

## Degenerate second order mean field games systems

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# Degenerate second order mean field games systems

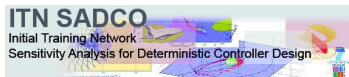
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We consider the following second order mean field games (MFG) system with degenerate diffusion and a local coupling

$$\begin{cases} -\partial_t \phi - A_{ij} \partial_{ij} \phi + H(x, D\phi) = f(x, m(x, t)) \\ \partial_t m - \partial_{ij} (A_{ij} m) - \operatorname{div}(m D_p H(x, D\phi)) = 0 \\ m(0) = m_0, \phi(x, T) = \phi_T(x) \end{cases}$$

where

- $A : \mathbb{R}^d \rightarrow \mathbb{R}^{d \times d}$  is symmetric and nonnegative
- the Hamiltonian  $H : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$  is convex in the second variable
- the coupling  $f : \mathbb{R}^d \times [0, +\infty) \rightarrow [0, +\infty)$  is increasing with respect to the second variable
- $m_0$  is a probability density
- $\phi_T : \mathbb{R}^d \rightarrow \mathbb{R}$  is a given function

Introduced by [Lasry and Lions](#) and by [Huang, Caines and Malhamé](#) to describe Nash equilibria in differential games with infinitely many players

## The optimal control problem of a typical small player

$\phi(t, x)$  is the **value function**

**Dynamics :**

$$dX_s = \alpha_s ds + \Sigma(s, X_s) dB_s,$$

where  $(\alpha_s)$  is the control,  $(B_s)$  is a  $d$ -dimensional Brownian motion and  $\Sigma \Sigma^T = A$

**Cost :**

$$\mathbb{E} \left[ \int_0^T H^*(s, X_s, -\alpha_s) + f(X_s, m(s, X_s)) ds + \phi_T(X_T) \right]$$

$\forall t \in [0, T]$   $m(t, x)$  denotes the **density** of population of small players at position  $x$

the **optimal control** is formally given by the feedback  
 $(t, x) \rightarrow -D_p H(x, D\phi(t, x))$

the second equation in (MFG) is the **Kolmogorov equation** of the process  $(X_s)$  when the small player plays in an optimal way

In the MFG systems with **uniformly parabolic diffusions** (typically  $A_{ij}\partial_{ij}\phi = \Delta\phi$ ) the solutions are **smooth**, (at least if the coupling is nonlocal and regularizing or if it has a "small growth")

Analysis by **PDE methods** : see Cardaliaguet, Lasry, Lions and Porretta (2012), Lasry and Lions (2006, 2007), Gomes, Pimentel and Sánchez-Morgado (2013), Lions (2011), Porretta (2013)

Analysis by **stochastic techniques** : see Carmona and Delarue (2013), Huang, Malhamé and Caines (2006)

The case of **couplings with an arbitrary growth** has been discussed in Cardaliaguet, Lasry, Lions and Porretta (2012) (for quadratic hamiltonians and smooth solutions) and in Porretta (2013) (for more general hamiltonians but weak solutions)

We consider **degenerate parabolic equations** : lack of regularity  $\Rightarrow$  break down of the uniformly parabolic techniques

**IDEA** : use convex optimization methods from optimal transport problems (see Benamou and Brenier (2000), Cardaliaguet, Carlier and Nazaret (2012))

These techniques were already used to study first order MFG systems (i.e.,  $A \equiv 0$ ): see Cardaliaguet (2013), Cardaliaguet and Graber (2013), Graber (2013)

We show the existence and uniqueness of a weak solution for the degenerate MFG system as well as the stability of solutions with respect to perturbation of the data

# Assumptions

- (H1)  $f : \mathbb{T}^d \times [0, +\infty) \rightarrow \mathbb{R}$  is continuous in both variables, **increasing** wrt the second variable  $m$ , and  $\exists q > 1, C_1$  s.t.

$$\frac{1}{C_1}|m|^{q-1} - C_1 \leq f(x, m) \leq C_1|m|^{q-1} + C_1 \quad \forall m \geq 0$$

Moreover  $f(x, 0) = 0 \quad \forall x \in \mathbb{T}^d$

- (H2)  $H : \mathbb{T}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$  is continuous in both variables, **convex** and differentiable in the second variable, with  $D_p H$  continuous in both variable, and  $\exists r > 1, C_2 > 0$  s.t.

$$\frac{1}{rC_2}|\xi|^r - C_2 \leq H(x, \xi) \leq \frac{C_2}{r}|\xi|^r + C_2 \quad \forall (x, \xi) \in \mathbb{T}^d \times \mathbb{R}^d$$

## Assumptions

(H3)  $A : \mathbb{T}^d \rightarrow \mathbb{R}^{d \times d}$  is Lipschitz continuous with **symmetric nonnegative** values:  $\exists C_3 > 0$  s.t.

$$|A(x) - A(y)| \leq C_3|x - y| \quad \forall x, y \in \mathbb{T}^d, \xi \in \mathbb{R}^d$$

Moreover, either  $r \geq p$  or  $A \equiv 0$ , where  $\frac{1}{p} + \frac{1}{q} = 1$

(H4)  $\phi_T : \mathbb{T}^d \rightarrow \mathbb{R}$  is of class  $C^2$ , while  $m_0 : \mathbb{T}^d \rightarrow \mathbb{R}$  is a  $C^1$  positive density

The **Fenchel conjugate**  $H^*$  of  $H$  wrt the second variable is continuous and

$$\frac{1}{r' C_2} |\xi|^{r'} - C_2 \leq H^*(x, \xi) \leq \frac{C_2}{r'} |\xi|^{r'} + C_2 \quad \forall (x, \xi) \in \mathbb{T}^d \times \mathbb{R}^d,$$

where  $r'$  is s.t. :  $\frac{1}{r} + \frac{1}{r'} = 1$



## Assumptions

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where  $r'$  is s.t. :  $\frac{1}{r} + \frac{1}{r'} = 1$

Let

$$F(x, m) = \begin{cases} \int_0^m f(x, \tau) d\tau & \text{if } m \geq 0 \\ +\infty & \text{otherwise} \end{cases}$$

Then  $F$  is continuous on  $\mathbb{T}^d \times (0, +\infty)$ , derivable and **strictly convex** in  $m$  and

$$\frac{1}{qC_1}|m|^q - C_1 \leq F(x, m) \leq \frac{C_1}{q}|m|^q + C_1 \quad \forall m \geq 0$$

Let  $F^*$  be the **Fenchel conjugate** of  $F$  wrt the second variable then  $F^*(x, a) = 0$  for  $a \leq 0$ , moreover,

$$\frac{1}{pC_1}|a|^p - C_1 \leq F^*(x, a) \leq \frac{C_1}{p}|a|^p + C_1 \quad \forall a \geq 0,$$

where  $p$  is s.t. :  $1/p + 1/q = 1$

## Key point : integral estimates

Assume that (H2) and (H3) hold true and let  $\phi$  satisfy

$$\begin{cases} -\partial_t \phi - A_{ij}(x) \partial_{ij} \phi + H(x, D\phi) \leq \alpha(t, x) \\ \phi(x, T) \leq \phi_T(x) \end{cases}$$

in the **sense of distribution**, with  $\alpha \in L^p((0, T) \times \mathbb{T}^d)$ ,  $\phi_T \in L^\infty(\mathbb{T}^d)$

i.e. for any nonnegative test function  $\zeta \in C_c^\infty((0, T] \times \mathbb{T}^d)$ ,

$$\begin{aligned} - \int_{\mathbb{T}^d} \zeta(T) \phi_T + \int_0^T \int_{\mathbb{T}^d} \phi \partial_t \zeta + \langle D\zeta, AD\phi \rangle + \zeta(\partial_i A_{ij} \partial_j \phi + H(x, D\phi)) \leq \\ \int_0^T \int_{\mathbb{T}^d} \alpha \zeta \end{aligned}$$

## Key point : integral estimates

### Theorem

Then, if  $\phi$  is bounded below, we have

$$\|\phi\|_{L^\infty((0,T),L^m(\mathbb{T}^d))} + \|\phi\|_{L^\gamma((0,T)\times\mathbb{T}^d)} \leq C \left( \|\alpha\|_{L^p((0,T)\times\mathbb{T}^d)} + \|\phi_T\|_{L^m(\mathbb{T}^d)} \right)$$

where  $m = \frac{d(r(p-1)+1)}{d-r(p-1)}$  and  $\gamma = \frac{rp(1+d)}{d-r(p-1)}$  if  $p < 1 + \frac{d}{r}$   
and  $m = \gamma = +\infty$  if  $p > 1 + \frac{d}{r}$ ,

with a constant  $C$  depending on  $T, p, d, r, C_2, C_3$  and on  $\|\alpha\|_{L^p((0,T)\times\mathbb{T}^d)}, \|\phi_T\|_{L^m(\mathbb{T}^d)}$  and  $\|\phi_-\|_\infty$ .

When  $r > 2$  and  $p > 1 + d/r$ , Cardaliaguet and Silvestre 2012 proved that the solution  $\phi$  is locally Hölder continuous, with Hölder modulus depending only on the growth condition of  $H$ , the  $L^\infty$  bound on  $u$  and the  $L^p$  norm of  $\alpha$

## Key point : integral estimates

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## Optimal control problems in duality

An optimal control problem for a **backward HJ equation** :

the state variable  $\phi$  is controlled by a distributed control  $\alpha : (0, T) \times \mathbb{T}^d \rightarrow \mathbb{R}$  in order to minimize the criterium

$$\int_0^T \int_{\mathbb{T}^d} F^*(x, \alpha(t, x)) \, dx dt - \int_{\mathbb{T}^d} \phi(0, x) dm_0(x)$$

when the state  $\phi$  is driven by

$$\begin{cases} -\partial_t \phi - A_{ij}(x) \partial_{ij} \phi + H(x, D\phi) = \alpha(t, x) \\ \phi(x, T) = \phi_T(x) \end{cases}$$

Precisely :

$$\inf_{\phi \in \mathcal{K}_0} \mathcal{A}(\phi)$$

where  $\mathcal{K}_0 := \{\phi \in \mathcal{C}^2([0, T] \times \mathbb{T}^d) \mid \phi(T, x) = \phi_T(x)\}$  and

$$\begin{aligned} \mathcal{A}(\phi) = & \int_0^T \int_{\mathbb{T}^d} F^*(x, -\partial_t \phi(t, x) - A_{ij} \partial_{ij} \phi + H(x, D\phi(t, x))) \, dx dt \\ & - \int_{\mathbb{T}^d} \phi(0, x) dm_0(x) \end{aligned}$$

The second optimal control problem is an optimal control problem for a **Fokker-Plank equation** :

we control the state variable  $m$  through a vector field  $v : (0, T) \times \mathbb{T}^d \rightarrow \mathbb{R}^d$  in order to minimize

$$\int_0^T \int_{\mathbb{T}^d} m(t, x) H^*(x, -v(t, x)) + F(x, m(t, x)) \, dx dt + \int_{\mathbb{T}^d} \phi_T(x) m(T, x) \, dx$$

when  $m$  solves the Fokker-Plank equation

$$\partial_t m - \partial_{ij}(A_{ij}(x)m) + \operatorname{div}(mv) = 0$$

Precisely :

$$\inf_{(m,w) \in \mathcal{K}_1} \mathcal{B}(m, w)$$

where

$$\mathcal{K}_1 := \left\{ (m, w) \in L^1((0, T) \times \mathbb{T}^d) \times L^1((0, T) \times \mathbb{T}^d, \mathbb{R}^d) \mid \right. \\ \left. m(t, x) \geq 0 \text{ a.e.}, \int_{\mathbb{T}^d} m(t, x) dx = 1 \text{ for a.e. } t \in (0, T), \text{ and} \right. \\ \left. \partial_t m - \partial_{ij}(A_{ij}(x)m) + \operatorname{div}(w) = 0 \text{ in } (0, T) \times \mathbb{T}^d, \quad m(0) = m_0 \right. \\ \left. \text{in the sense of distribution} \right\}$$

$$\mathcal{B}(m, w) = \int_0^T \int_{\mathbb{T}^d} m(t, x) H^* \left( x, -\frac{w(t, x)}{m(t, x)} \right) + F(x, m(t, x)) \, dx dt \\ + \int_{\mathbb{T}^d} \phi_T(x) m(T, x) dx$$

$$\text{for } m(t, x) = 0, \quad m(t, x) H^* \left( x, -\frac{w(t, x)}{m(t, x)} \right) = \begin{cases} +\infty & \text{if } w(t, x) \neq 0 \\ 0 & \text{if } w(t, x) = 0 \end{cases}$$



## Lemma

We have

$$\inf_{\phi \in \mathcal{K}_0} \mathcal{A}(\phi) = - \min_{(m, w) \in \mathcal{K}_1} \mathcal{B}(m, w)$$

Moreover, the minimum in the right-hand side is achieved by a **unique** pair  $(\bar{m}, \bar{w}) \in \mathcal{K}_1$  satisfying

$$(\bar{m}, \bar{w}) \in L^q((0, T) \times \mathbb{T}^d) \times L^{\frac{r'q}{r'+q-1}}((0, T) \times \mathbb{T}^d)$$

**IDEA** : Use the Fenchel-Rockafellar duality Theorem

# Relaxation

Let

$$\mathcal{K} := \left\{ (\phi, \alpha) \in L^\gamma((0, T) \times \mathbb{T}^d) \times L^p((0, T) \times \mathbb{T}^d) \mid D\phi \in L^r((0, T) \times \mathbb{T}^d) \right. \\ \left. \text{and which satisfies in the sense of distribution} \right. \\ \left. - \partial_t \phi - A_{ij}(x) \partial_{ij} \phi + H(x, D\phi) \leq \alpha, \quad \phi(T, \cdot) \leq \phi_T \right\}$$

Due to the presence of second order derivatives we do not expect the function  $\phi$  to be BV (as in the first order case)

What about **trace properties**?  $\phi$  has a trace in a weak sense

## Lemma

Let  $(\phi, \alpha) \in \mathcal{K}$ . Then, for any Lipschitz continuous map  $\zeta : \mathbb{T}^d \rightarrow \mathbb{R}$ , the map  $t \rightarrow \int_{\mathbb{T}^d} \zeta(x)\phi(t, x)dx$  has a **BV representative** on  $[0, T]$ .

Moreover, if we denote by  $\int_{\mathbb{T}^d} \zeta(x)\phi(t^+, x)dx$  its right limit at  $t \in [0, T)$ , then the map  $\zeta \rightarrow \int_{\mathbb{T}^d} \zeta(x)\phi(t^+, x)dx$  is continuous in  $L^{m'}(\mathbb{T}^d)$ .

$\Rightarrow$  for any nonnegative  $C^1$  map  $\zeta : [0, T] \times \mathbb{T}^d \rightarrow \mathbb{R}$ , one can write the integration by part formula: for any  $0 \leq t_1 \leq t_2 \leq T$ ,

$$\begin{aligned}
 - \left[ \int_{\mathbb{T}^d} \zeta \phi \right]_{t_1}^{t_2} + \int_{t_1}^{t_2} \int_{\mathbb{T}^d} \phi \partial_t \zeta + \langle D\zeta, A D\phi \rangle + \zeta (\partial_i A_{ij} \partial_j \phi + H(x, D\phi)) \leq \\
 \int_{t_1}^{t_2} \int_{\mathbb{T}^d} \alpha \zeta
 \end{aligned}$$

## Lemma

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 \int_{t_1}^{t_2} \int_{\mathbb{T}^d} \alpha \zeta
 \end{aligned}$$

Proof :

For any Lipschitz continuous, nonnegative map  $\zeta$ ,

$$-\frac{d}{dt} \int_{\mathbb{T}^d} \zeta \phi(t) + \int_{\mathbb{T}^d} \langle D\zeta, AD\phi(t) \rangle + \zeta(\partial_i A_{ij} \partial_j \phi + H(x, D\phi) - \alpha) \leq 0,$$

in the sense of distribution

As the second integral is in  $L^1((0, T))$ , the map  $t \rightarrow \int_{\mathbb{T}^d} \zeta \phi(t)$  is BV

If now  $\zeta$  is Lipschitz continuous and changes sign, one can write  $\zeta = \zeta^+ - \zeta^-$  and the map  $t \rightarrow \int_{\mathbb{T}^d} \zeta \phi(t) = \int_{\mathbb{T}^d} \zeta^+ \phi(t) - \int_{\mathbb{T}^d} \zeta^- \phi(t)$  is still BV

The continuity with respect to  $\zeta$  comes from the  $L^\infty((0, T), L^m(\mathbb{T}^d))$  estimate on  $\phi$

We extend the functional  $\mathcal{A}$  to  $\mathcal{K}$

$$\mathcal{A}(\phi, \alpha) = \int_0^T \int_{\mathbb{T}^d} F^*(x, \alpha(x, t)) \, dx dt - \int_{\mathbb{T}^d} \phi(x, 0) m_0(x) \, dx \quad \forall (\phi, \alpha) \in \mathcal{K}$$

## Proposition

We have

$$\inf_{\phi \in \mathcal{K}_0} \mathcal{A}(\phi) = \inf_{(\phi, \alpha) \in \mathcal{K}} \mathcal{A}(\phi, \alpha)$$

## Lemma

Let  $(\phi, \alpha) \in \mathcal{K}$  and  $(m, w) \in \mathcal{K}_1$ .

Assume that  $mH^*(\cdot, -w/m) \in L^1((0, T) \times \mathbb{T}^d)$  and  $m \in L^q$ .

Then, for a.e.  $t \in [0, T]$ ,  $m(t)\phi(t)$  is integrable and

$$\left[ \int_{\mathbb{T}^d} m\phi \right]_t^T + \int_t^T \int_{\mathbb{T}^d} m \left( \alpha + H^*(x, -\frac{w}{m}) \right) \geq 0$$

and

$$\left[ \int_{\mathbb{T}^d} m\phi \right]_0^t + \int_0^t \int_{\mathbb{T}^d} m \left( \alpha + H^*(x, -\frac{w}{m}) \right) \geq 0.$$

Moreover, if equality holds in the first inequality for  $t = 0$ , then  $w = -mD_p H(x, D\phi)$  a.e.

Proof :

Inequality  $\inf_{\phi \in \mathcal{K}_0} \mathcal{A}(\phi) \geq \inf_{(\phi, \alpha) \in \mathcal{K}} \mathcal{A}(\phi, \alpha)$  holds obviously

Let  $(\phi, \alpha) \in \mathcal{K}$ , then  $\forall (m, w) \in \mathcal{K}_1$  with  $mH^*(\cdot, -w/m) \in L^1$  we have,

$$\begin{aligned} \mathcal{A}(\phi, \alpha) &= \int_0^T \int_{\mathbb{T}^d} F^*(\alpha) - \int_{\mathbb{T}^d} \phi(0) m_0 \\ &\geq \int_0^T \int_{\mathbb{T}^d} \alpha m - F(m) - \int_{\mathbb{T}^d} m_0 \phi(0) \\ &\geq \int_0^T \int_{\mathbb{T}^d} -mH^*(x, -\frac{w}{m}) - F(m) - \int_{\mathbb{T}^d} m(T) \phi_T = -\mathcal{B}(m, w) \end{aligned}$$

Taking the sup with respect to  $(m, w)$  in the right-hand side

$$\mathcal{A}(\phi, \alpha) \geq - \inf_{(m, w) \in \mathcal{K}_1} \mathcal{B}(m, w) = \inf_{\phi \in \mathcal{K}_0} \mathcal{A}(\phi)$$



## Proposition

The relaxed problem has *at least one solution*  $(\bar{\phi}, \bar{\alpha}) \in \mathcal{K}$  which is bounded below by a constant depending on  $\|\phi_T\|_{C^2}$ , on  $\|A_{ij}\|_{C^0}$  and on  $\|H(\cdot, D\phi_T)\|_{\infty}$ .

Therefore, thanks to the equivalence, we have a infimum for  $\mathcal{A}$  over  $\mathcal{K}_0$  and a minimum for  $\mathcal{B}$  over  $\mathcal{K}_1$

$$\min_{(\phi, \alpha) \in \mathcal{K}} \mathcal{A}(\phi, \alpha) = \inf_{\phi \in \mathcal{K}_0} \mathcal{A}(\phi) = - \min_{(m, w) \in \mathcal{K}_1} \mathcal{B}(m, w)$$

## Existence and uniqueness

We say that a pair  $(\phi, m) \in L^\gamma((0, T) \times \mathbb{T}^d) \times L^q((0, T) \times \mathbb{T}^d)$  is a **weak solution to (MFG)** if

- (i)  $D\phi \in L^r$ ,  $mH^*(\cdot, D_p H(\cdot, D\phi)) \in L^1$  and  $mD_p H(\cdot, D\phi) \in L^1$
- (ii) The following inequality holds in the sense of distribution

$$-\partial_t \phi - \partial_i (A_{ij}(x) \partial_j \phi) + (\partial_i A_{ij}) \partial_j \phi + H(x, D\phi) \leq f(x, m) \quad \text{in } (0, T) \times \mathbb{T}^d,$$

with  $\phi(T, \cdot) \leq \phi_T$

- (iii) The following equation holds in the sense of distribution

$$\partial_t m - \partial_{ij} (A_{ij}(x) m) - \operatorname{div}(m D_p H(x, D\phi)) = 0 \quad \text{in } (0, T) \times \mathbb{T}^d, \quad m(0) = m_0$$

- (iv) The following equality holds :

$$\begin{aligned} & \int_0^T \int_{\mathbb{T}^d} m(t, x) (f(x, m(t, x)) + H^*(x, D_p H(x, D\phi)(t, x))) \, dx dt \\ & + \int_{\mathbb{T}^d} m(T, x) \phi_T(x) - m_0(x) \phi(0, x) \, dx = 0 \end{aligned}$$

## Theorem

There **exists** a weak solution  $(\bar{\phi}, \bar{m})$  to (MFG).

Moreover this solution is **unique** in the following sense: if  $(\bar{\phi}, \bar{m})$  and  $(\bar{\phi}', \bar{m}')$  are two solutions, then  $\bar{m} = \bar{m}'$  a.e. and  $\bar{\phi} = \bar{\phi}'$  in  $\{\bar{m} > 0\}$ .

Finally, there exists a solution which is **bounded below** by a constant depending on  $\|\phi_T\|_{C^2}$ , on  $\|A_{ij}\|_{C^0}$  and on  $\|H(\cdot, D\phi_T)\|_{\infty}$ .

Proof :

Let  $(\bar{m}, \bar{w}) \in \mathcal{K}_1$  be a minimizer of  $\min_{(m,w) \in \mathcal{K}_1} \mathcal{B}(m, w)$   
 and  $(\bar{\phi}, \bar{\alpha}) \in \mathcal{K}$  be a minimizer of  $\min_{(\phi, \alpha) \in \mathcal{K}} \mathcal{A}(\phi, \alpha)$

We have  $-\mathcal{B}(\bar{m}, \bar{w}) = \mathcal{A}(\bar{\phi}, \bar{\alpha})$

$$\int_0^T \int_{\mathbb{T}^d} F^*(x, \bar{\alpha}) + F(x, \bar{m}) + \bar{m} H^* \left( x, -\frac{\bar{w}}{\bar{m}} \right) dx dt + \int_{\mathbb{T}^d} \phi_T \bar{m}(T) - \bar{\phi}(0) m_0 dx = 0$$

By convexity of  $F$ ,

$$F^*(x, \bar{\alpha}) + F(x, \bar{m}) - \bar{\alpha} \bar{m} \geq 0,$$

hence

$$\int_0^T \int_{\mathbb{T}^d} \bar{\alpha} \bar{m} + \bar{m} H^* \left( x, -\frac{\bar{w}}{\bar{m}} \right) dx dt + \int_{\mathbb{T}^d} \phi_T \bar{m}(T) - \bar{\phi}(0) m_0 dx \leq 0$$

Therefore  $\bar{w} = -\bar{m} D_p H(\cdot, D\bar{\phi})$  a.e. and  $\bar{\alpha}(t, x) = f(x, \bar{m}(t, x))$  a.e.

and  $(\bar{\phi}, \bar{m})$  is a weak solution

Recall that :

## Lemma

Let  $(\phi, \alpha) \in \mathcal{K}$  and  $(m, w) \in \mathcal{K}_1$ . Assume that  $mH^*(\cdot, -w/m) \in L^1((0, T) \times \mathbb{T}^d)$  and  $m \in L^q$ .

Then, for a.e.  $t \in [0, T]$ ,  $m(t)\phi(t)$  is integrable and

$$\left[ \int_{\mathbb{T}^d} m\phi \right]_t^T + \int_t^T \int_{\mathbb{T}^d} m \left( \alpha + H^*(x, -\frac{w}{m}) \right) \geq 0$$

and

$$\left[ \int_{\mathbb{T}^d} m\phi \right]_0^t + \int_0^t \int_{\mathbb{T}^d} m \left( \alpha + H^*(x, -\frac{w}{m}) \right) \geq 0.$$

Moreover, if equality holds in the first inequality for  $t = 0$ , then  $w = -mD_p H(x, D\phi)$  a.e.

Conversely, using the convexity of  $F$  and the Lemma, we can show that any weak solution  $(\bar{\phi}, \bar{m})$  of (MFG) is such that :

the pair  $(\bar{m}, -\bar{m}D_p H(\cdot, D\bar{\phi}))$  is the minimizer of  $\min_{(m,w) \in \mathcal{K}_1} \mathcal{B}(m, w)$

while  $(\bar{\phi}, f(\cdot, \bar{m}))$  is a minimizer of  $\min_{(\phi, \alpha) \in \mathcal{K}} \mathcal{A}(\phi, \alpha)$

**Uniqueness** : Since the solution of  $\min_{(m,w) \in \mathcal{K}_1} \mathcal{B}(m, w)$  is unique  $\bar{m}$  is unique

The proof of the uniqueness of  $\bar{\phi}$  is more technical

# Stability

Assume that  $(A^n)$ ,  $(H^n)$ ,  $(f^n)$ ,  $m_0^n$  and  $\phi_T^n$  satisfy conditions (H1)...(H4) uniformly with respect to  $n$  and converge to  $A$ ,  $H$ ,  $f$ ,  $m_0$  and  $\phi_T$  locally uniformly.

## Theorem

Let  $(\phi^n, m^n)$  be a weak solution of (MFG) associated with  $A^n$ ,  $H^n$ ,  $f^n$  and with the initial and terminal conditions  $m_0^n$  and  $\phi_T^n$ . Assume also that the sequence  $\phi^n$  is uniformly bounded below.

Then  $(m^n)$  converges strongly to  $m$  in  $L^q$  while  $\phi^n$  converges weakly and up to a subsequence to a map  $\phi$  in  $L^\gamma$ , where the pair  $(\phi, m)$  is a weak solution to (MFG).

In particular the weak solution is stable with respect to **viscous approximation**

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