$ such that $\alpha \stackrel{q}{\sim} \alpha'$, by Lemma 3. Then $(\alpha, \alpha') \in E$, because $\text{dec}(\alpha, \neg p) = \{v_1, \dots, v_t\}$.

The edge (α, α') is the only edge that is adjacent to α : We have that for every $q \in \{p_1, \dots, p_t\}$, $\text{dec}(\alpha, \neg q) \neq \{v_1, \dots, v_t\}$ because for each $v \in \{v_1, \dots, v_{t+1}\}$ there is exactly one process in α that decides v , and q decides a value of $\{v_1, \dots, v_t\}$. Therefore, there does not exist a $\alpha'' \in PS_{t+1}$ such that $\alpha'' \neq \alpha'$ and $(\alpha, \alpha'') \in E$. Hence we get $\text{deg}(\alpha) = 1$.

For every $\alpha \in PS_{t+1}$, if $\text{dec}(\alpha) = \{v_1, \dots, v_t\}$, then $\text{deg}(\alpha) = 2$. Since $|\text{dec}(\alpha)| = |\{v_1, \dots, v_t\}| = t$ and $|\text{ps}(\alpha)| = |\{p_1, \dots, p_{t+1}\}| = t + 1$, we get that there must be a value $\bar{v} \in \{v_1, \dots, v_t\}$ such that there are two distinct processes $q_1, q_2 \in \{p_1, \dots, p_{t+1}\}$ that decide \bar{v} in α . Therefore, for each $i \in \{1, 2\}$, $\text{dec}(\alpha, \neg q_i) = \{v_1, \dots, v_t\}$. Also observe that \bar{v} is the unique value of $\{v_1, \dots, v_t\}$ that has that property.

We identify three subcases: q_1 is unseen and q_2 is seen in α , q_1 is seen and q_2 is unseen in α , and both q_1 and q_2 are seen in α . Note that it is impossible that both q_1 and q_2 are unseen.

Consider first the subcase q_1 is unseen and q_2 is seen in α . The argument is similar to the one in the previous case. If q_1 is unseen in α , then, by Lemma 4(2), PS_P contains the maximal prefix α' of α in which q_1 does not appear, where $P = \{p_1, \dots, p_{t+1}\} \setminus \{q_1\}$. Observe that $\text{dec}(\alpha') = \{v_1, \dots, v_t\}$. Thus, by Lemma 5 and the assumption that each p_i has a distinct input v_i , we get $P = \{p_1, \dots, p_{t+1}\} \setminus \{q_1\} = \{p_1, \dots, p_t\}$, and hence $q_1 = p_{t+1}$. Therefore, p_{t+1} is unseen in α and $\text{dec}(\alpha, \neg p_{t+1}) = \{v_1, \dots, v_t\}$, because $\text{dec}(\alpha, \neg q_1) = \{v_1, \dots, v_t\}$. Hence $(v^*, \alpha) \in E$.

For q_2 , by Lemma 3, there is an execution $\alpha' \in PS_{t+1}$ such that $\alpha \stackrel{q_2}{\sim} \alpha'$. Then $(\alpha, \alpha') \in E$, because $\text{dec}(\alpha, \neg q_2) = \{v_1, \dots, v_t\}$.

We claim that (v^*, α) and (α, α') are the unique edges adjacent to α . First, for q_1 , there is no execution $\alpha'' \in PS_{t+1}$ such that $\alpha \stackrel{\neg q_1}{\sim} \alpha''$, by Lemma 2. Second, for q_2 , there is no $\alpha'' \neq \alpha'$ such that $\alpha \stackrel{\neg q_2}{\sim} \alpha''$, by Lemma 3. And third, for every process $q \in \{p_1, \dots, p_{t+1}\}$ distinct from q_1 and q_2 , $\text{dec}(\alpha, \neg q) \neq \{v_1, \dots, v_t\}$ because q decides on a value in $\{v_1, \dots, v_t\}$ and, as mentioned above, there is no other process in $\{p_1, \dots, p_{t+1}\}$ that decides the same value as q . Therefore, $\text{deg}(\alpha) = 2$.

The subcase in which q_1 is seen and q_2 is unseen in α is symmetric to the previous one.

For the third subcase, that is, q_1 and q_2 are seen in α , for each $i \in \{1, 2\}$ there is an execution $\alpha'_i \in PS_{t+1}$ such that $\alpha \stackrel{\neg q_i}{\sim} \alpha'_i$, by Lemma 3. Then $(\alpha, \alpha'_i) \in E$, because $\text{dec}(\alpha, \neg q_i) = \{v_1, \dots, v_t\}$. As in the first subcase, it can be easily proved that there is no extra edge that is adjacent to α . Hence $\text{deg}(\alpha) = 2$.

Otherwise, $\text{deg}(\alpha) = 0$. We have two subcases: $|\text{dec}(\alpha)| < t$, or $|\text{dec}(\alpha)| = t$ and $\text{dec}(\alpha) \neq \{v_1, \dots, v_t\}$. In both subcases, for every process $p \in \{p_1, \dots, p_{t+1}\}$, $\text{dec}(\alpha, \neg p) \neq \{v_1, \dots, v_t\}$, hence it follows from the definition of G that $\text{deg}(\alpha) = 0$. \square

Theorem 1. *There is no wait-free algorithm that solves k -set agreement for $k < n$.*

Proof. Suppose that there is a wait-free algorithm A that solves k -set agreement, for some k , $1 \leq k \leq n - 1$. By Lemma 1, A solves \mathcal{T} . Consider n distinct input values v_1, \dots, v_n and let S be the set containing all minimal final IS executions of A in which process p_i has input v_i , $1 \leq i \leq n$. Consider the set $PS_{k+1}(S)$, namely, the set containing all executions in S with participating set p_1, \dots, p_{k+1} . By Lemma 6, $PS_{k+1}(S)$ contains an execution α such that $|\text{dec}(\alpha)| = k + 1$. But this contradicts the fact that A solves k -set agreement, since the k -agreement property means that in all executions $\alpha \in PS_{k+1}(S)$, $|\text{dec}(\alpha)| \leq k$. \square

5 An operational perspective

From an operational perspective we can think of the proof of Lemma 6, and hence the impossibility proof of k -set agreement, in the following way.

The induction hypothesis of the proof states that there is an odd number of minimal final IS executions $\alpha_1, \dots, \alpha_{2q+1}$, $q \geq 0$, such that for each $\alpha \in S = \{\alpha_1, \dots, \alpha_{2q+1}\}$, $\text{ps}(\alpha) = \{p_1, \dots, p_k\}$ and $\text{dec}(\alpha) = D = \{v_1, \dots, v_k\}$, where v_i is the input of p_i , $1 \leq i \leq k$. Namely, k processes decide k distinct values in α . As explained in the proof, each $\alpha \in E$ can be extended to a minimal final IS execution γ_1 such that $\text{ps}(\gamma_1) = \{p_1, \dots, p_{k+1}\}$ and p_{k+1} is unseen in γ_1 . Thus, α is the maximal prefix of γ_1 in which p_{k+1} does not appear, hence p_{k+1} decides after all processes p_1, \dots, p_k decide in γ_1 . Moreover, $\text{dec}(\gamma_1, \neg p_{k+1}) = D$ because $\text{dec}(\alpha) = D$. Let us fix α and γ_1 .

Then, taking advantage of the uncertainty related to IS execution, what the proof essentially does is to produce a path P in the graph G that starts in γ_1 .

If $|\text{dec}(\gamma_1)| = k + 1$, then P only contains γ_1 . Otherwise, $|\text{dec}(\gamma_1)| = |D| = k$ and the proof looks for an execution γ_2 such that there is a process p such that $\gamma_1 \stackrel{p}{\sim} \gamma_2$, and hence $\text{dec}(\gamma_2, \neg p) = D$. If there is no such execution γ_2 then P only contains γ_1 , otherwise γ_2 is appended to P and the procedure continues by considering γ_2 instead of γ_1 .

In the end we get a path $P = \gamma_1, \gamma_2, \dots, \gamma_s$, such that $s \geq 1$ and for each i , $1 \leq i \leq s - 1$, there is a process p such that $\gamma_i \stackrel{p}{\sim} \gamma_{i+1}$ and $\text{dec}(\gamma_i, \neg p) = D$. What is important to notice is that the last execution (vertex) γ_s of P holds either $|\text{dec}(\gamma_s)| = k + 1$, or $|\text{dec}(\gamma_s)| = |D| = k$ and p_{k+1} is unseen in γ_s . In the second case we have that the maximal prefix α' of γ_s in which p_{k+1} does not appear, belongs to S . Therefore, in some sense, the path P “matches” α (the maximal prefix of γ_1 in which p_{k+1} does not appear) to α' . For example, in the graph in Fig. 1, the sequence of IS executions $\{p\} \{q\} \{r\}$, $\{q\} \{p\} \{r\}$ matches $\{p\} \{q\}$ to $\{q\} \{p\}$. However, only an even number of execution of S can be matched in this way, and since $|S|$ is odd, we get that there must be a path that matches an $\alpha \in S$ to an execution in which $k + 1$ values are decided. In Fig. 1, the path that starts at $\{p\} \{q\} \{r\}$ and ends at $\{q\} \{r\} \{p\}$, matches $\{p\} \{q\}$ to $\{q\} \{r\} \{p\}$.

Finally, an execution γ with $|\text{dec}(\gamma)| = k + 1$, that is not matched to an execution in S , is matched to an execution γ' with $|\text{dec}(\gamma')| = k + 1$. In Fig. 1, $\{q\} \{r\} \{p\}$ is matched to $\{r\} \{q\} \{p\}$.

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