

Packing Plane Perfect Matchings into a Point Set

Ahmad Biniáz, Prosenjit Bose, Anil Maheshwari, Michiel Smid

► **To cite this version:**

Ahmad Biniáz, Prosenjit Bose, Anil Maheshwari, Michiel Smid. Packing Plane Perfect Matchings into a Point Set. Discrete Mathematics and Theoretical Computer Science, DMTCS, 2015, Vol. 17 no.2 (2), pp.119-142. hal-01349047

HAL Id: hal-01349047

<https://hal.inria.fr/hal-01349047>

Submitted on 26 Jul 2016

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

Packing Plane Perfect Matchings into a Point Set*

Ahmad Biniaz Prosenjit Bose Anil Maheshwari Michiel Smid

School of Computer Science, Carleton University, Ottawa, Canada

received 15th Jan. 2015, revised 22nd May 2015, accepted 28th Aug. 2015.

Given a set P of n points in the plane, where n is even, we consider the following question: How many plane perfect matchings can be packed into P ? For points in general position we prove the lower bound of $\lfloor \log_2 n \rfloor - 1$. For some special configurations of point sets, we give the exact answer. We also consider some restricted variants of this problem.

Keywords: geometric graph, packing matching, plane matching

1 Introduction

Let P be a set of n points in general position in the plane (no three points on a line). A *geometric graph* $G = (P, E)$ is a graph whose vertex set is P and whose edge set E is a set of straight-line segments with endpoints in P . We say that two edges of G *cross* each other if they have a point in common that is interior to both edges. Two edges are *disjoint* if they have no point in common. A subgraph S of G is said to be *plane* (*non-crossing* or *crossing-free*) if its edges do not cross. A *plane matching* is a plane graph consisting of pairwise disjoint edges. Two subgraphs S_1 and S_2 are *edge-disjoint* if they do not share any edge. A *complete geometric graph* $K(P)$ is a geometric graph on P which contains a straight-line edge between every pair of points in P .

We say that a set of subgraphs of $K(P)$ is *packed into* $K(P)$, if the subgraphs in the set are pairwise edge-disjoint. In a packing problem, we ask for the largest number of subgraphs of a given type that can be packed into $K(P)$. Among all subgraphs of $K(P)$, *plane perfect matchings*, *plane spanning trees*, and *plane spanning paths* are of interest [2, 3, 4, 5, 9, 12, 28, 34]. That is, one may look for the maximum number of plane spanning trees, plane Hamiltonian paths, or plane perfect matchings that can be packed into $K(P)$. Since $K(P)$ has $\frac{n(n-1)}{2}$ edges, at most $\frac{n}{2}$ spanning trees, at most $\frac{n}{2}$ spanning paths, and at most $n - 1$ perfect matchings can be packed into it. In this paper we consider perfect matchings. A *perfect matching* in $K(P)$ is a set of edges that do not share any endpoint and cover all the points in P .

A long-standing open question is to determine if the edges of $K(P)$ (where n is even) can be partitioned into $\frac{n}{2}$ plane spanning trees. In other words, is it possible to pack $\frac{n}{2}$ plane spanning trees into $K(P)$? If P is in convex position, the answer in the affirmative follows from the result of Bernhart and Kanien [11]. For P in general position, Aichholzer et al. [5] prove that $\Omega(\sqrt{n})$ plane spanning trees can be packed into $K(P)$. They also show the existence of at least 2 edge-disjoint plane spanning paths.

In this paper we consider a closely related question: How many plane perfect matchings can be packed into $K(P)$, where P is a set of n points in general position in the plane, with n even?

*Research supported by NSERC.

1.1 Previous Work

1.1.1 Existence of Plane Subgraphs

The existence of certain plane subgraphs in a geometric graph on a set P of n points is one of the classic problems in combinatorial and computational geometry.

One of the extremal problems in geometric graphs which was first studied by Avital and Hanani [10], Kuptiz [31], Erdős [19], and Perles (see reference [43]) is the following. What is the smallest number $e_k(n)$ such that any geometric graph with n vertices and more than $e_k(n)$ edges contains $k + 1$ pairwise disjoint edges, i.e., a plane matching of size at least $k + 1$. Note that $k \leq \lfloor n/2 \rfloor - 1$. By a result of Hopf and Pannwitz [27], Sutherland [41], and Erdős [19], $e_1(n) = n$, i.e., any geometric graph with $n + 1$ edges contains a pair of disjoint edges, and there are some geometric graphs with n edges which do not contain any pair of disjoint edges.

Alon and Erdős [8] proved that $e_2(n) < 6n - 5$, i.e., any geometric graph with n vertices and at least $6n - 5$ edges contains a plane matching of size three. This bound was improved to $e_2(n) \leq 3n$ by Goddard et al. [22]. Recently Černý [14] proved that $e_2(n) \leq \lfloor 2.5n \rfloor$; while the lower bound of $e_2(n) \geq \lceil 2.5n \rceil - 3$ is due to Perles (see [14]). For $e_3(n)$, Goddard et al. [22] showed that $3.5n - 6 \leq e_3(n) \leq 10n$, which was improved by Tóth and Valtr [43] to $4n - 9 \leq e_3(n) \leq 8.5n$.

For general values of k , Akiyama and Alon [7] gave the upper bound of $e_k(n) = O(n^{2-1/(k+1)})$. Goddard et al. [22] improved the bound to $e_k(n) = O(n(\log n)^{k-3})$. Pach and Törőcsik [36] obtained the upper bound of $e_k(n) \leq k^4 n$; which is the first upper bound that is linear in n . The upper bound was improved to $k^3(n+1)$ by Tóth and Valtr [43]; they also gave the lower bound of $e_k(n) \geq \frac{3}{2}(k-1)n - 2k^2$. Tóth [42] improved the upper bound to $e_k(n) \leq 2^9 k^2 n$, where the constant has been improved to 2^8 by Felsner [20]. It is conjectured that $e_k(n) \leq ckn$ for some constant c .

For the maximum value of k , i.e., $k = \frac{n}{2} - 1$, with n even, Aichholzer et al. [4] showed that $e_{n/2-1}(n) = \binom{n}{2} - \frac{n}{2} = \frac{n(n-2)}{2}$. That is, by removing $\frac{n}{2} - 1$ edges from any complete geometric graph, the resulting graph has $k + 1 = \frac{n}{2}$ disjoint edges, i.e., a plane perfect matching. This bound is tight; there exist complete geometric graphs, such that by removing $\frac{n}{2}$ edges, the resulting graph does not have any plane perfect matching. Similar bounds were obtained by Kupitz and Perles for complete convex graphs, i.e., complete graphs of point sets in convex position. Kupitz and Perles showed that any convex geometric graph with n vertices and more than kn edges contains $k + 1$ pairwise disjoint edges; see [22] (see also [7] and [8]). In particular, in the convex case, $2n + 1$ edges guarantee a plane matching of size three. In addition, Keller and Perles [29] gave a characterization of all sets of $\frac{n}{2}$ edges whose removal prevents the resulting graph from having a plane perfect matching.

Černý et al. [15] considered the existence of Hamiltonian paths in geometric graphs. They showed that after removing at most $\sqrt{n}/(2\sqrt{2})$ edges from any complete geometric graph of n vertices, the resulting graph still contains a plane Hamiltonian path. Aichholzer et al. [4] obtained tight bounds on the maximum number of edges that can be removed from a complete geometric graph, such that the resulting graph contains a certain plane subgraph; they considered plane perfect matchings, plane subtrees of a given size, and triangulations.

1.1.2 Counting Plane Graphs

The number of plane graphs of a given type in a set of n points is also of interest. In 1980, Newborn and Moser [35] asked for the maximal number of plane Hamiltonian cycles; they give an upper bound of $2 \cdot 6^{n-2} \lfloor \frac{n}{2} \rfloor!$, but conjecture that it should be of the form c^n , for some constant c . In 1982, Ajtai et

al. [6] proved that the number of plane graphs is at most 10^{13n} . Every plane graph is a subgraph of some triangulation (with at most $3n - 6$ edges). Since a triangulation has at most 2^{3n-6} plane subgraphs, as noted in [21], any bound of α^n on the number of triangulations implies a bound of $2^{3n-6}\alpha^n < (8\alpha)^n$ on the number of plane graphs. The best known upper bound of 30^n , for the number of triangulations is due to Sharir and Sheffer [37]. This implies the bound 240^n for plane graphs. As for plane perfect matchings, since a perfect matching has $\frac{n}{2}$ edges, Dumitrescu [18] obtained an upper bound of $\binom{3n-6}{n/2}\alpha^n \leq (3.87\alpha)^n$, where $\alpha = 30$. Sharir and Welzl [38] improved this bound to $O(10.05^n)$. They also showed that the number of all (not necessarily perfect) plane matchings is at most $O(10.43^n)$.

García et al. [21] showed that the number of plane perfect matchings of a fixed size set of points in the plane is minimum when the points are in convex position. Motzkin [33] showed that points in convex position have $C_{n/2}$ many perfect matchings (classically referred to as non-crossing configurations of chords on a circle), where $C_{n/2}$ is the $(n/2)^{\text{th}}$ Catalan number; $C_{n/2} = \Theta(n^{-3/2}2^n)$. Thus, the number of plane perfect matchings of n points in the plane is at least $C_{n/2}$. García et al. [21] presented a configuration of n points in the plane which has $\Omega(n^{-4}3^n)$ many plane perfect matchings. See Table 1.

1.1.3 Counting Edge-Disjoint Plane Graphs

The number of edge-disjoint plane graphs of a given type in a point set P of n points is also of interest. Nash-Williams [34] and Tutte [44] independently considered the number of (not necessarily plane) spanning trees. They obtained necessary and sufficient conditions for a graph to have k edge-disjoint spanning trees. Kundu [30] showed that any k -edge-connected graph contains at least $\lceil \frac{k-1}{2} \rceil$ edge-disjoint spanning trees.

As for the plane spanning trees a long-standing open question is to determine if the edges of $K(P)$ (where n is even) can be partitioned into $\frac{n}{2}$ plane spanning trees. In other words, is it possible to pack $\frac{n}{2}$ plane spanning trees into $K(P)$? If P is in convex position, the answer in the affirmative follows from the result of Bernhart and Kanien [11]. In [12], the authors characterize the partitions of the complete convex graph into plane spanning trees. They also describe a sufficient condition, which generalizes the convex case, for points in general position. Aichholzer et al. [5] showed that if the convex hull of P contains h vertices, then $K(P)$ contains at least $\lfloor \frac{h}{2} \rfloor$ edge-disjoint plane spanning trees, and if P is in a “regular wheel configuration”, $K(P)$ can be partitioned into $\frac{n}{2}$ spanning trees. For P in general position they showed that $K(P)$ contains $\Omega(\sqrt{n})$ edge-disjoint plane spanning trees. They obtained the following trade-off between the number of edge-disjoint plane spanning trees and the maximum vertex degree in each tree: For any $k \leq \sqrt{n/12}$, $K(P)$ has k edge-disjoint plane spanning trees with maximum vertex degree $O(k^2)$ and diameter $O(\log(n/k^2))$. They also showed the existence of at least 2 edge-disjoint plane Hamiltonian paths.

1.2 Our Results

Given a set P of n points in the plane, with n even, we consider the problem of packing plane perfect matchings into $K(P)$. From now on, a *matching* will be a *perfect matching*.

In Section 3 we prove bounds on the number of plane matchings that can be packed into $K(P)$. In Section 3.1 we show that if P is in convex position, then $\frac{n}{2}$ plane matchings can be packed into $K(P)$; this bound is tight.

The points in wheel configurations are considered in Section 3.2. We show that if P is in regular wheel configuration, then $\frac{n}{2} - 1$ edge-disjoint plane matchings can be packed into $K(P)$; this bound is tight as

Tab. 1: Number of plane perfect matchings in a point set P of n points (n is even).

Matching	$\forall P : \geq$	$\exists P : \leq$	$\exists P : \geq$	$\forall P : \leq$
total	2^n [21, 33]	2^n [33]	3^n [21]	$O(10.05^n)$ [38]
edge-disjoint	$\lceil \log_2 n \rceil - 1$	$\lceil \frac{n}{3} \rceil$	$\frac{n}{2}$	$n - 1$
non-crossing edge-disjoint	2	2	5	5

well. In addition, for a fixed size set of points, we give a wheel configuration of the points which contains at most $\lceil \frac{n}{3} \rceil$ edge-disjoint plane matchings.

Point sets in general position are considered in Section 3.3. We show how to find three edge-disjoint plane matchings in any set of at least 8 points. If n is a power of two, we prove that $K(P)$ contains at least $\log_2 n$ many edge-disjoint plane matchings. For the general case, where n is an even number, we prove that $K(P)$ contains at least $\lceil \log_2 n \rceil - 2$ edge-disjoint plane matchings.

In Section 3.4 we count the number of pairwise non-crossing plane matchings. Two plane matchings M_1 and M_2 are called *non-crossing* (or *compatible*) if the edges of M_1 and M_2 do not cross each other. We show that $K(P)$ contains at least two and at most five non-crossing plane matchings; these bounds are tight. Table 1 summarizes the results.

In Section 4 we study the concept of *matching persistency* in a graph. A graph G is called *matching-persistent*, if by removing any perfect matching M from G , the resulting graph, $G - M$, still contains a perfect matching. We define the *plane matching persistency* of a point set P , denoted by $pmp(P)$, to be the smallest number of edge-disjoint plane matchings such that, if we remove them from $K(P)$ the resulting graph does not have any plane perfect matching. In other words, $pmp(P) = |\mathcal{M}|$, where \mathcal{M} is the smallest set of edge-disjoint plane matchings such that $K(P) - \bigcup_{M \in \mathcal{M}} M$ does not have any plane perfect matching. Here, the challenge is to find point sets with high plane matching persistency. We show that $pmp(P) \geq 2$ for all point sets P . We give a configuration of P with $pmp(P) \geq 3$. Concluding remarks and open problems are presented in Section 5.

2 Preliminaries

2.1 Graph-Theoretical Background

Consider a graph $G = (V, E)$ with vertex set V and edge set E . If G is a complete graph on a vertex set V of size n , then G is denoted by K_n . A k -factor is a regular graph of degree k . If G is the union of pairwise edge-disjoint k -factors, their union is called a k -factorization and G itself is k -factorable [24]. A *matching* in a graph G is a set of edges that do not share vertices. A perfect matching of G is a 1-factor of G . In this paper only perfect matchings are considered and they are simply called matchings. Since a perfect matching is a regular graph of degree one, it is a 1-factor. It is well-known that for n even, the complete graph K_n is 1-factorable (See [24]). Note that K_n has $\frac{n(n-1)}{2}$ edges and every 1-factor has $\frac{n}{2}$ edges. Thus, K_n can be partitioned into at most $n - 1$ edge-disjoint perfect matchings.

On the other hand it is well-known that the edges of a complete graph K_n , where n is even, can be colored by $n - 1$ colors such that any two adjacent edges have a different color. Each color is assigned to $\frac{n}{2}$ edges, so that each color defines a 1-factor. The following geometric construction of a coloring, which uses a “regular wheel configuration”, is provided in [40]. In a regular wheel configuration, $n - 1$ equally spaced points are placed on a circle and one point is placed at the center of the circle. For each color class,

include an edge e from the center to one of the boundary vertices, and all of the edges perpendicular to the line through e , connecting pairs of boundary vertices.

The number of perfect matchings in a complete graph K_n (with n even), denoted by $M(n)$, is given by the double factorial; $M(n) = (n-1)!!$ [13], where $(n-1)!! = 1 \cdot 3 \cdot 5 \cdots (n-3) \cdot (n-1)$.

2.2 Plane Matchings in Colored Point Sets

Let P be a set of n colored points in general position in the plane with n even. A *colored matching* of P , is a perfect matching such that every edge connects two points of distinct colors. A *plane colored matching* is a colored matching which is non-crossing. A special case of a plane colored matching, where P is partitioned into a set R of $\frac{n}{2}$ red points and a set B of $\frac{n}{2}$ blue points, is called *plane bichromatic matching*, also known as *red-blue matching* (RB -matching). In other words, an RB -matching of P is a non-crossing perfect matching such that every edge connects a red point to a blue point. It is well-known that if no three points of P are collinear, then P has an RB -matching [1]. As shown in Figure 1(a), some point sets have a unique RB -matching. Hershberger and Suri [26] construct an RB -matching in $O(n \log n)$ time, which is optimal.

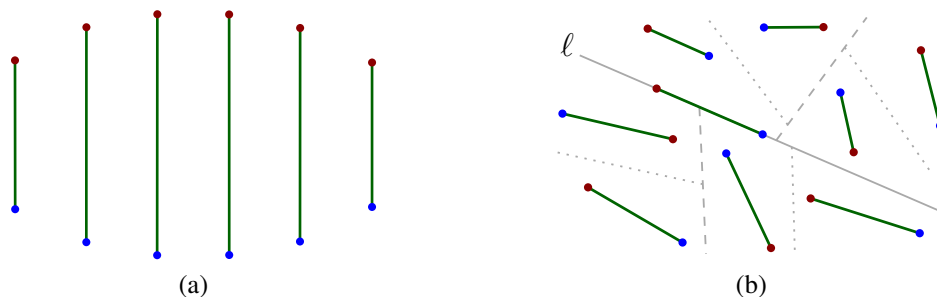


Fig. 1: (a) A point set with a unique RB -matching, (b) Recursive ham sandwich cuts: first cut is in solid, second-level cuts are in dashed, and third-level cuts are in dotted lines.

We review some proofs for the existence of a plane perfect matching between R and B :

- $\text{Min}(R, B)$: Consider a matching M between R and B which minimizes the total Euclidean length of the edges. The matching M is plane. To prove this, suppose that two line segments r_1b_1 and r_2b_2 in M intersect. By the triangle inequality, $|r_1b_2| + |r_2b_1| < |r_1b_1| + |r_2b_2|$. This implies that by replacing r_1b_1 and r_2b_2 in M by r_1b_2 and r_2b_1 , the total length of the matching is decreased; which is a contradiction.
- $\text{Cut}(R, B)$: The *ham sandwich theorem* implies that there is a line ℓ , known as a *ham sandwich cut*, that splits both R and B exactly in half; if the size of R and B is odd, the line passes through one of each. Match the two points on ℓ (if there are any) and recursively solve the problem on each side of ℓ ; the recursion stops when each subset has one red point and one blue point. By matching these two points in all subsets, a plane perfect matching for P is obtained. See Figure 1(b). A ham sandwich cut can be computed in $O(n)$ time [32], and hence the running time can be expressed as the recurrence $T(n) = O(n) + 2 \cdot T(\lfloor \frac{n}{2} \rfloor)$. Therefore, an RB -matching can be computed in $O(n \log n)$ time.

- **Tangent(R, B):** If R and B are separated by a line, we can compute an RB -matching in the following way. W.l.o.g. assume that R and B are separated by a vertical line ℓ . Let $CH(R)$ and $CH(B)$ denote the convex hulls of R and B . Compute the upper tangent rb of $CH(R)$ and $CH(B)$ where $r \in R$ and $b \in B$. Match r and b , and recursively solve the problem for $R - \{r\}$ and $B - \{b\}$; the recursion stops when the two subsets are empty. In each iteration, all the remaining points are below the line passing through r and b , thus, the line segments representing a matched pair in the successor iterations do not cross rb . Therefore, the resulting matching is plane.

Consider a set P of n points where n is even, and a partition $\{P_1, \dots, P_k\}$ of P into k color classes. Sufficient and necessary conditions for the existence of a colored matching in P follows from the following theorem by Sitton [39]:

Theorem 1 (Sitton [39]) *Let K_{n_1, \dots, n_k} be a complete multipartite graph with n vertices, where $n_1 \leq \dots \leq n_k$. If $n_k \leq n_1 + \dots + n_{k-1}$, then K_{n_1, \dots, n_k} has a matching of size $\lfloor \frac{n}{2} \rfloor$.*

Aichholzer et al. [4] showed that if K_{n_1, \dots, n_k} is a geometric graph corresponding to a colored point set P , then the minimum-weight colored matching of P is non-crossing. Specifically, they extend the proof of 2-colored point sets to multi-colored point sets:

Theorem 2 (Aichholzer et al. [4]) *Let P be a set of colored points in general position in the plane with $|P|$ even. Then P admits a non-crossing perfect matching such that every edge connects two points of distinct colors if and only if at most half the points in P have the same color.*

3 Packing Plane Matchings into Point Sets

Let P be a set of n points in the plane with n even. In this section we prove lower bounds on the number of plane matchings that can be packed into $K(P)$. It is obvious that every point set has at least one plane matching, because a minimum weight perfect matching in $K(P)$, denoted by $\text{Min}(P)$, is plane. A trivial lower bound of 2 (for $n \geq 4$) is obtained from a minimum weight Hamiltonian cycle in $K(P)$, because this cycle is plane and consists of two edge-disjoint matchings. We consider points in convex position (Section 3.1), wheel configuration (Section 3.2), and general position (Section 3.3).

3.1 Points in Convex Position

In this section we consider points in convex position. We show that if P is in convex position, $\frac{n}{2}$ plane matchings can be packed into $K(P)$; this bound is tight.

Lemma 1 *If P is in convex position, where $|P|$ is even and $|P| \geq 4$, then every plane matching in P contains at least two edges of $CH(P)$.*

Proof: Let M be a plane matching in P . We prove this lemma by induction on the size of P . If $|P| = 4$, then $|M| = 2$. None of the diagonals of P can be in M , thus, the two edges in M belong to $CH(P)$. If $|P| > 4$ then $|M| \geq 3$. If all edges of M are edges of $CH(P)$, then the claim in the lemma holds. Assume that M contains a diagonal edge pq , where pq is not an edge of $CH(P)$. Let P_1 and P_2 be the sets of points of P on each side of $\ell(p, q)$ (both including p and q). Let M_1 and M_2 be the edges of M in P_1 and P_2 , respectively. It is obvious that P_1 (resp. P_2) is in convex position and M_1 (resp. M_2) is a plane matching in P_1 (resp. P_2). By the induction hypothesis M_1 (resp. M_2) contains two edges of

$CH(P_1)$ (resp. $CH(P_2)$). Since $CH(P) = CH(P_1) \cup CH(P_2)$ and $|M_1 \cap M_2| = 1$, M contains at least two edges of $CH(P)$. \square

Theorem 3 For any set P of n points in convex position in the plane, with n even, the maximum number of plane matchings that can be packed into $K(P)$ is $\frac{n}{2}$.

Proof: By Lemma 1, every plane matching in P contains at least two edges of $CH(P)$. On the other hand, $CH(P)$ has n edges. Therefore, the number of plane matchings that can be packed into $K(P)$ is at most $\frac{n}{2}$.

Now we show how to pack $\frac{n}{2}$ plane matchings into $K(P)$. Let $P = \{p_0, \dots, p_{n-1}\}$, and w.l.o.g. assume that p_0, p_1, \dots, p_{n-1} is the radial ordering of the points in P with respect to a fixed point in the interior of $CH(P)$. For each p_i in the radial ordering, where $0 \leq i < \frac{n}{2}$, let $M_i = \{p_{i+j-1}p_{n+i-j} : j = 1, \dots, \frac{n}{2}\}$ (all indices are modulo n). Informally speaking, M_i is a plane perfect matching obtained from edge $p_i p_{i-1}$ and all edges parallel to $p_i p_{i-1}$; see Figure 2. Let $\mathcal{M} = \{M_i : i = 0, \dots, \frac{n}{2} - 1\}$. The matchings in \mathcal{M} are plane and pairwise edge-disjoint. Thus, \mathcal{M} is a set of $\frac{n}{2}$ plane matchings that can be packed into $K(P)$. \square

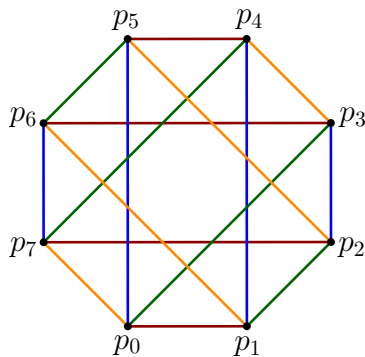


Fig. 2: Points in convex position.

3.2 Points in Wheel Configurations

A point set P of n points is said to be in “regular wheel configuration” in the plane, if $n - 1$ points of P are equally spaced on a circle C and one point of P is at the center of C . We introduce a variation of the regular wheel configuration as follows. Let the point set P be partitioned into X and Y such that $|X| \geq 3$ and $|X|$ is an odd number. The points in X are equally spaced on a circle C . For any two distinct points $p, q \in X$ let $\ell(p, q)$ be the line passing through p and q . Since X is equally spaced on C and $|X|$ is an odd number, $\ell(p, q)$ does not contain the center of C . Let $H(p, q)$ and $H'(p, q)$ be the two half planes defined by $\ell(p, q)$ such that $H'(p, q)$ contains the center of C . Let $C' = \bigcap_{p, q \in X} H'(p, q)$. The points in Y are in the interior of C' ; see Figure 3(a). For any two points $p, q \in X$, the line segment pq does not intersect the interior of C' . The special case when $|Y| = 1$ is the regular wheel configuration.

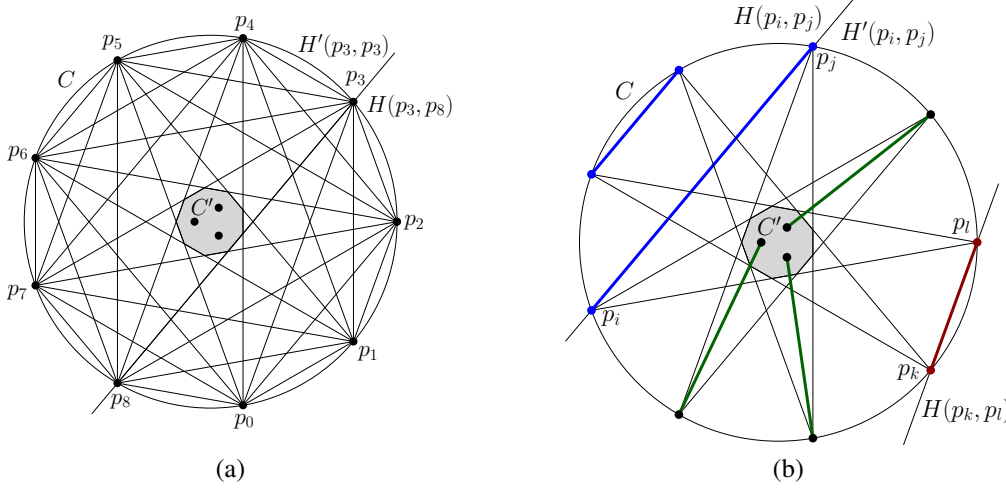


Fig. 3: (a) A variation of the regular wheel configuration. (b) Illustration of Lemma 2. The points of A and the edges of $M(A)$ are in blue, and the points of B and the edges of $M(B)$ are in red.

Lemma 2 Let P be a set of points in the plane where $|P|$ is an even number and $|P| \geq 6$. Let $\{X, Y\}$ be a partition of the points in P such that $|X|$ is an odd number and $|Y| \leq 2\lfloor \frac{|P|}{6} \rfloor - 1$. If P is in the wheel configuration described above, then any plane matching in P contains at least two edges of $CH(P)$.

Proof: Consider a plane matching M of P . It is obvious that $CH(P) = CH(X)$; we show that M contains at least two edges of $CH(X)$. Note that $|X| = |P| - |Y|$, and both $|X|$ and $|Y|$ are odd numbers. Observe that $|X| \geq 4\lfloor \frac{|P|}{6} \rfloor + 1 = 2|Y| + 3 \geq 5$; which implies that $|Y| \leq \frac{|X|-1}{2} - 1$. Thus, $|X| > |Y|$, and hence there is at least one edge in M with both endpoints in X . Let $p_i p_j$ be the longest such edge. Recall that $C' \subset H(p_i, p_j)$. Let A be the set of points of P in $H(p_i, p_j)$ (including p_i and p_j), and let A' be the set of points of P in $H'(p_i, p_j)$ (excluding p_i and p_j). By definition, $H(p_i, p_j) \cup \ell(p_i, p_j)$ does not contain any point of Y . Thus, $A \subset X$ and A is in convex position with $|A| \leq \frac{|X|-1}{2}$ (note that $|X|$ is an odd number). Let $M(A)$ and $M(A')$ be the edges of M induced by the points in A and A' , respectively. Clearly, $\{M(A), M(A')\}$ is a partition of the edges of M , and hence $M(A)$ (resp. $M(A')$) is a plane perfect matching for A (resp. A'). We show that each of $M(A)$ and $M(A')$ contains at least one edge of $CH(X)$. First we consider $M(A)$. If $|A| = 2$, then $p_i p_j$ is the only edge in $M(A)$ and it is an edge of $CH(X)$. Assume that $|A| \geq 4$. By Lemma 1, $M(A)$ contains at least two edges of $CH(A)$. On the other hand each edge of $CH(A)$, except for $p_i p_j$, is also an edge of $CH(X)$; see Figure 3(b). This implies that $M(A) - \{p_i p_j\}$ contains at least one edge of $CH(X)$. Now we consider $M(A')$. Let $X' = A' \cap X$, that is, $\{A, X'\}$ is a partition of the points in X . Since $|A| \leq \frac{|X|-1}{2}$, we have $|X'| \geq \frac{|X|+1}{2}$. Recall that $|Y| \leq \frac{|X|-1}{2} - 1$. Thus, $|Y| < |X'|$, and hence there is an edge $p_k p_l \in M(A')$ with both p_k and p_l in X' . Let B be the set of points of P in $H(p_k, p_l)$ (including p_k and p_l). By definition, $H(p_k, p_l) \cup \ell(p_k, p_l)$ does not contain any point of Y . Thus, $B \subset X$ and B is in convex position. On the other hand, by the choice of $p_i p_j$ as the longest edge, A cannot be a subset of B and hence $B \subset X'$. Let $M(B)$ be the edges of $M(A')$ induced by the points in B . We show that $M(B)$ contains at least one edge of $CH(X)$.

If $|B| = 2$, then $p_k p_l$ is the only edge in $M(B)$ and it is an edge of $CH(X)$. Assume that $|B| \geq 4$. By Lemma 1, $M(B)$ contains at least two edges of $CH(B)$. On the other hand, each edge of $CH(B)$, except for $p_k p_l$, is also an edge of $CH(X)$; see Figure 3(b). This implies that $M(B) - \{p_k p_l\}$ contains at least one edge of $CH(X)$. This completes the proof. \square

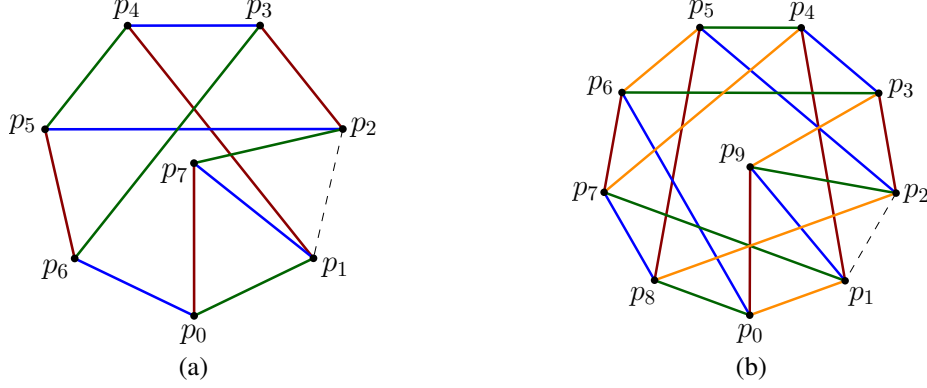


Fig. 4: Points in the regular configuration with (a) $n = 4k$ and (b) $n = 4k + 2$; one of the edges in $CH(P)$ cannot be matched.

Theorem 4 For a set P of $n \geq 6$ points in the regular wheel configuration in the plane with n even, the maximum number of plane matchings that can be packed into $K(P)$ is $\frac{n}{2} - 1$.

Proof: In the regular wheel configuration, P is partitioned into a point set X of size $n - 1$ and a point set Y of size 1. The points of X are equally spaced on a circle C and the (only) point of Y is the center of C . By Lemma 2, every plane matching in P contains at least two edges of $CH(P)$. On the other hand, $CH(P)$ has $n - 1$ edges. Therefore, the number of plane matchings that can be packed into $K(P)$ is at most $\frac{n-1}{2}$. Since n is an even number and the number of plane matchings is an integer, we can pack at most $\frac{n}{2} - 1$ plane matchings into $K(P)$.

Now we show how to pack $\frac{n}{2} - 1$ plane matchings into $K(P)$. Let $P = \{p_0, \dots, p_{n-1}\}$, and w.l.o.g. assume that p_{n-1} is the center of C . Let $P' = P - \{p_{n-1}\}$, and let p_0, p_1, \dots, p_{n-2} be the radial ordering of the points in P' with respect to p_{n-1} . For each p_i in the radial ordering, where $0 \leq i \leq \frac{n}{2} - 2$, let

$$R_i = \{p_{i+j} p_{i+2\lceil(n-2)/4\rceil - j + 1} : j = 1, \dots, \lceil(n-2)/4\rceil\},$$

and

$$L_i = \{p_{i-j} p_{i-2\lfloor(n-2)/4\rfloor + j - 1} : j = 1, \dots, \lfloor(n-2)/4\rfloor\}$$

(all indices are modulo $n - 1$). Let $M_i = R_i \cup L_i \cup \{p_i p_{n-1}\}$; informally speaking, M_i is a plane perfect matching obtained from edge $p_i p_{n-1}$ and edges parallel to $p_i p_{n-1}$. See Figure 4(a) for the case where $n = 4k$ and Figure 4(b) for the case where $n = 4k + 2$. Let $\mathcal{M} = \{M_i : i = 0, \dots, \frac{n}{2} - 2\}$. The matchings in \mathcal{M} are plane and pairwise edge-disjoint. Thus, \mathcal{M} is a set of $\frac{n}{2} - 1$ plane matchings that can be packed into $K(P)$. \square

In the following theorem we use the wheel configuration to show that for any even integer $n \geq 6$, there exists a set P of n points in the plane, such that no more than $\lceil \frac{n}{3} \rceil$ plane matchings can be packed into $K(P)$.

Theorem 5 *For any even number $n \geq 6$, there exists a set P of n points in the plane such that no more than $\lceil \frac{n}{3} \rceil$ plane matchings can be packed into $K(P)$.*

Proof: The set P of n points is partitioned into X and Y , where $|Y| = 2\lfloor \frac{n}{6} \rfloor - 1$ and $|X| = n - |Y|$. The points in X are equally spaced on a circle C and the points in Y are in the interior $\bigcap_{p,q \in X} H'(p, q)$. By Lemma 2, any plane matching in P contains at least two edges of $CH(P)$. Since $CH(P) = CH(X)$, any plane matching of P contains at least two edges of $CH(X)$. Thus, if \mathcal{M} denotes any set of plane matchings which can be packed into $K(P)$, we have (note that $|X|$ is odd)

$$|\mathcal{M}| \leq \frac{|X| - 1}{2} = \frac{n - 2\lfloor n/6 \rfloor}{2} = \frac{n}{2} - \lfloor \frac{n}{6} \rfloor \leq \frac{n}{2} - \frac{n-5}{6} \leq \lceil \frac{n}{3} \rceil.$$

□

3.3 Points in General Position

In this section we consider the problem of packing plane matchings for point sets in general position (no three points on a line) in the plane. Let P be a set of n points in general position in the plane, with n even. Let $M(P)$ denote the maximum number of plane matchings that can be packed into $K(P)$. As mentioned earlier, a trivial lower bound of 2 (when $n \geq 4$) is obtained from a minimum weight Hamiltonian cycle, which is plane and consists of two edge-disjoint perfect matchings.

In this section we show that at least $\lfloor \log_2 n \rfloor - 1$ plane matchings can be packed into $K(P)$. As a warm-up, we first show that if n is a power of two, then $\log_2 n$ plane matchings can be packed into $K(P)$. Then we extend this result to get a lower bound of $\lfloor \log_2 n \rfloor - 1$ for every point set with an even number of points. We also show that if $n \geq 8$, then at least three plane matchings can be packed into $K(P)$, which improves the result for $n = 10, 12$, and 14 . Note that, as a result of Theorem 5, there exists a set of $n = 6$ points such that no more than $\lceil \frac{n}{3} \rceil = 2$ plane matchings can be packed into $K(P)$. First consider the following observation.

Observation 1 *Let $\mathcal{P} = \{P_1, \dots, P_k\}$ be a partition of the point set P , such that $|P_i|$ is even and $CH(P_i) \cap CH(P_j) = \emptyset$ for all $1 \leq i, j \leq k$ where $i \neq j$. Let i be an index such that, $M(P_i) = \min\{M(P_j) : 1 \leq j \leq k\}$. Then, $M(P) \geq M(P_i)$.*

Lemma 3 *For a set P of n points in general position in the plane, where n is a power of 2, at least $\log_2 n$ plane matchings can be packed into $K(P)$.*

Proof: We prove this lemma by induction. The statement of the lemma holds for the base case, where $n = 2$. Assume that $n \geq 4$. Recall that $M(P)$ denotes the maximum number of plane matchings that can be packed into $K(P)$. W.l.o.g. assume that a vertical line ℓ partitions P into sets R and B , each of size $\frac{n}{2}$. By the induction hypothesis, $M(R), M(B) \geq \log_2(\frac{n}{2})$. By Observation 1, $M(P) \geq \min\{M(R), M(B)\} \geq \log_2(\frac{n}{2})$. That is, by pairing a matching M_R in R with a matching M_B in B we get a plane matching M_P in $K(P)$, such that each edge in M_P has both endpoints in R or in B . If we consider the points in R as red and the points in B as blue, $\text{Cut}(R, B)$ (see Section 2.2) gives us a plane

perfect matching M'_P in $K(P)$, such that each edge in M'_P has one endpoint in R and one endpoint in B . That is $M'_P \cap M_P = \emptyset$. Therefore, we obtain one more plane matching in $K(P)$, which implies that $M(P) \geq \log_2(\frac{n}{2}) + 1 = \log_2 n$. \square

Let R and B be two point sets which are separated by a line. A *crossing tangent* between R and B is a line l touching $CH(R)$ and $CH(B)$ such that R and B lie on different sides of l . Note that l contains a point $r \in R$, a point $b \in B$, and consequently the line segment rb ; we say that l is subtended from rb . It is obvious that there are two (intersecting) crossing tangents between R and B ; see Figure 5.

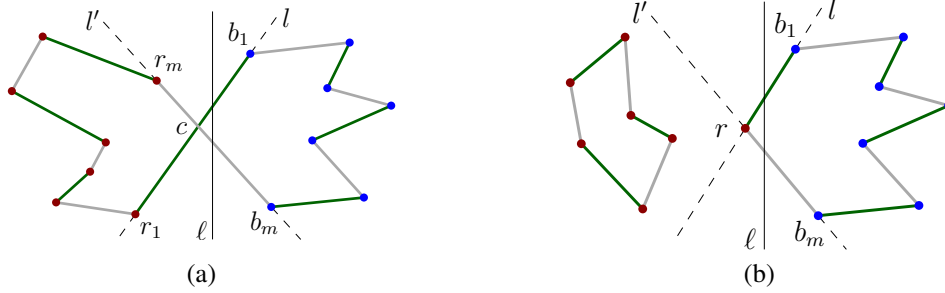


Fig. 5: (a) The crossing tangents intersect at a point $c \notin P$: R and B are sorted clockwise around c . (b) The crossing tangents intersect at a point $r \in R$: B is sorted clockwise around r . M_1 and M_2 are shown by green and gray line segments.

Lemma 4 For a set P of $n \geq 8$ points in general position in the plane with n even, at least three plane matchings can be packed into $K(P)$.

Proof: We describe how to extract three edge-disjoint plane matchings, M_1, M_2, M_3 , from $K(P)$. Let ℓ be a vertical line which splits P into sets R and B , each of size $\frac{n}{2}$. Consider the points in R as red and the points in B as blue. We differentiate between two cases: (a) $n = 4k$ and (b) $n = 4k + 2$, for some integer $k > 1$.

In case (a), both R and B have an even number of points. Let $M_1(R)$ and $M_2(R)$ (resp. $M_1(B)$ and $M_2(B)$) be two edge-disjoint plane matchings in R (resp. B) obtained by a minimum length Hamiltonian cycle in R (resp. B). Let $M_1 = M_1(R) \cup M_1(B)$ and $M_2 = M_2(R) \cup M_2(B)$. Clearly M_1 and M_2 are edge-disjoint plane matchings for P . Let $M_3 = \text{Cut}(R, B)$. It is obvious that M_3 is edge-disjoint from M_1 and M_2 , which completes the proof in the first case.

In case (b), both R and B have an odd number of points and we cannot get a perfect matching in each of them. Let l and l' be the two crossing tangents between R and B , subtended from rb and $r'b'$, respectively. We differentiate between two cases: (i) l and l' intersect in the interior of rb and $r'b'$, (ii) l and l' intersect at an endpoint of both rb and $r'b'$; see Figure 5.

- In case (i), let c be the intersection point; see Figure 5(a). Let r_1, r_2, \dots, r_m and b_1, b_2, \dots, b_m be the points of R and B , respectively, sorted clockwise around c , where $m = \frac{n}{2}$, $r_1 = r, r_m = r', b_1 = b, b_m = b'$. Consider the Hamiltonian cycle $H = \{r_i r_{i+1} : 1 \leq i < m\} \cup \{b_i b_{i+1} : 1 \leq i < m\} \cup \{r_1 b_1, r_m b_m\}$. Let M_1 and M_2 be the two edge-disjoint matchings obtained from H . Note that $r_1 b_1$ and $r_m b_m$ cannot be in the same matching, thus, M_1 and M_2 are plane. Let

$M_3 = \text{Tangent}(R, B)$. As described in Section 2.2, M_3 is a plane matching for P . In order to prove that $M_3 \cap (M_1 \cup M_2) = \emptyset$, we show that rb and $r'b'$ —which are the only edges in $M_1 \cup M_2$ that connect a point in R to a point in B —do not belong to M_3 . Note that $\text{Tangent}(R, B)$ iteratively selects an edge which has the same number of red and blue points below its supporting line, whereas the supporting lines of rb and $r'b'$ have different numbers of red and blue points below them. Thus rb and $r'b'$ are not considered by $\text{Tangent}(R, B)$. Therefore M_3 is edge-disjoint from M_1 and M_2 .

- In case (ii), w.l.o.g. assume that l and l' intersect at the red endpoint of rb and $r'b'$, i.e., $r = r'$; See Figure 5(b). Let $R' = R \setminus \{r\}$ and $B' = B \cup \{r\}$. Note that both R' and B' have an even number of points and $|R'|, |B'| \geq 4$. Let $M_1(R')$ and $M_2(R')$ be two edge-disjoint plane matchings in R' obtained by a minimum length Hamiltonian cycle in R' . Let b_1, b_2, \dots, b_m be the points of B sorted clockwise around r , where $m = \frac{n}{2}$, $b_1 = b$, $b_m = b'$. Consider the Hamiltonian cycle $H(R') = \{b_i b_{i+1} : 1 \leq i < m\} \cup \{rb_1, rb_m\}$. Let $M_1(B')$ and $M_2(B')$ be the two edge-disjoint plane matchings in B' obtained from $H(R')$. Let $M_1 = M_1(R') \cup M_1(B')$ and $M_2 = M_2(R') \cup M_2(B')$. Clearly M_1 and M_2 are edge-disjoint plane matchings in P . Let $M_3 = \text{Tangent}(R, B)$. As described in case (i), M_3 is a plane matching in P and $M_3 \cap (M_1 \cup M_2) = \emptyset$. Therefore, M_3 is edge-disjoint from M_1 and M_2 . □

As a direct consequence of Lemma 3 and Lemma 4 we have the following theorem.

Theorem 6 *For a set P of $n = 2^i \cdot m$ points in general position in the plane with n even, $m \geq 4$, $i \geq 0$, at least $i + 2$ plane matchings can be packed into $K(P)$.*

Proof: If $i = 0$, then a minimum weight Hamiltonian cycle in $K(P)$ consists of two plane matchings. Assume $i \geq 1$. Partition P by vertical lines, into 2^{i-1} point sets, each of size $2m$. By Lemma 4, at least three plane matchings can be packed into each set. Considering these sets as the base cases in Lemma 3, we obtain $i - 1$ plane matchings between these sets. Thus, in total, $i + 2$ plane matchings can be packed into $K(P)$. □

Theorem 7 *For a set P of n points in general position in the plane, with n even, at least $\lfloor \log_2 n \rfloor - 1$ plane matchings can be packed into $K(P)$.*

Proof: If n is a power of two, then by Lemma 3 at least $\log_2 n \geq \lfloor \log_2 n \rfloor - 1$ matchings can be packed into $K(P)$. Assume n is not a power of two. We describe how to pack a set \mathcal{M} of $\lfloor \log_2 n \rfloor - 1$ plane perfect matchings into $K(P)$. The construction consists of the following three main steps which we will describe in detail.

1. Building a binary tree T .
2. Assigning the points of P to the leaves of T .
3. Extracting \mathcal{M} from P using internal nodes of T .

1. Building the tree T . In this step we build a binary tree T such that each node of T stores an even number, and each internal node of T has a left and a right child. For an internal node u , let $left(u)$ and $right(u)$ denote the left child and the right child of u , respectively. Given an even number n , we build T in the following way:

- The root of T stores n .
- If a node of T stores 2, then that node is a leaf.
- For a node u storing m , with m even and $m \geq 4$, we store the following even numbers into $left(u)$ and $right(u)$:
 - If m is divisible by 4, we store $\frac{m}{2}$ in both $left(u)$ and $right(u)$; see Figure 6(a).
 - If m is not divisible by 4 and u is the root or the left child of its parent then we store $2\lfloor \frac{m}{4} \rfloor$ in $left(u)$ and $m - 2\lfloor \frac{m}{4} \rfloor$ in $right(u)$; see Figure 6(b).
 - If m is not divisible by 4 and u is the right child of its parent then we store $m - 2\lfloor \frac{m}{4} \rfloor$ in $left(u)$ and $2\lfloor \frac{m}{4} \rfloor$ in $right(u)$; see Figure 6(c).

Note that in the last two cases—where m is not divisible by four—the absolute difference between the values stored in $left(u)$ and $right(u)$ is exactly 2. See Figure 7.

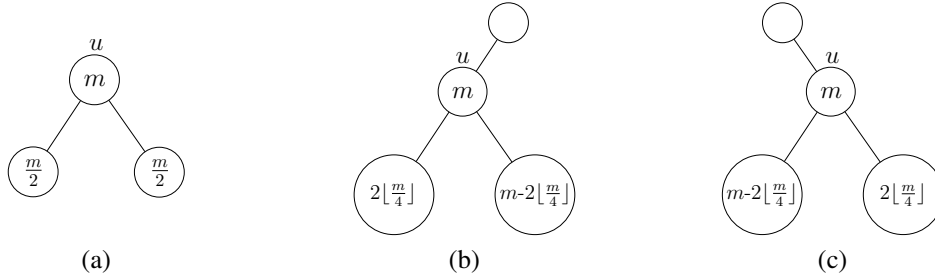


Fig. 6: (a) m is divisible by four, (b) m is not divisible by four and u is a left child, and (c) m is not divisible by four and u is a right child.

2. Assigning the points to the leaves of the tree. In this step we describe how to assign the points of P , in pairs, to the leaves of T . We may assume without loss of generality that no two points of P have the same x -coordinate. Sort the points of P in a increasing order of their x -coordinate. Assign the first two points to the leftmost leaf, the next two points to the second leftmost leaf, and so on. Note that T has $\frac{n}{2}$ leaves, and hence all the points of P are assigned to the leaves of T . See Figure 7.

3. Extracting the matchings. Let L be the number of edges in a shortest path from the root to any leaf in T ; in Figure 7, $L = 3$. For an internal node $u \in T$, let T_u be the subtree rooted at u . Let L_u and R_u be the set of points assigned to the left and right subtrees of T_u , respectively, and let $P_u = L_u \cup R_u$. Consider the points in L_u as red and the points in R_u as blue. Since the points in L_u have smaller x -coordinates than the points in R_u , we say that L_u and R_u are separated by a vertical line $\ell(u)$. For each internal node

u where u is in level $0 \leq i < L$ in T —assuming the root is in level 0—we construct a plane perfect matching M_u in P_u in the following way. Let m be the even number stored at u .

- If m is divisible by 4 (Figure 6(a)), then let $M_u = \text{Min}(L_u, R_u)$; see Section 2.2. Since $|L_u| = |R_u|$, M_u is a plane perfect matching for P_u . See vertices u_2, u_3 in Figure 7.
- If m is not divisible by 4 and u is the root or a left child (Figure 6(b)), then $|R_u| - |L_u| = 2$. Let a, b be the two points assigned to the rightmost leaf in T_u , and let $M_u = \{ab\} \cup \text{Min}(L_u, R_u - \{a, b\})$. Since $|L_u| = |R_u - \{a, b\}|$, M_u is a perfect matching in P_u . In addition, a and b are the two rightmost points in P_u , thus, ab does not intersect any edge in $\text{Min}(L_u, R_u - \{a, b\})$, and hence M_u is plane. See vertices u_0, u_1, u_5 in Figure 7.
- If m is not divisible by 4 and u is a right child (Figure 6(c)), then $|L_u| - |R_u| = 2$. Let a, b be the two points assigned to the leftmost leaf in T_u and let $M_u = \{ab\} \cup \text{Min}(L_u - \{a, b\}, R_u)$. Since $|L_u - \{a, b\}| = |R_u|$, M_u is a perfect matching in P_u . In addition, a and b are the two leftmost points in P_u , thus, ab does not intersect any edge in $\text{Min}(L_u - \{a, b\}, R_u)$, and hence M_u is plane. See vertices u_4, u_6 in Figure 7.

For each i , where $0 \leq i < L$, let $S(i)$ be the set of vertices of T in level i ; see Figure 7. For each level i let $M_i = \bigcup_{u \in S(i)} M_u$. Let $\mathcal{M} = \{M_i : 0 \leq i < L\}$. In the rest of the proof, we show that \mathcal{M} contains $\lfloor \log_2 n \rfloor - 1$ edge-disjoint plane matchings in P .

Claim 1: For each i , where $0 \leq i < L$, M_i is a plane perfect matching in P . Note that if u is the root of the tree, then $P_u = P$. In addition, for each internal node u (including the root), $\{L_u, R_u\}$ is a partition of the point set P_u . This implies that in each level i of the tree, where $0 \leq i < L$, we have $P = \bigcup_{u \in S(i)} P_u$. Moreover, the points in P are assigned to the leaves of T in non-decreasing order of their x -coordinate. Thus, $\mathcal{P}_i = \{P_u : u \in S(i)\}$ is a partition of the point set P ; the sets P_u with $u \in S(i)$ are separated by vertical lines; see Figure 7. Therefore, M_i is a perfect plane matching in P ; which proves the claim.

Claim 2: For all $M_i, M_j \in \mathcal{M}$, where $0 \leq i, j < L$ and $i \neq j$, $M_i \cap M_j = \emptyset$. In order to prove that M_i and M_j are edge-disjoint, we show that for each pair of distinct internal nodes u and v , $M_u \cap M_v = \emptyset$. If u and v are in the same level, then P_u and P_v are separated by $\ell(u)$, thus, M_u and M_v do not share any edge. Thus, assume that $u \in S(i)$ and $v \in S(j)$ such that $0 \leq i, j < L$, $i \neq j$, and w.l.o.g. assume that $i < j$. If $v \notin T_u$, then P_u and P_v are separated by line $\ell(w)$, where w is the lowest common ancestor of u and v ; this implies that M_u and M_v do not share any edge. Therefore, assume that $v \in T_u$, and w.l.o.g. assume that v is in the left subtree of T_u . Thus, P_v —and consequently M_v —is to the left of $\ell(u)$. The case where v is in the right subtree of T_u is symmetric. Let $m \geq 4$ be the number stored at u . We differentiate between three cases:

- If m is divisible by 4, then all the edges in M_u cross $\ell(u)$, while the edges in M_v are to the left of $\ell(u)$. This implies that M_u and M_v are disjoint.
- If m is not divisible by 4 and u is the root or a left child, then all the edges of M_u cross $\ell(u)$, except the rightmost edge ab which is to the right of $\ell(u)$. Since M_v is to the left of $\ell(u)$, it follows that M_u and M_v are disjoint.

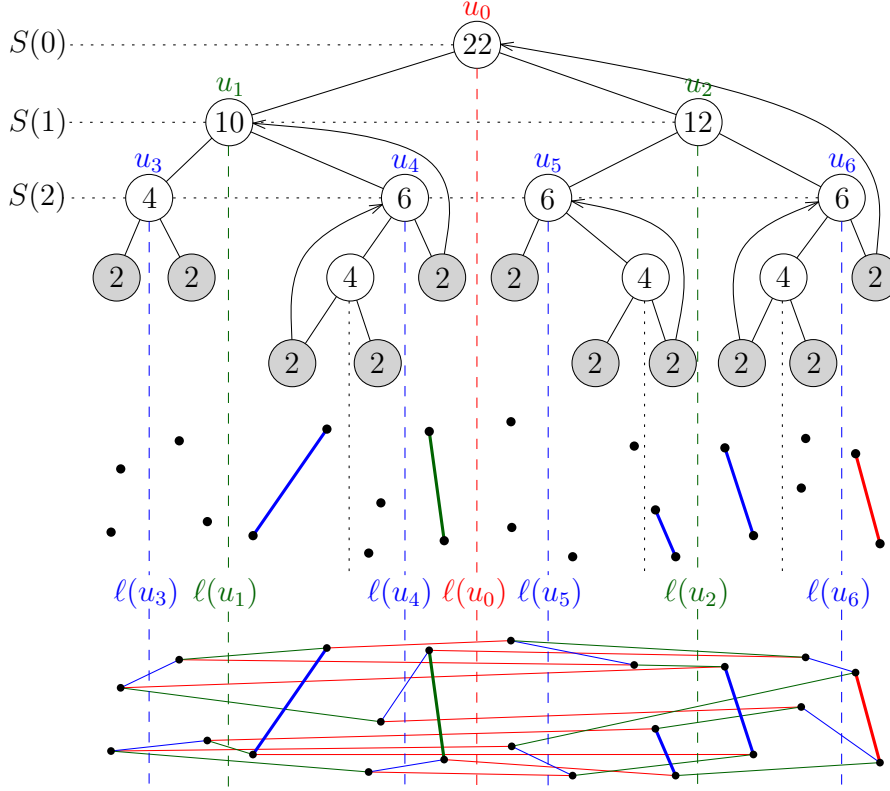


Fig. 7: The points in P are assigned, in pairs, to the leaves of T , from left to right. The point set P with the edge-disjoint plane matchings is shown as well. M_0 contains the bold red edge and the red edges crossing $\ell(u_0)$. M_1 contains the bold green edge and the green edges crossing $\ell(u_1), \ell(u_2)$. M_2 contains the bold blue edges and the blue edges crossing $\ell(u_3), \ell(u_4), \ell(u_5), \ell(u_6)$.

- If m is not divisible by 4 and u is a right child, then all the edges of M_u cross $\ell(u)$, except the leftmost edge ab . If $a, b \notin P_v$, then $ab \notin M_v$, and hence M_u and M_v are disjoint. If $a, b \in P_v$ then v is the left child of its parent and all the edges in M_v cross $\ell(v)$ (possibly except one edge which is to the right of $\ell(v)$), while ab is to the left of $\ell(v)$. Therefore M_u and M_v do not share any edge. This completes the proof of the claim.

Claim 3: For every two nodes u and v in the same level of T which store m and m' , respectively, $|m - m'| \leq 2$.

We prove the claim inductively for each level i of T . For the base case, where $i = 1$: (a) if n is divisible by four, then both u and v store $\frac{n}{2}$ and the claim holds, (b) if n is not divisible by four then u stores $2\lfloor \frac{n}{4} \rfloor$ and v stores $n - 2\lfloor \frac{n}{4} \rfloor$; as $0 \leq n - 2\lfloor \frac{n}{4} \rfloor - 2\lfloor \frac{n}{4} \rfloor \leq 2$, the claim holds for $i = 1$. Now we show that if the claim is true for the i th level of T , then the claim is true for the $(i + 1)$ th level of T . Let u and v , storing

m and m' , respectively, be in the i th level of T . By the induction hypothesis, the claim holds for the i th level, i.e., $|m - m'| \leq 2$. We prove that the claim holds for the $(i + 1)$ th level of T , i.e., for the children of u and v . Since m and m' are even numbers, $|m - m'| \in \{0, 2\}$. If $|m - m'| = 0$, then $m = m'$, and by a similar argument as in the base case, the claim holds for the children of u and v . If $|m - m'| = 2$, then w.l.o.g. assume that $m' = m + 2$. Let α be the smallest number and β be the largest number stored at the children of u and v (which are at the $(i + 1)$ th level). We show that $\beta - \alpha \leq 2$. It is obvious that $\alpha = 2\lfloor \frac{m}{4} \rfloor$ and $\beta = m' - 2\lfloor \frac{m'}{4} \rfloor$. Thus,

$$\begin{aligned} \beta - \alpha &= m' - 2\lfloor \frac{m'}{4} \rfloor - 2\lfloor \frac{m}{4} \rfloor \\ &= m + 2 - 2\lfloor \frac{m + 2}{4} \rfloor - 2\lfloor \frac{m}{4} \rfloor \end{aligned} \quad (1)$$

Now, we differentiate between two cases, where $m = 4k$ or $m = 4k + 2$. If $m = 4k$, then by Equation 1,

$$\begin{aligned} \beta - \alpha &= 4k + 2 - 2\lfloor \frac{4k + 2}{4} \rfloor - 2\lfloor \frac{4k}{4} \rfloor \\ &= 4k + 2 - 2k - 2k \\ &= 2. \end{aligned}$$

If $m = 4k + 2$, then by Equation 1,

$$\begin{aligned} \beta - \alpha &= 4k + 4 - 2\lfloor \frac{4k + 4}{4} \rfloor - 2\lfloor \frac{4k + 2}{4} \rfloor \\ &= 4k + 4 - 2(k + 1) - 2k \\ &= 2 \end{aligned}$$

which completes the proof of the claim.

Claim 4: $L \geq \lfloor \log_2 n \rfloor - 1$.

It follows from Claim 3 that all the leaves of T are in the last two levels. Since T has $\frac{n}{2}$ leaves, T has $n - 1$ nodes. Recall that L is the number of edges in a shortest path from the root to any leaf in T . Thus, $L \geq h - 1$, where h is the height of T . To give a lower bound on h , one may assume that the last level of T is also full, thus,

$$n - 1 \leq 2^0 + 2^1 + 2^2 + \dots + 2^h \leq 2^{h+1} - 1$$

and hence, $h \geq \log_2 n - 1$. Therefore, $L \geq h - 1 \geq \log_2 n - 2$. Since L is an integer and n is not a power of two, $L \geq \lceil \log_2 n \rceil - 2 = \lfloor \log_2 n \rfloor - 1$; which proves the claim.

Claim 1 and Claim 2 imply that \mathcal{M} contains L edge-disjoint plane perfect matchings. Claim 4 implies that $L \geq \lfloor \log_2 n \rfloor - 1$, which proves the statement of the theorem. \square

3.4 Non-crossing Plane Matchings

In this section we consider the problem of packing plane matchings into $K(P)$ such that any two different matchings in the packing are non-crossing. Two edge-disjoint plane matchings M_1 and M_2 are *non-crossing* (or *compatible*), if no edge in M_1 crosses any edge in M_2 . For a set P of n points in general position in the plane, with n even, we give tight lower and upper bounds on the number of pairwise non-crossing plane perfect matchings that can be packed into $K(P)$.

Lemma 5 *For a set P of n points in general position in the plane, with n even, at most five pairwise non-crossing plane matchings can be packed into $K(P)$.*

Proof: Let $\{M_1, M_2, \dots, M_m\}$ be any maximal set of non-crossing edge-disjoint plane matchings in $K(P)$. Let $M = M_1 \cup M_2 \dots \cup M_m$, and let G be the induced subgraph of $K(P)$ by M . It is obvious that G is an m -regular graph. Since M_1, \dots, M_m are plane and pairwise non-crossing, G is an m -regular plane graph. It is well known that every plane graph has a vertex of degree at most 5. Thus, G has a vertex of degree at most five and hence $m \leq 5$; which implies at most five pairwise non-crossing plane matchings can be packed into $K(P)$. \square

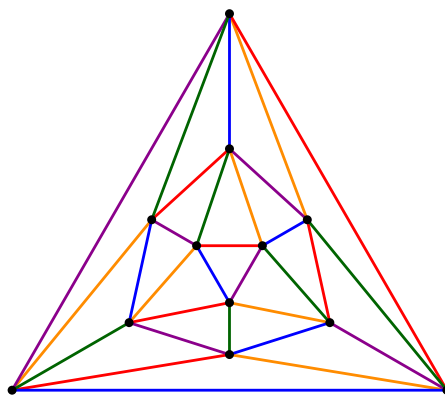


Fig. 8: A point set with five non-crossing edge-disjoint plane perfect matchings.

Figure 8 shows a 5-regular geometric graph on a set of 12 points in the plane which contains five non-crossing edge-disjoint plane matchings. In [25], the authors showed how to generate an infinite family of 5-regular planar graphs using the graph in Figure 8. By an extension of the five matchings shown in Figure 8, five non-crossing matchings for this family of graphs is obtained. Thus, the bound provided by Lemma 5 is tight.

It is obvious that if P contains at least four points, the minimum length Hamiltonian cycle in $K(P)$ contains two non-crossing edge-disjoint plane matchings. In the following lemma we show that there exist point sets which contain at most two non-crossing edge-disjoint plane matchings.

Lemma 6 *For a set P of $n \geq 4$ points in convex position in the plane, with n even, at most two pairwise non-crossing plane matchings can be packed into $K(P)$.*

Proof: The proof is by contradiction. Consider three pairwise non-crossing plane matchings M_1, M_2, M_3 in $K(P)$. Let G be the induced subgraph of $K(P)$ by $M_1 \cup M_2 \cup M_3$. Note that G is a 3-regular plane graph. Moreover, G is an outerplanar graph. It is well known that every outerplanar graph has a vertex of degree at most 2. This contradicts that every vertex in G has degree 3. \square

We conclude this section with the following theorem.

Theorem 8 For a set P of $n \geq 4$ points in general position in the plane, with n even, at least two and at most five pairwise non-crossing plane matchings can be packed into $K(P)$. These bounds are tight.

4 Matching Removal Persistency

In this section we define the matching persistency of a graph. A graph G is *matching persistent* if by removing any perfect matching M from G , the resulting graph, $G - M$, has a perfect matching. We define the *matching persistency* of G , denoted by $mp(G)$, as the size of the smallest set \mathcal{M} of edge-disjoint perfect matchings that can be removed from G such that $G - \mathcal{M}$ does not have any perfect matching. In other words, if $mp(G) = k$, then

1. by removing an arbitrary set of $k - 1$ edge-disjoint perfect matchings from G , the resulting graph still contains a perfect matching, and
2. there exists a set of k edge-disjoint perfect matchings such that by removing these matchings from G , the resulting graph does not have any perfect matching.

In particular, G is matching persistent iff $mp(G) \geq 2$.

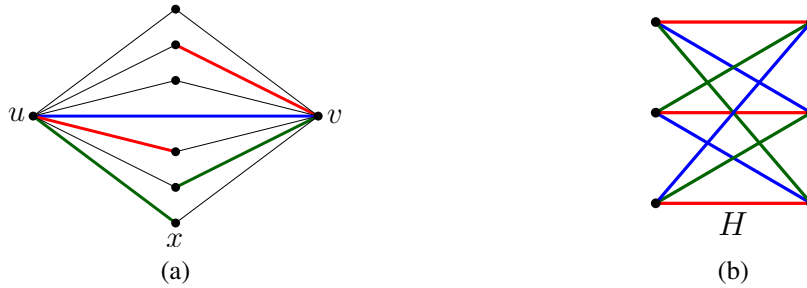


Fig. 9: (a) By removing any matching (red, green, or blue) from K_n , at most two paths between u and v disappear. (b) The edges of H are partitioned to $\frac{n}{2}$ perfect matchings, thus, $K_n - H$ does not have any perfect matching.

Lemma 7 Let K_n be a complete graph with n vertices, where n is even, and let \mathcal{M} be a set of k edge-disjoint perfect matchings in K_n . Then, $K_n - \mathcal{M}$ is an $(n - 1 - k)$ -regular graph which is $(n - 1 - 2k)$ -connected.

Proof: The regularity is trivial, because K_n is $(n - 1)$ -regular and every vertex has degree k in \mathcal{M} , thus, $K_n - \mathcal{M}$ is an $(n - 1 - k)$ -regular graph. Now we prove the connectivity. Consider two vertices u and v in $V(K_n)$. There are $n - 1$ many edge-disjoint paths between u and v in K_n : $n - 2$ many paths of length

two of the form (u, x, v) , where $x \in V(K_n) - \{u, v\}$ and a path (u, v) of length one; see Figure 9(a). By removing any matching in \mathcal{M} from K_n , at most two paths disappear, because u and v have degree one in each matching. Thus in $G - \mathcal{M}$, there are $(n - 1 - 2k)$ many edge-disjoint paths between u and v , which implies that $K_n - \mathcal{M}$ is $(n - 1 - 2k)$ -connected. \square

Lemma 8 *Let n to be an even number. Then, $mp(K_n) \geq \frac{n}{2}$.*

Proof: We show that by removing any set \mathcal{M} of k edge-disjoint perfect matchings from K_n , where $0 \leq k < \frac{n}{2}$, the resulting graph still has a perfect matching. By Lemma 7, the graph $K_n - \mathcal{M}$ is an $(n - 1 - k)$ -regular graph which is $(n - 1 - 2k)$ -connected. Since $k < \frac{n}{2}$, $K_n - \mathcal{M}$ is a connected graph and the degree of each vertex is at least $\frac{n}{2}$. Thus, by a result of Dirac [17], $K_n - \mathcal{M}$ has a Hamiltonian cycle and consequently a perfect matching. Therefore, by removing k arbitrary perfect matchings from K_n , where $k < \frac{n}{2}$, the resulting graph still has a perfect matching, which proves the claim. \square

Lemma 9 *If $n \equiv 0 \pmod{4}$, then $mp(K_n) \geq \frac{n}{2} + 1$.*

Proof: By Lemma 8, $mp(K_n) \geq \frac{n}{2}$. Let \mathcal{M} be any set of $\frac{n}{2}$ edge-disjoint perfect matchings in K_n . We will show that $K_n - \mathcal{M}$ contains a perfect matching. If $K_n - \mathcal{M}$ contains a Hamiltonian cycle then it has a perfect matching and we are done. Assume $K_n - \mathcal{M}$ does not contain any Hamiltonian cycle, while it is a $(\frac{n}{2} - 1)$ -regular graph. A result of Cranston and O [16] implies that $K_n - \mathcal{M}$ is disconnected. In order for $K_n - \mathcal{M}$ to be $(\frac{n}{2} - 1)$ -regular each component has to have at least $\frac{n}{2}$ vertices. Thus, $K_n - \mathcal{M}$ consists of two disjoint copies of $K_{\frac{n}{2}}$. Each of these components has a Hamiltonian cycle, and hence a perfect matching. Therefore, the union of these two components has a perfect matching. \square

Theorem 9 *If $n \equiv 2 \pmod{4}$, then $mp(K_n) = \frac{n}{2}$.*

Proof: By Lemma 8, $mp(K_n) \geq \frac{n}{2}$. In order to complete the proof, we show that $mp(K_n) \leq \frac{n}{2}$. Let $H = K_{\frac{n}{2}, \frac{n}{2}}$ be a complete bipartite subgraph of K_n . Note that $\frac{n}{2}$ is an odd number and H is an $\frac{n}{2}$ -regular graph. According to Hall's marriage theorem [23], for $k \geq 1$, every k -regular bipartite graph contains a perfect matching [24]. Since by the iterative removal of perfect matchings from H the resulting graph is still regular, the edges of H can be partitioned into $\frac{n}{2}$ perfect matchings; see Figure 9(a). It is obvious that $K_n - H$ consists of two connected components of odd size. Thus, by removing the $\frac{n}{2}$ matchings in H , the resulting graph, $K_n - H$, does not have any perfect matching. This proves the claim. \square

Theorem 10 *If $n \equiv 0 \pmod{4}$, then $mp(K_n) = \frac{n}{2} + 1$.*

Proof: By Lemma 9, $mp(K_n) \geq \frac{n}{2} + 1$. In order to complete the proof, we show that $mp(K_n) \leq \frac{n}{2} + 1$. Assume $n = 4k$. Let $A = \{a_1, \dots, a_{2k-1}\}$ and $B = \{b_1, \dots, b_{2k+1}\}$ be a partition of vertices of K_n . Let M_i be a matching consisting of the edges $b_i b_{i+1}$ and $a_j b_{j+i+1}$, where $+$ is modulo $2k + 1$ and j runs from 1 to $2k - 1$. It is easy to see that M_1, \dots, M_{2k+1} are disjoint perfect matchings, and after removing them we have a complete graph on A and a graph on B , which are disjoint. Since each of A and B has an odd number of points, there is no more perfect matching. This proves the claim. \square

In the rest of this section we consider plane matching removal from geometric graphs.

Let P be a set of n points in general position in the plane, with n even. Given a geometric graph G on P , we say that G is *plane matching persistent* if by removing any plane perfect matching M from G , the resulting graph, $G - M$, has a plane perfect matching. We define the *plane matching persistency* of G , denoted by $\text{pmp}(G)$ as the size of the smallest set \mathcal{M} of edge-disjoint plane perfect matchings that can be removed from G such that $G - \mathcal{M}$ does not have any plane perfect matching. In particular, G is plane matching persistent iff $\text{pmp}(G) \geq 2$.

Aichholzer et al. [4] and Perles (see [29]) showed that by removing any set of at most $\frac{n}{2} - 1$ edges from $K(P)$, the resulting graph has a plane perfect matching. This bound is tight [4]; that is, there exists a point set P such that by removing a set H of $\frac{n}{2}$ edges from $K(P)$ the resulting graph does not have any plane perfect matching. In the examples provided by [4], the $\frac{n}{2}$ edges in H form a connected component which has $\frac{n}{2} + 1$ vertices.

Thus, one may think if the removed edges are disjoint, it may be possible to remove more than $\frac{n}{2} - 1$ edges while the resulting graph has a plane perfect matching. In the following lemma we show that by removing any plane perfect matching, i.e., a set of $\frac{n}{2}$ disjoint edges, from $K(P)$, the resulting graph still has a perfect matching.

Lemma 10 *Let P be a set of n points in general position in the plane with n even, then $\text{pmp}(K(P)) \geq 2$.*

Proof: Let M be any plane perfect matching in $K(P)$. Assign $\frac{n}{2}$ distinct colors to the points in P such that both endpoints of every edge in M have the same color. By Theorem 2, P has a plane colored matching, say M' . Since both endpoints of every edge in M have the same color while the endpoints of every edge in M' have distinct colors, M and M' are edge-disjoint. Therefore, by removing any plane perfect matching from $K(P)$, the resulting graph still has a plane perfect matching, which implies that $\text{pmp}(K(P)) \geq 2$. \square

Theorem 11 *For a set P of $n \geq 4$ points in convex position in the plane with n even, $\text{pmp}(K(P)) = 2$.*

Proof: By Lemma 10, $\text{pmp}(K(P)) \geq 2$. In order to prove the theorem, we need to show that $\text{pmp}(K(P)) \leq 2$. Let M_1 and M_2 be two edge-disjoint plane matchings obtained from $CH(P)$. By Lemma 1, any plane perfect matching in $K(P)$ contains at least two edges of $CH(P)$, while $K(P) - \{M_1 \cup M_2\}$ does not have convex hull edges, and hence does not have any plane perfect matching. Therefore, $\text{pmp}(K(P)) \leq 2$. \square

Observation 2 *The union of two edge-disjoint perfect matchings in any graph is a set of even cycles.*

Lemma 11 *There exists a point set P in general position such that $\text{pmp}(K(P)) \geq 3$.*

Proof: We prove this lemma by providing an example. Figure 10(a) shows a set $P = \{a_1, \dots, a_n, b_1, \dots, b_n, c_1, \dots, c_n\}$ of $3n$ points in general position, where n is an even number. In order to prove that $\text{pmp}(K(P)) \geq 3$, we show that by removing any two edge-disjoint plane matchings from $K(P)$, the resulting graph still has a plane perfect matching. Let M_1 and M_2 be any two plane perfect matchings in $K(P)$. Let G be the subgraph of $K(P)$ induced by the edges in $M_1 \cup M_2$. Note that G is a 2-regular graph and by Observation 2 does not contain any odd cycle. For each $1 \leq i \leq n$, let t_i be the triangle which is defined by the three points a_i, b_i , and c_i . Let \mathcal{T} be the set of these n (nested) triangles. Since G does not have any odd cycle, for each $t_i \in \mathcal{T}$, at least one edge of t_i is not in G . Let M_3 be the matching containing an edge e_i from each $t_i \in \mathcal{T}$ such that $e_i \notin G$. See Figure 10(b). Now we describe how to complete M_3 ,

i.e., complete it to a perfect matching. Partition the triangles in \mathcal{T} into $\frac{n}{2}$ pairs of consecutive triangles. For each pair (t_i, t_{i+1}) of consecutive triangles we complete M_3 locally—on $a_i, b_i, c_i, a_{i+1}, b_{i+1}, c_{i+1}$ —in the following way. Let $t_i = (a_i, b_i, c_i)$ and $t_{i+1} = (a_{i+1}, b_{i+1}, c_{i+1})$. See Figure 10(c). W.l.o.g. assume that M_3 contains $a_i b_i$ and $a_{i+1} c_{i+1}$, that is $a_i b_i \notin G$ and $a_{i+1} c_{i+1} \notin G$. If $c_i b_{i+1} \notin G$, then we complete M_3 by adding $c_i b_{i+1}$. If $c_i b_{i+1} \in G$, then $a_{i+1} b_{i+1} \notin G$ or $c_{i+1} b_{i+1} \notin G$ because b_{i+1} has degree two in G . W.l.o.g. assume that $a_{i+1} b_{i+1} \notin G$. Then we modify M_3 by removing $a_{i+1} c_{i+1}$ and adding $a_{i+1} b_{i+1}$. Now, if $c_i c_{i+1} \notin G$, then we complete M_3 by adding $c_i c_{i+1}$. If $c_i c_{i+1} \in G$, then by Observation 2, $b_{i+1} c_{i+1} \notin G$. We modify M_3 by removing $a_{i+1} b_{i+1}$ and adding $b_{i+1} c_{i+1}$. At this point, since $c_i b_{i+1}$ and $c_i c_{i+1}$ are in G , $c_i a_{i+1} \notin G$ and we complete M_3 by adding $c_i a_{i+1}$. \square

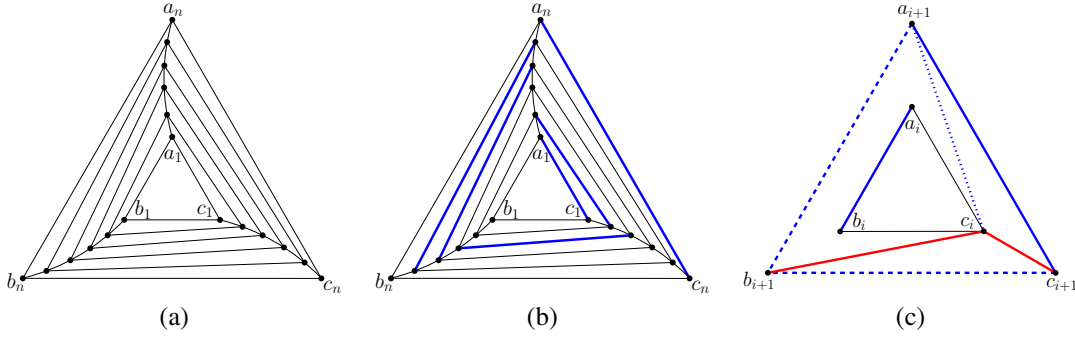


Fig. 10: (a) Set P of $3n$ points in general position. (b) M_3 contains one edge from each triangle. (c) Locally converting M_3 to a perfect matching, for t_i and t_{i+1} .

5 Conclusion

We considered the problem of packing edge-disjoint plane perfect matchings into a set P of n points in the plane. If P is in general position, we showed how to pack $\lfloor \log_2 n \rfloor - 1$ matchings. We also looked at some special cases and variants of this problem. We believe that the number of such matchings is linear. A natural open problem is to improve either the provided lower bound or the trivial upper bound of $n - 1$, where $n > 6$. Another problem is to provide point sets with large plane matching persistency.

Acknowledgements

We would like to thank the anonymous reviewers for their valuable comments and suggestions improving the quality of the paper. We are grateful to Thomas Hackl for his valuable comments; specifically for pointing out the outerplanarity of the graph in the proof of Lemma 6, which simplified the proof. We also thank Vida Dujmović for valuable discussions.

References

- [1] The 1979 Putnam exam. In G. L. Alexanderson, L. F. Klosinski, and L. C. Larson, editors, *The William Lowell Putnam Mathematical Competition Problems and Solutions: 1965-1984*. Mathematical Association of America, USA, 1985.

- [2] O. Aichholzer, A. Asinowski, and T. Miltzow. Disjoint compatibility graph of non-crossing matchings of points in convex position. *Electr. J. Comb.*, 22(1):P1.65, 2015.
- [3] O. Aichholzer, S. Bereg, A. Dumitrescu, A. G. Olaverri, C. Huemer, F. Hurtado, M. Kano, A. Márquez, D. Rappaport, S. Smorodinsky, D. L. Souvaine, J. Urrutia, and D. R. Wood. Compatible geometric matchings. *Comput. Geom.*, 42(6-7):617–626, 2009.
- [4] O. Aichholzer, S. Cabello, R. F. Monroy, D. Flores-Peñaloza, T. Hackl, C. Huemer, F. Hurtado, and D. R. Wood. Edge-removal and non-crossing configurations in geometric graphs. *Discrete Mathematics & Theoretical Computer Science*, 12(1):75–86, 2010.
- [5] O. Aichholzer, T. Hackl, M. Korman, M. J. van Kreveld, M. Löffler, A. Pilz, B. Speckmann, and E. Welzl. Packing plane spanning trees and paths in complete geometric graphs. In *Proceedings of the 26th Canadian Conference on Computational Geometry, CCCG*, 2014.
- [6] M. Ajtai, V. Chvátal, M. M. Newborn, and E. Szemerédi. Crossing-free subgraphs. *Ann. Discrete Math.*, 12:9–12, 1982.
- [7] J. Akiyama and N. Alon. Disjoint simplices and geometric hypergraphs. *Annals of the New York Academy of Sciences*, 555(1):1–3, 1989.
- [8] N. Alon and P. Erdős. Disjoint edges in geometric graphs. *Discrete & Computational Geometry*, 4:287–290, 1989.
- [9] G. Aloupis, L. Barba, S. Langerman, and D. L. Souvaine. Bichromatic compatible matchings. In *Symposium on Computational Geometry*, pages 267–276, 2013.
- [10] S. Avital and H. Hanani. Graphs (in Hebrew). *Gilyonot Lematematika*, 3:2–8, 1966.
- [11] F. Bernhart and P. C. Kainen. The book thickness of a graph. *J. Comb. Theory, Ser. B*, 27(3):320–331, 1979.
- [12] P. Bose, F. Hurtado, E. Rivera-Campo, and D. R. Wood. Partitions of complete geometric graphs into plane trees. *Comput. Geom.*, 34(2):116–125, 2006.
- [13] D. Callan. A combinatorial survey of identities for the double factorial. arXiv: 0906.1317, 2009.
- [14] J. Černý. Geometric graphs with no three disjoint edges. *Discrete & Computational Geometry*, 34(4):679–695, 2005.
- [15] J. Černý, Z. Dvořák, V. Jelínek, and J. Kára. Noncrossing Hamiltonian paths in geometric graphs. *Discrete Applied Mathematics*, 155(9):1096–1105, 2007.
- [16] D. W. Cranston and S. O. Hamiltonicity in connected regular graphs. *Inf. Process. Lett.*, 113(22-24):858–860, 2013.
- [17] G. A. Dirac. Some theorems on abstract graphs. *Proceedings of the London Mathematical Society*, 2:69–81, 1952.

- [18] A. Dumitrescu. On two lower bound constructions. In *Proceedings of the 11th Canadian Conference on Computational Geometry, UBC, Vancouver, British Columbia, Canada, August 15-18, 1999*, 1999.
- [19] P. Erdős. On the set of distances of n points. *The American Mathematical Monthly*, 53(5):248–250, 1946.
- [20] S. Felsner. *Geometric Graphs and Arrangements: Some Chapters from Combinatorial Geometry*. Vieweg, Wiesbaden, 2004.
- [21] A. García, M. Noy, and J. Tejel. Lower bounds on the number of crossing-free subgraphs of K_N . *Comput. Geom.*, 16(4):211–221, 2000.
- [22] W. Goddard, M. Katchalski, and D. J. Kleitman. Forcing disjoint segments in the plane. *Eur. J. Comb.*, 17(4):391–395, 1996.
- [23] P. Hall. On representatives of subsets. *Journal of the London Mathematical Society*, s1-10(1):26–30, 1935.
- [24] F. Harary. *Graph theory*. Addison-Wesley, 1991.
- [25] M. Hasheminezhad, B. D. McKay, and T. Reeves. Recursive generation of simple planar 5-regular graphs and pentangulations. *J. Graph Algorithms Appl.*, 15(3):417–436, 2011.
- [26] J. Hershberger and S. Suri. Applications of a semi-dynamic convex hull algorithm. *BIT*, 32(2):249–267, 1992.
- [27] H. Hopf and E. Pannwitz. Aufgabe no. 167. *Jahresbericht der Deutschen Mathematiker-Vereinigung*, 43:114, 1934.
- [28] M. Ishaque, D. L. Souvaine, and C. D. Tóth. Disjoint compatible geometric matchings. *Discrete & Computational Geometry*, 49(1):89–131, 2013.
- [29] C. Keller and M. Perles. On the smallest sets blocking simple perfect matchings in a convex geometric graph. *Israel Journal of Mathematics*, 187(1):465–484, 2012.
- [30] S. Kundu. Bounds on the number of disjoint spanning trees. *Journal of Combinatorial Theory, Series B*, 17(2):199–203, 1974.
- [31] Y. Kupitz. Extremal problems in combinatorial geometry. *Aarhus University Lecture Notes Series*, 53, 1979.
- [32] C. Lo, J. Matousek, and W. L. Steiger. Algorithms for ham-sandwich cuts. *Discrete & Computational Geometry*, 11:433–452, 1994.
- [33] T. Motzkin. Relations between hypersurface cross ratios, and a combinatorial formula for partitions of a polygon, for permanent preponderance, and for non-associative products. *Bull. Amer. Math. Soc.*, 54(4):352–360, 1948.

- [34] C. St. J. A. Nash-Williams. Edge-disjoint spanning trees of finite graphs. *Journal of the London Mathematical Society*, 36(1):445–450, 1961.
- [35] M. M. Newborn and W. O. J. Moser. Optimal crossing-free Hamiltonian circuit drawings of K_n . *J. Comb. Theory, Ser. B*, 29(1):13–26, 1980.
- [36] J. Pach and J. Törőcsik. Some geometric applications of Dilworth’s theorem. *Discrete & Computational Geometry*, 12:1–7, 1994.
- [37] M. Sharir and A. Sheffer. Counting triangulations of planar point sets. *Electr. J. Comb.*, 18(1), 2011.
- [38] M. Sharir and E. Welzl. On the number of crossing-free matchings, cycles, and partitions. *SIAM J. Comput.*, 36(3):695–720, 2006.
- [39] D. Sitton. Maximum matchings in complete multipartite graphs. *Furman University Electronic Journal of Undergraduate Mathematics*, 2:6–16, 1996.
- [40] A. Soifer. *The Mathematical Coloring Book: Mathematics of Coloring and the Colorful Life of its Creators*. New York: Springer, 2009.
- [41] J. W. Sutherland. Lösung der aufgabe 167. *Jahresbericht der Deutschen Mathematiker-Vereinigung*, 45:33–35, 1935.
- [42] G. Tóth. Note on geometric graphs. *J. Comb. Theory, Ser. A*, 89(1):126–132, 2000.
- [43] G. Tóth and P. Valtr. Geometric graphs with few disjoint edges. *Discrete & Computational Geometry*, 22(4):633–642, 1999.
- [44] W. T. Tutte. On the problem of decomposing a graph into n connected factors. *Journal of the London Mathematical Society*, 36(1):221–230, 1961.