

Bin Packing Problem with Generalized Time Lags: A Branch-Cut-and-Price Approach

François Clautiaux, Ruslan Sadykov, Orlando Rivera-Letelier

► **To cite this version:**

François Clautiaux, Ruslan Sadykov, Orlando Rivera-Letelier. Bin Packing Problem with Generalized Time Lags: A Branch-Cut-and-Price Approach. Roadef 2019 - 20ème Congrès Annuel de la Société Française de Recherche Opérationnelle et d'Aide à la Décision, Feb 2019, Le Havre, France. hal-02378993

HAL Id: hal-02378993

<https://hal.inria.fr/hal-02378993>

Submitted on 25 Nov 2019

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

Bin Packing Problem with Generalized Time Lags: A Branch-Cut-and-Price Approach

François Clautiaux^{2,1} **Ruslan Sadykov**^{1,2}
Orlando Rivera-Letelier^{3,2}

¹ Inria Bordeaux,
France



² Université Bordeaux,
France



³ Universidad Adolfo
Ibáñez, Chili



ROADEF 2019
Le Havre, France, February 21

Bin Packing With Time Lags Problem

Classic Bin Packing Problem

- ▶ Set of items to pack into bins.
- ▶ Items have positive weight, and bins have capacity.
- ▶ Objective: Minimize number of bins used.

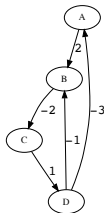
Bin Packing Problem with Time Lags

- ▶ Bins are assigned to time periods.
- ▶ Number of bins in each period is unbounded
- ▶ Pairs of items have precedence constraints with lags.

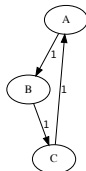
Precedence Constraints

- ▶ Precedences are represented by a directed graph $G = (I, A)$.
- ▶ Each arc $(i, j) \in A$ has a lag $l_{ij} \in \mathbb{Z}$.
- ▶ Bins are assigned to time periods, and items are assigned to the time period of the bin it belongs to.
- ▶ Each lag l_{ij} imposes the following constraint: The time period that item j is assigned must be at least l_{ij} time periods after the time period item i is assigned.

The graph is not necessarily acyclic.



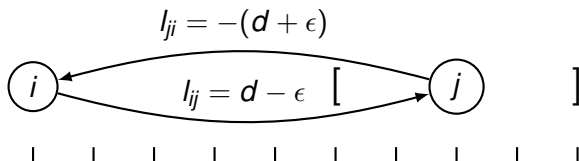
An instance is infeasible if and only if there is a cycle of positive length in the graph.



Motivation

Applications

- ▶ Performing a set of periodic tasks using rented capacitated resources



- ▶ Flexible periodic vehicle routing (generalisation)

Special cases

- ▶ Simple Assembly Line Balancing Problem of type 1 ($l_{ij} = 0$) [Becker and Scholl, 2006]
- ▶ Bin Packing with Precedences ($l_{ij} = 1$) [Pereira, 2016]
- ▶ Bin Packing with Generalized Precedences ($l_{ij} \geq 0$) [Kramer et al., 2017]

An IP formulation: variables and objective

Notation

- ▶ The bin capacity $W \in \mathbb{Z}^+$.
- ▶ A weight $w_i \in \mathbb{Z}^+$, $w_i \leq W$, for each $i \in V$.
- ▶ $\mathcal{B} = \{1, 2, \dots, B\}$ the set of potential bins in a period.
- ▶ $\mathcal{T} = \{1, 2, \dots, T\}$ the set of time periods.

Variables

- ▶ $x_{ibt} \in \{0, 1\}$ for each $i \in V, j \in \mathcal{B}, t \in \mathcal{T}$. Takes value 1 iff item i is assigned to bin b of time period t .
- ▶ $u_{bt} \in \{0, 1\}$ for each $j \in \mathcal{B}, t \in \mathcal{T}$. Takes value 1 iff bin b of time period t is in use.

Objective

$$\min \sum_{b \in \mathcal{B}} \sum_{t \in \mathcal{T}} u_{bt}$$

An IP formulation: constraints

Basic Structure

$$\sum_{b \in \mathcal{B}} \sum_{t \in \mathcal{T}} x_{ibt} = 1 \quad \forall i \in I,$$

$$x_{ibt}, u_{bt} \in \{0, 1\} \quad \forall i \in I, b \in \mathcal{B}, t \in \mathcal{T}.$$

Bin use and capacity

$$\sum_{i \in I} w_i x_{ibt} \leq W u_{bt} \quad \forall b \in \mathcal{B}, t \in \mathcal{T}.$$

Precedence Constraints

$$l_{ij} + \sum_{t \in \mathcal{T}} t \cdot \sum_{b \in \mathcal{B}} x_{ibt} \leq \sum_{t \in \mathcal{T}} t \cdot \sum_{b \in \mathcal{B}} x_{jbt} \quad \forall (i, j) \in A.$$

Symmetry-breaking constraints

$$u_{b-1,t} \geq u_{bt} \quad \forall t \in \mathcal{T}, \forall b \in \mathcal{B} \setminus \{1\}.$$

Suitable partitions

Suitable partition

Partition \mathcal{P} of I is **suitable** if graph $G'_{\mathcal{P}} = (I, A \cup A'_{\mathcal{P}})$ has **no cycle of positive length**, where $A'_{\mathcal{P}}$ contains arcs (i, j) with $l_{ij} = 0$ for all $i, j \in P, P \in \mathcal{P}$.

Proposition

Partition \mathcal{P} induces a feasible solution **if and only if**

- ▶ \mathcal{P} contains all items in I
- ▶ \mathcal{P} is a suitable partition.
- ▶ $\sum_{i \in P} w_i \leq W$ for each $P \in \mathcal{P}$.

Distance

d_{ij} — the total lag of the longest directed path from i to j in G .
If no path between i and j in G , $d_{ij} = -\infty$.

Sufficient condition

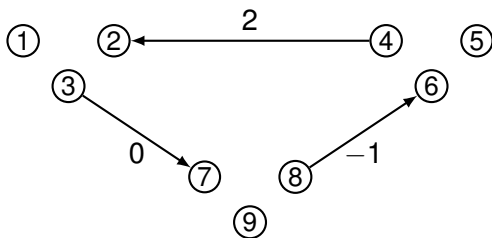
Any partition \mathcal{P} containing set $B \supseteq \{i, j\}$, $d_{ij} > 0$, is non-suitable

Set partitioning formulation

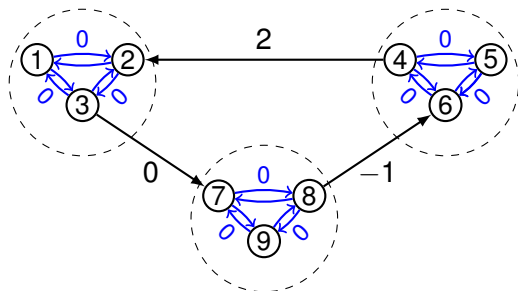
- ▶ \mathcal{B} — set of all items set which can be put to the same bin
- ▶ Variable λ_B , $B \in \mathcal{B}$, — whether set B is put to the same bin
- ▶ $\mathbb{1}_B(i) = 1 \Leftrightarrow i \in B$
- ▶ $\mathcal{N} \subset \mathcal{B}$ — set of **non-suitable** partitions

$$\begin{aligned} \min \quad & \sum_{B \in \mathcal{B}} \lambda_B \\ \text{s.t.} \quad & \sum_{B \in \mathcal{B}} \mathbb{1}_B(i) \lambda_B = 1, & \forall i \in I, \\ & \sum_{B \in \mathcal{P}} \lambda_B \leq |\mathcal{P}| - 1, & \forall \mathcal{P} \in \mathcal{N}, \\ & \lambda_B \in \{0, 1\}, & \forall B \in \mathcal{B}. \end{aligned}$$

Characterising non-suitable partitions

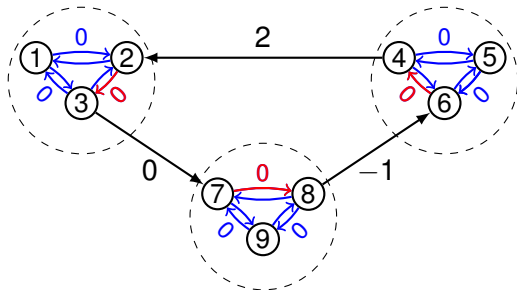


Characterising non-suitable partitions



- ▶ Partition \mathcal{P} is non-suitable \Rightarrow there is a cycle of positive length in graph $G'_\mathcal{P} = (I, A \cup A'_\mathcal{P})$.

Characterising non-suitable partitions



- ▶ Partition \mathcal{P} is non-suitable \Rightarrow there is a cycle of positive length in graph $G'_\mathcal{P} = (I, A \cup A'_\mathcal{P})$.
- ▶ Let $C_\mathcal{P} \subseteq A \cup A'_\mathcal{P}$ be such a cycle, and $F_\mathcal{P} = (C_\mathcal{P} \setminus A) \subseteq A'_\mathcal{P}$ be the set of arcs in the cycle induced by the partition
- ▶ Then constraint $\sum_{B \in \mathcal{P}} \lambda_B \leq |\mathcal{P}| - 1$ can be replaced by

$$\sum_{(i,j) \in F_\mathcal{P}} \sum_{\substack{B \in \mathcal{B}: \\ \{i,j\} \in B}} \lambda_B \leq |F_\mathcal{P}| - 1$$

Pricing problem

- ▶ $\pi_i, i \in I$, — dual values from the set partitioning constraints
- ▶ $\mu_{\mathcal{P}}, \mathcal{P} \in \bar{\mathcal{N}}$, — dual values from the active “suitability” constraints

Binary knapsack problem with hard and soft conflicts

$$\max \sum_{i \in I} \pi_i z_i + \sum_{\mathcal{P} \in \bar{\mathcal{N}}} \sum_{(i,j) \in F_{\mathcal{P}}} \mu_{\mathcal{P}} y_{ij}$$

$$\text{s.t. } \sum_{i \in I} w_i z_i \leq W,$$

$$z_i + z_j \leq 1,$$

$$z_i + z_j \leq 1 + y_{ij},$$

$$z_i \in \{0, 1\},$$

$$y_{ij} \geq 0,$$

$$\forall i, j \in I, d_{ij} > 0,$$

$$\forall \mathcal{P} \in \bar{\mathcal{N}}, \forall (i, j) \in F_{\mathcal{P}},$$

$$\forall i, j \in I.$$

$$\forall \mathcal{P} \in \bar{\mathcal{N}}, \forall (i, j) \in F_{\mathcal{P}}.$$

Solution is using a MIP solver.

Separation of “non-suitability” constraints

Integer solution \mathcal{P}

We search for a positive cycle in $G'_{\mathcal{P}}$ in $O(|I|^2)$ time.

Fractional solution $(\bar{\mathcal{P}}, \bar{\lambda})$

1. We create valued directed graph $\bar{G}'_{\bar{\mathcal{P}}} = (I, A \cup A'_{\bar{\mathcal{P}}})$:

$$v_{ij} = \begin{cases} 1 - \sum_{B \in \bar{\mathcal{P}}: \{i,j\} \in B} \bar{\lambda}_B, & (i,j) \in A'_{\bar{\mathcal{P}}}, \\ 0, & (i,j) \in A. \end{cases}$$

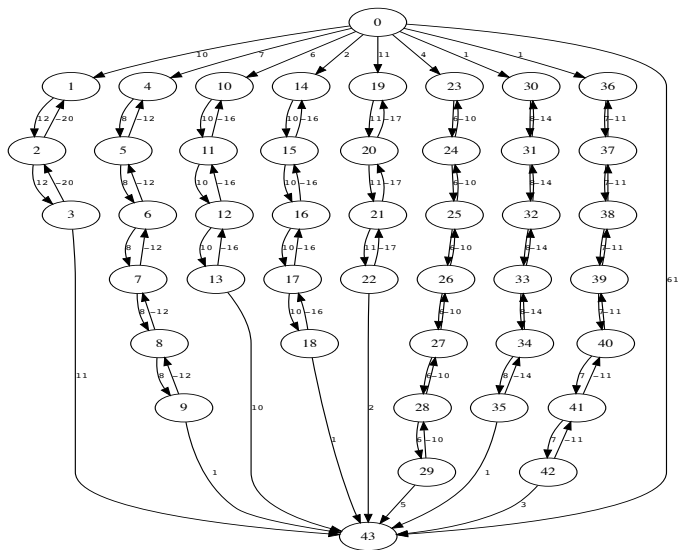
2. We search (by enumeration) in $\bar{G}'_{\bar{\mathcal{P}}}$ for cycles C such that

$$\begin{cases} \sum_{(i,j) \in C} l_{ij} > 0, \\ \sum_{(i,j) \in C} v_{ij} < 1. \end{cases}$$

Other components of the Branch-Cut-and-Price

- ▶ Automatic dual price smoothing **stabilization** [Pessoa et al., 2018]
- ▶ Ryan & Foster branching [Ryan and Foster, 1981]
- ▶ Multi-phase **strong branching** [Pecin et al., 2017]
- ▶ Strong **diving heuristic** with Limited Discrepancy Search [Sadykov et al., 2018]
 - ▶ 10 dives are performed
 - ▶ 10 candidates are evaluated before each fixing
 - ▶ Each time a set of items is fixed, we update the hard conflicts

Structure of test instances



Dimension of test instances

1386 instances

- ▶ Same flexibility (relative interval for the distance between consecutive tasks)
- ▶ Number of time periods $\in \{20, 30, \dots, 110, 120\}$
- ▶ Number of chains $\in \{3, 4, \dots, 9\}$.
- ▶ Average number of items per chain $\in \{5, 6, \dots, 10\}$.
- ▶ Average number of items per bin $\in \{2, 3, 4\}$.
- ▶ As a result, number of items $\in [15, 117]$ with \approx normal distribution.

Main experiment results

Solved to optimality within 3 hours

Method	% Solved
BCP	69.5%
CPLEX 12.8	46.2%

On the set of instances solved by both methods, BCP is **9 times faster** on average

Other experiment results (1)

Percentage of solved instance by number of chains

# of chains	% BCP	% CPLEX
3	100.0%	93.4%
4	98.0%	75.3%
5	83.8%	58.1%
6	65.2%	35.4%
7	55.1%	26.8%
8	43.4%	17.7%
9	40.9%	16.7%

Other experiment results (1)

Percentage of solved instances by number of periods

# of periods	% BCP	% CPLEX
20	72%	67%
30	75%	63%
40	79%	67%
50	75%	53%
60	70%	48%
70	67%	41%
80	66%	34%
90	61%	33%
100	66%	37%
110	67%	35%
120	66%	31%

Perspectives

Ongoing work

- ▶ Support of Chvátal-Gomory rank-1 cuts
- ▶ Custom branch-and-bound algorithm for the pricing problem
- ▶ Tests on the instances of the special cases of the problem

Research directions

- ▶ Limit on the number of bins per period
- ▶ Makespan objective
- ▶ (Flexible) Periodic Vehicle Routing

References I



Becker, C. and Scholl, A. (2006).

A survey on problems and methods in generalized assembly line balancing.

European Journal of Operational Research, 168(3):694 – 715.



Kramer, R., Dell'Amico, M., and Iori, M. (2017).

A batching-move iterated local search algorithm for the bin packing problem with generalized precedence constraints.

International Journal of Production Research, 55(21):6288–6304.



Pecin, D., Pessoa, A., Poggi, M., and Uchoa, E. (2017).

Improved branch-cut-and-price for capacitated vehicle routing.

Mathematical Programming Computation, 9(1):61–100.



Pereira, J. (2016).

Procedures for the bin packing problem with precedence constraints.

European Journal of Operational Research, 250(3):794 – 806.

References II



Pessoa, A., Sadykov, R., Uchoa, E., and Vanderbeck, F. (2018).
Automation and combination of linear-programming based stabilization
techniques in column generation.

INFORMS Journal on Computing, 30(2):339–360.



Ryan, D. M. and Foster, B. A. (1981).

An integer programming approach to scheduling.

In Wren, A., editor, *Computer Scheduling of Public Transport Urban
Passenger Vehicle and Crew Scheduling*, pages 269 – 280.

North-Holland, Amsterdam.



Sadykov, R., Vanderbeck, F., Pessoa, A., Tahiri, I., and Uchoa, E.
(2018).

Primal heuristics for branch-and-price: the assets of diving methods.

INFORMS Journal on Computing, (Forthcoming).