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Link Quality Estimation with the Gilbert-Elliot Model for Wireless Sensor Networks

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Abstract—In this paper, we apply the Gilbert-Elliot model to analyze measurements on a large-scale wireless sensor testbed with nodes equipped with CC1101 and CC2420 radio chips. The model considers a packet loss process as a sequence of transitions between Good and Bad states. We analyze the Packet Reception Ratio (PRR) based on the probabilities derived from the Gilbert-Elliot model. We show that the probabilities and other parameters (run and loss lengths) can very well discriminate between the main categories of link quality such as *good* and *weak* links. Identification of link quality is crucial for routing protocols such as RPL and LOADng.

Keywords—Gilbert-Elliot Model, Link Quality Indicator (LQI), link and routing metrics, Wireless Sensor Networks, IoT-LAB

I. INTRODUCTION

In this paper, we present an approach based on the Gilbert-Elliot model at the packet level to analyze the Packet Reception Ratio (PRR) and to find the best way to discriminate *good* links from *weak* ones. Recent work on routing protocols emphasized the importance of using stable metrics of link quality (one metric used with RPL is ETX that depends on PRR [1] and LOADng uses the number of weak links in a path as a metric [2]). This paper complements our previous work on characterizing the quality of wireless links in wireless sensor networks [3].

The transmission quality in terms of the Packet Reception Ratio (PRR) depends on the received signal strength, the level of interference, and the ability of the receiver to correctly decode transmitted information. The RSSI (Received Signal Strength Indicator) indicator provides an estimate of the signal energy at the receiver. LQI (Link Quality Indicator) may provide a better correlation with PRR than RSSI. LQI for CC1101 gives “*an estimate of how easily a received signal can be demodulated by accumulating the magnitude of the error between ideal constellations and the received signal over the 64 symbols immediately following the sync word*” [4].

In the previous work, we reported results of measurements on SensLAB (now IoT-LAB) [5], an indoor wireless sensor network testbed with a large number of nodes equipped with CC1101 and CC2420 radio chip (IoT-LAB is the current name of the platform [6]).

In this paper, we apply the Gilbert-Elliot model to analyze PRR based on measurements on IoT-LAB. We consider the packet reception process as a sequence of bits: 1 stands for a successful packet reception whereas 0 denotes a lost or corrupted packet. Such formulation leads to the possibility of

computing the stationary probabilities of being in the Good or Bad state in the Gilbert-Elliot model. We show that the probabilities and other parameters (run and loss lengths) can discriminate fairly well between links of different quality. We also apply the same approach to LQI by transforming a LQI value to a 0-1 process and computing the Gilbert-Elliot probabilities. Similarly, the resulting probabilities lead to good discrimination of quality for intermediate links.

II. EXPERIMENTAL SET UP

We recall the experimental set up reported in the previous work [3]: we have run experiments on the IoT-LAB platform available in Strasbourg composed of 240 WSN430 nodes with the CC1101 radio distributed across three trays at different heights. Each tray contains 80 nodes arranged in a regular grid (10x8) with a distance between contiguous nodes of about 1m. A node is composed of a MSP430F1611 CPU (48KB ROM, 10KB RAM) and a CC1101 radio operating at 868MHz. Its transmission power ranges between -30dBm and 10dBm, and the reception sensitivity is set to -88dBm.

In a single experiment, we use one tray at a time, i.e. 80 nodes. We observe the quality of transmission of a node that broadcasts a total of 5000 packets of 110 bytes every 0.5s. There is no other ongoing transmissions so there is no interference nor contention between nodes. When one node broadcasts its packet, the other 79 nodes are active and ready to receive—they log the values of LQI and RSSI of the received packet. The values are recorded for the correctly received packets with good CRC and also for those with incorrect CRC. As there is one sender at a time, we are able to relate the sender and the receiver of a packet even if the receiver cannot decode a packet.

The receiver nodes do not acknowledge frames and the MAC layer does not retransmit frames in case of failed transmissions. After the experiment, we compute for each link: i) the average value of RSSI over all received packets, ii) the average value and the standard deviation of LQI, iii) the average value of the Packet Reception Ratio (PRR) of each link as the proportion between the number of correctly received packets (correct CRC) to the total number of sent packets. The observed values of RSSI only slightly varied, so we have not analyzed the standard deviation of RSSI.

We assume that all nodes can potentially communicate with each other so that the number of unidirectional links is 6320 (80 sender nodes times 79 receiver nodes). We run the experiments with two levels of the transmission power: 0dBm and -10dBm. The bit rate is 60kb/s and nodes use the

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2FSK modulation. Table I summarizes the parameters of the experiments.

TABLE I. EXPERIMENT PARAMETERS FOR CC1101

Experiment area	10m x 8m x 2m
Number of nodes	3 x 80
Traffic type, interpacket interval	broadcast, 100ms
Number of sent packets	5000
Packet size	110 bytes
Transmission power	0dBm, -10dBm
Topology	grid

For experiments with the CC2420 radio, we have used the IoT-LAB platform in Lille composed of 256 WSN430 nodes scattered across two horizontal trays of different heights and one vertical tray. Each of the horizontal tray contains 100 nodes arranged in a grid of 20x5 with a distance of about 0.6m between nodes. A node has a CC2420 radio chip operating at the 2.4GHz band.

Table II shows the parameters of the experiments. We use for our study one tray of 100 nodes. The bit rate is 250kb/s and nodes use the OQPSK modulation. The measurement process of packet reception was the same as on the CC1101 platform.

TABLE II. EXPERIMENT PARAMETERS FOR CC2420

Experiment area	11.4m x 2.4m
Number of nodes	20 x 5
Traffic type, interpacket interval	broadcast, 100ms
Number of sent packets	1000
Packet size	110 bytes
Transmission power	0dBm, -10dBm
Topology	grid

III. LINK CHARACTERIZATION

A. Categories of Link Quality

We consider three main categories of link quality: *good* links with $PRR \geq 80\%$, *intermediate* with $20\% \leq PRR < 80\%$, and *bad* ones with $0 < PRR < 20\%$. Such categories appeared in previous studies [7], [8], but other thresholds are also possible, e.g. 90%–10%.

Table III gives the proportion of links in each category (over all 6320 unidirectional links) for the CC1101 platform. In addition to the categories, we provide the proportion of the links with $PRR = 0\%$ (actually, no link between nodes).

TABLE III. PROPORTION OF LINKS IN EACH CATEGORY

Transmission power	good	intermediate	bad	$PRR = 0\%$
0dBm	49%	8%	10%	33%
-10dBm	44%	6%	9%	41%

We can observe that roughly half of links are good, a large number of links are bad and decreasing the transmission power to -10dBm only slightly affects the proportion of good links. The number of intermediate links is fairly low.

B. Gilbert-Elliot Model

In this part, we apply the Gilbert-Elliot model (GE), a 2-state Markov model, to packet reception sequences to analyse PRR.

The GE model is widely used to represent the state of a channel (G - Good, B - Bad) by analyzing the errors on the

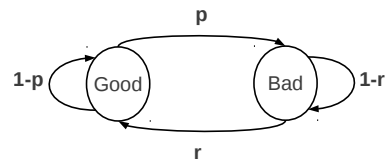


Fig. 1. Transition probability Gilbert-Elliot: 2-state Markov diagram. Good state represents a better quality channel whereas Bad state corresponds to a lower quality channel.

channel [9] (cf. Figure 1). The model has two states, the Good state corresponds to a successful reception and the Bad state to a loss. It was also used in communication networks to capture the temporal correlation of packet losses [10]. To study PRR using the model, we consider the packet reception process as a sequence of bits: 1 stands for a successful packet reception whereas 0 denotes a lost or corrupted packet.

The GE model is defined by the transition matrix M between states s_t at time t :

$$M = \begin{pmatrix} 1-p & p \\ r & 1-r \end{pmatrix}$$

where $p = P(s_t = B | s_{t-1} = G)$, and $r = P(s_t = G | s_{t-1} = B)$, $0 < p < 1$ and $0 < r < 1$ are the transition probabilities between states, respectively.

A transition from G to B takes place whenever the current packet is lost when the previous one was successful. In the opposite direction, a transition from B to G state takes place whenever the current packet is successfully received, but the previous one was lost. The conditional loss probability of remaining in the good state (probability that a loss arises after a success) is given by p while the conditional loss probability remaining in the bad state is denoted by $1-r$ (probability that a loss arises after a loss).

The stationary probability of the Good state π_G and the Bad state π_B are given by:

$$\pi_G = \frac{r}{p+r}, \quad \pi_B = \frac{p}{p+r}. \quad (1)$$

Considering the given stationary state probabilities, the loss probability is defined as:

$$\pi_{loss} = p * \pi_G + (1-r) * \pi_B = \pi_B \quad (2)$$

Parameter μ called *channel memory* is defined as:

$$\mu = 1 - p - r, \quad -1 \leq \mu \leq 1. \quad (3)$$

When $\mu = 0$, the packet loss process is *memory-less*. μ becomes negative for oscillatory links.

To show how the parameters of the GE model can be obtained from packet loss observations, let us consider that the first link has $sequence_1 = [011110]$ (1 denotes a received packet, 0 denotes a lost packet). The second link is characterized by $sequence_2 = [101011]$. We see that $sequence_1$ has 4 consecutive successful packet receptions whereas $sequence_2$ records only 2.

Transition matrices $M_1(p_1, r_1)$, $M_2(p_2, r_2)$ for sequence 1 and 2 are the following:

$$M_1 = \begin{pmatrix} 0.75 & 0.25 \\ 1 & 0 \end{pmatrix} \quad M_2 = \begin{pmatrix} 0.33 & 0.66 \\ 1 & 0 \end{pmatrix}$$

We obtain the following transition probabilities: the first link has $p_1 = 0.25$ and $r_1 = 1$, and the second link has $p_2 = 0.66$ and $r_2 = 1$.

TABLE IV. PERFORMANCE FOR $Link_1$ AND $Link_2$.

Link	PRR	p	r	π_G	π_B	π_{loss}	μ
1	0.67	0.25	1	0.8	0.2	0.2	-0.25
2	0.67	0.66	1	0.6	0.39	0.39	-0.66

Table IV summarizes the performance derived from the GE model applied to $Link_1$ and $Link_2$. Moreover, even if both links have a the same $PRR = 0.67$ (67%), $Link_1$ would be preferred over $Link_2$ as it records a higher good stationary probability (π_G of 0.8 compared to 0.6) and a higher negative channel memory ($\mu = -0.25$ indicating that $Link_1$ is less oscillatory than $Link_2$ with $\mu = -0.66$).

Our goal is to use the stationary probabilities given by the GE model to estimate the quality of links.

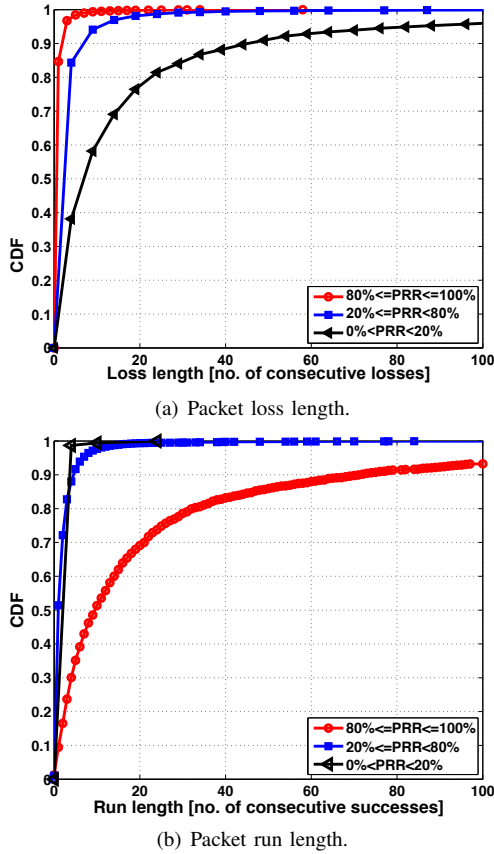


Fig. 2. Cumulative Distribution Function for each link category: good, intermediate, bad for a) packet loss length, b) packet run length, CC1101, 110B, 0dBm.

C. Analysis of Packet Losses

We call a *run length* the number of consecutive successful reception of packets and a *loss length* the number of consecutive lost packets.

Figure 2a shows that the distribution of packet losses and successful receptions depends on the link category. For instance, 98% of good links have an average 1.6 loss length, meaning that the probability of having consecutive lost packets is low. We have observed large average loss length of about 5.3 for intermediate links and about 56.8 for bad links, which shows that good links have independent losses with respect to intermediate and bad links. Yet, bad links may have bad states that last seconds. Figure 2b illustrates that run length varies in function of link category. Good links stick to the good state for long periods, while bad links have quite small run length about 1, which means that after only one successful reception bad links most probably return to the bad state.

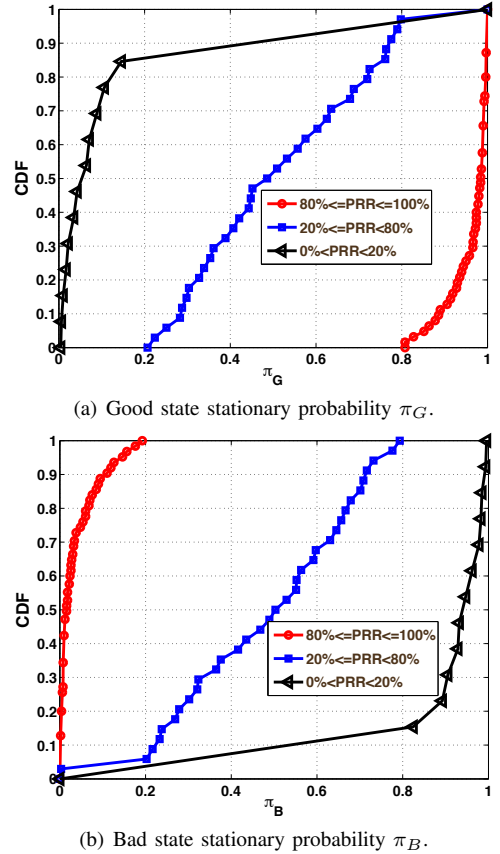


Fig. 3. Cumulative Distribution Function for each link category: good, intermediate, bad for a) stationary probability in good state π_G , b) stationary probability in bad state π_B , CC1101, 110B, 0dBm.

Figures 3c and 3d show that good and bad stationary probabilities can discriminate quite well link categories.

TABLE V. GE PARAMETERS, 110B PACKET SIZE, CC1101.

Category	run length	loss length	p	r
$PRR \geq 80\%$	74.2	1.6	0.03	0.84
$20\% \leq PRR < 80\%$	14.8	12.5	0.43	0.42
$0 < PRR < 20\%$	2.2	43.4	0.81	0.07

TABLE VI. GE PARAMETERS, 110B PACKET SIZE, CC1101.

Category	π_G	π_B	π_{Loss}	μ
$PRR \geq 80\%$	0.96	0.03	0.03	0.13
$20\% \leq PRR < 80\%$	0.49	0.50	0.50	0.15
$0 < PRR < 20\%$	0.07	0.92	0.92	0.12

Tables V and VI summarize the parameters of the GE model: transition probabilities and stationary state probabilities. We can see that a good link has high π_G (0.96) and low π_B (0.03).

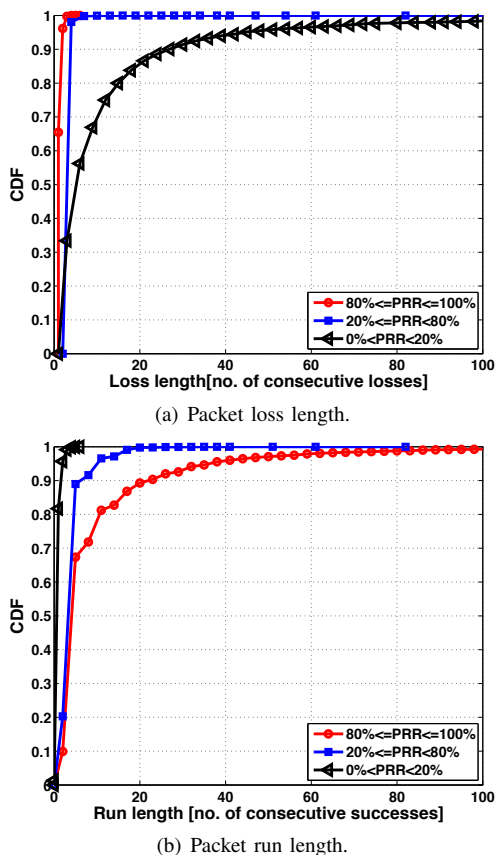


Fig. 4. Cumulative Distribution Function for each link category: good, intermediate, bad for a) packet loss length, b) packet run length, CC2420, 110B, 0dBm.

On the CC2420 radio platform, we have observed that loss length is below 1.5 for good links and increases for the decreasing link quality (cf. Figure 4a). Run lengths continue to be low for bad links (about 1) and high for good links (above 5) (cf. Figure 4b).

Again, π_G discriminates links categories fairly well as it takes values within: 0.8–1 (good links), 0.6–0.8 (intermediate links), and 0–0.2 (bad links) (cf. Figure 5a). Figure 5b also shows that π_B distinguishes well link categories (0–0.2 for good links, 0.2–0.4 for intermediate links, and 0.8–1 for bad links).

TABLE VII. GE PARAMETERS, 110B PACKETS, 0dBm, CC2420.

Category	run length	loss length	p	r
$PRR \geq 80\%$	13.1	1.2	0.13	0.84
$20\% \leq PRR < 80\%$	3.5	1.9	0.29	0.78
$0 < PRR < 20\%$	1.0	28.0	0.92	0.08

For the CC2420 radio, Table VII highlights that like for CC1101, good links have a small average loss length per link of 1.2. Intermediate links may encounter losses with an average length of 1.9 and bad links show a loss length of 28. Again, transition probabilities strongly depend on the link category:

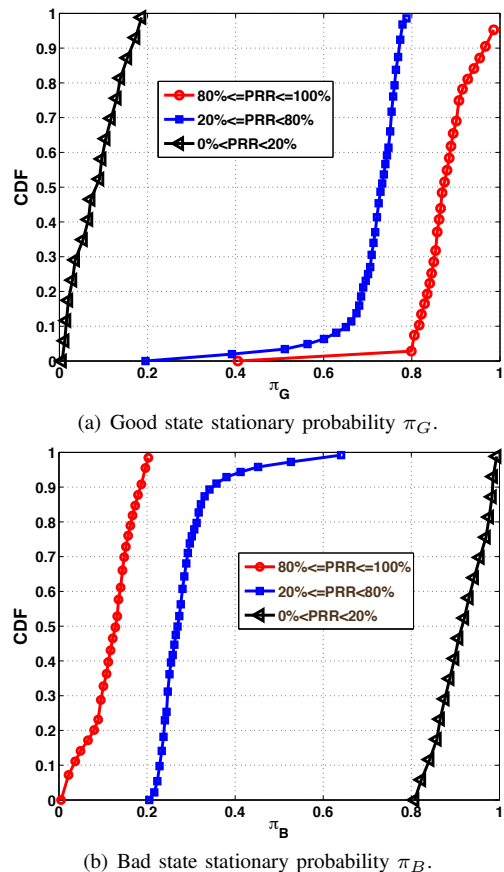


Fig. 5. Cumulative Distribution Function for each link category: good, intermediate, bad for a) stationary probability in good state π_G , b) stationary probability in bad state π_B , CC2420, 110B, 0dBm.

TABLE VIII. GE PARAMETERS, 110B PACKETS, 0dBm, CC2420.

Category	π_G	π_B	π_{Loss}	μ
$PRR \geq 80\%$	0.86	0.13	0.13	0.03
$20\% \leq PRR < 80\%$	0.72	0.27	0.27	-0.07
$0 < PRR < 20\%$	0.08	0.92	0.92	0

$p \sim 0.10$ for good links, $p \sim 0.3$ for intermediate, and $p \sim 0.9$ for bad links. On the other hand, r decreases from $r \sim 0.80$ for good links to $r \sim 0.04$ for bad links. Table VIII shows that for CC2420, loss probability remains a good link quality discriminator (0.13 for good links, 0.27 for intermediate links, and 0.92 for bad links).

D. Estimating PRR using LQI

The results show that stationary probabilities (π_G and π_B) for the reception process are good discriminators of the link quality. In this section, we apply the GE model to the average (avg) of the LQI measured values for highly variable links.

We consider the avg LQI values of the received packets as a sequence of bits:

$$f(\overline{lqi}) = \begin{cases} 1, & \text{if } \overline{lqi} \leq \overline{LQI_{threshold}} \\ 0, & \text{otherwise.} \end{cases} \quad (4)$$

where $\overline{LQI_{threshold}}$ is the threshold value of avg LQI that may be chosen with respect to the hardware and a given

environment. For our analysis, we have chosen $\overline{LQI}_{threshold}$ of 1.7: an avg LQI value below 1.7 corresponds to 1 (good reception) whereas an avg LQI above 1.7 corresponds to 0 (bad reception) (cf. Eq. 4). The threshold value of 1.7 was decided by observing fitting the LQI values with a Fermi-Dirac function [3].

For applying this approach, we have chosen a node that has only intermediate links in its neighborhood (Node 6, CC1101, 0dBm) with different levels of PRR: 6 \rightarrow 20 (PRR=64%), 6 \rightarrow 57 (PRR=54%), 6 \rightarrow 34 (PRR=34%). We compute the stationary probability π_G associated with the avg LQI to see if it can discriminate the quality of these links.

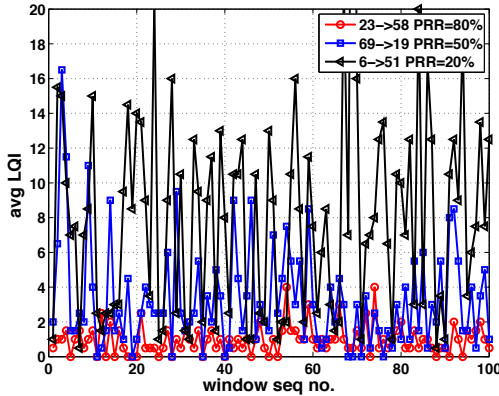


Fig. 6. Temporal evolution of avg LQI computed over windows of size 2, for link 23 \rightarrow 58 (PRR=80%), link 69 \rightarrow 19 (PRR=50%), and link 6 \rightarrow 51 (PRR=20%), $w=2$, CC1101, 0dBm.

Figure 6 depicts the temporal evolution of avg LQI computed over small windows of size 2. We can observe important overlapping of the curves for the link with PRR=50% and PRR=20%.

To apply the GE model, we associate each value of the avg LQI with a sequence of bits and then, we compute the stationary probability π_G for each sequence of five values as illustrated in Figure 7 (the figure presents the computation process for the average and standard variation of the LQI values, however, we only consider the average values of LQI due to the lack of space).

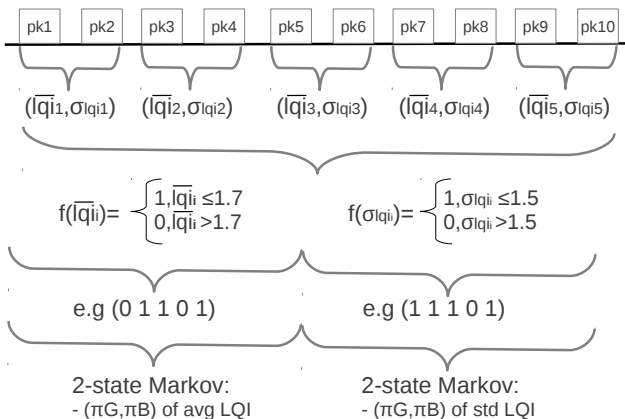


Fig. 7. Computing the stationary probabilities from avg and std LQI values.

Figure 8 shows stationary probability π_G computed for avg LQI. We can see that the link with PRR of 80% can be easily

distinguished from links with 50% or 20% of PRR— π_G of avg LQI helps to discriminate the links with these values of PRR (cf. Figure 8).

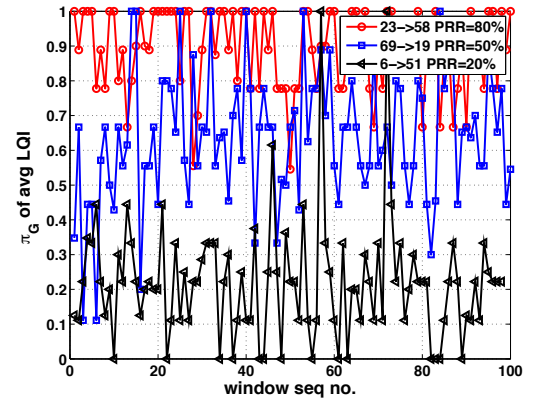


Fig. 8. Stationary probability π_G derived from the measured avg LQI values (threshold of 1.7) for link 23 \rightarrow 58 (PRR=80%), link 69 \rightarrow 19 (PRR=50%), and link 6 \rightarrow 51 (PRR=20%), $w=10$, CC1101, 0dBm.

Figure 9 shows that π_G of avg LQI also enables fairly good differentiation between the links of PRR=64%, PRR=54%, and PRR=34%.

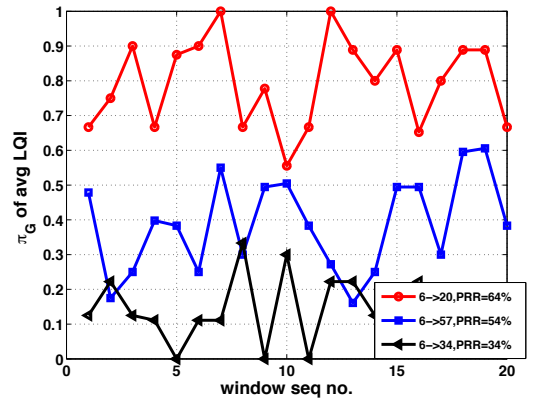


Fig. 9. Stationary probability π_G derived from the measured avg LQI values (threshold of 1.7) for link 6 \rightarrow 20 (PRR=64%), link 6 \rightarrow 57 (PRR=54%), and link 6 \rightarrow 34 (PRR=34%), CC1101, 0dBm.

We have also evaluated the relevance and the efficiency of using stationary probabilities to categorize high variable CC2420 links. Like CC1101, we assess the temporal fluctuation of intermediate links with different reception ratio: 174 \rightarrow 127 (PRR=60%), 99 \rightarrow 179 (PRR=40%), 188 \rightarrow 105 (PRR=20%). We apply the same approach as represented in Figure 7 with $\overline{LQI}_{threshold} = 70$.

Figure 10 shows that π_G of avg LQI can very well distinguish among links with PRR=60%, PRR=40%, and PRR=20%.

IV. RELATED WORK

Much research work considered the problem of characterizing the quality of wireless links in sensor networks. On a 60 mote indoor/outdoor testbed, Zhao *et al.* [11] showed the existence of spatial gray regions corresponding to high variation in packet reception. Woo *et al.* [12] observed good connectivity of links to nodes up to 3m and a transitional

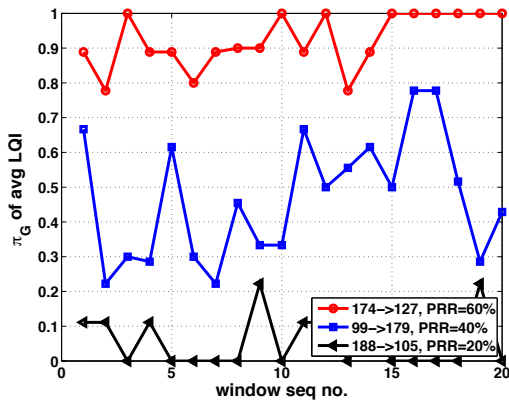


Fig. 10. Stationary probability π_G derived from the measured avg LQI values (threshold of 70) for 174 \rightarrow 127 (PRR=60%), 99 \rightarrow 179 (PRR=40%), 188 \rightarrow 105 (PRR=20%), CC2420, 0dBm.

(grey) zone between 3m and 12m with links exhibiting large variability. In another paper, the authors modeled packet loss with a binomial distribution and observed that good links are symmetric [13]. Other researchers confirmed the existence of three zones: the well connected, the transitional (grey), and the disconnected one [14], [15]. They reported that the links in the connected zone are stable contrary to the transitional zone.

As mentioned in the introduction, Srinivasan *et al.* [16] analyzed RSSI and LQI of CC2420. They highlighted the utility of RSSI in detecting links with good PRR and observed good correlation of LQI and PRR. Meier *et al.* [17] analyzed measurements of an indoor sensor network with CC2420 exhibiting high link quality variability and considered metrics derived from modeling the loss process as a Bernoulli process.

Tang *et al.* [18] evaluated the temporal and spatial link fluctuation in a factory environment and characterized channel variations. Bas *et al.* [19] demonstrated that the angle of the direction influences the correlation of the link quality with the distance. Rondinone *et al.* [20] analyzed the link quality in sensor networks and proposed to use as a link quality indicator the product of PRR and the normalized average RSSI.

V. CONCLUSION

In this paper, we have applied the Gilbert-Elliott model to analyze PRR based on measurements on a large-scale wireless sensor testbed. First, we derive the stationary probabilities of the Gilbert-Elliott model from the packet loss process. We show that the probabilities and other parameters such as run and loss lengths can very well discriminate between the main categories of link quality. Second, we also apply the same approach to LQI by transforming the average of LQI values to a 0-1 process. Similarly, the Gilbert-Elliott probabilities of the avg LQI lead to good discrimination of quality for intermediate links. In the future, we plan to use the reported results to derive metrics for RPL and LOADng routing protocols and study their performance on the IoT-LAB testbed.

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