# Hierarchical Zonotopal Power Ideals 

Matthias Lenzlld<br>${ }^{1}$ Technische Universität Berlin, Berlin, Germany


#### Abstract

Zonotopal algebra deals with ideals and vector spaces of polynomials that are related to several combinatorial and geometric structures defined by a finite sequence of vectors. Given such a sequence $X$, an integer $k \geq-1$ and an upper set in the lattice of flats of the matroid defined by $X$, we define and study the associated hierarchical zonotopal power ideal. This ideal is generated by powers of linear forms. Its Hilbert series depends only on the matroid structure of $X$. It is related to various other matroid invariants, e. g. the shelling polynomial and the characteristic polynomial.

This work unifies and generalizes results by Ardila-Postnikov on power ideals and by Holtz-Ron and Holtz-Ron-Xu on (hierarchical) zonotopal algebra. We also generalize a result on zonotopal Cox modules due to Sturmfels-Xu. Résumé. La théorie de l'algèbre "zonotopique" s'occupe d'idéaux et d'espaces vectoriels de polynômes qui ont un rapport avec plusieurs structures combinatoires et géométriques définies par des suites finies de vecteurs. Étant donné une telle suite $X$, un nombre entier $k \geq-1$ et un ensemble supérieur dans le treillis des plans du matroïde défini par $X$, nous définissons et étudions l'idéal hiérarchique zonotopique, engendré par des puissances de formes linéaires. Sa série de Hilbert dépend seulement de la structure matroïdale de $X$. Il existe des relations avec d'autres invariants de matroïdes, tels que le polynôme d'épluchage et le polynôme caractéristique.

Ce travail unifie et généralise des résultats d'Ardila-Postnikov sur les idéaux de puissances et de Holtz-Ron et Holtz-Ron-Xu sur l'algèbre zonotopique (hiérarchique). Nous généralisons aussi un résultat sur les modules de Cox zonotopiques, dû à Sturmfels-Xu.


Keywords: matroids, Tutte polynomials, power ideals, zonotopal algebra, Hilbert series

## 1 Introduction

Let $X=\left(x_{1}, \ldots, x_{N}\right) \subseteq \mathbb{R}^{r}$ be a sequence of vectors that span $\mathbb{R}^{r}$. For a vector $\eta$, let $m(\eta)$ denote the number of vectors in $X$ that are not perpendicular to $\eta$. A vector $v \in \mathbb{R}^{r}$ defines a linear polynomial $p_{v}:=\sum_{i} v_{i} t_{i} \in \mathbb{R}\left[t_{1}, \ldots, t_{r}\right]$. For $Y \subseteq X$, let $p_{Y}:=\prod_{x \in Y} p_{x}$. Then define

$$
\begin{equation*}
\mathcal{P}(X):=\operatorname{span}\left\{p_{Y}: X \backslash Y \text { spans } \mathbb{R}^{r}\right\} \quad \text { and } \quad \mathcal{I}(X):=\operatorname{ideal}\left\{p_{\eta}^{m(\eta)}: \eta \neq 0\right\} \tag{1.1}
\end{equation*}
$$

The following theorem and several generalizations are well known:

[^0]Theorem 1.1 ([1, 5, 11]).

$$
\begin{equation*}
\mathcal{P}(X)=\operatorname{ker} \mathcal{I}(X):=\operatorname{span}\left\{q \in \mathbb{R}\left[t_{1}, \ldots, t_{r}\right]: f\left(\frac{\partial}{\partial t_{1}}, \ldots, \frac{\partial}{\partial t_{r}}\right) q=0 \text { for all } f \in \mathcal{I}(X)\right\} \tag{1.2}
\end{equation*}
$$

In addition, $\mathcal{I}(X)=\mathcal{I}^{\prime}(X):=\left\{p_{\eta}^{m(\eta)}:\right.$ the vectors in $X$ that are perpendicular to $\eta$ span a hyperplane $\}$
We show that a statement as in Theorem 1.1 holds in a far more general setting: we study the kernel of the hierarchical zonotopal power ideal

$$
\begin{equation*}
\mathcal{I}(X, k, J):=\operatorname{ideal}\left\{p_{\eta}^{m(\eta)+k+\chi_{J}(\eta)}: \eta \neq 0\right\} \tag{1.3}
\end{equation*}
$$

where $k \geq-1$ is an integer and $\chi_{J}$ is the indicator function of an upper set $J$ in the lattice of flats of the matroid defined by $X$. We study those spaces in a slightly more abstract setting, e.g. $\mathcal{P}(X, k, J)$ is contained in the symmetric algebra over some $\mathbb{K}$-vector space, where $\mathbb{K}$ is a field of characteristic zero.
The choice of a sequence of vectors $X$ defines a large number of objects in various mathematical fields which are all related to zonotopal algebra [11]. Examples include combinatorics (matroids, matroid and graph polynomials, generalized parking functions and chip firing games if $X$ is graphic [15, 18]), discrete geometry (hyperplane arrangements, zonotopes and tilings of zonotopes), approximation theory (box splines [6], least map interpolation) and algebraic geometry (Cox rings, fat point ideals [1, 10, 19]).

Central $\mathcal{P}$-spaces (in our terminology the kernel of $\mathcal{I}^{\prime}(X, 0,\{X\})$ ) were introduced in the literature on approximation theory around 1990 (e.g. [5]). A dual space called $\mathcal{D}(X)$ appeared almost 30 years ago. See [11, Section 1.2] for a historic survey.

Recently, Olga Holtz and Amos Ron coined the term zonotopal algebra [11]. They introduced internal $(k=-1)$ and external $(k=+1) \mathcal{P}$-spaces and $\mathcal{D}$-spaces. Federico Ardila and Alexander Postnikov constructed $\mathcal{P}$-spaces for arbitrary integers $k \geq-1$ (Combinatorics and geometry of power ideals [1], presented at FPSAC 2009). Olga Holtz, Amos Ron, and Zhiqiang Xu [12] introduced hierarchical zonotopal spaces, i.e. structures that depend on the choice of an upper set $J$ in addition to $X$ and $k$. They studied semi-internal and semi-external spaces (i.e. $k=-1$ and $k=0$ and some special upper sets $J$ ). The central case was treated in an algebraic setting in [8]. Other related results include [2, 20].

The least map [7] assigns to a finite set $S \subseteq \mathbb{R}^{r}$ of cardinality $m$ an $m$-dimensional space of homogeneous polynomials in $\mathbb{R}\left[t_{1}, \ldots, t_{r}\right]$. Holtz and Ron [11] showed that in the internal, central and external case, $\mathcal{P}$-spaces can be obtained via the least map if $X \subseteq \mathbb{Z}^{r}$ is unimodular. In those cases, the $\mathcal{P}$-spaces are obtained by choosing the set $S$ as a certain subset of the set of integral points in the zonotope

$$
\begin{equation*}
Z(X):=\left\{\sum_{i=1}^{N} \lambda_{i} x_{i}: 0 \leq \lambda_{i} \leq 1\right\} \tag{1.4}
\end{equation*}
$$

There is also a discrete theory, where differential operators are replaced by difference operators. ([8] and A Tutte polynomial for toric arrangements (Luca Moci) [16], presented at FPSAC 2010). In this theory, the connection with lattice points in zonotope remains valid even if $X$ is not unimodular.

As an example for the connections between zonotopal algebra and combinatorics, we now explain various relationships between zonotopal spaces and matroid/graph polynomials. They can be deduced from the fact that both, the matroid/graph polynomials [9] and the Hilbert series of the zonotopal spaces [1] are evaluations of the Tutte polynomial.
$\operatorname{Hilb}(\mathcal{P}(X, 0,\{X\}), t)$ equals the shelling polynomial [3] $h_{\Delta\left(X^{*}\right)}(t)$ of the matroid dual to $X$ with the coefficients reversed. The $t^{N-r-i}$ coefficient of $h_{\Delta\left(X^{*}\right)}(t+1)$ equals the number of independent sets of cardinality $i$ in the matroid $X$. Let $X_{G}$ denote the reduced oriented incidence matrix of a connected graph $G$, i.e. the matrix that is obtained from the oriented incidence matrix by removing one row so that it has full rank. The Hilbert series of $\mathcal{P}\left(X_{G},-1,\left\{X_{G}\right\}\right)$ is related to the flow polynomial $\phi_{G}$. By duality it is also related to the chromatic polynomial of the graph resp. the characteristic polynomial of the matroid in the general case. The connection is as follows: if $G$ is connected, then

$$
\begin{equation*}
\phi_{G}(t)=(t-1)^{N-r} \operatorname{Hilb}\left(\mathcal{P}\left(X_{G},-1,\left\{X_{G}\right\}\right), 1 /(1-t)\right) \tag{1.5}
\end{equation*}
$$

The four color theorem is equivalent to the following statement: if $G$ is a planar graph and $G^{*}$ denotes its dual, then

$$
\begin{equation*}
\operatorname{Hilb}\left(\mathcal{P}\left(X_{G^{*}},-1,\left\{X_{G^{*}}\right\}\right),-1 / 3\right)>0 \tag{1.6}
\end{equation*}
$$

Organization of the article: In Section 2, we introduce our notation and review the mathematical background. In Section 3, we define hierarchical zonotopal power ideals. A simple description of their kernels is given by our Main Theorem. In Section 4 , we construct bases for the vector spaces $\mathcal{P}(X, k, J)$ and we deduce several formulas for their Hilbert series. In Section 5, we apply our results to prove a statement about zonotopal Cox modules that were defined by Bernd Sturmfels and Zhiqiang Xu [19]. In Section6, we give some examples. The full paper is available on the arXiv [14].

## 2 Preliminaries

Notation: The following notation is used throughout this paper: $\mathbb{K}$ is a fixed field of characteristic zero. $V$ denotes a finite-dimensional $\mathbb{K}$-vector space of dimension $r \geq 1$ and $U:=V^{*}$ its dual. Our main object of study is a finite sequence $X=\left(x_{1}, \ldots, x_{N}\right) \subseteq U$ whose elements span $U$. We slightly abuse notation by using the symbol $\subseteq$ for subsequences. For $Y \subseteq X$, the deletion $X \backslash Y$ denotes the deletion of a subsequence and not the deletion of a subset, i.e. $\left(x_{1}, x_{2}\right) \backslash\left(x_{1}\right)=\left(x_{2}\right)$ even if $x_{1}=x_{2}$. The order of the elements in $X$ is irrelevant except in Section 4 .

Matroids and posets: Let $X=\left(x_{1}, \ldots, x_{N}\right)$ be a finite sequence whose elements span $U$. Let $\mathfrak{M}(X):=\left\{I \subseteq\{1, \ldots, N\}:\left\{x_{i}: i \in I\right\}\right.$ linearly independent $\}$. Then $\mathfrak{M}(X)$ is a matroid of rank $r$ on $N$ elements. $X$ is called a $\mathbb{K}$-representation of the matroid $\mathfrak{M}(X)$. For more information about matroids, see Oxley's book [17].

We now introduce some additional matroid theoretic concepts. To facilitate notation, we always write $X$ instead of $\mathfrak{M}(X)$. The rank of $Y \subseteq X$ is defined as the cardinality of a maximal independent set contained in $Y$. It is denoted $\operatorname{rk}(Y)$. The closure of $Y$ in $X$ is defined as $\mathrm{cl}_{X}(Y):=\{x \in X: \operatorname{rk}(Y \cup x)=\operatorname{rk}(Y)\}$. $C \subseteq X$ is called a flat if $C=\operatorname{cl}(C)$. A hyperplane is a flat of rank $r-1$. The set of all hyperplanes in $X$ is denoted by $\mathcal{H}=\mathcal{H}(X)$.

Given a flat $C \subseteq X$, we call $\eta \in V$ a defining normal for $C$ if $C=\{x \in X: \eta(x)=0\}$. Note that for hyperplanes, there is a unique defining normal (up to scaling). The set of bases of the matroid $X$ (i.e. the subsequences of $X$ of cardinality $r$ and rank $r$ ) is denoted $\mathbb{B}(X)$. If $x=0$, then $x$ is called a loop. If $\operatorname{rk}(X \backslash x)=r-1$, then $x$ is called a coloop.

The set of flats of a given matroid $X$ ordered by inclusion forms a lattice (i.e. a poset with joins and meets) called the lattice of flats $\mathcal{L}(X)$. An upper set $J \subseteq \mathcal{L}(X)$ is an upward closed set, i.e. $C \subseteq C^{\prime}$,
$C \in J$ implies $C^{\prime} \in J$. We call $C \in \mathcal{L}(X)$ a maximal missing flat if $C \notin J$ and $C$ is maximal with this property.

The Tutte polynomial [4] $T_{X}(x, y):=\sum_{A \subseteq X}(x-1)^{r-\mathrm{rk}(A)}(y-1)^{|A|-\mathrm{rk}(A)}$ captures a lot of information about the matroid $\mathfrak{M}(X)$.

Algebra: $\operatorname{Sym}(V)$ denotes the symmetric algebra over $V$. This is a base-free version of the ring of polynomials over $V$. The choice of a basis $B=\left\{b_{1}, \ldots, b_{n}\right\} \subseteq V$ yields an isomorphism $\operatorname{Sym}(V) \cong$ $\mathbb{K}\left[b_{1}, \ldots, b_{r}\right]$.

A derivation on $\operatorname{Sym}(V)$ is a $\mathbb{K}$-linear map $D$ satisfying Leibniz's law, i.e. $D(f g)=D(f) g+f D(g)$ for $f, g \in \operatorname{Sym}(V)$. For $v \in V$, we define the directional derivative in direction $v, D_{v}: \operatorname{Sym}(U) \rightarrow$ $\operatorname{Sym}(U)$ as the unique derivation which satisfies $D_{v}(u)=v(u)$ for all $u \in U$. For $\mathbb{K}=\mathbb{R}$ and $\mathbb{K}=\mathbb{C}$, this definition agrees with the analytic definition of the directional derivative. It follows that $\operatorname{Sym}(V)$ can be identified with the ring of differential operators on $U$.

Now we define a pairing $\langle\cdot, \cdot\rangle: \operatorname{Sym}(U) \times \operatorname{Sym}(V) \rightarrow \mathbb{K}$ by $\langle f, q\rangle:=(q(D) f)(0)$ where $q(D) f$ means that $q$ acts as a differential operator on $f$.
A graded vector space is a vector space $V$ that decomposes into a direct sum $V=\bigoplus_{i \geq 0} V_{i}$. For a graded vector space, we define its Hilbert series as the formal power series $\operatorname{Hilb}(V, t):=\sum_{i \geq 0} \operatorname{dim}\left(V_{i}\right) t^{i}$. A graded algebra $V$ has the additional property $V_{i} V_{j} \subseteq V_{i+j}$. We use the symmetric algebra with its natural grading. This grading is characterized by the property that the degree 1 elements are exactly the ones that are contained in $V$. A $\mathbb{Z}^{n}$-multigraded ring $R$ is defined similarly: $R$ decomposes into a direct $\operatorname{sum} R=\bigoplus_{\boldsymbol{a} \in \mathbb{Z}^{n}} R_{\boldsymbol{a}}$ and $R_{\boldsymbol{a}} R_{\boldsymbol{b}} \subseteq R_{\boldsymbol{a}+\boldsymbol{b}}$.

A linear map $f: V \rightarrow W$ induces an algebra homomorphism $\operatorname{Sym}(f): \operatorname{Sym}(V) \rightarrow \operatorname{Sym}(W)$.
Homogeneous ideals and their kernels: An ideal $\mathcal{I} \subseteq \operatorname{Sym}(V)$ is called a power ideal [1] if $\mathcal{I}=$ ideal $\left\{D_{\eta}^{e_{\eta}}: \eta \in Z\right\}$ for some $Z \subseteq V \backslash\{0\}$ and $e \in \mathbb{Z}_{\geq 0}^{Z}{ }^{\text {(i) }} D_{\eta}$ denotes the image of $\eta$ under the canonical injection $V \hookrightarrow \operatorname{Sym}(V)$. By definition, power ideals are homogeneous.

Definition 2.1. Let $\mathcal{I} \subseteq \operatorname{Sym}(V)$ be a homogeneous ideal. Its kernel (or inverse system) is defined as

$$
\begin{equation*}
\operatorname{ker} \mathcal{I}:=\{f \in \operatorname{Sym}(U):\langle f, q\rangle=0 \text { for all } q \in \mathcal{I}\} \tag{2.1}
\end{equation*}
$$

It is known that for a homogeneous ideal $\mathcal{I} \subseteq \operatorname{Sym}(V)$ of finite codimension the Hilbert series of ker $\mathcal{I}$ and $\operatorname{Sym}(V) / \mathcal{I}$ are equal. ${ }^{\text {(ii) }}$

A remark on the notation: As zonotopal spaces were studied by people from different fields, the notation and the level of abstraction used in the literature varies. Authors with a background in spline theory usually work over $\mathbb{R}^{n}$ while other authors prefer an abstract setting as we do.

Since the Euclidean setting captures all the important parts of the theory, a reader with no background in abstract algebra may safely make the following substitutions: $\mathbb{K}=\mathbb{R}, U \cong V \cong \mathbb{R}^{n}$. $f \in \mathbb{R}\left[t_{1}, \ldots, t_{r}\right]=\operatorname{Sym}(V)$ acts on $\mathbb{R}\left[t_{1}, \ldots, t_{r}\right]=\operatorname{Sym}(U)$ as the differential operator that is obtained from $f$ by substituting $t_{i} \mapsto \frac{\partial}{\partial t_{i}}$.

[^1]Some authors work in the dual setting and consider a central hyperplane arrangement instead of a finite sequence of vectors $X$. While hierarchical zonotopal power ideals can be defined in both settings, it is natural for us to work with vectors as we are also interested in the zonotope $Z(X)$.

## 3 Hierarchical zonotopal power ideals and their kernels

In this section, we define hierarchical zonotopal power ideals. Our Main Theorem gives a simple description of their kernels.

Definitions and the Main Theorem: Recall that $U=V^{*}$ denotes an $r$-dimensional vector space over a field $\mathbb{K}$ of characteristic zero and $X=\left(x_{1}, \ldots, x_{N}\right)$ denotes a finite sequence whose elements span $U$.

A vector $\eta \in V$ defines a flat $C \subseteq X$. Define $m_{X}(C)=m_{X}(\eta):=|X \backslash C|$. Given an upper set $J \subseteq \mathcal{L}(X), \chi_{J}: \mathcal{L}(X) \rightarrow\{0,1\}$ denotes its indicator function. The index of $\chi$ and $m$ is omitted if it is clear which upper set is meant. We define $\chi$ for arbitrary sets $A \subseteq X$ as $\chi(A):=\chi(\operatorname{cl}(A))$.

For a given $x \in U$, we denote the image of $X$ under the canonical injection $U \hookrightarrow \operatorname{Sym}(U)$ by $p_{x}$. For $Y \subseteq X$, we define $p_{Y}:=\prod_{x \in Y} p_{x}$. For $\eta \in V$, we write $D_{\eta}$ for the image of $\eta$ under the canonical injection $V \hookrightarrow \operatorname{Sym}(V)$ in order to stress the fact that we mostly think of $\operatorname{Sym}(V)$ as the algebra generated by the directional derivatives on $\operatorname{Sym}(U)$.
Definition 3.1 (Hierarchical zonotopal power ideals and $\mathcal{P}$-spaces). Let $\mathbb{K}$ be a field of characteristic zero, $V$ be a finite-dimensional $\mathbb{K}$-vector space of dimension $r \geq 1$ and $U=V^{*}$. Let $X=\left(x_{1}, \ldots, x_{N}\right) \subseteq U$ be a finite sequence whose elements span $U$. Let $k \geq-1$ be an integer and let $J \subseteq \mathcal{L}(X)$ be a non-empty upper set, where $\mathcal{L}(X)$ denotes the lattice of flats of the matroid defined by $X$.

Let $\chi: \mathcal{L}(X) \rightarrow\{0,1\}$ denote the indicator function of $J$. Let $E: \mathcal{L}(X) \rightarrow V$ be a function that assigns a defining normal to every flat. Now define

$$
\begin{align*}
\mathcal{I}^{\prime}(X, k, J, E) & :=\operatorname{ideal}\left\{D_{E(C)}^{m(C)+k+\chi(C)}: C \text { hyperplane or maximal missing flat }\right\}  \tag{3.1}\\
\mathcal{I}(X, k, J) & :=\operatorname{ideal}\left\{D_{\eta}^{m(\eta)+k+\chi(\eta)}: \eta \in V \backslash\{0\}\right\} \subseteq \operatorname{Sym}(V)  \tag{3.2}\\
\mathcal{P}(X, k, J) & :=\operatorname{span} S(X, k, J) \subseteq \operatorname{Sym}(U) \tag{3.3}
\end{align*}
$$

where

$$
S(X, k, J):= \begin{cases}\left\{f p_{Y}: Y \subseteq X, 0 \leq \operatorname{deg} f \leq \chi(X \backslash Y)+k-1\right\} & \text { for } k \geq 1 \\ \left\{p_{Y}: Y \subseteq X, \operatorname{cl}(X \backslash Y) \in J\right\} & \text { for } k=0 \\ \left\{p_{Y}:|Y \backslash C|<m(C)-1+\chi(C) \text { for all } C \in \mathcal{L}(X) \backslash\{X\}\right\} & \text { for } k=-1\end{cases}
$$

Note that the definition of $S(X, 0, J)$ can be seen as a special case of the definition of $S(X, k, J)$ for $k \geq 1$. For examples, see Section 6, Remark 3.7 and Proposition 3.8
Theorem 3.2 (Main Theorem). We use the same terminology as in Definition 3.1. For $k=-1$, we assume in addition that $J \supseteq \mathcal{H}$, i.e. $J$ contains all hyperplanes in $X$. Then,

$$
\begin{equation*}
\mathcal{P}(X, k, J)=\operatorname{ker} \mathcal{I}(X, k, J) \subseteq \operatorname{ker} \mathcal{I}^{\prime}(X, k, J, E) \tag{3.4}
\end{equation*}
$$

Furthermore, for $k \in\{-1,0\}, \mathcal{I}^{\prime}(X, k, J, E)$ is independent of the choice of $E$ and $\mathcal{P}(X, k, J)=$ $\operatorname{ker} \mathcal{I}(X, k, J)=\operatorname{ker} \mathcal{I}^{\prime}(X, k, J, E)$.

Corollary 3.3. In the setting of the Main Theorem, $\mathcal{P}(X, k, \mathcal{L}(X))=\mathcal{P}(X, k+1,\{X\})$.
Corollary 3.4. The Hilbert series of $\mathcal{P}(X, k, J)$ depends only on the matroid $\mathfrak{M}(X)$, but not on the representation $X$.
Remark 3.5. One might wonder if similar theorems can be proved for $k \leq-2$. One would of course need to impose extra conditions on $X$ to ensure that the exponents appearing in the definition of the ideals are non-negative. It is easy to prove that $\mathcal{I}$ and $\mathcal{I}^{\prime}$ are equal in this case. However, we do not know how to construct a generating set for the kernel. A different approach would be required: in general, it is not spanned by a set of polynomials of type $p_{Y}$ for some $Y \subseteq X$ [1].

Basic results: In this paragraph, we state an important lemma and we give an explicit formula for $\mathcal{P}(X, k, J)$ in two particularly simple cases.
Lemma 3.6. $\mathcal{P}(X, k, J) \subseteq \operatorname{ker} \mathcal{I}(X, k, J) \subseteq \operatorname{ker} \mathcal{I}^{\prime}(X, k, J)$ holds for all $k \geq-1$ and all $J \subseteq \mathcal{L}(X)$.
Remark 3.7. Suppose that $\operatorname{dim} U=1$ and that $X$ contains $N^{\prime}$ non-zero entries. Let $x \in U$ and $y \in V$ be non-zero vectors. Note that $\emptyset$ is the only hyperplane in $X$. Hence, $\mathcal{I}^{\prime}(X, k, J)=\mathcal{I}(X, k, J)=$ ideal $\left\{D_{y}^{N^{\prime}+k+\chi(\emptyset)}\right\}$ and $\mathcal{P}(X, k, J)=\operatorname{span}\left\{p_{x}^{i}: i \in\left\{0,1, \ldots, N^{\prime}-1+k+\chi(\emptyset)\right\}\right\}$.
Proposition 3.8. We use the same terminology as in Definition 3.1. Let $X=\left(x_{1}, \ldots, x_{r}\right)$ be a basis for $U$. Then $\mathcal{P}(X, k, J)=\operatorname{ker} \mathcal{I}(X, k, J) \subseteq \operatorname{ker} \mathcal{I}^{\prime}(X, k, J, E)$. Furthermore, for $k \in\{-1,0\}$, $\operatorname{ker} \mathcal{I}(X, k, J)=\operatorname{ker} \mathcal{I}^{\prime}(X, k, J, E)$ for arbitrary $E$.

More precisely, writing $p_{i}:=p_{x_{i}}$ as shorthand notation, we get

$$
\begin{equation*}
\mathcal{P}(X, k, J)=\operatorname{span}\left\{\prod_{i \in I} p_{i}^{a_{i}+1}: I \subseteq[r], a_{i} \in \mathbb{Z}_{\geq 0}, \sum_{i \in I} a_{i} \leq k+\chi\left(X \backslash\left\{x_{i}: i \in I\right\}\right)-1\right\} \tag{3.5}
\end{equation*}
$$

For $k=0$, this specializes to $\mathcal{P}(X, 0, J)=\operatorname{span}\left\{p_{Y}: X \backslash Y \in J\right\}$. For $k=-1, \mathcal{P}(X,-1, J)=$ $\operatorname{span}\{1\}$ if $J \supseteq \mathcal{H}$ and $\mathcal{P}(X,-1, J)=\{0\}$ otherwise.
For a two-dimensional example, see Example 6.1 and Figure 1.
Deletion and Contraction: In this paragraph, we define deletion and contraction for matroids $X$ and upper sets $J$.

Fix an element $x \in X$. The deletion of $x$ is the matroid defined by the sequence $X \backslash x$. Let $\pi_{x}$ : $U \rightarrow U / x$ denote the projection to the quotient space. The contraction of $x$ is the matroid defined by the sequence $X / x$ which contains the images of the elements of $X \backslash x$ under $\pi_{x}$.

Let $Y \subseteq X \backslash x$. We write $\bar{Y}$ to denote the subsequence of $X / x$ with the same index set as $Y$ and vice versa.

Let $J \subseteq \mathcal{L}(X)$ be an upper set. Then define

$$
\begin{align*}
J \backslash x & :=\{C \backslash x: C \in J \text { and } C=\operatorname{cl}(C \backslash x)\} \subseteq \mathcal{L}(X \backslash x)  \tag{3.6}\\
J / x & :=\{(\overline{C \backslash x}): x \in C \in J\} \subseteq \mathcal{L}(X / x) \tag{3.7}
\end{align*}
$$

On the proof of the Main Theorem: The Main Theorem can be proven by induction. Proposition 3.8 is used as the base case. Deletion-contraction gives rises to a short exact sequence from which the result follows. This short exact sequence is recorded in the following proposition:

Proposition 3.9. We use the same terminology as in Definition 3.1. Suppose that $x \in X$ is neither a loop nor a coloop. For $k=-1$, we assume in addition that $J \supseteq \mathcal{H}$ or $J=\{X\}$. Then, the following sequence is exact:

$$
\begin{equation*}
0 \rightarrow \operatorname{ker} \mathcal{I}(X \backslash x, k, J \backslash x) \xrightarrow{\cdot p_{x}} \operatorname{ker} \mathcal{I}(X, k, J) \xrightarrow{\operatorname{Sym}\left(\pi_{x}\right)} \operatorname{ker} \mathcal{I}(X / x, k, J / x) \rightarrow 0 \tag{3.8}
\end{equation*}
$$

Remark 3.10. We do not know if the Main Theorem holds for $k=-1$ and $J \nsupseteq \mathcal{H}$. In general, our proof does not work in this case and Proposition 3.9 is false. The difficulty of the case $k=-1$ was already observed by Holtz and Ron. They conjectured that the Main Theorem holds in the internal case i.e. for $k=-1$ and $J=\{X\}$, but they were unable to prove it [11, Conjecture 6.1]. An incorrect prove of this special case has appeared in the literature [1, Part 3 of Proposition 4.5].

## 4 Bases and Hilbert series

In this section, we show how to select a basis for $\mathcal{P}(X, k, J)$ from $S(X, k, J)$ for $k \geq 0$ and we give several formulas for the Hilbert series of $\mathcal{P}(X, k, J)$.
Bases: Our construction of a basis depends on the order on $X$. This order is used to define internal and external activity with respect to a given basis (see [4] Section 6.6.] for a reference). Recall that $\mathbb{B}(X)$ denotes the set of all bases $B \subseteq X$. Fix a basis $B \in \mathbb{B}(X) . b \in B$ is called internally active if $b=\max (X \backslash \operatorname{cl}(B \backslash b))$, i.e. $b$ is the maximal element of the unique cocircuit contained in $(X \backslash B) \cup b$. The set of internally active elements in $B$ is denoted $I(B) . x \in X \backslash B$ is called externally active if $x \in \operatorname{cl}\{b \in B: b \leq x\}$, i.e. $x$ is the maximal element of the unique circuit contained in $B \cup x$. The set of externally active elements with respect to $B$ is denoted $E(B)$.

We generalize [1, Proposition 4.21] to hierarchical spaces:
Definition 4.1. We use the same terminology as in Definition 3.1. In addition, let $k \geq 0$. Then define

$$
\begin{align*}
\Gamma(X, k, J) & :=\left\{\left(B, I, \boldsymbol{a}_{I}\right): B \in \mathbb{B}(X), I \subseteq I(B), \boldsymbol{a}_{I} \in \mathbb{Z}_{\geq 0}^{I}, \sum_{x \in I} a_{x} \leq k+\chi((B \cup E(B)) \backslash I)-1\right\} \\
\mathcal{B}(X, k, J) & :=\left\{p_{X \backslash(B \cup E(B))} \prod_{x \in I} p_{x}^{a_{x}+1}:\left(B, I, \boldsymbol{a}_{I}\right) \in \Gamma(X, k, J)\right\} \subseteq \operatorname{Sym}(U) \tag{4.1}
\end{align*}
$$

Theorem 4.2 (Basis Theorem). We use the same terminology as in Definition 3.1. Let $k \geq 0$. Then $\mathcal{B}(X, k, J)$ is a basis for $\mathcal{P}(X, k, J)$.
Remark 4.3. We do not know if there is a simple method to construct bases for $\mathcal{P}(X,-1, J)$. This difficulty was already observed in the internal case by Holtz and Ron [11].
Recursive formulas for the Hilbert series: The following statement is a direct consequence of Proposition 3.9 and of the Main Theorem:
Corollary 4.4. We use the same terminology as in Definition 3.1. Let $x \in X$ be an element that is not a coloop. For $k=-1$, we assume in addition that $J \supseteq \mathcal{H}$ or $J=\{X\}$, i.e. $J$ contains either all or no hyperplanes. Then,

$$
\operatorname{Hilb}(\mathcal{P}(X, k, J)), t)= \begin{cases}\operatorname{Hilb}(\mathcal{P}(X \backslash x, k, J \backslash x), t) & \text { if } x \text { is a loop } \\ t \operatorname{Hilb}(\mathcal{P}(X \backslash x, k, J \backslash x), t)+\operatorname{Hilb}(\mathcal{P}(X / x, k, J / x), t) & \text { otherwise }\end{cases}
$$

For coloops, the situation is more complicated and requires an additional definition. Fix a coloop $x \in X$. Then, $X \backslash x$ is a hyperplane and the following is an upper set:

$$
\begin{equation*}
\widehat{J / x}:=\{\bar{C}: x \notin C \in J\} \cup\{\overline{X \backslash x}\} \subseteq \mathcal{L}(X / x) \tag{4.2}
\end{equation*}
$$

$\widehat{J / x}$ forgets about the flats containing $x$, whereas $J / x$ forgets about the flats not containing $x$. While the latter is always an upper set in $\mathcal{L}(X / x)$, some elements of $\widehat{J / x}$ are not closed unless $X \backslash x$ is a hyperplane.
Theorem 4.5. We use the same terminology as in Definition 3.1. Let $x \in X$ be a coloop and $k \geq 0$. Then,

$$
\operatorname{Hilb}(\mathcal{P}(X, k, J)), t)= \begin{cases}\operatorname{Hilb}(\mathcal{P}(X / x, k, J / x)), t) &  \tag{4.3}\\ +\sum_{j=0}^{k} t^{j+1} \operatorname{Hilb}(\mathcal{P}(X / x, k-j, \widehat{J / x}), t) & \text { if } X \backslash x \in J \\ \operatorname{Hilb}(\mathcal{P}(X / x, k, J / x)), t) \\ +\sum_{j=0}^{k-1} t^{j+1} \operatorname{Hilb}(\mathcal{P}(X / x, k-j, \widehat{J / x}), t) & \text { if } X \backslash x \notin J\end{cases}
$$

For $k=-1, \operatorname{Hilb}(\operatorname{ker} \mathcal{I}(X,-1, J)), t)=\operatorname{Hilb}(\operatorname{ker} \mathcal{I}(X / x, k, J / x)), t)$ if $X \backslash x \in J$ and otherwise $\operatorname{Hilb}(\operatorname{ker} \mathcal{I}(X,-1, J)), t)=0$. This holds for arbitrary non-empty upper sets $J \subseteq \mathcal{L}(X)$.

For an example, see Example 6.1. We actually prove a more general statement, namely decomposition formulas for the $\mathcal{P}$-spaces of type $\mathcal{P}(X, k, J) \cong \mathcal{P}(X / x, k, J / x) \oplus \bigoplus_{j} p_{x}^{j+1} \mathcal{P}(X / x, k-j, \widehat{J / x})$.

Combinatorial formulas for $k \geq 0$ : Theorem 4.2 provides a method to compute the Hilbert series of a $\mathcal{P}$-space combinatorially:
Corollary 4.6. We use the same terminology as in Definition 3.1 Let $k \geq 0$. Then,

$$
\begin{equation*}
\operatorname{Hilb}(\mathcal{P}(X, k, J), t)=\sum_{B \in \mathbb{B}(X)} t^{N-r-|E(B)|}\left(1+\sum_{\emptyset \neq I \subseteq I(B)} \sum_{j=0}^{\substack{\chi((B \cup E(B)) \backslash I) \\+k-1}} t^{|I|+j}\binom{j+|I|-1}{|I|-1}\right) \tag{4.4}
\end{equation*}
$$

where $E(B)$ and $I(B)$ denote the sets of externally resp. internally active elements.
From this, we can deduce a result, which relates the dimension of $\mathcal{P}(X, 0, J)$ and the number of independent sets satisfying a certain property. This was already proven with a different method by Holtz, Ron, and Xu [12].

Corollary 4.7. $\operatorname{dim} \mathcal{P}(X, 0, J)=\mid\{Y \subseteq X: Y$ independent, $\operatorname{cl}(Y) \in J\} \mid$
Corollary 4.6 gives a formula in terms of the internal and external activity of the bases of $X$. For $k=0$, there is also a subset expansion formula similar to the one for the Tutte polynomial. In the internal, central and external case, the Hilbert series of the $\mathcal{P}$-spaces are evaluations of the Tutte polynomial [1]. In particular, $\operatorname{Hilb}(\mathcal{P}(X, 0,\{X\}), t)=t^{N-r} T_{X}\left(1, \frac{1}{t}\right)$ and $\operatorname{Hilb}(\mathcal{P}(X, 1,\{X\}), t)=t^{N-r} T_{X}\left(1+t, \frac{1}{t}\right)$. The following theorem provides a formula for the semi-external case which "interpolates" between those two formulas:

Theorem 4.8. We use the same terminology as in Definition 3.1 .

$$
\begin{equation*}
\operatorname{Hilb}(\mathcal{P}(X, 0, J), t)=t^{N-r} \sum_{\substack{A \subset X \\ \chi(A)=1}} t^{r-\operatorname{rk}(A)}\left(t^{-1}-1\right)^{|A|-\mathrm{rk}(A)} \tag{4.5}
\end{equation*}
$$

The case $k=-1$ : For $k=-1$, we do not know if there is such a nice formula as in Corollary 4.6 or Theorem 4.8 However, in a special case, a formula is known.

Fix $C_{0} \in \mathcal{L}(X)$ and set $J_{C_{0}}:=\left\{C \in \mathcal{L}(X): C \supseteq C_{0}\right\}$. All maximal missing flats in $J_{C_{0}}$ are hyperplanes. They have unique defining normals (up to scaling). Holtz, Ron, and Xu [12] showed that $\operatorname{ker} \mathcal{I}\left(X,-1, J_{C_{0}}\right)=\operatorname{ker} \mathcal{I}^{\prime}\left(X,-1, J_{C_{0}}\right)=\bigcap_{x \in C_{0}} \mathcal{P}(X \backslash x, 0,\{X \backslash x\})$.

Fix an independent set $K \subseteq X$ that spans $C_{0}$. Choose an order on $X$ s.t. $K$ is maximal and define $\mathbb{B}_{-}\left(X, J_{C_{0}}\right)=\{B \in \mathbb{B}(X): I(B) \cap K=\emptyset\}$. Then, the following theorem holds:
Theorem 4.9 ([12, p. 20]). We use the same terminology as in Definition 3.1. In addition, let $C_{0} \in \mathcal{L}(X)$. Then,

$$
\begin{equation*}
\operatorname{Hilb}\left(\operatorname{ker} \mathcal{I}\left(X,-1, J_{C_{0}}\right), t\right)=\sum_{B \in \mathbb{B}_{-}\left(X, J_{C_{0}}\right)} t^{N-r-|E(B)|} \tag{4.6}
\end{equation*}
$$

## 5 Zonotopal Cox Rings

In this section, we briefly describe the zonotopal Cox rings defined by Sturmfels and Xu [19] and we show that our Main Theorem can be used to generalize a result on zonotopal Cox modules due to Ardila and Postnikov [1].

Fix $m$ vectors $D_{1}, \ldots, D_{m} \in V$ and $\boldsymbol{u}=\left(u_{1}, \ldots, u_{m}\right) \in \mathbb{Z}_{\geq 0}^{m}$. Sturmfels and Xu [19] introduced the Cox-Nagata ring $R^{G} \subseteq \mathbb{K}\left[s_{1}, \ldots, s_{m}, t_{1}, \ldots, t_{m}\right]$. This is the ring of polynomials that are invariant under the action of a certain group $G$ which depends on the vectors $D_{1}, \ldots, D_{m}$. It is multigraded with a $\mathbb{Z}^{m+1}$-grading. For $r \geq 3, R^{G}$ is equal to the Cox ring of the variety $X_{G}$ which is gotten from $\mathbb{P}^{r-1}$ by blowing up the points $D_{1}, \ldots, D_{m}$. Cox rings have received a considerable amount of attention in the recent literature in algebraic geometry. See [13] for a survey.

Cox-Nagata rings are closely related to power ideals: let $\mathcal{I}_{\boldsymbol{u}}:=\operatorname{ideal}\left\{D_{1}^{u_{1}+1}, \ldots, D_{m}^{u_{m}+1}\right\}$ and let $\mathcal{I}_{d, \boldsymbol{u}}^{-1}$ denote the homogeneous component of grade $d$ of $\operatorname{ker} \mathcal{I}_{\boldsymbol{u}}$. Then, $R_{(d, \boldsymbol{u})}^{G}$, the homogeneous component of $R^{G}$ of grade $(d, \boldsymbol{u})$, is naturally isomorphic to $\mathcal{I}_{d, \boldsymbol{u}}$ ([19, Proposition 2.1]).

Cox-Nagata rings are an object of great interest but in general, it is quite difficult to understand their structure. However, for some choices of the vectors $D_{1}, \ldots, D_{m}$, we understand a natural subring of the Cox-Nagata ring very well.

Let $\mathcal{H}=\left\{H_{1}, \ldots, H_{m}\right\}$ denote the set of hyperplanes in $\mathcal{L}(X)$. Let $\mathfrak{H} \in\{0,1\}^{m \times N}$ denote the noncontainment vector-hyperplane matrix, i.e. the $0-1$ matrix whose $(i, j)$ entry is 1 if and only if $x_{j}$ is not contained in $H_{i}$.

Sturmfels and Xu defined the following structures: the zonotopal Cox ring

$$
\begin{equation*}
\mathcal{Z}(X):=\bigoplus_{(d, \boldsymbol{a}) \in \mathbb{Z} \geq 0} R_{(d, \mathfrak{H} \boldsymbol{a})}^{G} \tag{5.1}
\end{equation*}
$$

and $\mathcal{Z}(X, \boldsymbol{w}):=\bigoplus_{(d, \boldsymbol{a}) \in \mathbb{Z}_{\geq 0}^{N+1}} R_{(d, \mathfrak{H} \boldsymbol{a}+\boldsymbol{w})}^{G}$, the zonotopal Cox module of shift $\boldsymbol{w}$ for $\boldsymbol{w} \in \mathbb{Z}^{n}$.
Let $X(\boldsymbol{a})$ denote the sequence of $\sum_{i} a_{i}$ vectors in $U$ that is obtained from $X$ by replacing each $x_{i}$ by $a_{i}$ copies of itself and let $e:=(1, \ldots, 1) \in \mathbb{Z}_{\geq 0}^{m}$. Ardila and Postnikov prove the following isomorphisms [1, Proposition 6.3]: $R_{(d, \mathfrak{H} \boldsymbol{a})}^{G} \cong \mathcal{P}(X(\boldsymbol{a}), 1,\{X\})_{d}, R_{(d, \mathfrak{H} \boldsymbol{a}-\boldsymbol{e})}^{G} \cong \mathcal{P}(X(\boldsymbol{a}), 0,\{X\})_{d}$, and $R_{(d, \mathfrak{H} \boldsymbol{a}-2 \boldsymbol{e})}^{G} \cong$ $\mathcal{P}(X(\boldsymbol{a}),-1,\{X\})_{d}$

Using the Main Theorem, we can generalize those results. Let $J_{b}:=\left\{C \in \mathcal{L}(X): b_{H}=1\right.$ for all $H \subseteq$ $C\}$. We have the following results on hierarchical zonotopal Cox modules and their Hilbert series:
Proposition 5.1. We use the same terminology as in Definition 3.1. For the graded components of the semi-external zonotopal Cox module $\mathcal{Z}(X, \mathfrak{H} \boldsymbol{a}-\boldsymbol{e}+\boldsymbol{b})$, the following holds:

$$
\begin{equation*}
R_{(d, \mathfrak{H} \boldsymbol{a}-\boldsymbol{e}+\boldsymbol{b})}^{G} \cong \mathcal{P}\left(X(\boldsymbol{a}), 0, J_{\boldsymbol{b}}\right)_{d} \quad \text { for all } d \tag{5.2}
\end{equation*}
$$

Proposition 5.2. We use the same terminology as in Definition 3.1 Let $C_{0} \in \mathcal{L}(X)$ be a fixed flat and $J_{C_{0}}:=\left\{C \in \mathcal{L}(X): C \supseteq C_{0}\right\}$ (cf. Subsection 4). If $\boldsymbol{b} \in\{0,1\}^{\mathcal{A}}$ satisfies $b_{H}=1$ if and only if $H \supseteq C_{0}$, then for the graded components of the semi-internal zonotopal Cox module $\mathcal{Z}(X, \mathfrak{H} \boldsymbol{a}-2 \boldsymbol{e}+\boldsymbol{b})$ ), the following holds:

$$
\begin{equation*}
R_{(d, \mathfrak{H} \boldsymbol{a}-2 \boldsymbol{e}+\boldsymbol{b})}^{G} \cong \operatorname{ker} \mathcal{I}\left(X(\boldsymbol{a}),-1, J_{C_{0}}\right)_{d} \quad \text { for all } d \tag{5.3}
\end{equation*}
$$

Corollary 5.3. In the setting of Proposition 5.1. the dimension of $R_{(d, \mathfrak{H} \boldsymbol{a}-\boldsymbol{e}+\boldsymbol{b})}^{G}$ equals the coefficient of $t^{d}$ in

$$
\operatorname{Hilb}\left(\mathcal{P}\left(X(\boldsymbol{a}), 0, J_{\boldsymbol{b}}\right), t\right)=t^{\sum_{i} a_{i}-r} \sum_{\substack{A \subseteq X \\ \chi(\bar{A})=1}} t^{r-\operatorname{rk}(A)} \sum_{\substack{1 \leq s_{i} \leq a_{i} \\ \boldsymbol{s} \in \mathbb{Z} \geq 0 \\ \geq \\ A_{i}, x_{i} \in A}}\left(\prod_{i}\binom{a_{i}}{s_{i}}\right)\left(\frac{1}{t}-1\right)^{\sum_{i} s_{i}-\operatorname{rk}(A)}
$$

Corollary 5.4. In the setting of Proposition 5.2 the dimension of $R_{(d, \mathfrak{5} \boldsymbol{a}-2 \boldsymbol{e}+\boldsymbol{b})}^{G}$ equals the coefficient of $t^{d}$ in

$$
\begin{equation*}
\operatorname{Hilb}\left(\operatorname{ker} \mathcal{I}\left(X(\boldsymbol{a}),-1, J_{C_{0}}\right), t\right)=\sum_{B \in \mathbb{B}_{-}\left(X, J_{C_{0}}\right)} \sum_{\substack{0 \leq s_{i} \leq a_{i}-1 \\ s \in \mathbb{Z}_{\geq 0}^{B}}} t^{\sum_{i: x_{i} \notin E(B)} a_{i}-r-\sum_{x_{i} \in B} s_{i}} \tag{5.4}
\end{equation*}
$$

## 6 Examples

In this section, we give examples for the structures and constructions appearing in this extended abstract. Here, we do the following identifications: $\operatorname{Sym}(V)=\operatorname{Sym}(U)=\mathbb{K}[x, y]$ and $\mathbb{K}[x, y] / x=\mathbb{K}[y]$.

$$
X_{1}:=\left[\begin{array}{lll}
1 & 0 & 1  \tag{6.1}\\
0 & 1 & 1
\end{array}\right]=\left(x_{1}, x_{2}, x_{3}\right)
$$

Let $J_{1}:=\left\{X,\left(x_{1}\right),\left(x_{3}\right)\right\}$. The set of bases is $\mathbb{B}(X)=\left\{\left(x_{1} x_{2}\right),\left(x_{1} x_{3}\right),\left(x_{2} x_{3}\right)\right\}$ and the ideal is $\mathcal{I}\left(X_{1}, 0, J_{1}\right)=\operatorname{ideal}\left\{x^{2}, x y^{2}, y^{3}\right\}$.

$$
\begin{aligned}
& S\left(X_{1}, 0, J_{1}\right)=\left\{1, p_{x_{1}}, p_{x_{2}}, p_{x_{3}}, p_{x_{1} x_{2}}, p_{x_{2} x_{3}}\right\} \quad \sim \mathcal{P}\left(X, 0, J_{1}\right)=\operatorname{span}\left\{1, x, y, x y, y^{2}\right\} \\
& \Gamma\left(X_{1}, 0, J_{1}\right)=\left\{\left(\left(x_{1} x_{2}\right), \emptyset, 0\right),\left(\left(x_{1} x_{3}\right), \emptyset, 0\right),\left(\left(x_{1} x_{3}\right),\left(x_{3}\right), 0\right),\left(\left(x_{2} x_{3}\right), \emptyset, 0\right),\left(\left(x_{2} x_{3}\right),\left(x_{2}\right), \emptyset, 0\right)\right\} \\
& \mathcal{B}\left(X_{1}, 0, J_{1}\right)=\left\{p_{\emptyset}, p_{x_{2}}, p_{x_{2} x_{3}}, p_{x_{1}}, p_{x_{1} x_{2}}\right\}
\end{aligned}
$$

Now we consider the deletion and contraction of $x_{1}$. For the upper set $J_{1}$, we obtain $J_{1} \backslash x_{1}=$ $\left\{\left(x_{2}, x_{3}\right),\left(x_{3}\right)\right\}$ and $J_{1} / x_{1}=\left\{\left(\bar{x}_{2}, \bar{x}_{3}\right), \bar{\emptyset}\right\}$.

$$
\begin{array}{rlrl}
X_{1} \backslash x_{1} & =\left[\begin{array}{ll}
0 & 1 \\
1 & 1
\end{array}\right]=\left(x_{2}, x_{3}\right) & X_{1} / x_{1}=\left[\begin{array}{ll}
1 & 1
\end{array}\right]=\left(\bar{x}_{2}, \bar{x}_{3}\right) \\
\mathcal{I}\left(X_{1} \backslash x_{1}, 0, J_{1} \backslash x_{1}\right) & =\operatorname{ideal}\left\{x, y^{2}\right\} & \mathcal{I}\left(X_{1} / x_{1}, 0, J_{1} / x_{1}\right) & =\operatorname{ideal}\left\{y^{3}\right\} \\
\mathcal{P}\left(X_{1} \backslash x_{1}, 0, J_{1} \backslash x_{1}\right) & =\operatorname{span}\{1, y\} & \mathcal{P}\left(X_{1} / x_{1}, 0, J_{1} / x_{1}\right)=\operatorname{span}\left\{1, y, y^{2}\right\}
\end{array}
$$

Example 6.1. This is an example for the recursion in Theorem 4.5 and for Proposition 3.8. Let $X_{2}:=$


Fig. 1: On the left, we see $\mathcal{P}\left(X_{2}, 2, J_{3}\right)$ and on the right we see $\mathcal{P}\left(X_{2}, 2, J_{2}\right)$. For both spaces, the decompositions corresponding to Theorem 4.5 are shown.
$\left[\begin{array}{ll}1 & 0 \\ 0 & 1\end{array}\right]=\left(x_{1}, x_{2}\right), J_{2}:=\left\{X_{2}\right\}$, and $J_{3}:=\left\{X_{2},\left(x_{1}\right)\right\}$. This implies $\widehat{J_{2} / x_{2}}=\widehat{J_{3} / x_{2}}=\left\{\left(x_{1}\right)\right\}$. For a graphic description of the $\mathcal{P}$-spaces involved in the decomposition, see Figure 1 .

$$
\begin{array}{ll}
\mathcal{I}\left(X_{2}, 2, J_{2}\right)=\operatorname{ideal}\left\{x^{3}, y^{3}, x^{2} y^{2}\right\} & \mathcal{P}\left(X_{2}, 2, J_{2}\right)=\operatorname{span}\left\{1, x, y, x^{2}, x y, y^{2}, x^{2} y, x y^{2}\right\} \\
\mathcal{I}\left(X_{2}, 2, J_{3}\right)=\operatorname{ideal}\left\{x^{3}, y^{4}, x^{2} y^{2}, x y^{3}\right\} & \mathcal{P}\left(X_{2}, 2, J_{3}\right)=\operatorname{span}\left\{1, x, y, x^{2}, x y, y^{2}, x^{2} y, x y^{2}, y^{3}\right\}
\end{array}
$$

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[^1]:    ${ }^{(i)}$ In the original definition in [1], 1 is added to every exponent.
    ${ }^{(i i)} \operatorname{ker} \mathcal{I}$ is sometimes defined slightly differently in the literature: The pairing $\langle\bullet, \bullet\rangle$ is defined on $\operatorname{Sym}(V)^{*} \times \operatorname{Sym}(V)$ and ker $\mathcal{I}$ is the subset of $\operatorname{Sym}(V)^{*}$ that is annihilated by $\mathcal{I}$. In our setting, both definitions agree.

