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► **To cite this version:**

| David Bonnin, Corentin Travers. α -register. 2013. <hal-00863060v2>

HAL Id: hal-00863060

<https://hal.inria.fr/hal-00863060v2>

Submitted on 20 Sep 2013

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α -register*

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Abstract

It is well known that in an asynchronous message-passing system, one can emulate an atomic register providing that more than half of the processes are non-faulty. By contrast, when a majority of the processes may fail, simulating atomic register is not possible. This paper investigates weak variants of atomic registers that can be simulated tolerating a majority of processes failures. Specifically, the paper introduces a new class of registers, called α -register and shows how to emulate them.

For atomic registers, a read operation returns the last written value when there is no concurrent write operations. α -registers generalize atomic registers in the following sense: In any interval I , at most α values written before I are returned by the read operations in I . A simulation of an α -register tolerating f failures in a n -processes system is presented for $\alpha = 2M - 1$, where $M = \max(1, 2f - n + 2)$. The simulation is optimal up to a constant multiplicative factor: the paper establishes that α -registers cannot be simulated tolerating f failures if $\alpha \leq M$.

*This work is supported in part by the ANR project DISPLEXITY.

1 Introduction

Registers A *register* is a basic shared object that allows processes to store and retrieve values. The state of a register consists in a value in some set \mathcal{V} ; it supports two operation: $\text{WRITE}(v)$, that changes its state to v and $\text{READ}()$ that returns the value stored in the register. Several consistency conditions have been defined that specify correct responses for $\text{READ}()$ operations overlapping concurrent $\text{WRITE}()$ operations [21]. In their strongest form, registers are *atomic*: each operation appears to take place instantaneously at some point between its invocation and its response.

Twenty years ago, Attiya, Bar-Noy and Dolev showed that atomic registers can be emulated in asynchronous, crash prone message passing systems provided that a *majority* of the processes do not fail [5]. This fundamental result enables shared-memory algorithms to be automatically implemented in message passing environment. Furthermore, impossibility results and lower bounds established in the shared memory model can directly be translated to message passing. For example, the asynchronous computability theorem that characterizes tasks wait-free solvable in shared memory [20] and its extensions to the t -resilient case [17] apply as well to the asynchronous message passing model with a majority of non-faulty processes.

Beyond the majority barrier A key ingredient of the simulation of registers in message passing is a *quorum system*, that is a collection of sets of processes such that any two sets intersect. In Attiya, Bar-Noy and Dolev protocol (*ABD protocol* [5]), a quorum is any set of $n - f$ processes, where n is the total number of processes in the system and $f < \frac{n}{2}$ an upper bound on the number of failures. Intuitively, a $\text{WRITE}(v)$ involves communicating v to a quorum while a $\text{READ}()$ returns the most recent value in a quorum. By the intersection property, some process participate in both operations, allowing the $\text{READ}()$ to return an up to date value. Quorums defined as set of $n - f$ processes are *live*, in the sense that any process can broadcast a request and eventually receives replies from $n - f$ processes. However, if less than a majority of the processes are non-faulty, i.e. $f \geq \frac{n}{2}$, contacting $n - f$ processes in a $\text{READ}()$ operation may not ensure that the value returned by that operation is up to date. Indeed, simulating atomic registers while tolerating $f \geq \frac{n}{2}$ failures in asynchronous message passing is not possible [5].

A few approaches has been proposed to circumvent this impossibility. Probabilistic quorums systems allow two quorums to be non-intersecting with some small probability [1, 15, 22], leading to a small probability that $\text{READ}()$ operations return stall values. Dynamic atomic storage systems, such as RAMBO [19] and DynaStore [3] emulate atomic registers in dynamic environments. They support a reconfiguration operation for adding or removing processes. Reconfiguration may thus be used to replace failed processes. However, failures are typically assumed to be limited when reconfigurations take place. The approaches [16, 24] are also based on stronger model assumptions.

Another approach consists in relaxing the consistency guarantees of the implementation. *Eventual consistency* [14, 23] essentially only requires that if finitely many $\text{WRITE}()$ operations are performed, eventually every $\text{READ}()$ operation returns the last written value. When availability is a primary concern, eventually consistent services has been implemented and deployed for large-scale, geo-replicated systems (e.g., [9, 12]). In this settings, network partitions may occur but operation must complete even in the case of such events.

The question addressed in the paper The paper investigates the following question:

Given n and $\frac{n}{2} \leq f < n$, what type of (weak) register can be simulated in an n -processes asynchronous message passing system tolerating f failures?

By the ABD emulation, shared memory may be seen as an high-level language to design message passing algorithms tolerating a minority of failures. The question above thus amounts to finding an equivalent high level construct for the case in which a majority of the processes may fail.

Moreover, recently, non-trivial asynchronous algorithms for k -set agreement and k -parallel consensus¹ that tolerate $f(k) \geq \{\frac{n}{2}, k\}$ failures have been designed for message passing systems [7, 8]. While the liveness of these algorithms depends on some additional assumption (such as, e.g., an eventual, non-faulty leader), the safety part relies solely on the bound $f(k)$ on the number of failures. As $f(k) \geq \frac{n}{2}$, the existence of those algorithms cannot be inferred from shared memory results. Identifying weak types of registers, that one can simulate when a majority of the processes could fail, might help understanding what can be computed in such systems.

Contributions of the paper The paper introduces a new type of registers, called α -register and shows an implementation in message passing systems tolerating a majority of faulty processes. Implementations of α -registers are required to be available, that is any WRITE() or READ() request must eventually complete, and partition-tolerant. Indeed, in an asynchronous system in which $f \geq \frac{n}{2}$ processes may fail, processes can be partitioned in two or more sets of at least $n - f$ processes, and messages exchanged between partitions may be arbitrarily delayed. Hence, according to the CAP theorem ([18], Corollary 1.1), it is unavoidable that some READ() operations return outdated values. The parameter α specifies how many distinct outdated values can be read in any interval I , that is values that have been written before I . When $\alpha = 1$, the definition boils down to atomic register.

In more detail, the contribution of the paper is threefold: (1) it introduces α -registers, a new type of register that generalizes atomic registers (Section 2); (2) for $f \geq \frac{n}{2}$ and $M = 2f - n + 2$, it presents a f -resilient message passing implementation of a single-writer multi-reader α -register with $\alpha = 2M - 1$ (Section 3); (3) finally, the paper establishes a lower bound linking f, n and α , namely there is no n -processes, f -resilient implementation of an α -register for $\alpha \leq M$ (Section 4). This lower bound implies that our α -register implementation is within an additive term of at most $\frac{\alpha}{4}$ of the maximal number of failures that can be tolerated.

2 Computational Model and Definition of α -Registers

Message passing asynchronous distributed system We consider a distributed system made of a set Π of n asynchronous processes $\{p_1, \dots, p_n\}$, as described in e.g. [6, 10]. Each process runs at its own speed, independently of the other processes.

Processes communicate by sending and receiving messages over a reliable but asynchronous network. Each pair of processes $\{p_i, p_j\}$ is connected by a bi-directional channel. Channels are reliable and asynchronous, meaning that each message sent by p_i to p_j is received by p_j after some finite, but unknown, time; there is no global upper bound on message transfer delays. The algorithm in Section 3 assumes *FIFO* channels, that is for any pair of processes p_i, p_j , the order in which the messages sent by p_i to p_j are received is the same as the order in which they are sent.

¹ k -set agreement [11] and k -parallel consensus [2] generalize the consensus problem. In k -set agreement, at most k distinct values may be decided. k -parallel consensus consider k instances of consensus and requires each non-faulty process to decide in at least one of them.

The system is equipped with a global clock whose ticks range \mathbb{T} is the set of positive integers. This clock is not available to the processes, it is used from an external point of view to state and prove properties about executions.

In a *step*, a process may send a message to some other process, performs arbitrary local computation and receives a message that has been previously sent to it but has not been already received. An *execution* is a possibly infinite sequence of steps. Processes may fail by *crashing*. A process that crashes prematurely halts and never recovers. In an execution, a process is *faulty* if it fails and *correct* otherwise. f denote an upper bound on the maximal number of processes that may fail.

Definition of α -registers As classical read/write registers, an α -register supports two operations: $\text{WRITE}(v)$, where v is value taken from some set \mathcal{V} and $\text{READ}()$. A $\text{WRITE}(v)$ operation returns an acknowledgment *ok* and a $\text{READ}()$ returns a value $u \in \mathcal{V} \cup \{\perp\}$ where u is the input of a $\text{WRITE}()$ operation or the initial value \perp of the α -register. In an *admissible execution*, no process starts a $\text{WRITE}(v)$ or $\text{READ}()$ operation while its previous operation, if any, has not returned. The *execution interval* $I(op)$ of an operation instance op by process p begins when p calls $\text{WRITE}()$ or $\text{READ}()$ and ends when p returns from that call; if p never returns, $I(op)$ has no end. We sometimes simply say operation instead of operation instance. Two operations op_1 and op_2 are *concurrent* if $I(op_1) \cap I(op_2) \neq \emptyset$. A terminating operation op_1 *precedes* operation op_2 if $I(op_1) \cap I(op_2) = \emptyset$ and $I(op_1)$ ends before $I(op_2)$ begins. An operation op is *active* in an interval I if $I \cap I(op) \neq \emptyset$. To simplify the exposition, we assume without loss of generality that no two distinct $\text{WRITE}()$ operations have the same input value².

In any admissible execution e , a α -register satisfies the following properties.

1. *Termination.* Any $\text{READ}()$ or $\text{WRITE}(v)$ operation performed by a correct process terminates.
2. *Non-spurious value.* For any terminating $\text{READ}()$ operation R that returns u , either $u = \perp$ or there exists a $\text{WRITE}(u)$ operation that precedes or is concurrent with R .
3. *Chronological read.* Let R, R' be two terminating $\text{READ}()$ operations performed by the same process in that order and let u, u' be the values returned. If $u \neq \perp$, then $u' \neq \perp$ and $\text{WRITE}(u)$ precedes or is concurrent with $\text{WRITE}(u')$.
4. *Non-triviality.* Let R be a $\text{READ}()$ operation by process p and let u be the value returned by R . If there is a $\text{WRITE}()$ operation by p that precedes R , $u \neq \perp$. Moreover, if W is the last $\text{WRITE}()$ operation by p that precedes R , $\text{WRITE}(u)$ is either W or a $\text{WRITE}()$ operation by another process that is concurrent with or is preceded by W .
5. *Propagation.* Let u be the input of a terminating $\text{WRITE}()$ or the value returned by a $\text{READ}()$ performed by a correct process. Eventually, for every terminating $\text{READ}()$ operation R' with return value u' either $u = u'$ or $\text{WRITE}(u)$ is concurrent with or precedes $\text{WRITE}(u')$.
6. *α -Bounded reads.* In any interval I , the set of values that have been written by $\text{WRITE}()$ operations that terminate before I and returned by $\text{READ}()$ operation active during I is of size at most α .

The termination property implies that an α -register is always available. In particular, any $\text{READ}()$ operation by a non-faulty process always returns a value. The properties chronological read and

²This can be enforced by appending a sequence number and the id of the writer to each value to be written.

non-triviality express consistency requirements in the context of a single process. Chronological read requires that successive $\text{READ}()$ by the same process p_i do not return older values. Non-triviality intuitively requires that p_i “sees” its writes. After a $\text{WRITE}(u)$ operation, every subsequent $\text{READ}()$ by p_i returns a value as least as recent as u . The propagation properties implies that α -register are eventually consistent. If after some time no $\text{WRITE}()$ operations are performed, eventually every $\text{READ}()$ operation returns the last value written.

Since $f \geq \frac{n}{2}$, it can be shown by a partition argument that $\text{READ}()$ may return arbitrary old values. Consider two sets Q_1, Q_2 of $n - f$ processes that do not intersect and suppose that every process not in $Q_1 \cup Q_2$ initially fails. As communication is asynchronous, messages exchanged between Q_1 and Q_2 may be delayed during an arbitrary long interval I . For some process $p_i \in Q_i, 1 \leq i \leq 2$, the operations by p_i may thus return after messages have been exchanged only with the processes in Q_i (this is indistinguishable for p_i from an execution in which every process not in Q_i fail before I). Therefore, if p_1 performs $\text{WRITE}()$ operations, the values it writes are not seen by p_2 . Thus $\text{READ}()$ operations by p_2 may return values that have written before any $\text{WRITE}()$ operations by p_2 .

Rather than bounding the staleness of values returned by $\text{READ}()$ operation, which is impossible if asynchrony and a majority of failures have to be tolerated, the α -bounded read property imposes that not too many stale values, namely no more than α , are returned by $\text{READ}()$ operations.

3 Single-writer Multiple-reader α -register

This section presents a protocol (Algorithm 3.1) that implements a single-writer multiple-readers (SWMR) α -register in an asynchronous system in which up to $f \leq n - 1$ processes may fail. The value of α depends on the number of failures the protocol tolerates, namely $\alpha = 2M - 1$, where $M = 2f - n + 2$ if $f \geq \frac{n}{2}$ and $M = 1$ otherwise. The algorithm assumes that channels are FIFO.

The algorithm is similar to the ABD protocol [5]. Each time a new value is written it is first associated with a unique timestamp (line 7). Timestamps are increasing so that more recent values get larger timestamps. As there is a single writer, no two values are associated with the same timestamp. Each process p_i maintains a pair of local variables $\langle v_i, ts_i \rangle$ which store the most recent value p_i knows of together with its timestamp. We say that p_i *accepts* a pair $\langle v, t \rangle$ when p_i changes $\langle v_i, ts_i \rangle$ to $\langle v, t \rangle$ (line 25).

Processes constantly exchange messages of type UPDATE that contain the most recent value and its timestamp known by the message’s sender³. For any pair of processes p_i, p_j , UPDATE messages are exchanged between p_i and p_j following a “ping-pong” pattern. Initially, p_i and p_j send UPDATE messages to each other, and each time p_i (resp. p_j) receives UPDATE from p_i (resp. p_j), it replies with an UPDATE message. Each such message contains a triple $(sq, \langle v, ts \rangle, osq)$, where sq and osq are sequence numbers, and $\langle v, ts \rangle$ is the current value and timestamp of the process sending the message. p_i maintains a sequence number that is incremented each time p_i starts a new $\text{WRITE}()$ operation or a new phase in a $\text{READ}()$ operation (see below). If message $m = \text{UPDATE}(sq, \langle v, ts \rangle, osq)$ is sent by p_i in reply to a message $\text{UPDATE}(sq', \langle v', ts' \rangle, osq')$ from p_j (see line 18–line 26), then $osq = sq'$ and sq is the current sequence number of p_i . Thus, by

³The algorithm is not quiescent: processes keep sending and receiving messages even if no $\text{WRITE}()$ or $\text{READ}()$ operations are performed. The algorithm can be made quiescent at the price of an increasing complexity in the pseudo-code. We choose to ignore this issue to keep the pseudo-code simple.

Algorithm 3.1 SWMR α -register (code for process p_i)

```
1: INITIALIZATION
2:    $seq_i \leftarrow 1$ ;  $\langle v_i, ts_i \rangle \leftarrow \langle \perp, 0 \rangle$ ;  $\langle vr_i, tsr_i \rangle \leftarrow \langle \perp, 0 \rangle$ ;
3:    $Qr_i \leftarrow \emptyset$ ;  $Qe_i \leftarrow \emptyset$ ;  $Qw_i \leftarrow \emptyset$ ;
4:    $Accept_i[1..n] \leftarrow [2, \dots, 2]$   $\triangleright$  array of  $n$  integers initialized to 2;
5:   for each  $p_j : 1 \leq j \leq n$  do send UPDATE( $seq_i, \langle v_i, ts_i \rangle, 0$ )
6:   function WRITE( $v$ )
7:      $\langle v_i, ts_i \rangle \leftarrow \langle v, ts_i + 1 \rangle$ ;  $seq_i \leftarrow seq_i + 1$ ;  $Qw_i \leftarrow \emptyset$ ;
8:     wait until  $|Qw_i| \geq n - f$ ;
9:     return ok
10:  function READ( )
11:     $n\_iter \leftarrow 0$ ;
12:    repeat
13:       $\langle vr_i, tsr_i \rangle \leftarrow \langle v_i, ts_i \rangle$ ;  $seq_i \leftarrow seq_i + 1$ ;  $Qr_i \leftarrow \emptyset$ ;  $Qe_i \leftarrow \emptyset$ ;
14:      wait until  $|Qr_i \cup Qe_i| \geq n - f$ ;
15:       $n\_iter \leftarrow n\_iter + 1$ 
16:    until ( $|Qe_i| \geq n - f$ ) or ( $n\_iter \geq N$ )  $\triangleright N = 2(2f + 1)(\lfloor \frac{n}{n-f} \rfloor + 1) + 1$ 
17:    return  $vr_i$ 
18:  WHEN UPDATE( $seq, \langle v, ts \rangle, old\_seq$ ) FROM PROCESS  $p_j$  IS RECEIVED
19:    if  $old\_seq = seq_i$  then
20:      if  $ts = ts_i$  then  $Qw_i \leftarrow Qw_i \cup \{p_j\}$ 
21:      if  $ts > tsr_i$  then  $Qr_i \leftarrow Qr_i \cup \{p_j\}$ 
22:      if  $ts = tsr_i$  then  $Qe_i \leftarrow Qe_i \cup \{p_j\}$ 
23:    if  $ts > ts_i$  then
24:      if  $Accept_i[j] > 0$  then  $Accept_i[j] \leftarrow Accept_i[j] - 1$ 
25:      else  $\langle v_i, ts_i \rangle \leftarrow \langle v, ts \rangle$ ;  $Accept_i[1..n] \leftarrow [2, \dots, 2]$   $\triangleright Accept_i[j] = 0$ 
26:      send UPDATE( $seq_i, \langle v_i, ts_i \rangle, seq$ ) to  $p_j$ 
```

comparing osq with its current sequence number, process p_j can determine whether m is related to its current operation or to a previous operation.

Write() operations The implementation of WRITE(v) is similar to the implementation in the ABD protocol. After a new timestamp t has been associated with v on line 7, the writer p_n changes its local variable $\langle v_n, ts_n \rangle$ to $\langle v, t \rangle$. It then waits until each process in a quorum of $(n - f)$ processes have accepted $\langle v, t \rangle$, and the operation then returns (line 8–line 9). In more detail, the local variable Qw_n , intended to contain a set of processes ids, is emptied at the beginning of the operation (line 7). Then, each time, a message UPDATE containing the pair $\langle v, t \rangle$ from a process p_j is received, p_j is added to Qw_n (line 20). The operation returns when $|Qw| \geq n - f$.

The new pair $\langle v, t \rangle$ is disseminated by the UPDATE messages sent by the writer: once $\langle v_n, ts_n \rangle$ has been changed to $\langle v, t \rangle$, and until a new WRITE() operation is initiated, every UPDATE sent by p_n contains $\langle v, t \rangle$.

Value dissemination As newly written values are propagated asynchronously, at any point in time there might be pending UPDATE that have been sent to p_i by the processes in some set S , but not yet received by p_i . Each of these messages may contain a distinct pair $\langle \text{value}, \text{timestamp} \rangle$

from some set $\{\langle w_1, t_1 \rangle, \dots, \langle w_m, t_m \rangle\}$. If $\langle v_i, ts_i \rangle$ changes each time p_i receives a newer value, the successive values of v_i might be w_1, \dots, w_m . Furthermore, if the same happens at each process in set of size at least $n - f$, it could be the case that each value w_1, \dots, w_m is returned by a `READ()` operation. Instead, to avoid that `READ()` operations return many old values, we ensure that if $\langle v_i, ts_i \rangle$ changes from $\langle w, t \rangle$ to $\langle w', t' \rangle$, some process p_j stores $\langle w', t' \rangle$ after $\langle v_i, ts_i \rangle$ is set to $\langle w, t \rangle$ and before it is changed to $\langle w', t' \rangle$.

Due to the “ping-pong” pattern followed by messages exchanged between processes p_i and p_j , there are at most two messages that have been sent by p_j but have not yet been received by p_i at any point in time. Hence, if p_i receives three `UPDATE` from p_j in some interval I , the last one of these messages has been sent during I . The array $Accept_i$ is used to keep track of how many consecutive messages from the same process carrying new values have been received. Initially, $Accept_i[j] = 2$ and at any time, $Accept_i[j] \in \{0, 1, 2\}$ for any $j, 1 \leq j \leq n$. $Accept_i[j]$ is decremented each time p_i receives an `UPDATE` from p_j (line 24) carrying a value newer than p_i 's current value. The array is also reset to $[2, \dots, 2]$ when $\langle v_i, ts_i \rangle$ changes (line 25). Hence, $Accept_i[j] < 2$ means that p_i knows that its current value is outdated by p_j 's current value (line 23 – line 24). If `UPDATE`($*$, $\langle w, t \rangle$, $*$) where $\langle w, t \rangle$ is newer than $\langle v_i, ts_i \rangle$ is received from p_j when $Accept_i[j] = 0$, $\langle v_i, ts_i \rangle$ is changed to $\langle w, t \rangle$ (line 25).

Suppose that at some point a set X of messages have not been yet received by p_i . Note that if, when some message $m \in X$ is received, $\langle v_i, ts_i \rangle$ changes, then no other message in X updates $\langle v_i, ts_i \rangle$. This is because $Accept_i$ is reset to $[2, \dots, 2]$ each time $\langle v_i, ts_i \rangle$ changes, messages are received in FIFO order and at any point time and for any process p_j , no more than two messages sent by p_j have not been received by p_i .

Read() operations A `READ()` operation (line 11–line 17) by process p_i consists in up to $N = O(\frac{fn}{n-f})$ iterations. Each iteration is identified by an increasing sequence number seq_i . At the beginning of iteration s , the pair $\langle v, ts \rangle$ currently hold by p_i is stored in $\langle vr_i, tsr_i \rangle$ and the two sets Qe_i and Qr_i , intended to contain processes that hold a pair equal to or more recent than, respectively, $\langle vr_i, tsr_i \rangle$ are emptied (line 13). An iteration terminates when p_i knows that at least $n - f$ processes store values as least as recent than vr_i , i.e., when $|Qr_i \cup Qe_i| \geq n - f$. The `READ()` operation terminates (1) immediately if $|Qe_i| \geq n - f$, i.e., for each process $p_j \in Qe_i$, there is a time at which $v_j = vr_i$ or (2) after N iterations have been performed. The value returned is then vr_i , the value of v_i at the beginning of the last iteration. We show in the proof that for every `READ()` operation op that returns a value w written before the operation starts, the operation terminates by condition (1) above. That is, each process p_j in a set Q of size $n - f$ stores v at some point during the interval of op . Intuitively, in each iteration for which condition (1) is not satisfied, p_i learns a newer value. This value is propagated to at least $n - f$ processes in the following iterations. Since the number of values that have been written before op starts and that can be learned and propagated is bounded by a function of f and n , every process knows the last value written before op starts after some constant number of iterations or new values are written concurrently with op .

Consider an interval I . Let w_ℓ be the value written by the last `WRITE()` that terminates before I . When `WRITE`(w_ℓ) returns, each process in a set Q_ℓ of size $n - f$ stores w_ℓ . Since a process can only replace its value with a newer one, the value stored by any process of Q_ℓ at any point in I is w_ℓ or a more recent value. Therefore, any value older than w_ℓ present in the system at the beginning of I is stored or contained in a message not yet received by a processes of $\Pi \setminus Q_\ell$. Let L, T be respectively the values stored by the processes of $\Pi \setminus Q_\ell$ and the values contained in the messages not yet received by the processes of $\Pi \setminus Q_\ell$.

In the worst case, $|L| = f$. The protocol ensures that if $v \in L$ is returned by a $\text{READ}()$ performed during I , then at least $n - f$ processes stores v at some point during I . Since no process changes its value for an older one, the $n - f - 1$ oldest values in L cannot be returned by $\text{READ}()$ operations. Hence, at most $f - (n - f - 1) = 2f - n + 1 = M - 1$ distinct values of L can be read in I .

As previously explained, for each process $p_i \in \Pi \setminus Q_\ell$, at most one message not yet received by p_i at the beginning of I may change the value v_i stored by p_i . Therefore, at most f values of T may be stored by the processes and thus be returned by $\text{READ}()$ operations. As in the case of the values of L , the $n - f - 1$ oldest values cannot be returned by $\text{READ}()$ operations. Therefore, at most $f - (n - f - 1) = 2f - n + 1 = M - 1$ distinct values of T can be read in I . In addition, w_ℓ may be read in I . It thus follows that the number of values written before I and returned by $\text{READ}()$ operations during this interval is at most $2(M - 1) + 1 = 2M - 1 = \alpha$.

3.1 Proof of the protocol

We consider an arbitrary infinite admissible execution α in which the unique writer is the process p_n . var_i denote the local variable var of process p_i and var_i^τ its value at time τ .

Whenever the writer initiates a new $\text{WRITE}()$ operation, it increases a counter whose value ts is assigned as a timestamp to the value v being written (line 7). This timestamp is unique and no other timestamp is ever associated to v . That is, for any process p_i , whenever the local variable v_i is changed to v , ts_i is changed accordingly to the timestamp ts associated with v (line 25). Values can thus be totally ordered according to their timestamp. In particular we say that value v is *newer* than or *more recent* than value v' if the timestamp ts assigned to v is larger than or equal to the timestamp ts' assigned to v' and we note $\langle v', ts' \rangle \preceq \langle v, ts \rangle$. Note that, for any process p_i , whenever the pair $\langle v_i, ts_i \rangle$ is modified (line 7 or line 25), it is replaced by a more recent value. That is,

Observation 3.1. *For every process p_i , and every times $\tau < \tau'$, $\langle v_i^\tau, ts_i^\tau \rangle \preceq \langle v_i^{\tau'}, ts_i^{\tau'} \rangle$.*

Each time a process p_i receives a message UPDATE from a process p_j , it sends back an UPDATE to process p_j (line 18 and line 26). Moreover, initially each process sends an UPDATE message to every process (line 5). It thus follows that messages UPDATE are perpetually exchanged between p_i and p_j if both processes are correct:

Lemma 3.2. *Let p_i, p_j be two correct processes. p_i receives infinitely many messages UPDATE from p_j .*

Proof. Initially, p_i sends an UPDATE message to p_j (initialization, line 5). By the code (line 18 and line 26), each time a correct process p receives a message UPDATE from a process q , p sends a message UPDATE to q . Since p_i and p_j are two correct processes, p_i receives infinitely many messages UPDATE from p_j . \square

Next Lemma shows that whenever a correct process learns a new value, every other correct eventually learn that value or a more recent one. It forms the basis to show that $\text{READ}()$ (Lemma 3.4) and $\text{WRITE}()$ (Lemma 3.5) operations performed by correct processes terminate.

Lemma 3.3. *Let p_i, p_j be two correct processes. If at some time, $\langle v_i, ts_i \rangle = \langle v, ts \rangle \neq \langle \perp, 0 \rangle$, then eventually $\langle v, ts \rangle \preceq \langle v_j, ts_j \rangle$.*

Proof. By Lemma 3.2, process p_j receives infinitely many UPDATE messages from process p_i . Each of these messages contains the value stored in $\langle v_i, ts_i \rangle$ when the message is sent (line 26). As timestamps stored in ts_i never decrease (Observation 3.1), p_j receives infinitely many messages $\text{UPDATE}(*, \langle v', ts' \rangle, *)$ sent by p_i , where $\langle v, ts \rangle \prec \langle v', ts' \rangle$. Suppose that such a message $\text{UPDATE}(*, \langle v', ts' \rangle, *)$ is received by p_j when $\langle v_j, ts_j \rangle \prec \langle v, ts \rangle$ (Otherwise, the Lemma is true). By the code $\text{Accept}_j[i]$ is decremented (line 24) or, if $\text{Accept}_j[i] = 0$, $\langle v_j, ts_j \rangle$ is changed to $\langle v', ts' \rangle$ (line 25). In the latter case, the Lemma is true.

Suppose for contradiction that the Lemma is not true. Hence, each time p_j receives $\text{UPDATE}(*, \langle v', ts' \rangle, *)$ from p_i with $\langle v, ts \rangle \prec \langle v', ts' \rangle$, $\text{Accept}_j[i]$ is decremented. By the code, $\text{Accept}_j[i] \in \{0, 1, 2\}$ and is reset to its initial value 2 when it reaches 0. Since p_j receives infinitely many messages $\text{UPDATE}(*, \langle v', ts' \rangle, *)$ from p_i , with $\langle v, ts \rangle \prec \langle v', ts' \rangle$, it follows that $\text{Accept}_j[i]$ is reset to 2 infinitely many times. However, each time this happens, the value of $\langle v_j, ts_j \rangle$ is replaced by a pair with a strictly higher timestamp (line 25). Therefore, eventually $\langle v, ts \rangle \prec \langle v_j, ts_j \rangle$: a contradiction. \square

Lemma 3.4. *Let p_i be a correct process. Every invocation of $\text{READ}()$ by p_i returns.*

Proof. Assume for contradiction that a $\text{READ}()$ operation R by p_i does not return. By the code, p_i waits forever at line 14, i.e., after some time $|Qr_i \cup Qe_i| < n - f$ forever.

Let $\langle vr, tsr \rangle$ and s be respectively the values stored in $\langle v_i, ts_i \rangle$ and seq_i immediately before p_i enters the non-terminating wait-statement. Note that variables $\langle vr_i, tsr_i \rangle$ and seq_i are no longer modified after p_i has started waiting. Note also that the sets of processes Qr_i and Qe_i are never reset to \emptyset after that point.

Let p_j denote a correct process. Since p_i is correct, and $\langle vr, tsr \rangle$ is stored in $\langle v_i, ts_i \rangle$ at some point in time, it follows from Lemma 3.3 that eventually $\langle vr, tsr \rangle \preceq \langle v_j, ts_j \rangle$. By Lemma 3.2 and the fact that s is the final value of seq_i , p_j receives infinitely many messages $\text{UPDATE}(s, *, *)$ from p_i . To each of these messages, p_j replies to p_i with a message $\text{UPDATE}(*, *, s)$ (line 26). As eventually $\langle vr, tsr \rangle \preceq \langle v_j, ts_j \rangle$, it follows that p_i receives infinitely many messages $\text{UPDATE}(*, \langle v', ts' \rangle, s)$ with $\langle vr, tsr \rangle \preceq \langle v', ts' \rangle$. Therefore, by the code (line 19–line 21), p_j is eventually added to the set $Qr_i \cup Qe_i$. As this is true for any correct process, eventually $|Qr_i \cup Qe_i| \geq n - f$ and the exit condition of the wait statement is thus eventually satisfied: a contradiction. \square

Lemma 3.5. *Assume that the writer p_n is a correct process. Every invocation of $\text{WRITE}()$ by p_n returns.*

Proof. Assume for contradiction that a $\text{WRITE}()$ operation W does not terminate. Let v be the input value of that operation and let ts be the timestamp associated with it (line 7). Let also s be the value stored in seq_i after line 7 has been executed by p_n .

Let p_i be a correct process. At the beginning of W (line 7), the value of $\langle v_n, ts_n \rangle$ is changed to $\langle v, ts \rangle$. As we assume that p_n is a correct process, it follows from Lemma 3.3 that eventually, $\langle v, ts \rangle \preceq \langle v_i, ts_i \rangle$. Moreover, as new timestamps are introduced only by $\text{WRITE}()$ operations, it follows from the fact that W never returns that ts is the largest timestamp ever. Hence, eventually $\langle v_i, ts_i \rangle$ no longer changes and stores forever $\langle v, ts \rangle$. By Lemma 3.2, p_n thus receives infinitely many messages $\text{UPDATE}(s, \langle v, ts \rangle, *)$ from p_i . Therefore, by the code (line 20), we have eventually $p_i \in Qw_n$.

The reasoning above applies to any correct process. Hence, eventually $|Qw_n| \geq n - f$ and W returns (line 8 and line 9): a contradiction. \square

Proof of the bounded reads property In the following we consider an interval \mathcal{I} in which no `WRITE()` operation is active. Let $\mathcal{R} = \{R_1, \dots, R_m\}$ be a set of `READ()` operations whose execution intervals are contained in \mathcal{I} . Let w_i be the value returned by operation R_i and let $\mathcal{V}_R = \{w_1, \dots, w_m\}$.

The remainder of this section is devoted to the proof of the following Lemma:

Lemma 3.6. $|\mathcal{V}_R \setminus \mathcal{V}_W| \leq 2M - 1$ where $M = \max(1, 2f - n + 2)$, where \mathcal{V}_W is the set of values written during \mathcal{I} .

The values returned by each `READ()` of \mathcal{R} is a value that is either written by one of the Write operation active during \mathcal{I} , or a value present in the system at the beginning of \mathcal{I} . A value v with timestamp ts is present in the system at the beginning of \mathcal{I} if it is the value locally stored by a process, i.e., $\langle v, ts \rangle = \langle v_i, ts_i \rangle$ for some process p_i or $\langle v, ts \rangle$ is carried by a message `UPDATE` that has not yet been delivered. Let τ_b be the time at which \mathcal{I} starts. We define:

- \mathcal{V}_W the set of the values written during \mathcal{I} . That is, $w \in \mathcal{V}_W$ if $I(\text{WRITE}(w)) \cap \mathcal{I} \neq \emptyset$.
- $Inc_{j \rightarrow i}$ as the set of incoming messages `UPDATE` that have been sent by p_j but has not yet been received by p_i by time τ_b ;
- $\mathcal{V}_L = \{v : v \notin \mathcal{V}_W \text{ and } \exists p_i, \langle v_i, ts_i \rangle = \langle v, ts \rangle \text{ at time } \tau_b \}$;
- $\mathcal{V}_I = \{v : v \notin \mathcal{V}_L \cup \mathcal{V}_W \text{ and } \exists p_i, p_j, \text{UPDATE}(*, \langle v, ts \rangle, *) \in Inc_{j \rightarrow i}\}$;
- $vlast$, the value written by the last `WRITE()` operation that precedes \mathcal{I} .

That is, \mathcal{V}_L is the set of values locally stored by the processes at the beginning of \mathcal{I} , while \mathcal{V}_I is the set of values that are not locally stored, but part of the content of some messages still in transit. Note that $\mathcal{V}_R \setminus \mathcal{V}_W \subseteq \mathcal{V}_L \cup \mathcal{V}_I$.

We first observe that $|\mathcal{V}_L| \leq f + 1$ (Corollary 3.8). Essentially, this follows from the fact that a quorum Q_{last} of at least $n - f$ processes must have accepted the value written by the last `WRITE()` operation W_{last} preceding \mathcal{I} in order for that operation to return (Lemma 3.7). As a process replace the value it stores locally only with a more recent one (Observation 3.1), the value locally stored by each process $p_i \in Q_{last}$ is newer than or equal to $vlast$, at any time in \mathcal{I} . In other words, the value stored by p_i during \mathcal{I} belongs to $\{vlast\} \cup \mathcal{V}_W$.

Lemma 3.7. *Let $vlast$ be the value written by the last `WRITE()` operation preceding \mathcal{I} and let ts_{last} denote the timestamp associated with it. There is a set Q_{last} of at least $n - f$ processes such that at any time in \mathcal{I} , $v_i \in \{vlast\} \cup \mathcal{V}_W$ and $ts_i \geq ts_{last}$.*

Proof. Let W_{last} be the last `WRITE()` that precedes \mathcal{I} . When this operation returns, p_n has received a message `UPDATE`(*, $\langle v_{last}, ts_{last} \rangle$, *) from each process in a set Q of size at least $n - f$ (line 8). This means that for each $p_i \in Q$, we have at some time $\langle v_i, ts_i \rangle = \langle v_{last}, ts_{last} \rangle$ (line 26).

Moreover, by the code each value v written by the single writer p_n before v_{max} is associated with a timestamp strictly smaller than ts_{max} . As each time the value stored locally (in v_i for process p_i) is modified, it is replaced by a more recent value, i.e., a value associated with a larger timestamp (Observation 3.1), it follows from the fact that W_{last} is the last write operation preceding \mathcal{I} that for every process $p_j \in Q$, $ts_j \geq ts_{last}$ and $v_j \in \{vlast\} \cup \mathcal{V}_W$ at any time in \mathcal{I} . \square

Corollary 3.8. $|\mathcal{V}_L| \leq f + 1$

Proof. By Lemma 3.7, at the beginning of \mathcal{I} , for each process $p_i \in Q_{last}$, $v_i \in \{v_{last}\} \cup \mathcal{V}_W$. As $\mathcal{V}_W \cap \mathcal{V}_L = \emptyset$ and as $|Q_{last}| \geq n - f$, $|\mathcal{V}_L| \leq f + 1$. \square

Consider two processes p_j and p_i . By the code p_j sends a message UPDATE to p_i each time it receives a message UPDATE from that process (line 18–line 26). Since initially both p_i and p_j send a message UPDATE to each other, it follows that at any time at most two messages UPDATE have been sent by p_j to p_i and has not yet been received by the latter:

Observation 3.9. *For every pair of processes p_i, p_j , $|Inc_{j \rightarrow i}| \leq 2$.*

Let $\mathcal{U} \subseteq \mathcal{V}_I$ be the set of values that are not locally stored by any process at the beginning of \mathcal{I} , but later stored by at least one process at some time in \mathcal{I} . That is,

$$u \in \mathcal{U} \iff u \in \mathcal{V}_I \text{ and at some time in } \mathcal{I}, v_i = u \text{ for some process } p_i$$

We upper-bound the size of \mathcal{U} (Lemma 3.10) by f . This upper bound is a key ingredient in establishing that, for any value v read during \mathcal{I} , there is set of at least $(n - f)$ processes p_j that hold v at some point in \mathcal{I} , that is $v_j = v$ at some time in \mathcal{I} (Lemma 3.11).

Lemma 3.10. $|\mathcal{U}| \leq f$

Proof. Let $u \in \mathcal{V}_I$ be a value and let ts denote the timestamp associated with it. Suppose that at some time τ in \mathcal{I} , $\langle v_x, ts_x \rangle = \langle u, ts \rangle$ for some process p_x . At the beginning of \mathcal{I} , no process stores locally u (for every process p_j , $v_j \neq u$) but a message UPDATE whose content contains u has been sent to some process but has not yet been received by that process.

Let p_i be the first process that, during \mathcal{I} change its pair $\langle \text{local value}, \text{timestamp} \rangle$ to $\langle u, ts \rangle$ (at line 25). Since $u \notin \mathcal{V}_L$, this occurs when p_i receives a message $m = \text{UPDATE}(*, \langle u, ts \rangle, *)$ sent to it before \mathcal{I} , that is there exists a process p_j such that $m \in Inc_{j \rightarrow i}$.

Consider another value $u' \neq u$ that similarly to u (1) is contained in \mathcal{V}_I and (2) at some time τ' in \mathcal{I} is stored locally by some process $p_{x'}$ (i.e., at time τ' , $v_{x'} = u'$). Let $p_{i'}$ be the first process that changes during \mathcal{I} its local value $v_{i'}$ to u' . As explained above, this occurs when $p_{i'}$ receives a message $m' \in Inc_{j' \rightarrow i'}$.

Suppose for contradiction that $p_i = p_{i'}$. Assume without loss of generality that p_i first changes v_i to u and then later to u' . By the code, immediately after $\langle v_i, ts_i \rangle$ has been modified, the array $Accept_i$ is reset to $[2, \dots, 2]$ (line 25). As the channels are FIFO, any message received from $p_{j'}$ by p_i during \mathcal{I} and before m' is received are contained in $Inc_{j' \rightarrow i}$. Hence, after m has been received and before the reception of m' , p_i has received at most $|Inc_{j' \rightarrow i}| - 1$ messages from $p_{j'}$. As $|Inc_{j' \rightarrow i}| \leq 2$ (Observation 3.9), it thus follows that $Accept_i[j'] > 0$ when m' is received by p_i (Recall that the counter $Accept_i[j']$ is decremented at most once each time a message from $p_{j'}$ is received line 23–line 24). Therefore (line 24–line 25), v_i remains unchanged when m' is received: a contradiction.

Finally, note that neither p_i nor $p_{i'}$ are contained in Q_{last} since for each process p_j in this set, v_j does not change during \mathcal{I} (Lemma 3.7). As $|Q_{last}| \geq n - f$, we conclude that $|\mathcal{U}| \leq f$. \square

Lemma 3.11. *Let $R \in \mathcal{R}$ be a READ() operation and let v be the value returned by R . Either $v \in \mathcal{V}_W$, or there is a set Q_R of at least $n - f$ processes such that for each $p_i \in Q_R$, there is a time in $I(R)$ at which $v_i = v$.*

Proof. Assume for contradiction the lemma is false. Let ts denote the timestamp associated with v and let p_i be the process that performs R . The **repeat** loop (line 12–line 16) performed by p_i during R terminates either after N iterations or when $|Qe_i| \geq n - f$. In the latter case, this means that p_i receives a message UPDATE carrying $\langle v, ts \rangle$ from each process $p_j \in Qe_i$ (line 22). Therefore, for each process $p_j \in Qe_i$ there is a time during the execution interval of R at which $\langle v_j, ts_j \rangle = \langle v, ts \rangle$. As we assume that the Lemma is false, this case does not occur.

Hence, p_i performs N iterations of the **repeat** loop. In each iteration s of the **repeat** loop, it must receive at least one message of the form UPDATE($*$, $\langle w^s, ts^s \rangle$, s) with $\langle v_i^s, ts_i^s \rangle \prec \langle w^s, ts^s \rangle$, where $\langle v_i^s, ts_i^s \rangle$ is the value of $\langle v_i, ts_i \rangle$ at the beginning of the iteration s . Otherwise, p_i would receive in this iteration messages UPDATE($*$, $\langle w_i^s, ts_i^s \rangle$, s) from $n - f$ distinct processes, meaning that $n - f$ processes hold the pair $\langle w_i^s, ts_i^s \rangle$ at some point. Moreover R would terminate and return w_i^s .

Let us examine what happens at process p_i , when $\langle w^s, ts^s \rangle$, with $\langle v_i^s, ts_i^s \rangle \prec \langle w^s, ts^s \rangle$ is received, say from process p_j . If $ts_i < ts^s$, either $Accept_i[j]$ is decremented or, if the counter has already reached 0, the pair $\langle v_i, ts_i \rangle$ is changed to $\langle w^s, ts^s \rangle$. Otherwise, we have $ts_i \geq ts^s > ts_i^s$ (ts_i^s is the timestamp hold by p_i at the beginning of the iteration). This means that between the beginning of iteration s and the reception of $\langle w^s, ts^s \rangle$, the $\langle v_i, ts_i \rangle$ has been updated with a pair $\langle v, ts \rangle$ with $\langle v_i^s, ts_i^s \rangle \prec \langle v, ts \rangle$. To summarize, in each iteration either $\langle v_i, ts_i \rangle$ is updated to a newer value or the counter $Accept_i[j]$ is decremented, for some process p_j .

Consider a block b of $N_1 = 2 \lfloor \frac{n}{n-f} \rfloor + 2$ consecutive iterations. In each iteration s , p_i receives a pair $\langle w^s, ts^s \rangle$, $\langle v_i^s, ts_i^s \rangle \prec \langle w^s, ts^s \rangle$ where $\langle v_i^s, ts_i^s \rangle$ is the value of $\langle v_i, ts_i \rangle$ at the beginning of the iteration. As an iteration terminates after p_i has received $n - f$ UPDATE messages, it follows that there are at least three iterations s_1, s_2, s_3 in b in which the “newer” pair is sent by the same process, say p_j . That is, for $x = 1, 2, 3$ in iteration s_x , p_i receives from p_j UPDATE($*$, $\langle w^{s_x}, ts^{s_x} \rangle$, s_x) with $\langle v_i^{s_x}, ts_i^{s_x} \rangle \prec \langle w^{s_x}, ts^{s_x} \rangle$. Assuming that the pair $\langle v_i, ts_i \rangle$ is not modified during iterations $1, \dots, s_3 - 1$ (and thus the array $Accept_i$ is not reset to $[2, \dots, 2]$), $Accept_i[j]$ is decremented each time UPDATE($*$, $\langle w^{s_x}, ts^{s_x} \rangle$, s_x), $x = 1, 2$ is received. As the maximal value of $Accept_i[j]$ is 2, $Accept_i[j] = 0$ when UPDATE($*$, $\langle w^{s_3}, ts^{s_3} \rangle$, s_3) is received, that is $\langle v_i, ts_i \rangle$ is changed to $\langle w^{s_3}, ts^{s_3} \rangle$ (line 25). Therefore, in every sequence of N_1 consecutive iterations, $\langle v_i, ts_i \rangle$ is modified at least once.

Now, the READ() operation R takes place in an interval \mathcal{I} with no concurrent WRITE(). The possible successive values of $\langle v_i, ts_i \rangle$ are values in \mathcal{V}_L (values hold by the processes at the beginning of \mathcal{I}) and in \mathcal{U} (values not in \mathcal{V}_L , but hold by at least one process at some point in \mathcal{I}). By Corollary 3.8 and Lemma 3.10, $|\mathcal{V}_L \cup \mathcal{U}| \leq 2f + 1 = N_2$. As the value of $\langle v_i, ts_i \rangle$ can only be replaced by a newer pair (Observation 3.1), it follows that after at most $N_1(N_2 - 1)$ iterations, $\langle v_i, ts_i \rangle$ is equal to the newest pair $\langle v_\ell, ts_\ell \rangle$ in $\mathcal{V}_L \cup \mathcal{U}$. Consider the iteration that immediately follows the iteration in which $\langle v_i, ts_i \rangle$ is changed to $\langle v_\ell, ts_\ell \rangle$ (iteration $N_1(N_2 - 1) + 1 = N$ at the latest). When this iteration terminates, p_i has received from each process p of a set Q , $|Q| \geq n - f$, a message UPDATE($*$, $\langle v_p, ts_p \rangle$, $*$) with $\langle v_\ell, ts_\ell \rangle \preceq \langle v_p, ts_p \rangle$. But as $\langle v_\ell, ts_\ell \rangle$ is the most recent value that any process may locally store during \mathcal{I} , $\langle v_\ell, ts_\ell \rangle = \langle v_p, ts_p \rangle$. Hence, during this iteration, p_i receives $n - f$ UPDATE messages containing $\langle v_\ell, ts_\ell \rangle$, which is value of $\langle v_i, ts_i \rangle$ at the beginning of the iteration. It follows that the operation R returns v_ℓ , value that is at some time in \mathcal{I} the value of v_p for each of the $n - f$ processes in Q , as desired: a contradiction. \square

Finally, we bound the number of values that are read and, on one hand, stored by at least one process (Lemma 3.12), or, on the other hand, only contained in messages that have not yet been

delivered at the beginning of \mathcal{I} (Lemma 3.13). As any old value (i.e., a value not in \mathcal{V}_W) that is read during \mathcal{I} is either stored locally by some process or contains in message not yet delivered at the beginning of \mathcal{I} , the bound on the number of values read during \mathcal{I} follows.

Lemma 3.12. $|\mathcal{V}_L \cap \mathcal{V}_R| \leq M = 2f - n + 2$

Proof. The Lemma is trivially true if $|\mathcal{V}_L| \leq 2f - n + 2$. Suppose that $|\mathcal{V}_L| = x > 2f - n + 2$. Let u_1, \dots, u_x be the values of \mathcal{V}_L ordered from the oldest to the newest, i.e. $t_i < t_{i+1}$ for $1 \leq i < x$, where t_i, t_{i+1} are the timestamps associated with u_i and u_{i+1} respectively. Let $m = x - (2f - n + 2)$.

By Lemma 3.7, there is a set Q_{last} of at least $(n - f)$ processes p_i such that at any point in \mathcal{I} , $v_i \in \{vlast\} \cup \mathcal{V}_W$ and $ts_i \geq tslast$, where $vlast$ is the last value written before \mathcal{I} . By definition of \mathcal{V}_L , $v_i \notin \mathcal{V}_L \setminus \{vlast\}$. For at least $2f - n + 1$ processes $p_j \notin Q_{last}$ the value of v_j at the beginning of \mathcal{I} is in the set $\{u_{m+1}, \dots, u_{x-1}\}$. Hence, at most $n - ((n - f) + (2f - n + 1)) = n - f - 1$ processes p_j have a value in $\{u_1, \dots, u_m\}$ at the beginning of \mathcal{I} .

According to Lemma 3.11, in order for a value $u \in \{u_1, \dots, u_m\}$ to be returned by a $\text{READ}()$ operation, each process p_j in a set $Q, |Q| \geq n - f$ should store u in v_j at some point in \mathcal{I} (because $u \notin \mathcal{V}_W$). As a process only changes the value in v_j to a more recent one (Observation 3.1), Q can contain only processes whose value at the beginning of \mathcal{I} is in $\{u_1, \dots, u_m\}$. As there are at most $n - f - 1$ such processes, no value $u \in \{u_1, \dots, u_m\}$ can be read. Therefore, $\mathcal{V}_L \cap \mathcal{V}_R \subseteq \{u_{m+1}, \dots, u_x\}$, from which it follows that $|\mathcal{V}_L \cap \mathcal{V}_R| \leq 2f - n + 2$. \square

Lemma 3.13. $|\mathcal{V}_I \cap \mathcal{V}_R| \leq M - 1 = 2f - n + 1$

Proof. As in the proof of Lemma 3.12, let u_1, \dots, u_x denote the values in $\mathcal{V}_I \cap \mathcal{V}_R$ ordered from oldest to newest. As value u_1 is returned by a $\text{READ}()$ operation, there is a set Q of $n - f$ processes that hold value u_1 during \mathcal{I} , i.e. for every $p_j \in Q$, there is a time in \mathcal{I} at which $v_j = u_1$.

Let $u' \neq u_1 \in \mathcal{V}_I \cap \mathcal{V}_R$ and let t' denote the timestamp associated with it. We show that the first process p_i that changes its pair $\langle \text{value}, \text{timestamp} \rangle$ to $\langle u', t' \rangle$ does not belong to Q . To see why, assume that for process $p_j \in Q$, $\text{Inc}_{k \rightarrow j}$ contains a message $\text{UPDATE}(*, \langle u', t' \rangle, *)$. As $\langle u_1, t_1 \rangle \notin \mathcal{V}_L$, $\langle v_i, ts_i \rangle$ has been changed to $\langle u_1, t_1 \rangle$ at some time during \mathcal{I} . When this occurs, the counter $\text{Accept}_i[k]$ is reset to 2 (line 25). By observation 3.1, $\langle v_i, ts_i \rangle = \langle u', t' \rangle$ may occur only after $\langle v_i, ts_i \rangle = \langle u_1, t_1 \rangle$ since $t' > t_1$, that is only after the $\text{Accept}_i[k]$ has been changed to 2. Since the channels are FIFO, the messages in $\text{Inc}_{k \rightarrow i}$ are received by p_i before any message sent by p_k during \mathcal{I} . Finally, as $|\text{Inc}_{k \rightarrow i}| \leq 2$ (Observation 3.9), and since the counter $\text{Accept}_i[k]$ does not change or is decremented when a message from p_k is received by p_i , it follows that $\text{Accept}_i[k] > 0$ when p_k 's message $\text{UPDATE}(*, \langle u', t' \rangle, *)$ is received by p_i . By the code (line 25), the message cannot the pair $\langle v_i, ts_i \rangle$ to be changed to $\langle u', t' \rangle$.

Hence $p_i \notin Q$. Note also that $p_i \notin Q_{last}$ and $Q_{last} \cap Q = \emptyset$, as Q_{last} is the set of processes that store the last value written $vlast$ or a more recent value (Lemma 3.7). That is, for each value $u_i \in (\mathcal{V}_I \cap \mathcal{V}_R) \setminus \{u_1\}$, the first process p_i that, during \mathcal{I} is such that $v_i = u_i$ does not belong to $Q \cup Q_{last}$. Finally, as seen in the proof of Lemma 3.10, for any $u_i \neq u_j \in \mathcal{V}_I \cap \mathcal{V}_R$, the first processes p_i, p_j for which during \mathcal{I} $v_i = u_i, v_j = u_j$ respectively are distinct. Therefore, $|\mathcal{V}_I \cap \mathcal{V}_R| \leq n - (n - f) - (n - f) + 1 = 2f - n + 1$. \square

Proof of Lemma 3.6. Any value that is returned by a $\text{READ}()$ operation during \mathcal{I} is either contained in \mathcal{V}_L or \mathcal{V}_I or \mathcal{V}_W . As $|\mathcal{V}_L \cap \mathcal{V}_R| \leq 2f - n + 2$ (Lemma 3.12), and $|\mathcal{V}_I \cap \mathcal{V}_R| \leq 2f - n + 1$ (Lemma 3.13), $|\mathcal{V}_R \setminus \mathcal{V}_W| = |\mathcal{V}_R \cap (\mathcal{V}_L \cup \mathcal{V}_I)| \leq (2f - n + 2) + (2f - n + 1) = 2M - 1$ \square

Finally, the correctness of Algorithm 3.1 is implied by the following theorem.

Theorem 3.14. *Algorithm 3.1 implements a SWMR $(2M - 1)$ -register, where $M = 2f - n + 2$.*

Proof. Consider an admissible execution of Algorithm 3.1. The *termination* property of α -registers immediately follows from Lemma 3.4 and Lemma 3.5. For the *Non-spurious value*, the value returned by a $\text{READ}()$ operation by process p_i is the value of the variable v_i at some time in the execution interval of the operation. At any point in the execution, v_i stores \perp or a value that has been introduced by the writer.

For the *Chronological read* property, consider u, u' two values returned in that order by $\text{READ}()$ operations performed by the same process and let t, t' be the timestamp associated with u, u' respectively. By Observation 3.1, $\langle u, t \rangle \prec \langle u', t' \rangle$. Henceforth, $\text{WRITE}(u)$ precedes $\text{WRITE}(u')$ since there is a single writer. The *Non-triviality* property immediately follows from Observation 3.1: For the single writer, every $\text{READ}()$ operation returns the input of its last preceding $\text{WRITE}()$ or \perp if there is no preceding $\text{WRITE}()$.

To see why the *propagation* property is satisfied, let u be the input of a terminating $\text{WRITE}()$ or the value returned by a $\text{READ}()$ performed by a correct process p_i and let t denote its timestamp. By the code, at some point $\langle v_i, ts_i \rangle = \langle u, t \rangle$. Then, by Lemma 3.3, for every non-faulty process p_j , eventually $\langle u, t \rangle \preceq \langle v_j, ts_j \rangle$. Hence, eventually every value u' returned by $\text{READ}()$ operations is either u or a value written after u . Finally, the α -*Bounded reads* property with $\alpha = 2M - 1$ follows immediately from Lemma 3.6. \square

4 Lower bound

This section presents a lower bound on α for any implementation of an α -register. More precisely, it proves the following theorem:

Theorem 4.1. *Let n, f such that $f \geq \frac{n}{2}$. For any implementation of a SWMR α -register for n processes that tolerates f failures, $\alpha \geq M$.*

Proof. (Sketch) Without loss of generality, assume that A is a full information f -resilient protocol that implements a SWMR α -register. That is, the state of each process consists in its initial state and all its history and each time a process sends a message, it sends its entire state. The single writer is the process p_n .

We construct a family of executions of A . Each execution is parametrized by M integers k_1, \dots, k_M . We show that for some values of k_1, \dots, k_M , M distinct values are returned by $\text{READ}()$ operations in an interval in which no $\text{WRITE}()$ operation is active. Each execution is divided into two phases, each phase consisting in M sequential rounds.

Recall that $M = 2f - n + 2$. Let $\mathcal{V} = \{v_1, \dots, v_M\}$ be a set of M distinct values. $k = (k_1, \dots, k_M)$ is a M -tuple of positive integers. For $i, 1 \leq i \leq M$, let Q_i, Q'_i denote the sets of $n - f$ processes $Q_i = \{p_i\} \cup \{p_{f+2}, \dots, p_n\}$ and $Q'_i = \{p_i\} \cup \{p_{M+1}, \dots, p_{M+(n-f)-1}\}$, respectively. Observe that $Q_i \cap Q'_i = \{p_i\}$ since $M + (n - f) - 1 = f + 1$. Execution \mathcal{E}_k is defined as follows:

First phase. This phase consists in M rounds r_1, \dots, r_n . For each $i, 1 \leq i < M$, round r_{i+1} begins after the end of round r_i . Only processes in Q_i take steps in round r_i . We first let every message that have been sent to processes in Q_i during the previous rounds (if any) to be received. Then, $k_i + 2$ operations on the α -register implemented by A are performed sequentially, in that order:

1. $\text{WRITE}(v_i)$ is performed by process p_n ;

2. Process p_n performs READ();
3. k_i READ() operations are performed by process p_i .

The messages sent to processes $p_j \notin Q_i$ are delayed until some time specified later. As $|Q_i| = n - f$, the execution is indistinguishable by processes in Q_i from an execution that is the same as \mathcal{E}_k until the end of round r_{i-1} and in which the f processes $\notin Q_i$ fail at the beginning of r_i . As A tolerates f failures, every operation performed during round r_i terminates.

Note that the READ() operation performed by p_n return v_i by the non-triviality property of α -registers. Moreover, observe that if k_i is chosen large enough, the last READ() operation performed by p_i returns also v_i by the propagation property.

Second phase. This phase consists also in M rounds r'_1, \dots, r'_M . In round r'_i , which begins after round r'_{i-1} has ended, only processes in Q'_i take steps. We first let the messages that have been sent to the processes in Q'_i during previous rounds $r'_j, 1 \leq j < i$ to be delivered. Then, process p_i performs a READ() operation. As in round r_i , the execution is indistinguishable to the processes in Q'_i from an execution that is the same until the end of round r_{i-1} and in which the f processes $\notin Q_i$ fail at the beginning of r'_i . Since A tolerates f failures, the READ() operation terminates.

Assuming that k_i has been chosen large enough, the previous READ() operation performed by p_i (in round r_i) returns v_i . By the chronological read property of α -registers, the READ() by p_i in r'_i must return v_i or more recent value, that is a value v_j with $j > i$.

Consider the rounds r_{i+1}, \dots, r_M . The set of processes that take steps in these rounds is $P = \{p_{i+1}, \dots, p_M\} \cup \{p_{f+2}, \dots, p_n\}$. On the other hand, the set of processes that takes steps during rounds r'_1, \dots, r'_i is $P' = \{p_1, \dots, p_i\} \cup \{p_{M+1}, \dots, p_{M+(n-f)-1}\}$. Note that $P \cap P' = \emptyset$. Moreover, by construction, for every pair of processes $p \in P, p' \in P'$, every message sent by p (if any) to p' during any round r_{i+1}, \dots, r_M has not been received by p' by the end of r'_i . Therefore, until the end of r'_i the execution is indistinguishable to the processes in P' from an execution \mathcal{E}' that is the same except that rounds r_{i+1}, \dots, r_M do not occur in \mathcal{E}' . Therefore, the READ() performed by p_i in r'_i cannot return v_j , for any $j > i$. That is, this operation returns v_i .

In the second phase, no WRITE() operation is active. M distinct values are returned by READ() operation performed during this phase. Hence $\alpha \geq M$. \square

Remark. The lower bound can be slightly improved by a similar, though more involved, argument to yield $\alpha \geq M + 1$. See Appendix A.

5 Conclusion

The paper has introduced α -registers. For n processes and at most $f \geq \frac{n}{2}$ failures, an implementation of a SWMR $(2M - 1)$ -register is presented, where $M = 2f - n + 2$. The implementation is complemented by a lower bound stating that f -resilient simulation of an α -register for $\alpha < M + 1$ is impossible.

Many questions remain open for future research including closing the gap between the implementation and the lower bound, designing a multi-writer multi-reader implementation and understanding the computing power of α -registers. Another challenging direction is to generalize the bounded version of the ABD simulation [5]. Doing so may entail solving problems similar to the ones encountered in the design of fault-tolerant and self-stabilizing atomic registers [4, 13].

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A An improved lower bound on α

This section slightly improves the lower bound of section 4 on α for any implementation of an f -resilient α -register.

Theorem A.1. *Let n, f such that $f \geq \frac{n}{2}$. For any implementation of a SWMR α -register for n processes that tolerates f failures, $\alpha \geq M + 1$.*

Proof. (Sketch) Let us consider the same hypotheses as in proof of theorem 4.1. Moreover, we assume without loss of generality that in algorithm A , every message is broadcast, that is sent to every process. We exhibit an execution $\mathcal{E}'_{k'}$ of A in which $M + 1$ distinct values are read in an interval without active WRITE() operations.

To define execution $\mathcal{E}'_{k'}$, we start from execution \mathcal{E}_k (defined in the proof of theorem 4.1), and add two special rounds denoted by r_0 and r'_0 to it. In what follows, $k' = (k_0, k'_0, \dots, k_M)$ is an $M + 2$ -tuple of positive integers, $\mathcal{V} = \{v_0\} \cup \{v_1, \dots, v_M\}$ is a set of $M + 1$ distinct values where values $v_i, 1 \leq i \leq M$ are the values written in \mathcal{E}_k . Recall that $Q_i = \{p_i\} \cup \{p_{f+2}, \dots, p_n\}$ and $Q'_i = \{p_i\} \cup \{p_{M+1}, \dots, p_{M+(n-f)-1}\}$, for every $i, 1 \leq i \leq M$. As execution \mathcal{E}_k , execution $\mathcal{E}'_{k'}$ is divided in two phases, each phase consisting in $M + 1$ sequential rounds. The phases in $\mathcal{E}'_{k'}$ are defined as follows:

First phase. This phase consists in $M + 1$ rounds r_0, \dots, r_n . For each $i, 2 \leq i < M$, round r_{i+1} begins after the end of round r_i . Additionnaly, round r_2 begins after the end of the special round r_0 , which begins after the end of round r_1 . Rounds $r_i, i > 0$ are exactly as before.

During round r_0 , the following operations are performed sequentially, divided into two parts :

1. During the first part, each message sent to any process $p_j \notin Q_M$ is delayed until some time specified later, and the processes $p_j \notin Q_M$ do not take any step.
 - (a) WRITE(v_0) is performed by process p_n ;
 - (b) Process p_n performs a READ() operation;
 - (c) Process p_M performs k'_0 READ() operations;
2. In the second part, processes $p_j \notin Q'_1 \cup \{p_n\}$ do not take any step nor receive any message. Also, each process $p_i \in Q'_1$ receives messages sent by any process $p_j \notin Q'_1$ only when explicitly said. The second part consists in k_0 repetitions of the following steps:
 - (a) Process p_1 performs one READ() operation;
 - (b) p_n receives every message that has been sent during the last iteration, and may send back some answer(s), which are delayed until specified;
 - (c) If p_n sends at least one message, each process in Q'_1 receives exactly the same message broadcast by some process $p_j \notin Q'_1$.

As $|Q'_1| = n - f$, the execution is indistinguishable by processes in Q'_1 from an execution that is the same as $\mathcal{E}'_{k'}$ until the end of round r_1 and in which the M processes $\notin (Q'_1 \cup Q_M)$ fail at the beginning of r_0 , and in which the $n - f - 1$ processes $\in Q_M \setminus (Q'_1 \cup \{p_n\})$ fail just after the READ() operation performed by p_n . As A tolerates f failures, every operation performed during round r_0 terminates.

Note that the READ() operation performed by p_n return v_0 by the non-triviality property of α -registers. Moreover, observe that if k_0 is chosen large enough, the last READ() operation performed

by p_1 returns also v_0 by the propagation property. We denote by $K_0 + 1$ the smallest k_0 such that the $\text{READ}()$ of p_1 return v_0 . $K_0 \geq 1$ since the first of the Read performed by p_1 happens before receiving any message from processes $\notin Q'_1$ sent after the end of round r_1 , and thus it will return v_1 (if k_1 is large enough).

Similarly, if k'_0 is chosen large enough, the last $\text{READ}()$ operation performed by p_M returns v_0 . This means that, if k'_0 is large enough, at least one message is sent (and broadcast) by p_n during the first part of r_0 . Now, at the beginning of each iteration of the second part of round r_0 , at least one message has been sent by p_n but not yet received by processes $\in Q'_1$. It can easily be seen since a message is only received if p_n sent one during the same iteration.

Finally, we may assume that messages are received by Q'_1 in the same order they were sent (according to the global time).

Second phase. This phase consists also in $M + 1$ rounds r'_0, \dots, r'_M . Again, rounds r'_1 happens before r'_0 which happens before r'_2 . Rounds $r'_i, i > 0$ are defined as in \mathcal{E}_k .

During round r'_0 , first each process in Q'_1 receives one message that was sent to it during round r_0 , and then p_1 performs a $\text{READ}()$ operation. Each message that is not sent by a process in Q'_1 to a process in Q'_1 is delayed.

Now, assume $k_0 = K_0 - 1$. Thus, from the definition of K_0 , and the fact that no messages have been received by Q'_1 after the end of round r_0 , the $\text{READ}()$ executed in round r'_1 returns v_1 (if k_1 is large enough) and cannot return v_0 (because this is the K_0 th Read, and only the $K_0 + 1$ th would return v_0). Then, during round r'_0 , each process in Q'_1 receives one message from $p_j \notin Q'_1$ that was sent during r_0 (and there is at least one, as explained before, if k'_0 is large enough). Then, p_1 performs a $\text{READ}()$ operation, and since this situation is indistinguishable from the situation where the execution is still performing round r_0 (at the $K_0 + 1$ th iteration) from Q'_1 point of view, this $\text{READ}()$ returns v_0 .

Since r'_1 and r'_0 use the same set of processes Q'_1 , the rounds $r_i, i > 1$ might not have happened from the point of view of Q'_1 , which explains why no value $v_j, j > 1$ is returned here. Additionnaly, the addition of rounds r_0 and r'_0 does not change anything for the other rounds $r'_j, j > 1$, since v_0 and v_1 are both older than v_j .

In the second phase, no $\text{WRITE}()$ operation is active. $M + 1$ distinct values are returned by $\text{READ}()$ operation performed during this phase. Hence $\alpha \geq M + 1$. \square