

Exponential Stability of the System of Transmission of the Wave Equation with a Delay Term in the Boundary Feedback

Salah-Eddine Rebiai

► **To cite this version:**

Salah-Eddine Rebiai. Exponential Stability of the System of Transmission of the Wave Equation with a Delay Term in the Boundary Feedback. Dietmar Hömberg; Fredi Tröltzsch. 25th System Modeling and Optimization (CSMO), Sep 2011, Berlin, Germany. Springer, IFIP Advances in Information and Communication Technology, AICT-391, pp.276-285, 2013, System Modeling and Optimization. <10.1007/978-3-642-36062-6_28>. <hal-01347547>

HAL Id: hal-01347547

<https://hal.inria.fr/hal-01347547>

Submitted on 21 Jul 2016

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.



Exponential stability of the system of transmission of the wave equation with a delay term in the boundary feedback

Salah-Eddine Rebiai

Laboratoire des Techniques Mathématiques, Faculté des Sciences,
Université de Batna, 05000 Batna, Algeria
rebiai@hotmail.com

Abstract. We consider a system of transmission of the wave equation with Neumann feedback control that contains a delay term and that acts on the exterior boundary. First, we prove under some assumptions that the closed-loop system generates a C_0 -semigroup of contractions on an appropriate Hilbert space. Then, under further assumptions, we show that the closed-loop system is exponentially stable. To establish this result, we introduce a suitable energy function and use multiplier method together with an estimate taken from [3] (Lemma 7.2) and compactness-uniqueness arguments.

Keywords: Wave equation, transmission problem, time delays, boundary stabilization, exponential stability.

1 Introduction

It is by now well-known that certain infinite-dimensional second-order systems are not robust with respect to arbitrarily small delays in the damping. This lack of stability robustness was first shown to hold for the one-dimensional wave equation ([2]). Later, further examples illustrating this phenomenon were considered in [1]: the two-dimensional wave equation with damping introduced through Neumann-type boundary conditions on one edge of a square boundary and the Euler-Bernoulli beam equation in one dimension with damping introduced through a specific set of boundary conditions on the right end point.

Recently, Xu et al [9] established sufficient conditions that guarantee the exponential stability of the one-dimensional wave equation with a delay term in the boundary feedback. Nicaise and Pignotti [5] extended this result to the multi-dimensional wave equation with a delay term in the boundary or internal feedbacks. The same type of result was obtained by Nicaise and Rebiai [6] for the Schrödinger equation.

Motivated by the references [9], [5] and [6]; we investigate in this paper the problem of exponential stability for the system of transmission of the wave equation with a delay term in the boundary feedback.

Let Ω be an open bounded domain of \mathbb{R}^n with a boundary Γ of class C^2 which consists of two non-empty parts Γ_1 and Γ_2 such that $\overline{\Gamma_1} \cap \overline{\Gamma_2} = \emptyset$. Let Γ_0

with $\overline{\Gamma_0} \cap \overline{\Gamma_1} = \overline{\Gamma_0} \cap \overline{\Gamma_2} = \emptyset$ be a regular hypersurface of class C^2 which separates Ω into two domains Ω_1 and Ω_2 such that $\Gamma_1 \subset \partial\Omega_1$ and $\Gamma_2 \subset \partial\Omega_2$. Furthermore, we assume that there exists a real vector field $h \in (C^2(\overline{\Omega}))^n$ such that:

(H.1) The Jacobian matrix J of h satisfies

$$\int_{\Omega} J(x)\zeta(x) \cdot \zeta(x) d\Omega \geq \alpha \int_{\Omega} |\zeta(x)|^2 d\Omega,$$

for some constant $\alpha > 0$ and for all $\zeta \in L^2(\Omega; \mathbb{R}^n)$;

(H.2) $h(x) \cdot \nu(x) \leq 0$ on Γ_1 ;

(H.3) $h(x) \cdot \nu(x) \geq 0$ on Γ_0 .

where ν is the unit normal on Γ or Γ_0 pointing towards the exterior of Ω or Ω_1 .

Let $a_1, a_2 > 0$ be given. Consider the system of transmission of the wave equation with a delay term in the boundary conditions:

$$y''(x, t) - a(x)\Delta y(x, t) = 0 \quad \text{in } \Omega \times (0, +\infty), \quad (1)$$

$$y(x, 0) = y^0(x), y'(x, 0) = y^1(x, 0) \quad \text{in } \Omega, \quad (2)$$

$$y_1(x, t) = 0 \quad \text{on } \Gamma_1 \times (0, +\infty), \quad (3)$$

$$\frac{\partial y_2(x, t)}{\partial \nu} = -\mu_1 y_2'(x, t) - \mu_2 y_2'(x, t - \tau) \quad \text{on } \Gamma_2 \times (0, +\infty), \quad (4)$$

$$y_1(x, t) = y_2(x, t), \quad \text{on } \Gamma_0 \times (0, +\infty), \quad (5)$$

$$a_1 \frac{\partial y_1(x, t)}{\partial \nu} = a_2 \frac{\partial y_2(x, t)}{\partial \nu} \quad \text{on } \Gamma_0 \times (0, +\infty), \quad (6)$$

$$y_2'(x, t - \tau) = f_0(x, t - \tau) \quad \text{on } \Gamma_2 \times (0, \tau). \quad (7)$$

where:

- $a(x) = \begin{cases} a_1, & x \in \Omega_1 \\ a_2, & x \in \Omega_2 \end{cases}$
- $y(x, t) = \begin{cases} y_1(x, t), & (x, t) \in \Omega_1 \times (0, +\infty) \\ y_2(x, t), & (x, t) \in \Omega_2 \times (0, +\infty) \end{cases}$
- $\frac{\partial}{\partial \nu}$ is the normal derivative.
- μ_1 and μ_2 are positive real numbers.
- τ is the time delay

- y^0, y^1, f_0 are the initial data which belong to suitable spaces.

In the absence of delay, that is $\mu_2 = 0$, Liu and Williams [4] have shown that the solution of (1)-(6) decays exponentially to zero in the energy space $H_{\Gamma_1}^1(\Omega) \times L^2(\Omega)$ provided that

$$a_1 > a_2 \quad (8)$$

and $\{\Omega, \Gamma_0, \Gamma_1, \Gamma_2\}$ satisfies (H.1), (H.2), (H.3), and

(H.4) $h(x) \cdot \nu(x) \geq \gamma > 0$.

The purpose of this paper is to investigate the stability of problem (1) – (7) in the case where both μ_1 and μ_2 are different from zero. To this end, assume as in [5] that

$$\mu_1 > \mu_2. \quad (9)$$

and define the energy of a solution of (1) – (7) by

$$E(t) = \frac{1}{2} \int_{\Omega} \left[|y'(x, t)|^2 + a(x) |\nabla(y(x, t))|^2 \right] dx + \frac{\xi}{2} \int_{\Gamma_2} \int_0^1 |y(x, t - \tau\rho)|^2 d\rho d\sigma(x), \quad (10)$$

where

$$a_2\tau\mu_2 < \xi < a_2\tau(2\mu_1 - \mu_2), \quad (11)$$

We show that if $\{\Omega, \Gamma_0, \Gamma_1, \Gamma_2\}$ satisfies (H.1), (H.2) and (H.3), then there is an exponential decay rate for $E(t)$. The proof of this result combines multipliers technique and compactness-uniqueness arguments.

The main result of this paper can be stated as follows.

Theorem 1. *Assume (H1), (H.2), (H.3), (8) and (9). Then there exist constants $M \geq 1$ and $\omega > 0$ such that*

$$E(t) \leq Me^{-\omega t} E(0).$$

Theorem 1 is proved in Section 3. In Section 2, we investigate the well-posedness of system (1) – (7) using semigroup theory.

2 Well-posedness of problem (1) – (7)

Inspired from [5] and [6], we introduce the auxilliary variable $z(x, \rho, t) = y(x, t - \tau\rho)$. With this new unknown, problem (1) – (7) is equivalent to

$$y''(x, t) - a(x)\Delta y(x, t) = 0 \quad \text{in } \Omega \times (0, +\infty), \quad (12)$$

$$y(x, 0) = y^0(x), y'(x, 0) = y^1(x) \quad \text{in } \Omega, \quad (13)$$

$$y(x, t) = 0 \quad \text{on } \Gamma_1 \times (0, +\infty), \quad (14)$$

$$\frac{\partial z(x, \rho, t)}{\partial t} + \frac{1}{\tau} \frac{\partial z(x, \rho, t)}{\partial \rho} = 0 \quad \text{on } \Gamma_2 \times (0, +\infty) \quad (15)$$

$$\frac{\partial y_2(x, t)}{\partial \nu} = -\mu_1 y_2'(x, t) - \mu_2 z(x, 1, t) \quad \text{on } \Gamma_2 \times (0, +\infty), \quad (16)$$

$$y_1(x, t) = y_2(x, t) \quad \text{on } \Gamma_0 \times (0, +\infty), \quad (17)$$

$$a_1 \frac{\partial y_1(x, t)}{\partial \nu} = a_2 \frac{\partial y_2(x, t)}{\partial \nu} \quad \text{on } \Gamma_0 \times (0, +\infty), \quad (18)$$

$$z(x, 0, t) = y'(x, t) \quad \text{on } \Gamma_2 \times (0, +\infty) \quad (19)$$

$$z(x, \rho, 0) = f_0(x, -\tau\rho) \quad \text{on } \Gamma_2 \times (0, 1) \quad (20)$$

Now, we endow the Hilbert space

$$\mathcal{H} = H_{\Gamma_1}^1(\Omega) \times L^2(\Omega) \times L^2(\Gamma_2; L^2(0, 1))$$

with the inner product

$$\left\langle \begin{pmatrix} u \\ v \\ z \end{pmatrix}; \begin{pmatrix} \bar{u} \\ \bar{v} \\ \bar{z} \end{pmatrix} \right\rangle = \int_{\Omega} (a(x)\nabla u(x)\nabla \bar{u}(x) + v(x)\bar{v}(x)) dx + \xi \int_{\Gamma_2} \int_0^1 z(x, \rho)\bar{z}(x, \rho) d\rho d\sigma(x)$$

and define a linear operator in \mathcal{H} by

$$D(A) = \{(u, v, z)^T \in H^2(\Omega_1, \Omega_2, \Gamma_1) \times H_{\Gamma_1}^1(\Omega) \times L^2(\Gamma_2; H^1(0, 1)); \frac{\partial u}{\partial \nu} = -\mu_1 v - \mu_2 z(\cdot, 1), v = z(\cdot, 0) \text{ on } \Gamma_2\} \quad (21)$$

$$A \begin{pmatrix} u \\ v \\ z \end{pmatrix} = \begin{pmatrix} v \\ a(x)\Delta u \\ -\tau^{-1} \frac{\partial z}{\partial \rho} \end{pmatrix} \quad (22)$$

The spaces used for the definition of \mathcal{H} and $D(A)$ are

$$H_{\Gamma_1}^1(\Omega) = \{u \in H^1(\Omega) : u = 0 \text{ on } \Gamma_1\}$$

$$H^2(\Omega_1, \Omega_2, \Gamma_1) = \{u_i \in H^2(\Omega_i) : u = 0 \text{ on } \Gamma_1, u_1 = u_2 \text{ and } a_1 \frac{\partial u_1}{\partial \nu} = a_2 \frac{\partial u_2}{\partial \nu} \text{ on } \Gamma_0\}$$

Then we can rewrite (12) – (20) as an abstract Cauchy problem in \mathcal{H}

$$\begin{cases} \frac{d}{dt} Y(t) = AY(t) \\ Y(0) = Y_0 \end{cases} \quad (23)$$

where

$$Y(t) = (y, y', z)^T \text{ and } Y_0 = (y_0, y_1, f_0(\cdot, -\cdot, \tau))^T$$

Proposition 1. *The operator A defined by (21) and (22) generates a strongly continuous semigroup on \mathcal{H} . Thus, for every $Y_0 \in \mathcal{H}$, problem (23) has a unique solution Y whose regularity depends on the the initial datum Y_0 as follows:*

$$Y(\cdot) \in C([0, +\infty); \mathcal{H}) \text{ if } Y_0 \in \mathcal{H},$$

$$Y(\cdot) \in C([0, +\infty); D(A)) \cap C^1([0, +\infty); \mathcal{H}) \text{ if } Y_0 \in D(A).$$

Proof. Let $Y = \begin{pmatrix} u \\ v \\ z \end{pmatrix} \in D(A)$. Then

$$\begin{aligned} \langle AY, Y \rangle &= \int_{\Omega} a(x)\nabla u(x)\nabla v(x) dx + \int_{\Omega} (a(x)\Delta u(x))v(x) dx - \\ &\quad \frac{\xi}{\tau} \int_{\Gamma_2} \int_0^1 z_{\rho}(x, \rho)z(x, \rho) d\rho d\Gamma \end{aligned} \quad (24)$$

Applying Green's first theorem, we obtain

$$\begin{aligned}
 \int_{\Omega} (a(x)\Delta u(x))v(x)dx &= a_1 \int_{\Gamma_1} v(x) \frac{\partial u(x)}{\partial \nu} d\Gamma - a_1 \int_{\Omega_1} \nabla u(x) \cdot \nabla v(x) dx + \\
 & a_2 \int_{\Gamma_2} v(x) \frac{\partial u(x)}{\partial \nu} d\Gamma - a_2 \int_{\Omega_2} \nabla u(x) \cdot \nabla v(x) dx \\
 &= a_2 \int_{\Gamma_2} v(x) \{-\mu_1 v(x) - \mu_2 z(x, 1)\} d\Gamma - \int_{\Omega} a(x) \nabla u(x) \cdot \nabla v(x) dx \quad (25)
 \end{aligned}$$

Integrating by parts in ρ , we get

$$\int_{\Gamma_2} \int_0^1 z_{\rho}(x, \rho) z(x, \rho) d\rho d\Gamma = \frac{1}{2} \int_{\Gamma_2} \{z^2(x, 1) - z^2(x, 0)\} d\Gamma \quad (26)$$

Inserting (25) and (26) into (24) results in

$$\begin{aligned}
 \langle AY, Y \rangle &= -a_2 \mu_1 \int_{\Gamma_2} v^2(x) d\Gamma - a_2 \mu_2 \int_{\Gamma_2} v(x) z(x, 1) d\Gamma - \\
 & \frac{\xi}{2\tau} \int_{\Gamma_2} z^2(x, 1) d\Gamma + \frac{\xi}{2\tau} \int_{\Gamma_2} v^2(x) d\Gamma
 \end{aligned}$$

from which follows using the Cauchy-Schwarz inequality

$$\langle AY, Y \rangle \leq -(a_2 \mu_1 - \frac{a_2 \mu_2}{2} + \frac{\xi}{2\tau}) \int_{\Gamma_2} v^2(x) d\Gamma - (\frac{\xi}{2\tau} - \frac{a_2 \mu_2}{2}) \int_{\Gamma_2} z^2(x, 1) d\Gamma \quad (27)$$

(27) implies that

$$\langle AY, Y \rangle \leq 0$$

Thus A is dissipative.

Now we show that for a fixed $\lambda > 0$ and $(g, h, k)^T \in \mathcal{H}$, there exists $Y = (u, v, z)^T \in D(A)$ such that

$$(\lambda I - A)Y = (g, h, k)^T$$

or equivalently

$$\lambda u - v = g \quad (28)$$

$$\lambda v - a(x)\Delta u = h \quad (29)$$

$$\lambda z + \frac{1}{\tau} z_{\rho} = k \quad (30)$$

Suppose that we have found u with the appropriate regularity, then we can determine z . Indeed, from (21) and (30) we have

$$\begin{cases} z_{\rho}(x, \rho) = -\lambda \tau z(x, \rho) + \tau k(x, \rho) \\ z(x, 0) = v(x) \end{cases}$$

The unique solution of the above initial value problem is

$$z(x, \rho) = e^{-\lambda\tau\rho}v(x) + \tau e^{-\lambda\tau\rho} \int_0^\rho e^{\lambda\tau s}k(x, s)ds$$

and in particular

$$z(x, 1) = \lambda e^{-\lambda\tau}u(x) + z_0(x), \quad x \in \Gamma_2$$

where

$$z_0(x) = -e^{-\lambda\tau}g(x) + \tau e^{-\lambda\tau} \int_0^1 e^{\lambda\tau s}k(x, s)ds$$

By (28) and (29), the function u satisfies

$$\lambda^2 u - a(x)\Delta u = h + \lambda g \quad (31)$$

Problem (31) can be reformulated as

$$\int_\Omega (\lambda^2 u - a(x)\Delta u)w dx = \int_\Omega (h + \lambda g)w dx, \quad w \in H_{\Gamma_1}^1(\Omega) \quad (32)$$

Using Green's first theorem and recalling (21), we express the right-hand side of (32) as follows

$$\begin{aligned} \int_\Omega (\lambda^2 u - a(x)\Delta u)w dx &= \int_\Omega (\lambda^2 u w + a(x)\nabla u \cdot \nabla w) dx + a_2 \int_{\Gamma_2} \{\mu_1(\lambda u - g)w \\ &+ \mu_2(\lambda e^{-\lambda\tau}u(x) + z_0(x))w\} d\Gamma \end{aligned}$$

Therefore (32), can be rewritten as

$$\begin{aligned} \int_\Omega (\lambda^2 u w + a(x)\nabla u \cdot \nabla w) dx + a_2 \int_{\Gamma_2} (\mu_1 + \mu_2 e^{-\lambda\tau})\lambda u w d\Gamma &= \int_\Omega (h + \lambda g)w d\Gamma \\ + a_2 \mu_1 \int_{\Gamma_2} g w d\Gamma - a_2 \mu_2 \int_{\Gamma_2} z_0 w d\Gamma, \quad \forall w \in H_{\Gamma_1}^1(\Omega). \end{aligned} \quad (33)$$

Since the left-hand side of (33) is coercive on $H_{\Gamma_1}^1(\Omega)$, the Lax-Milgram Theorem guarantees the existence and uniqueness of a solution $y \in H_{\Gamma_1}^1(\Omega)$ of (31). If we consider $w \in \mathcal{D}(\Omega)$ in (28), then y is a solution in $\mathcal{D}'(\Omega)$ of

$$\lambda^2 u - a(x)\Delta u = h + \lambda g \quad (34)$$

and thus $\Delta u \in L^2(\Omega)$.

Combining (33) together with (34), we obtain after using Green's first theorem

$$a_2 \int_{\Gamma_2} (\mu_1 + \mu_2 e^{-\lambda\tau})\lambda u w d\Gamma + a_2 \int_\Omega \frac{\partial u}{\partial \nu} w d\Gamma = a_2 \mu_1 \int_{\Gamma_2} g w d\Gamma - a_2 \mu_2 \int_{\Gamma_2} z_0 w d\Gamma$$

which implies that

$$\frac{\partial u(x)}{\partial \nu} = -\mu_1 v(x) - \mu_2 z(x, 1)$$

So, we have found $(u, v, z)^T \in D(A)$ which satisfies (28) – (30). Thus, by the Lumer-Phillips Theorem (see for instance [8], Theorem 1.4.3), generates a strongly continuous semigroup of contractions on \mathcal{H} .

3 Proof of Theorem 1

We prove Theorem 1 for smooth initial data. The general case follows by a standard density argument.

We proceed in several steps.

Step 1.

Since

$$E(t) = \frac{1}{2} \|(y, y', z)\|_{\mathcal{H}}^2$$

Then, we deduce from the proof of Proposition 1 that $E(t)$ is non-increasing and

$$\frac{d}{dt}E(t) \leq -C \int_{\Gamma_2} \{y^2(x, t) + y'^2(x, t)\} d\Gamma \quad (35)$$

where

$$C = \min\left\{a_2\mu_1 - \frac{a_2\mu_2}{2} + \frac{\xi}{2\tau}, \frac{\xi}{2\tau} - \frac{a_2\mu_2}{2}\right\}$$

Step 2.

Set

$$E(t) = \mathcal{E}(t) + E_d(t)$$

where

$$\mathcal{E}(t) = \frac{1}{2} \int_{\Omega} \{a(x) |\nabla y(x, t)|^2 + |y'(x, t)|^2\} dx$$

and

$$E_d(t) = \frac{\xi}{2\tau} \int_{\Gamma_2} \int_0^1 |y'(x, t - \tau\rho)|^2 d\rho d\Gamma$$

$E_d(t)$ can be rewritten via a change of variable as

$$E_d(t) = \frac{\xi}{2\tau^2} \int_t^{t+\tau} \int_{\Gamma_2} y'^2(x, s - \tau) d\Gamma ds \quad (36)$$

From (36), we obtain

$$E_d(t) \leq C_1 \int_0^T \int_{\Gamma_2} y'^2(x, s - \tau) d\Gamma ds \quad (37)$$

for $0 \leq t \leq T$ and T large enough.

Step 3.

By applying energy methods (multiplier $2h \cdot \nabla y + (\operatorname{div} h - \alpha)y$) (see the appendix) to problem (1) – (7), we obtain for all $T > 0$,

$$\begin{aligned} \int_0^T \mathcal{E}(t) dt &\leq C_2(\mathcal{E}(0) + \mathcal{E}(T)) + C_3 \int_0^T \int_{\Gamma_2} \left\{ \left(\frac{\partial y(x, t)}{\partial \nu} \right)^2 + y'^2(x, t) \right\} d\Gamma dt + \\ &C_4 \int_0^T \int_{\Gamma_2} |\nabla_{\sigma} y(x, t)|^2 d\Gamma dt + C_5 \int_0^T \int_{\Omega} |y(x, t)|^2 d\Omega dt \end{aligned} \quad (38)$$

where $\nabla_\sigma y$ is the tangential gradient of y .

Step 4.

We eliminate the tangential gradient from (38) by using the following estimate due to Lasiecka and Triggiani (Lemma 7.2 in [3])

$$\int_\epsilon^{T-\epsilon} \int_{\Gamma_2} |\nabla_\sigma y(x, t)|^2 d\Gamma dt \leq C_6 \left\{ \int_0^T \int_{\Gamma_2} \left\{ \left(\frac{\partial y(x, t)}{\partial \nu} \right)^2 + y'^2(x, t) \right\} d\Gamma dt + \|y\|_{L^2(0, T; H^{1/2+\delta}(\Omega))}^2 \right\}$$

where ϵ and δ are arbitrary positive constants. We obtain

$$\int_0^T \mathcal{E}(t) dt \leq C_2(\mathcal{E}(0) + \mathcal{E}(T)) + C_7 \int_0^T \int_{\Gamma_2} \left\{ \left(\frac{\partial y(x, t)}{\partial \nu} \right)^2 + y'^2(x, t) \right\} d\Gamma dt + C_8 \|y\|_{L^2(0, T; H^{1/2+\delta}(\Omega))}^2 \quad (39)$$

Step 5.

We differentiate $\mathcal{E}(t)$ with respect to t and apply Green's first theorem. We obtain

$$\frac{d}{dt} \mathcal{E}(t) = a_2 \int_{\Gamma_2} y'(x, t) \frac{\partial y(x, t)}{\partial \nu} d\Gamma dt \quad (40)$$

From (40), we get via the Cauchy-Schwarz inequality

$$\mathcal{E}(0) \leq \mathcal{E}(T) + \frac{a_2}{2} \int_0^T \int_{\Gamma_2} \left\{ y'^2(x, t) + \left(\frac{\partial y(x, t)}{\partial \nu} \right)^2 \right\} d\Gamma dt \quad (41)$$

Insertion of (41) into (39) yields

$$\int_0^T \mathcal{E}(t) dt \leq 2C_2 \mathcal{E}(T) + C_9 \int_0^T \int_{\Gamma_2} \left\{ \left(\frac{\partial y(x, t)}{\partial \nu} \right)^2 + y'^2(x, t) \right\} d\Gamma dt + C_8 \|y\|_{L^2(0, T; H^{1/2+\delta}(\Omega))}^2 \quad (42)$$

Step 6.

Since $E(t)$ is non-increasing and $E(t) = \mathcal{E}(t) + E_d(t)$, then (42) together with (37) implies that

$$TE(T) \leq 2C_2 \mathcal{E}(T) + C_9 \int_0^T \int_{\Gamma_2} \left\{ \left(\frac{\partial y(x, t)}{\partial \nu} \right)^2 + y'^2(x, t) \right\} d\Gamma dt + C_8 \|y\|_{L^2(0, T; H^{1/2+\delta}(\Omega))}^2 + TC_1 \int_0^T \int_{\Gamma_2} y'^2(x, t - \tau) d\Gamma dt \quad (43)$$

Thus invoking again the identity $E(t) = \mathcal{E}(t) + E_d(t)$ and recalling the boundary condition (4), we obtain from (43)

$$E(T) \leq C_{10} \int_0^T \int_{\Gamma_2} \left\{ y'^2(x, t) + y'^2(x, t - \tau) \right\} d\Gamma dt + C_{11} \|y\|_{L^2(0, T; H^{1/2+\delta}(\Omega))}^2 \quad (44)$$

for T large enough.

Step 7.

We drop the lower order term on the right-hand side of (44) by a compactness-uniqueness argument to obtain

$$E(T) \leq C_{12} \int_0^T \int_{\Gamma_2} \{y'^2(x, t) + y'^2(x, t - \tau)\} d\Gamma dt \quad (45)$$

Step 8.

The estimate (45) together with (35) yields

$$E(T) \leq \frac{C_{13}}{1 + C_{13}} E(0) \quad (46)$$

The desired conclusion follows now from (46) since the system (1) – (7) is invariant by translation.

References

1. Datko, D.: Not all feedback stabilized hyperbolic systems are robust with respect to small time delays in their feedbacks. *SIAM J. Control Optim.* 26, 697-713 (1988)
2. Datko, R., Lagnese, J., Polis, M.P.: An example on the effect of time delays in boundary feedback stabilization of wave equations. *SIAM J. Control Optim.* 24, 152-156 (1986)
3. Lasiecka, I., Triggiani, R.: Uniform stabilization of the wave equation with Dirichlet or Neumann feedback control without geometrical conditions. *Appl. Math. Optim.* 25, 189-244 (1992)
4. Liu, W., Williams, G.H.: The exponential stability of the problem of transmission of the wave equation. *Bull. Austra. Math. Soc.* 97, 305-327 (1998)
5. Nicaise, S., Pignotti, C.: Stability and instability results of the wave equation with a delay term in the boundary or internal feedbacks. *SIAM J. Control Optim.* 45, 1561-1585 (2006)
6. Nicaise, N., Rebiai, S.E.: Stabilization of the Schrödinger equation with a delay term in boundary feedback or internal feedback. *Portugal. Math.* 68, 19-39 (2011).
7. Nicaise, S., Valein, J.: Stabilization of second order evolution equations with unbounded feedback with delay. *ESAIM Control Optim. Calc. Var.* 16, 420-456 (2010)
8. Pazy, A.: *Semigroups of linear operators and applications to partial differential equations.* Springer-Verlag, New York (1983)
9. Xu, G.Q., Yung, S.P., Li, L.K.: Stabilization of wave systems with input delay in the boundary control, *ESAIM Control Optim. Calc. Var.* 12, 770-785 (2006)

Appendix: Sketch of Proof of (38)

We multiply both sides of (1) by $2h \cdot \nabla y + (\operatorname{div} h - \alpha)y$ and integrate over $(0, T) \times \Omega$.

We obtain

$$\begin{aligned}
& 2 \int_0^T \int_{\Omega} a(x) J \nabla y \cdot \nabla y d\Omega dt + \alpha \int_0^T \int_{\Omega} \{y'^2 - a(x) |\nabla y|^2\} d\Omega dt = \\
& - \int_{\Omega} \{2y' h \cdot \nabla y + (\operatorname{div} h - \alpha) y' y\}_0^T d\Omega - \int_0^T \int_{\Omega} a(x) y \nabla y \cdot \nabla (\operatorname{div} h - \alpha) d\Omega dt + \\
& a_1 \int_0^T \int_{\Gamma_1} \left| \frac{\partial y_1}{\partial \nu} \right|^2 h \cdot \nu d\Gamma dt - (a_1 - a_2) \int_0^T \int_{\Gamma_0} |\nabla y_1|^2 h \cdot \nu d\Gamma dt - \\
& \frac{(a_1 - a_2)^2}{a_2} \int_0^T \int_{\Gamma_0} \left| \frac{\partial y_1}{\partial \nu} \right|^2 h \cdot \nu d\Gamma dt + \int_0^T \int_{\Gamma_2} |y_2'|^2 h \cdot \nu d\Gamma dt + \\
& 2a_2 \int_0^T \int_{\Gamma_2} \left| \frac{\partial y_2}{\partial \nu} \right|^2 h \cdot \nabla y_2 d\Gamma dt - a_2 \int_0^T \int_{\Gamma_2} |\nabla y_2|^2 h \cdot \nu d\Gamma dt + \\
& a_2 \int_0^T \int_{\Gamma_2} \left| \frac{\partial y_2}{\partial \nu} \right|^2 (\operatorname{div} h - \alpha) d\Gamma dt \tag{47}
\end{aligned}$$

after using the boundary conditions (3) and (5). Identity (47) is used together with (H.1), (H.2), (H.3) and (8) to obtain estimate (38).