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# The number of spanning trees of finite Sierpiński graphs

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We show that the number of spanning trees in the finite Sierpiński graph of level  $n$  is given by

$$\sqrt[4]{\frac{3}{20}} \left(\frac{5}{3}\right)^{-n/2} (\sqrt[4]{540})^{3^n}.$$

The proof proceeds in two steps: First, we show that the number of spanning trees and two further quantities satisfy a 3-dimensional polynomial recursion using the self-similar structure. Secondly, it turns out, that the dynamical behavior of the recursion is given by a 2-dimensional polynomial map, whose iterates can be computed explicitly.

**Keywords:** combinatorial enumeration, spanning trees, finite Sierpiński graphs

## 1 Introduction

The enumeration of spanning trees in a finite graph ranges among the classical tasks of combinatorics and has been studied for more than 150 years. The number of spanning trees in a graph  $X$  is often called the *complexity* and denoted by  $\tau(X)$ . Let us recall the famous Matrix-Tree Theorem of Kirchhoff [Kirchhoff(1847)]: The complexity  $\tau(X)$  of a graph  $X$  is equal to any cofactor of the Laplace matrix of  $X$ , which is the degree matrix of  $X$  minus the adjacency matrix of  $X$ . As a consequence the number of spanning trees in the complete graph with  $n$  vertices is given by  $n^{n-2}$ .

In the following the complexity of finite Sierpiński graphs is computed. These graphs are discrete analogs of the well-known Sierpiński gasket (see [Sierpinski(1915)]) and can be defined as follows: Denote by

$$\mathbf{e}_1 = (1, 0, 0), \quad \mathbf{e}_2 = (0, 1, 0), \quad \text{and} \quad \mathbf{e}_3 = (0, 0, 1)$$

the canonical basis vectors of  $\mathbb{R}^3$ . For  $n = 0$  the Sierpiński graph  $X_0$  is given by  $VX_0 = \{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$  and  $EX_0 = \{\{\mathbf{e}_1, \mathbf{e}_2\}, \{\mathbf{e}_2, \mathbf{e}_3\}, \{\mathbf{e}_3, \mathbf{e}_1\}\}$ . For  $n > 0$  the Sierpiński graph  $X_n$  is defined iteratively by

$$VX_n = (2^{n-1}\mathbf{e}_1 + VX_{n-1}) \cup (2^{n-1}\mathbf{e}_2 + VX_{n-1}) \cup (2^{n-1}\mathbf{e}_3 + VX_{n-1})$$

and

$$EX_n = (2^{n-1}\mathbf{e}_1 + EX_{n-1}) \uplus (2^{n-1}\mathbf{e}_2 + EX_{n-1}) \uplus (2^{n-1}\mathbf{e}_3 + EX_{n-1}).$$

The graph  $X_n$  is called *Sierpiński graph of level  $n$* ; see Figure 1 for  $X_0$ ,  $X_1$ , and  $X_2$ . A simple computation shows that  $|VX_n| = \frac{3}{2}(3^n + 1)$  and  $|EX_n| = 3^{n+1}$ .

## 2 Main result

The complexity  $\tau(X_n)$  of the Sierpiński graph of level  $n$  is given by

$$\tau(X_n) = \sqrt[4]{\frac{3}{20}} \left(\frac{5}{3}\right)^{-n/2} (\sqrt[4]{540})^{3^n}.$$

The first numbers of this sequence are 3, 54, 524880, 803355125990400000, ...

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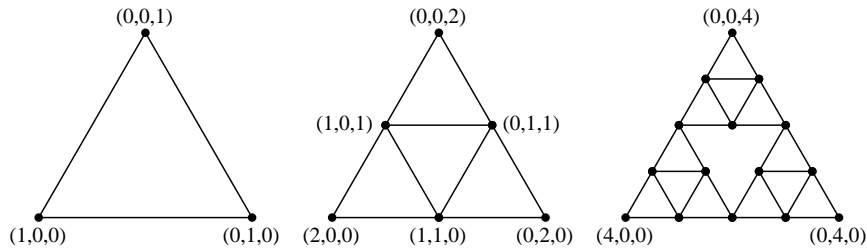


Fig. 1: The Sierpiński graphs  $X_0$ ,  $X_1$ , and  $X_2$ .

Since every spanning tree is a subset of the edge set  $EX_n$ , it is natural to rewrite this formula in terms of  $|EX_n|$ : This yields

$$\tau(X_n) = \sqrt[4]{\frac{5}{12}} |EX_n|^{(1-2/d_s)/2} (\sqrt[12]{540})^{|EX_n|}.$$

Here  $d_s$  is the spectral dimension of the Sierpiński gasket, which is given by

$$d_s = 2 \frac{\log 3}{\log 5}.$$

The spectral dimension was first introduced using the integrated density of states of the Laplacian on the infinite Sierpiński graph. Later on, the exponent  $d_s$  was studied from several points of view, see for example [Barlow(1998), Kigami(2001)] and the references therein. Furthermore, note that the fraction  $\frac{5}{3}$  is the so-called resistance scaling factor of the Sierpiński gasket.

We conjecture that the formula

$$\tau(X_n) = C |EX_n|^{\beta(1-2/d_s)} \alpha^{|EX_n|}$$

holds for a large class of sequences  $(X_n)_{n \geq 0}$  of finite self-similar graphs, where  $C > 0$ ,  $\beta \geq 0$  and  $\alpha \in (1, 2)$  are some constants; see [Teufl and Wagner(2006)].

### 3 Proof

The proof is based on the work in the paper [Teufl and Wagner(2006)]. For  $n \geq 0$  and  $k \in \{1, 2, 3\}$  denote by  $\mathcal{F}_k(n)$  the set of spanning forests in  $X_n$  with  $k$  components, so that each component contains at least one vertex of  $B_n = 2^n \{e_1, e_2, e_3\}$ , and set  $\mathcal{F}(n) = \mathcal{F}_1(n) \uplus \mathcal{F}_2(n) \uplus \mathcal{F}_3(n)$ . For  $n \geq 0$  and  $i \in \{1, 2, 3\}$  let  $X_n^i$  be the subgraph of  $X_n$ , which is induced by  $2^{n-1}e_i + VX_{n-1}$ , and note that  $X_n^i$  is isomorphic to  $X_{n-1}$ . The restriction of a spanning forest in  $\mathcal{F}_k(n)$  to  $X_n^i$  yields a spanning forest in  $\mathcal{F}_j(n-1)$  for some  $j \in \{1, 2, 3\}$ . Hence each spanning forest in  $\mathcal{F}(n)$  can be decomposed into three forests in  $\mathcal{F}(n-1)$ . For example, each spanning tree in  $\mathcal{F}_1(n)$  is composed of two trees in  $\mathcal{F}_1(n-1)$  and one forest in  $\mathcal{F}_2(n-1)$ , see Figure 2.

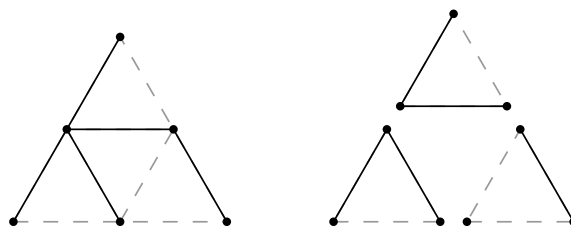


Fig. 2: The decomposition of a spanning tree of  $X_1$ .

Denote by  $c(n)$  the 3-dimensional counting vector

$$c(n) = (c_1(n), c_2(n), c_3(n)) = (|\mathcal{F}_1(n)|, \frac{1}{3}|\mathcal{F}_2(n)|, |\mathcal{F}_3(n)|).$$

Note that there are three possibilities to arrange the vertices of  $B_n$  in two components of a spanning forest in  $\mathcal{F}_2(n)$ , and the factor  $\frac{1}{3}$  takes care of that. Furthermore, the complexity  $\tau(X_n)$  is given by  $\tau(X_n) = c_1(n)$ .

The decomposition of forests in  $\mathcal{F}(n)$  into three forests in  $\mathcal{F}(n-1)$  implies that  $c(n)$  satisfies the polynomial recursion

$$c(n) = Q(c(n-1))$$

for  $n > 0$ , where  $Q$  is given by

$$Q : \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \mapsto \begin{pmatrix} 6x_1^2x_2 \\ 7x_1x_2^2 + x_1^2x_3 \\ 14x_2^3 + 12x_1x_2x_3 \end{pmatrix}$$

The initial vector is given by  $c(0) = (3, 1, 1)$ .

Now define the map  $v : \mathbb{R}_+^2 \rightarrow \mathbb{R}^3$  by

$$v(a, b) = (3a, b, b^2/a),$$

then  $c(0) = v(1, 1)$  and  $c(1) = v(18, 30)$ . Finally, define  $T : \mathbb{R}_+^2 \rightarrow \mathbb{R}_+^2$  by

$$T(a, b) = (18a^2b, 30ab^2),$$

then the function  $Q$  maps the set  $v(\mathbb{R}_+^2)$  into itself and  $Q \circ v = v \circ T$ .

Thus the vector  $c(n)$  is given by

$$c(n) = v(T^n(1, 1)),$$

where  $T^n$  is the  $n$ -fold iterate of  $T$ . The  $n$ -fold iterate of  $T$  can be computed explicitly:

$$T^n(a, b) = \begin{pmatrix} \left(\frac{5}{3}\right)^{-n/2} (\sqrt[4]{540})^{3^n-1} a^{(3^n+1)/2} b^{(3^n-1)/2} \\ \left(\frac{5}{3}\right)^{n/2} (\sqrt[4]{540})^{3^n-1} a^{(3^n-1)/2} b^{(3^n+1)/2} \end{pmatrix}$$

for all  $n \geq 0$ . This implies the statement.

## 4 Conclusion

The ideas of this proof can be formalized and generalized to a large class of fractal-like graphs. In addition, it is also possible to count different combinatorial objects in those graphs; for example matchings (independent edge subsets), connected subsets, subtrees, colorings, factors, and vertex or edge coverings. Using a decomposition argument it is possible to obtain a multi-dimensional polynomial recursion. Of course, one cannot expect to get explicit formulas in general. However, the asymptotic behavior can be deduced under suitable conditions. See [Teufl and Wagner(2006)] for more information.

An interesting reformulation of the Matrix-Tree Theorem states, that the complexity of a graph  $X$  is given by the product of all non-zero eigenvalues of the Laplace matrix of  $X$  taking the multiplicities into account divided by the number of vertices. Note that the Dirichlet spectrum of the Laplace matrix of finite Sierpiński graphs  $X_n$  with respect to the boundary  $B_n$  is well understood, see [Shima(1991)]. However, it seems to be much more difficult to understand the normal spectrum.

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