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Equivalent Absorbing Boundary Conditions for Heterogeneous Acoustic Media

Manuela L. Castro, Julien Diaz, Victor Péron

Abstract

In this work, we derive high order Equivalent Absorbing Boundary Conditions EABCs that model the propagation of waves in semi-infinite bilayered acoustic media. Our motivation is to restrict the computational domain in the simulation of seismic waves that are propagated from the earth and transmitted to the stratified heterogeneous media composed by ocean and atmosphere. These EABCs are adapted to Hagstrom-Warburton ABCs and appear as first and second order of approximation with respect to a small parameter involved in a multiscale expansion. Computational tests illustrate the accuracy of the first approximate model with respect to the small parameter.

1 Introduction

The numerical simulation of geophysical phenomena is of utmost importance in our society. Considering the massive destruction seismic activities can generate, it is crucial to apply science towards a better understanding of the impact of earthquake waves.

Part of the job is to obtain effective models yielding the numerical simulation of seismic activity at an affordable computational cost - observe that running times are a very important factor when dealing with eminent tragedies. On the other hand, a complete description of the physical problem at hand is extremely intricate. In particular, it involves the coupling of elastic and acoustic waves in heterogeneous media, and the absence of viscosity produces waves that travel long distances without changing much their shape or amplitude. This aspect of the problem generates difficulties for the numerical simulation, since the physical domain, if one includes the atmosphere, is unbounded. Moreover, as waves propagate much slower in the atmosphere than in the sea or in the subsurface, one has to consider meshes composed of very thin cells in this region. Since the primary interest is to compute seismograms in the subsurface, it is necessary to consider techniques allowing to reduce at most as possible the computations inside the

atmosphere. The imposition of artificial contours and appropriate boundary conditions (BCs) is an aspect to be considered. Among many possibilities, one could use a non-reflecting BC, defined through pseudo-differential operators [1, 2, 3, 4], or choose from a variety of approximate BCs, such as PMLs [5, 6, 7] or Absorbing Boundary Conditions (ABCs) [8, 9, 10, 11, 12, 13]. In this work the Hagstrom-Warburton ABC [10, 14] is chosen. The benefit of implementing non-reflecting BCs is discussed in [8] and it has been proven in [15] that the Hagstrom-Warburton ABC is equivalent to the popular Higdon ABC, with advantages with respect to implementation and computational cost.

However, even when using High-Order BCs, the artificial boundary should be placed at a distance ϵ of the subsurface, in order to avoid spurious reflections. Hence, it is still necessary to mesh the small layer of the atmosphere with very thin cells. In this work, an alternative method is proposed, based on the use of asymptotic techniques in order to obtain Equivalent BCs that we could impose directly at the interface between the atmosphere and the subsurface.

The concept of equivalent boundary conditions (ECs) has become well-known in the mathematical modeling of wave propagation phenomena [16, 17, 18, 19, 20]. Such conditions are usually used to reduce and simplify the computational domain, replacing an exact model that must be applied in the periphery of the domain by an artificial contour and a BC that resembles the effects of the exact model on the part of the domain that was excluded. The main tool for the construction of ECs are two scale asymptotic expansions on the parameter defining the thickness of the layer to be eliminated.

A key hypothesis for the validation of this technique relies on the smallness of the ratio between the thickness of the layer to be eliminated and the remainder of the domain, typically with respect to the wavelength. It is worth to notice that the original physical problem inspiring this work does not satisfy such hypothesis. As a matter of fact in the original problem the atmosphere layer is an unbounded layer. What motivates this model is that, according to [14], it is possible to approximate the solution in the unbounded domain with any set precision tolerance if one applies an ABC of order high enough. At this stage, therefore, the focus is on the approximation of this problem with an absorbing boundary, rather than the physical problem with an unbounded layer.

The originality of this work is the derivation of ECs adapted to Hagstrom-Warburton ABCs, that will be called Equivalent Absorbing Boundary Conditions (EABCs). The EABCs appear as a first and second order approximations (Sec. 3.2) with respect to the small parameter and which are satisfied

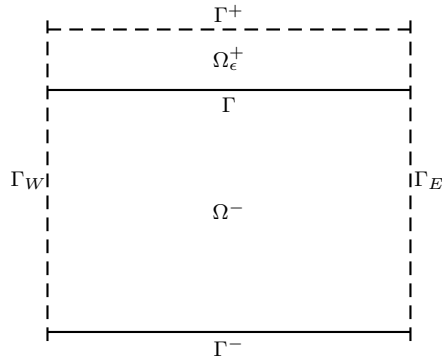


Figure 1: Simplified spatial model and its contours. The contour Γ^+ is artificial and demands an absorbing boundary condition.

by the acoustic pressure. This paper presents a preliminary study that illustrates the feasibility of the approach. It focuses essentially on the formal derivation of EABCs and on the numerical accuracy of low order EABCs.

This article is organized as follows. In section 2, we introduce the mathematical model. Section 3 is devoted for the equivalent boundary conditions obtained through asymptotical methods. We conclude presenting some numerical results obtained so far.

2 Mathematical Modelling

In this work, a region of interest consisting of two media (ocean and atmosphere, for instance) is considered. Starting from a rectangularly shaped, double layered spatial model (see Fig. 1), where the boundaries Γ^+ , Γ^- , Γ_W and Γ_E are artificial. The focus here is on the treatment of Γ^+ defined as an absorbing boundary, whereas the contours Γ_W and Γ_E are modeled as periodic boundaries and a Dirichlet boundary condition (BC) is set on Γ^- (4). The Dirichlet data f set on Γ^- can be thought as a forcing term generated by waves that were transmitted to Ω^- from an elastic media underneath Γ^- . The goal is to obtain a reduced model for the acoustic pressure p^- in Ω^- of a wave with frequency ω that propagates with velocity c_1 in Ω^- and is transmitted to Ω_ϵ^+ (ϵ is the thickness of the layer Ω_ϵ^+) with velocity c_2 .

Denoting by $\kappa_1 = \frac{\omega}{c_1}$, $\kappa_2 = \frac{\omega}{c_2}$ one has

$$(\Delta + \kappa_2^2)p^+ = 0 \quad \text{in } \Omega_\epsilon^+ \quad (1)$$

$$(\Delta + \kappa_1^2)p^- = 0 \quad \text{in } \Omega^- \quad (2)$$

$$p^+ = p^- \quad \text{and} \quad c_2^2 \frac{\partial}{\partial n} p^+ = c_1^2 \frac{\partial}{\partial n} p^- \quad \text{on } \Gamma \quad (3)$$

$$p^- = f \quad \text{on } \Gamma^- \quad (4)$$

$$\left(-a_0 \nu \kappa_2 + \frac{\partial}{\partial n}\right) \prod_{j=1}^P \left(-a_j \nu \kappa_2 + \frac{\partial}{\partial n}\right)^2 p^+ = 0 \quad \text{on } \Gamma^+ \quad (5)$$

complemented with periodic BCs set on Γ_W and Γ_E :

$$p^\pm|_{\Gamma_W} = p^\pm|_{\Gamma_E} \quad \text{and} \quad \frac{\partial}{\partial n} p^\pm|_{\Gamma_W} = \frac{\partial}{\partial n} p^\pm|_{\Gamma_E} \quad (6)$$

The time-harmonic wave field is characterized by using the Helmholtz equations (1)-(2) for the acoustic pressures p^+ in Ω_ϵ^+ and p^- in Ω^- . The transmission conditions (3) require that the pressures and the normal velocities match on the interface Γ ; the first condition results from the equilibrium of forces on Γ . The boundary condition (5) is a Higdon BC [9] and coefficients $a_j \in (0, 1]$ are given parameters. Rewriting (5) according to the Hagstrom-Warburton formulation [10, 14, 15], adapted to the problem stated in the frequency domain, BC (5) becomes

$$\left(-a_0 \nu \kappa_2 + \frac{\partial}{\partial n}\right) p^+ = -\nu \kappa_2 \phi^1 \quad (7)$$

$$\left(-a_j \nu \kappa_2 + \frac{\partial}{\partial n}\right) \phi^j = \left(-a_j \nu \kappa_2 - \frac{\partial}{\partial n}\right) \phi^{j+1}, \quad j = 1, \dots, P \quad (8)$$

$$\phi^{P+1} = 0. \quad (9)$$

Here the functions ϕ^j ($j = 1, \dots, P+1$) are auxiliary variables, defined on Γ^+ and in a vicinity \mathcal{V} which is located above the domain Ω_ϵ^+ , and we assume that (7)-(8)-(9) hold on $\Gamma^+ \cup \mathcal{V}$. Then, following the procedure stated in [10], we have that $(\Delta + \kappa_2^2)\phi^j = 0$ in \mathcal{V} ; what leads to the elimination of the normal derivatives with respect to the boundary Γ^+ . This yields rewriting (7)-(9) as

$$\left(-a_0 \nu \kappa_2 + \frac{\partial}{\partial n}\right) p^+ = -\nu \kappa_2 \phi^1 \quad \text{on } \Gamma^+ \quad (10)$$

$$-\kappa_2^2 \mathbf{L}\Phi = \mathbf{M} \frac{\partial^2}{\partial x^2} \Phi + 2 \frac{\partial^2}{\partial x^2} p^+ \vec{e}_1 \quad \text{on } \Gamma^+ \quad (11)$$

where $\Phi = (\phi^1, \dots, \phi^P)^T$ and \mathbf{L}, \mathbf{M} are tridiagonal matrices $P \times P$ whose entries l_{ij} and m_{ij} depend on the parameters a_j . More specifically,

$$l_{11} = 1 + a_1^2 + 2a_1a_0, \quad l_{12} = 1 - a_1^2, \quad l_{j,j+1} = a_{j-1}(1 - a_j^2), \quad j = 2, \dots, P-1$$

$$l_{j,j-1} = a_j(1 - a_{j-1}^2), \quad l_{jj} = a_j(1 + a_{j-1}^2) + a_{j-1}(1 + a_j^2), \quad j = 2, \dots, P$$

$$m_{11} = a_1 + a_0, \quad m_{12} = a_0, \quad m_{j,j+1} = a_{j-1}, \quad j = 2, \dots, P-1$$

$$m_{j,j-1} = a_j, \quad m_{jj} = a_j + a_{j-1}, \quad j = 2, \dots, P$$

Unlike (7)-(8)-(9), the formulation (10)-(11) involves only the values of ϕ^j on the boundary Γ^+ . This decreases considerably the computational cost of numerical simulations. Finally the problem of interest writes (1)-(4) with the BCs (6) and (10)-(11).

3 Main Results - Equivalent Conditions

In the framework above, it is possible to replace the region Ω_ϵ^+ by appropriate boundary conditions (BCs) set on Γ called equivalent absorbing boundary conditions (EABCs). Firstly, a two-step formal derivation of EABCs is presented. In Section 3.2, the first two EABCs are stated. Elements of derivation are presented in Section 3.3.

3.1 Formal derivation of equivalent conditions

First step : a multiscale expansion. The first step consists to derive a multiscale expansion for the solution $p^+ = p_\epsilon^+$, $p^- = p_\epsilon^-$ and $\Phi = \Phi_\epsilon$ of the problem (1)-(4) complemented with the BCs (6)-(10)-(11): it possesses an asymptotic expansion in power series of the small parameter ϵ

$$\begin{aligned} p^+(\mathbf{x}) &= p_0^+(\mathbf{x}; \epsilon) + \epsilon p_1^+(\mathbf{x}; \epsilon) + \mathcal{O}(\epsilon^2) \quad \text{in } \Omega_\epsilon^+, \quad p_j^+(\mathbf{x}; \epsilon) = \mathfrak{p}_j(x, \frac{y}{\epsilon}); \\ p^-(\mathbf{x}) &= p_0^-(\mathbf{x}) + \epsilon p_1^-(\mathbf{x}) + \mathcal{O}(\epsilon^2) \quad \text{in } \Omega^-; \\ \Phi(x, \epsilon) &= \Phi_0(x) + \epsilon \Phi_1(x) + \mathcal{O}(\epsilon^2). \end{aligned} \tag{12}$$

Here $\mathbf{x} = (x, y) \in \mathbb{R}^2$ are the cartesian coordinates. The “profiles” \mathfrak{p}_j are defined on $\Gamma \times (0, 1)$ whereas the terms p_j^- (resp. Φ_j) are defined in Ω^- (resp. on Γ).

Second step : construction of equivalent conditions. The second step consists to identify a simpler problem satisfied by the truncated expansions

$$\begin{aligned} p_{k,\epsilon}^- &:= p_0^- + \epsilon p_1^- + \epsilon^2 p_2^- + \cdots + \epsilon^k p_k^- \quad \text{in } \Omega^- \\ \Phi_{k,\epsilon} &= \Phi_0 + \epsilon \Phi_1 + \epsilon^2 \Phi_2 + \cdots + \epsilon^k \Phi_k \quad \text{on } \Gamma \end{aligned}$$

up to a residual term in $\mathcal{O}(\epsilon^{k+1})$. The simpler problems are stated in Sec. 3.2 when $k \in \{0, 1\}$. There holds (at least) formal estimates

$$\|p_\epsilon^- - p_\epsilon^k\|_{\Omega^-} = \mathcal{O}(\epsilon^{k+1}) \quad (13)$$

where p_ϵ^k solves the simpler problem, an *equivalent model of order k* .

3.2 Main results - Equivalent models

In the framework above, the equivalent models (EABCs) of order $k \in \{0, 1\}$ are stated.

Order 0 model. p_0^- and $\Phi_0(x) = (\phi_0^1, \dots, \phi_0^P)^T(x)$ solves the problem

$$\begin{aligned} \Delta p_0^- + \kappa_1^2 p_0^- &= 0 && \text{in } \Omega^- \\ \left(-a_0 \nu \kappa_2 + \left(\frac{c_1}{c_2}\right)^2 \frac{\partial}{\partial n}\right) p_0^- &= -\nu \kappa_2 \phi_0^1 && \text{on } \Gamma \\ -\kappa_2^2 \mathbf{L} \Phi_0 - \mathbf{M} \frac{\partial^2}{\partial x^2} \Phi_0 &= 2 \frac{\partial^2}{\partial x^2} p_0^- \vec{e}_1 && \text{on } \Gamma \\ p_0^- &= f && \text{on } \Gamma^-, \end{aligned} \quad (14)$$

complemented with periodic BCs on Γ_W and Γ_E .

Order 1 model. p_ϵ^1 and $\Phi_\epsilon^1(x) = (\phi_\epsilon^1, \dots, \phi_\epsilon^P)^T(x)$ solves the problem

$$\begin{aligned} \Delta p_\epsilon^1 + \kappa_1^2 p_\epsilon^1 &= 0 && \text{in } \Omega^- \\ \left(-a_0 \nu \kappa_2 + \left(\frac{c_1}{c_2}\right)^2 \frac{\partial}{\partial n}\right) p_\epsilon^1 &= (-\nu \kappa_2 + \epsilon a_0 \kappa_2^2) \phi_\epsilon^1 + \epsilon \left(\frac{\partial^2}{\partial x^2} p_\epsilon^1 + \kappa_2^2 (1 - a_0^2) p_\epsilon^1\right) && \text{on } \Gamma \\ -\kappa_2^2 \mathbf{L} \Phi_\epsilon^1 - \mathbf{M} \frac{\partial^2}{\partial x^2} \Phi_\epsilon^1 &= 2 \left((1 + \epsilon a_0 \nu \kappa_2) \frac{\partial^2}{\partial x^2} p_\epsilon^1 - \epsilon \nu \kappa_2 \frac{\partial^2}{\partial x^2} \phi_\epsilon^1\right) \vec{e}_1 && \text{on } \Gamma \\ p_\epsilon^1 &= f && \text{on } \Gamma^- \end{aligned}$$

with periodic BCs set on Γ_W and Γ_E .

3.3 Derivation of equivalent models

After applying a change of scale $y \mapsto Y = \frac{y}{\epsilon}$ in Ω_ϵ^+ , equations (1)-(4) complemented with the BCs (10)-(11) become

$$\begin{aligned}
\left(\epsilon^{-2} \frac{\partial^2}{\partial Y^2} + \frac{\partial^2}{\partial x^2} + \kappa_2^2\right) \mathbf{p}^+(x, Y) &= 0 \text{ in } \Gamma \times (0, 1) \\
(\Delta + \kappa_1^2) p^- &= 0 \text{ in } \Omega^- \\
\mathbf{p}^+ &= p^- \text{ on } \Gamma (Y = 0) \\
c_2^2 \epsilon^{-1} \frac{\partial}{\partial Y} \mathbf{p}^+ &= c_1^2 \frac{\partial}{\partial n} p^- \text{ on } \Gamma (Y = 0) \\
p^- &= f \text{ on } \Gamma^- \\
(-a_0 \nu \kappa_2 + \epsilon^{-1} \frac{\partial}{\partial Y}) \mathbf{p}^+(x, 1) &= -\nu \kappa_2 \phi^1(x) \\
-\kappa_2^2 \mathbf{L} \Phi(x, \epsilon) &= \mathbf{M} \frac{\partial^2}{\partial x^2} \Phi(x, \epsilon) + 2 \frac{\partial^2}{\partial x^2} \mathbf{p}^+(x, 1) \bar{e}_1
\end{aligned}$$

Here $\mathbf{p}^+(x, \frac{y}{\epsilon}) = p^+(x, y)$ and $\Phi =: (\phi^1, \dots, \phi^P)^T$.

Equations for the first asymptotics. Substituting the ansatz (12) for p^+ , p^- and Φ into previous equations and performing the identification of terms with the same power of ϵ , a collection of equations for the coefficients (p_j^-, \mathbf{p}_j) and Φ_j is obtained. One finds that (p_0^-, \mathbf{p}_0) and $\Phi_0 = (\phi_0^1, \dots, \phi_0^P)^T$ solve

$$\frac{\partial^2}{\partial Y^2} \mathbf{p}_0^+ = 0 \text{ in } \Gamma \times (0, 1) \quad (15)$$

$$(\Delta + \kappa_1^2) p_0^- = 0 \text{ in } \Omega^- \quad (16)$$

$$\mathbf{p}_0^+ = p_0^- \text{ on } \Gamma (Y = 0) \quad (17)$$

$$c_2^2 \frac{\partial}{\partial Y} \mathbf{p}_0^+ = 0 \text{ on } \Gamma (Y = 0) \quad (18)$$

$$p_0^- = f \text{ on } \Gamma^- \quad (19)$$

$$\frac{\partial}{\partial Y} \mathbf{p}_0^+(x, 1) = 0 \quad (20)$$

$$-\kappa_2^2 \mathbf{L} \Phi_0(x) = \mathbf{M} \frac{\partial^2}{\partial x^2} \Phi_0(x) + 2 \frac{\partial^2}{\partial x^2} \mathbf{p}_0^+(x, 1) \bar{e}_1 \quad (21)$$

with periodic BCs set on Γ_W and Γ_E , and $(p_1^-, \mathbf{p}_1, \Phi_1)$ solves

$$\frac{\partial^2}{\partial Y^2} \mathbf{p}_1^+ = 0 \text{ in } \Gamma \times (0, 1) \quad (22)$$

$$(\Delta + \kappa_1^2) p_1^- = 0 \text{ in } \Omega^- \quad (23)$$

$$\mathbf{p}_1^+ = p_1^- \text{ on } \Gamma \text{ (} Y = 0 \text{)} \quad (24)$$

$$c_2^2 \frac{\partial}{\partial Y} \mathbf{p}_1^+ = c_1^2 \frac{\partial}{\partial n} p_0^- \text{ on } \Gamma \text{ (} Y = 0 \text{)} \quad (25)$$

$$p_1^- = 0 \text{ on } \Gamma^- \quad (26)$$

$$-a_0 \nu \kappa_2 \mathbf{p}_0^+(x, 1) + \frac{\partial}{\partial Y} \mathbf{p}_1^+(x, 1) = -\nu \kappa_2 \phi_0^1(x) \quad (27)$$

$$-\kappa_2^2 \mathbf{L} \Phi_1(x) = \mathbf{M} \frac{\partial^2}{\partial x^2} \Phi_1(x) + 2 \frac{\partial^2}{\partial x^2} \mathbf{p}_1^+(x, 1) \vec{e}_1 \quad (28)$$

with periodic BCs set on Γ_W and Γ_E .

Construction of the first asymptotics and equivalent conditions.

From (15), (18) and (20), \mathbf{p}_0^+ must have the form

$$\mathbf{p}_0^+(x, Y) = \alpha_0(x).$$

Equation (17) provides $\alpha_0(x) = p_0^-(x, 0)$. Also, from (22) one has

$$\mathbf{p}_1^+(x, Y) = \beta_0(x) + \beta_1(x)Y.$$

Additionally, (25) provides

$$c_2^2 \beta_1(x) = c_1^2 \frac{\partial}{\partial n} p_0^-(x, 0)$$

whereas equation (27) rewrites as

$$-a_0 \nu \kappa_2 \alpha_0(x) + \beta_1(x) = -\nu \kappa_2 \phi_0^1(x).$$

Therefore one gets

$$c_2^2 a_0 \nu \kappa_2 p_0^-(x, 0) = c_1^2 \frac{\partial}{\partial n} p_0^-(x, 0) + c_2^2 \nu \kappa_2 \phi_0^1(x).$$

Finally (21) and $\mathbf{p}_0^+(x, Y) = \alpha_0(x) = p_0^-(x, 0)$ yield

$$-\kappa_2^2 \mathbf{L} \Phi_0(x) = \mathbf{M} \frac{\partial^2}{\partial x^2} \Phi_0(x) + 2 \frac{\partial^2}{\partial x^2} p_0^-(x, 0) \vec{e}_1,$$

where $\Phi_0(x) = (\phi_0^1, \dots, \phi_0^P)^T(x)$ providing the order 0 model (14). Further computations also provide the order 1 model, Sec. 3.2.

4 Numerical Results

For the model problem considered, our findings indicate that the use of an equivalent absorbing boundary condition can be a viable and effective alternative for numerical simulation; mainly for the gain in computational cost provided by such conditions.

The numerical solution was obtained using the Interior Penalty Discontinuous Galerkin Method [21] with \mathcal{P}^3 elements. The normal derivative of p_0 that arise after applying the classical IPDG discretization to the first equation of (14) is replaced using the second equation of (14). Finally, the third equation of (14) is discretized by applying a 1D IPDG method on Γ . Hence, for $P = 1$, we have to solve a linear system that reads as

$$\begin{aligned} (K_{2D} + \kappa_1^2 M_{2D})\mathbf{P} &+ B_{2D1D}\mathbf{\Psi} &= F \\ B_{1D2D}\mathbf{P} &+ (K_{1D} + \kappa_2^2 M_{1D})\mathbf{\Psi} &= 0, \end{aligned} \quad (29)$$

where \mathbf{P} and $\mathbf{\Psi}$ are the vectors containing respectively the value of p_0 and ϕ_0^1 at their degrees of freedom (recalling that ϕ_0^1 is a 1D function defined only on Γ). M_{2D} and K_{2D} are the mass and stiffness matrices obtained by the 2D IPDG method, M_{1D} and K_{1D} are the mass and stiffness matrices obtained by the 1D IPDG method and B_{2D1D} and B_{1D2D} are the two matrices that ensures the coupling between the two equations.

In a test problem, we have compared the solution of (1)-(4) with the boundary conditions (10)-(11)-(6) for p^- in Ω^- with the solution p_0 obtained using the order 0 model (14) here presented. The Dirichlet data

$$f = \exp\left(i\frac{\omega}{c_1}(x \cos \theta)\right),$$

models the diffraction of an incident wave of frequency $\omega = 10$ Hz and hitting the boundary Γ^- at an angle of $\theta = \frac{5\pi}{12}$. Taking $c_1/c_2 = 2$, $P = 1$ (with $a_0 = 1$ and $a_1 = 1$) and modelling f as an incident wave, we have reached relative errors below 0.2%, considering the ratio of 10^{-2} for ϵ/H , where H is the thickness of the layer Ω^- (see Fig. 2). The results are summarized for various values of ϵ/H in table 1. The convergence rate coincides with the formal estimate (13) when $k = 0$. It is worth to notice that in order to satisfy periodicity, the parameters chosen must relate to the width L of the domain respecting $L = \frac{2q\pi c_1}{\omega \cos \theta}$, where $q \in \mathcal{N}$. Besides, there should be some extra care in the choice of ω : it should not be too big (else the condition $\epsilon \ll \frac{2\pi c_{1,2}}{\omega}$ will not be satisfied) or too small (this would demand a very large domain, since L is inversely proportional to ω). In the test case presented,

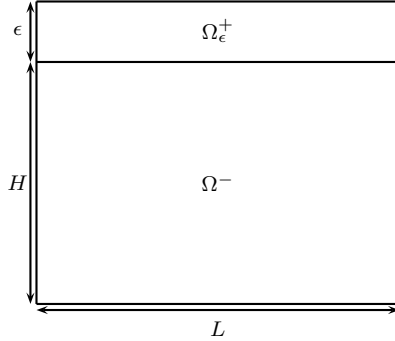


Figure 2: Configuration of the numerical experiment

L was set to approximately 1885 m. The triangular double layer meshes (necessary to compute p_0) used had around 10^5 elements, with triangle sizes set around 0.08 in the thin layer and its vicinity.

ϵ/H	$\ p^- - p_0\ $	relative error
0.01	0.282	0.18%
0.001	0.0281	0.018%
0.0005	0.0141	0.009%
0.00025	0.00703	0.00449%

Table 1: Comparative test between p^- and p_0 . $\|p^- - p_0\|$ refers to the euclidean distance between p^- and p_0 in a sample of 1000 points over a regular mesh on the domain Ω^- .

Conclusion

We have derived high order Equivalent Absorbing Boundary Conditions EABCs that model the propagation of waves in semi-infinite bilayered acoustic media. The numerical results illustrate the fact that for $P = 1$ and $k = 0$, the EABC models very accurately problem (1)-(4) with the conditions (10)-(11) and (6), as soon as $\epsilon/H \leq 0.0005$. Obviously, for such small values of ϵ/H , this problem is not able to reproduce accurately the case where the upper media is infinite. Hence, the next step will be to study the effect of P on the solution. This will provide a minimal value P_0 for which the EABC in (14) is efficient enough. Finally, the order 1 model is expected to

allow for considering higher values of ϵ/H and to provide a smaller value for P_0 , which would reduce the number of auxiliary functions ϕ and the computational costs.

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