



On the cross-sectional distribution of portfolio returns

Ludovic Calès, Apostolos Chalkis, Ioannis Z. Emiris

► **To cite this version:**

Ludovic Calès, Apostolos Chalkis, Ioannis Z. Emiris. On the cross-sectional distribution of portfolio returns. [Research Report] EU publications. 2019. hal-02398730

HAL Id: hal-02398730

<https://hal.inria.fr/hal-02398730>

Submitted on 9 Dec 2019

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

On the cross-sectional distribution of portfolio returns*

Ludovic Calès¹, Apostolos Chalkis², and Ioannis Z. Emiris^{2,3}

¹European Commission, Joint Research Centre, Ispra, Italy

²Department of Informatics & Telecommunications

National and Kapodistrian University of Athens, Greece

³ATHENA Research Center, Maroussi, Greece

November 19, 2019

Abstract

The aim of this paper is to study the distribution of portfolio returns across portfolios, and for given asset returns. We focus on the most common type of investment, considering portfolios whose weights are non-negative and sum up to 1. We provide algorithms and formulas from computational geometry and the literature on splines to compute the exact values of the probability density function, and of the cumulative distribution function, at any point. We also provide closed form solutions for the computation of its first four moments, and an algorithm to compute the higher moments. All algorithms and formulas allow for equal asset returns.

Keywords: Cross-section of portfolios, Finance, Geometry, B-spline

1 Introduction

The study of the distribution of portfolio returns, across portfolios and for given asset returns, has attracted less attention than it deserves in the finance

*The views expressed are those of the authors and do not necessarily reflect official positions of the European Commission.

literature. However it is a natural tool to understand the relative performance of portfolios, as well as the behavior of asset cross-section and market dynamics in general. Indeed, consider an investment set defined as the set of portfolios in which a manager can invest. The most common is such that the portfolio weights are non-negative and sum up to 1.¹ Let us define the score of a portfolio as the percentage of portfolios, within the investment set, that this portfolio outperforms. For instance, in a market of 3 assets whose returns are 0%, 1% and 1.5%, the score of a portfolio as a function of its return is as given in Figure 1. Here, a portfolio whose return is 0.866% outperforms 50% of the portfolios.

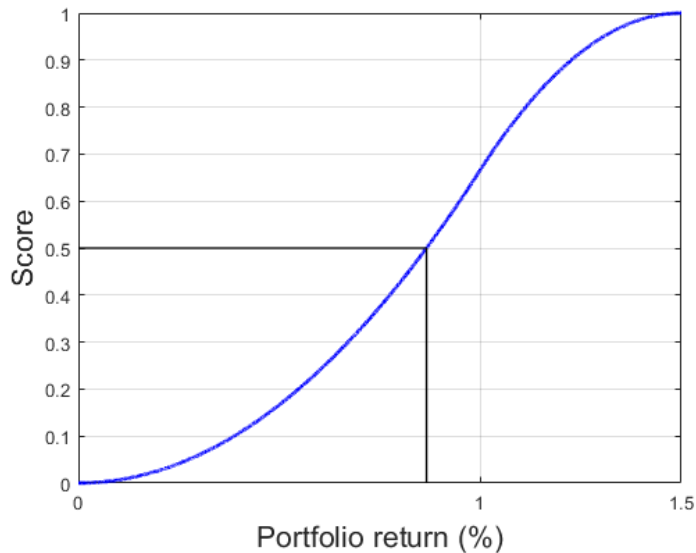


Figure 1: Score of a long-only portfolio in a market of 3 assets whose returns are 0%, 1%, and 1.5%.

This portfolio score has been introduced in [Pouchkarev, 2005] and has been used in related studies by the same author. In [Pouchkarev, 2005, Pouchkarev et al., 2004, Hallerbach et al., 2002], the relative performance of value-weighted indices with respect to long-only portfolios is assessed in the Dutch, Spanish and German markets². It leads the authors to question the representativeness of these indices. In [Hallerbach and Pouchkarev, 2005, Hallerbach and Pouchkarev, 2016], the dispersion of the cross-sectional portfolio returns is used to assess the performance of asset managers whose mandate implies tracking error volatility constraints. This score has also been proposed

¹It corresponds to the long-only strategy.

²considering the MSCI Netherlands 24, IBEX 35, and DAX 30 components, respectively.

independently in [Billio et al., 2011], and in [Banerjee and Hung, 2011]. In [Billio et al., 2011], this score is used as a portfolio performance measure whose informativeness is shown to be higher than the Sharpe and the Sortino ratios in an asset allocation exercise. In [Banerjee and Hung, 2011], a simplified score assigning a reward ranging from -2 to 2 according to the quintile of the score is used to assess the performance of the momentum strategy. This investment strategy is shown to not be outperforming an uninformed naive investor. Recently, in [Calès et al., 2018], the score is used to study the time-varying dependency of portfolios' return and volatility, and relates this dependency to periods of financial turmoils.

In terms of computation, [Pouchkarev, 2005, Theorem 4.2.2] proposes a geometry-based closed form expression of the score. It consists in representing the long only investment set as a simplex. The score is then the volume of the intersection of the simplex and a linear half-space. It is computed by decomposing this intersection in smaller simplices. Following this approach, the score of a portfolio whose return is R , in a market of n assets whose returns are $(R_i)_{i=1}^n$, can be computed as in Equation (1):

$$\text{Score}(R) = \sum_{R_k \leq R} \left((R - R_k)^{n-1} \prod_{i=1, i \neq k}^n \frac{1}{R_i - R_k} \right). \quad (1)$$

However, this computation is not valid when some asset returns are equal and it presents floating point errors limiting its use to around 20 assets. As a consequence, in [Pouchkarev, 2005] and in related studies, the score is estimated by a quasi-Monte Carlo sampling of the portfolios as described in [Rubinstein and Melamed, 1998]. In [Banerjee and Hung, 2011, Thm A2], the same approach is considered,³ for illustration purposes only, and the authors also rely on portfolio sampling for their application. In [Billio et al., 2011], the set of portfolios considered is the specific set of long/short equally weighted zero-dollar portfolios. The estimation of the score relies on combinatorics and order statistics, and it is computationally limited to around 20 assets. Finally, in [Calès et al., 2018], the score is also computed as the volume of the intersection of the simplex and a linear half-space. The authors noticed that an algorithm by [Varsi, 1973] can be used to compute this volume exactly and efficiently for any number of assets, even when some asset returns are equal.

In this paper, we intend to characterize statistically the distribution of the portfolios' returns, the score being its cumulative distribution function

³Note that the formula proposed contains a couple of mistakes: the sum is over the number of assets whose returns are lower than the return of the portfolio considered, and the term within parentheses in the numerator should be the opposite.

(CDF). We provide algorithms and formulas to compute exactly its CDF, its probability density function (PDF) and its moments. We consider the most common investment set, i.e. the set of portfolios whose weights are non-negative and sum up to 1. In Section 2, we formalize the representation of this set as a unit simplex. The portfolios considered are then uniformly distributed over this simplex, allowing us to integrate over it, later on.

In Section 3, we first recall the computation of the CDF as proposed in [Calès et al., 2018]. The set of portfolios having the same return is a hyperplane, hence the question consists in computing the volume of the intersection of a simplex and a linear half-space. Based on equivalent results by [Varsi, 1973] using a geometric approach, and [Ali, 1973] with a divided differences approach, the algorithm consists in a recurrence formula. We also propose its computation with a closed form formula by [Lasserre, 2015] and [Calès, 2019], which includes the case of equal asset returns, as opposed to [Pouchkarev, 2005] and [Banerjee and Hung, 2011], whose Equation (1) precludes equality among returns.

In Section 4, we compute exactly the PDF. The first approach is based on the geometric interpretation of univariate B-splines by [Curry and Schoenberg, 1966], and it uses the de Boor-Cox recursive formula, see [de Boor, 1972] and [Cox, 1972]. The second approach is a direct derivation of the CDF, obtained using the closed form formula by [Lasserre, 2015]. Finally, since both of these approaches suffer from numerical instability in high dimensions, we propose to derive it numerically from Varsi’s results.

In Section 5, we derive the moments of the distribution. Our method is based on a result by [Lasserre and Avrachenkov, 2001] which provides an elegant way to integrate symmetric q -linear forms on a simplex. It allows us to propose closed form solutions for the first four moments, and an algorithm to compute higher moments.

We conclude with an overall discussion and open questions. The Annexes contain some mathematical proofs.

2 Geometric representation of the set of portfolios

In this section we formalize the geometric representation of sets of portfolios with an arbitrary number of assets.

Let us consider a portfolio x investing in n assets, whose weights are $x = (x_1, \dots, x_n)$. The portfolios in which a long-only asset manager can invest are subject to $\sum_{i=1}^n x_i = 1$ and $x_i \geq 0, \forall i$. Thus, the set of portfolios

available to this asset manager is the unit $(n - 1)$ -dimensional simplex, denoted by Δ^{n-1} and defined as

$$\Delta^{n-1} = \left\{ \sum_{i=1}^n x_i v_i \mid (x_1, \dots, x_n) \in \mathbb{R}^n, \sum_{i=1}^n x_i = 1, \text{ and } x_i \geq 0, \forall i \in \{1, \dots, n\} \right\}, \quad (2)$$

where $v_1, \dots, v_n \in \mathbb{R}^{n-1}$ are a set of n affinely independent points in a Euclidean space of dimension $n - 1$. The vertices $(v_i)_{i=1, \dots, n}$ represent the n portfolios made of a single asset and the simplex is the convex hull of these vertices.

For instance, we can define v_1, \dots, v_n such that:

1. the center of the simplex is set to the origin,
2. the distances of the simplex vertices to its center are equal,
3. the angle subtended by any two vertices through its center is $\arccos(\frac{-1}{n-1})$.

The weights $(x_i)_{i=1, \dots, n}$ of portfolio x are called its barycentric coordinates, whereas the corresponding coordinates in \mathbb{R}^{n-1} are called its Cartesian coordinates, and are denoted by $\check{x} = (\check{x}_1, \dots, \check{x}_{n-1})$. We use the Cartesian coordinates in Section 5 to compute the moments of the portfolios' returns distribution.

3 The CDF of the portfolios' returns distribution

In this section we focus on the exact computation of the cumulative distribution function (CDF) of the portfolio returns, given the asset returns. Let us consider the set of long-only portfolios providing a return lower than a given return R^* over a period of time for which the asset returns were $\mathbf{R} = (R_1, \dots, R_n)$. It corresponds to a linear half-space defined as

$$H(R^*) = \left\{ (x_1, \dots, x_n) \in \mathbb{R}^n \mid \sum_{i=1}^n R_i x_i \leq R^* \right\}. \quad (3)$$

Denoting by $V(A)$ the Euclidean volume of a geometric object A , the allocation score of a portfolio providing a return R^* can be obtained by computing the

ratio of the volume of the intersection of the simplex with this half-space over the volume of the simplex, i.e.

$$S(R^*) = \frac{V(H(R^*) \cap \Delta^{n-1})}{V(\Delta^{n-1})}. \quad (4)$$

We illustrate such a volume in Figure 2. Consider a market of 4 assets whose returns are observed, and a portfolio providing a given return R^* . The pyramid is the simplex representing the set of long-only portfolios. The surface highlighted in the left figure represents the set of portfolios returning R^* . The volume highlighted in the right figure represents the set of portfolios providing a return lower or equal to R^* .

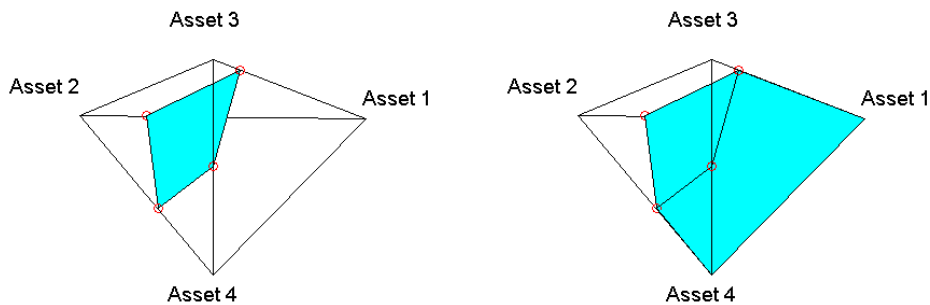


Figure 2: (left) Surface of portfolios providing this given return. (right) Volume of portfolios outperformed by this return.

3.1 Varsi's algorithm

As noticed in [Calès et al., 2018], there exists an exact, iterative formula for the volume defined by intersecting a simplex with a half-space. It is provided in Algorithm 1. A geometric proof is given in [Varsi, 1973], by subdividing the polytope into pyramids and, recursively, to simplices. For a comparison between alternative proofs and algorithms, the reader may refer to [Calès et al., 2018] and the references thereof.

Algorithm 1. *Let $H = \{(\omega_1, \dots, \omega_n) \mid \sum_{i=1}^n R_i \omega_i \leq R^*\}$ be a linear half-space.*

1. Compute $u_i = R_i - R^*$, $i = 1, 2, \dots, n$.

2. Label the non-negative u_j as Y_1, \dots, Y_K , and the negative ones as X_1, \dots, X_J .
3. Initialize $A_0 = 1$, $A_1 = A_2 = \dots = A_K = 0$.
4. For $j = 1, 2, \dots, J$, repeat: $A_k \leftarrow \frac{Y_k A_k - X_j A_{k-1}}{Y_k - X_j}$, for $k = 1, 2, \dots, K$.

Then, at the last iteration $j = J$, it holds that

$$A_K = \frac{V(H(R^*) \cap \Delta_{n-1})}{V(\Delta_{n-1})}.$$

Notice that $K + J = n$.

This algorithm requires $O(n^2)$ operations, and thus can be computed very quickly. As an illustration, we compute the score of a portfolio, whose return is $R^* = 0$, in markets of 100, 1000 and 10,000 assets whose returns are randomly drawn from a standard normal distribution. The computation is repeated 1000 times. We report in Table 1 the average computation time and its standard deviation.

Number of Assets	100	1000	10,000
Mean computation time	5.89e-5	3.63e-3	0.4734
Standard deviation	1.99e-4	1.79e-4	0.0416

Table 1: Mean computation time in seconds and standard deviation of computing the CDF at a point for markets of 100, 1000 and 10,000 assets. The computations were performed using Matlab© on a bi-xeon E2620 v3 under Windows©.

To illustrate the CDF obtained using Algorithm 1, let us consider a market of 10 assets whose returns are as in Table 2 and let R^* denote a portfolio return. The CDF of the portfolios returns for any given return is reported in Figure 3. With these asset returns, 10% of the portfolios have a negative return and a bit more than 20% of the portfolios have a return greater than 1%.

R_1	R_2	R_3	R_4	R_5
0.5377%	1.8339%	-2.2588%	0.8622%	0.3188%
R_6	R_7	R_8	R_9	R_{10}
-1.3077%	-0.4336%	0.3426%	3.5784%	2.7694%

Table 2: Some asset returns.

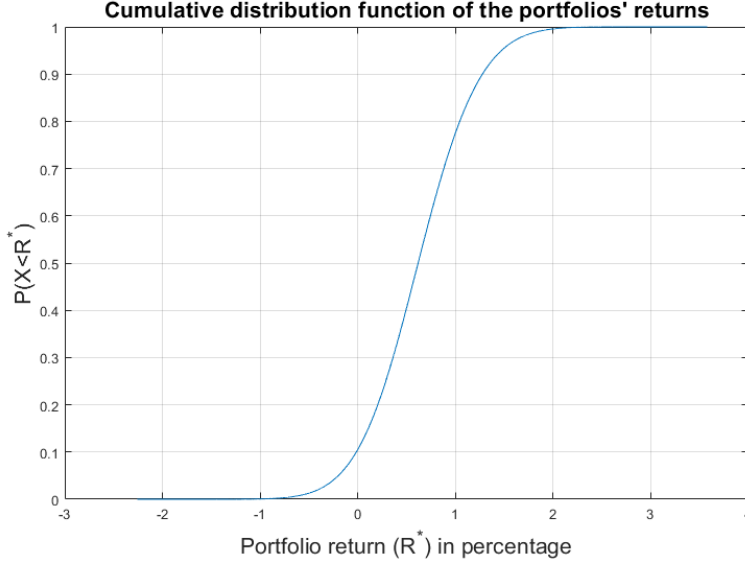


Figure 3: Illustration of the CDF of the portfolios returns.

3.2 Closed form expression

In [Lasserre, 2015], a closed form formula is proposed to compute this volume taking into account the case of equal asset returns. However, it missed some extra terms and has been corrected in [Calès, 2019]. We report it here, adapted to our notation: Let $\mathbf{R} = (R_i)_{i=1}^n$ be the asset returns, $(S_i)_{i=1}^d$ the d distinct returns, where $d \leq n$, and $(m_i)_{i=1}^d$ their multiplicities (i.e. number of occurrences). We denote by $(J_i)_{i=1}^d$ the subsets of indices in $\{1, \dots, n\}$ associated to each S_i and,

$$\text{for } j = 1, \dots, d, \text{ we let } \mathbf{b}_j = \left(\frac{1}{R_i - S_j} \right)_{i \in \{1, \dots, n\} \setminus J_j}.$$

Among the distinct returns we distinguish between those whose multiplicities are 1, and those whose multiplicities are greater than 1. The indices of the first group form a set denoted by I , while those of the second group form set K , where $S = I \cup K$. Finally, $(x)_+$ stands for $\max\{0, x\}$. The CDF computed in R^* is given by:

$$S(R^*, \mathbf{R}) = \sum_{i \in I} \frac{(R^* - S_i)_+^{n-1}}{\prod_{j=1, j \neq i}^n (S_j - S_i)} + \sum_{i \in K} \left(\sum_{j=0}^{m_i-1} (-1)^{j+m_i+1} \binom{n-1}{j} \frac{(R^* - S_i)_+^{n-j-1}}{\prod_{k \in S \setminus \{S_i\}} (S_k - S_i)} \Phi_{m_i-1-j}(\mathbf{b}_i) \right), \quad (5)$$

where

$$\Phi_k(x) = \sum_{i_1=1}^n \sum_{i_2=1}^{i_1} \cdots \sum_{i_k=1}^{i_{k-1}} x_{i_1} \cdots x_{i_k}, \mathbf{x} \in \mathbb{R}^n.$$

This formula is similar to the one proposed in [Pouchkarev, 2005, Thm 4.2.2] and [Banerjee and Hung, 2011, Thm A2], but with extra terms correcting for the equal asset returns. Unfortunately, when it comes to calculations, the formula becomes numerically unstable for $n \geq 20$ at the usual machine precision.

To illustrate the computation times, we consider markets of 10 and 20 assets whose returns \mathbf{R} are randomly drawn from a standard normal distribution. We report in Table 3 the average computation time and its standard deviation when we compute the PDF of the portfolio returns at the cross-sectional average of the asset returns, i.e. $R^* = \bar{R}$. The computation is repeated 1000 times.

Number of Assets	10	20
Mean computation time	3.34e-4	5.92e-4
Standard deviation	3.31e-5	4.62e-5

Table 3: Mean computation time in seconds and standard deviation of computing the PDF at a point for markets of 10 and 20 assets. The computations were performed using Matlab© on a bi-xeon E2620 v3 under Windows©.

3.3 Properties of the score

As noticed in [Banerjee and Hung, 2011], the score is invariant under some linear transformation of the asset returns. To see this, let us consider a market of n assets providing the returns $\mathbf{R} = (R_i)_{i=1}^n$. We are interested in the score of a portfolio $\mathbf{x} = (x_i)_{i=1}^n$ providing a return $R^* = \mathbf{x}'\mathbf{R}$, where \mathbf{x}' stands for the transpose vector. As explained before, this score is the volume of simplex Δ^{n-1} intersected with half-space $H(R^*)$ as in Equation (3). So, it is

$$S(R^*|\mathbf{R}) = \left\{ \mathbf{x} \in \Delta^{n-1} \mid \sum_{i=1}^n R_i x_i \leq R^* \right\}. \quad (6)$$

Property 1. *The score is invariant under linear transformations of the asset returns such that $\mathbf{R} \rightarrow \sigma\mathbf{R} + \alpha$, with $\alpha \in \mathbb{R}$ and $\sigma \in \mathbb{R}^+$.*

Proof.

$$\begin{aligned}
S(\sigma R^* + \alpha | \sigma \mathbf{R} + \alpha) &= \left\{ \mathbf{x} \in \Delta^{n-1} \mid \sum_{i=1}^n (\sigma R_i + \alpha) x_i \leq \sigma R^* + \alpha \right\} \\
&= \left\{ \mathbf{x} \in \Delta^{n-1} \mid \sigma \sum_{i=1}^n R_i x_i + \alpha \leq \sigma R^* + \alpha \right\} \\
&= \left\{ \mathbf{x} \in \Delta^{n-1} \mid \sigma \sum_{i=1}^n R_i x_i \leq \sigma R^* \right\} \\
&= S(R^* | \mathbf{R}).
\end{aligned}$$

The main implication of this property is that the asset returns can be standardized cross-sectionally without affecting the score. It is interesting to note that such a transformation is common in financial event studies, since the seminal work of [Boehmer et al., 1991]. This approach has the advantages of being robust to event-induced heteroskedasticity and of not requiring data from a pre-event estimation period.

4 The PDF of the portfolios' returns distribution

In this section we focus on the exact computation of the probability density function (PDF) of the portfolios' returns distribution.

4.1 Geometric interpretation of B-splines

In [Curry and Schoenberg, 1966], a seminal paper on splines, Theorem 2 shows that the univariate B-spline resulting from the orthogonal projection of the volumetric slices of a unit simplex on \mathbb{R} can be interpreted as the PDF of these slices' volume. For instance, in Figure 4, we have the projections of the areas of the intersection of planes with the 3-d simplex on the real line. In our case, the simplex is the set of portfolios, while the planes are the equi-return portfolios. The resulting univariate B-spline is the PDF of the portfolio returns. For any value, it can be computed using the de Boor-Cox recursion formula, see [de Boor, 1972] and [Cox, 1972], as shown in Algorithm 2.

Algorithm 2. Let $\mathbf{R} = (R_i)_{i=1}^n$ be the returns of the n assets, ordered such that $R_i \leq R_j$, for $i < j$. To evaluate the PDF at x , we set the initial iterator

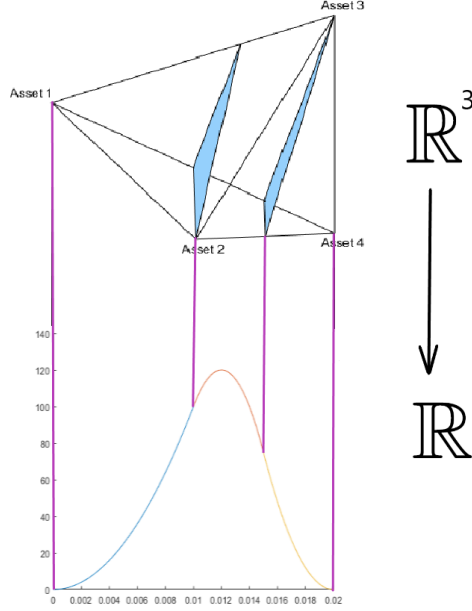


Figure 4: Geometric interpretation of the PDF of the portfolio returns: a univariate B-spline, as the orthogonal projection of the volumetric slices of a unit simplex on \mathbb{R} . In this example, we have 4 assets whose returns are 0%, 1%, 1.5%, and 2%.

of the spline order m to 0, the B-spline order k to $n - 1$ and the knot vector to \mathbf{R} . Next, we execute $y = \text{bspline_pdf}(m = 0, k = n - 1, \mathbf{R}, x)$, where function $\text{bspline_pdf}(\cdot)$ is specified below. The outcome is then normalized such that $y \leftarrow \frac{k}{R_n - R_1} y$.

function $y = \text{bspline_pdf}(m, k, \mathbf{R}, x)$

1. $y = 0$

2. if $k > 1$ then

(a) $b = \text{bspline_pdf}(m, k - 1, \mathbf{R}, x)$;

(b) if $R_{m+k} \neq R_{m+1}$, then $y \leftarrow y + b \left(\frac{x - R_{m+1}}{R_{m+k} - R_{m+1}} \right)$

(c) $b = \text{bspline_pdf}(m + 1, k - 1, \mathbf{R}, x)$;

(d) if $R_{m+k+1} \neq R_{m+2}$, then **return** $y \leftarrow y + b \left(\frac{R_{m+k+1} - x}{R_{m+k+1} - R_{m+2}} \right)$

3. elseif $R_{m+1} \leq x$

(a) if $R_{m+2} < R_n$ and $x < R_{m+2}$, then **return** $y \leftarrow 1$, else **return** $y \leftarrow 0$

4. else

(a) if $R_{m+1} \leq x$ and $R_{m+2} > R_n$, then **return** $y \leftarrow 1$, else **return** $y \leftarrow 0$

As an illustration, let us consider the previous example with 10 assets. Using Algorithm 2, we compute the PDF of the portfolios' returns and report it in Figure 5. In this example, we observe that the distribution is uni-modal with most portfolios having a return close to 0.6%.

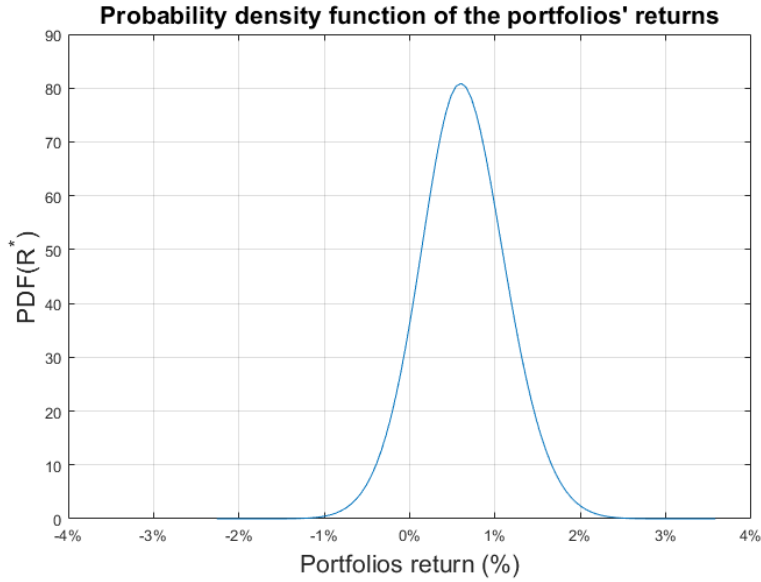


Figure 5: Illustration of the PDF of the portfolios returns.

Regarding the computation time, we consider markets of 10 and 20 assets whose returns are randomly drawn from a standard normal distribution. We report in Table 4 the average computation time and its standard deviation when we compute the PDF of the portfolio returns at the cross-sectional average of the asset returns, i.e. $R^* = \bar{R}$. The computation is repeated 1000 times.

It shall be noted that the high computation time prevents its use when the number of assets is above 20 roughly.

Number of Assets	10	20
Mean computation time	2.91e-4	0.3050
Standard deviation	2.65e-5	0.0122

Table 4: Mean computation time in seconds and standard deviation of computing the PDF at a point for markets of 10 and 20 assets. The computations were performed using Matlab© on a bi-xeon E2620 v3 under Windows©.

4.2 Closed form expression

It is straightforward to get the PDF by deriving Equation (5). Using the same notation as in Section 3.2, this leads to the following closed form formula for the PDF:

$$\begin{aligned}
f(R^*, \mathbf{R}) &= (n-1) \sum_{i \in I} \frac{(R^* - S_i)_+^{n-2}}{\prod_{j=1, j \neq i}^n (S_j - S_i)} + \\
&+ \sum_{i \in K} \left(\sum_{j=0}^{m_i-1} (-1)^{j+m_i+1} (n-j-1) \binom{n-1}{j} \frac{(R^* - S_i)_+^{n-j-2}}{\prod_{k \in S \setminus \{S_i\}} (S_k - S_i)} \Phi_{m_i-1-j}(\mathbf{b}_i) \right).
\end{aligned} \tag{7}$$

Its computation suffers from the same drawback as the computation of the CDF, providing numerically unstable results for $n \geq 20$ at the usual machine precision.

4.3 Numerical derivation

The iterative nature of the de Boor-Cox formula makes the computation of the PDF slow for large number of assets, say ≥ 20 , and its computation using the closed form formula above is numerically unstable for $n \geq 20$. So, an alternative is to approximate the PDF by deriving numerically the CDF obtained earlier, using Varsi's algorithm, by finite differences.

Let F be the CDF and x_0 the point in which we wish to estimate its derivative. One may employ central differences and the five points' method, thus having

$$F'(x_0) = \frac{-F(x_0 + 2h) + 8F(x_0 + h) - 8F(x_0 - h) + F(x_0 - 2h)}{12h} + \frac{h^4}{30} F^{(5)}(c), \tag{8}$$

with $c \in [x_0 - 2h, x_0 + 2h]$. The truncation error is then $O(h^4)$. Even though it is only an estimate of the PDF, this approach enables us to scale up to thousands of assets with computation times being 5 times higher than those reported in Table 1 for an estimate at a single point with the 5-points method.

We note that one may approximate the PDF with arbitrarily small error by using higher order differences.

5 Moments of the portfolios' returns distribution

In this section, we compute the moments of the portfolios returns. In Section 5.1, we provide affine maps to pass from barycentric to Cartesian coordinates, and vice-versa. In Section 5.2, we state the moments' definitions in Cartesian coordinates. In Section 5.3, we recall a theorem proposed in [Lasserre and Avrachenkov, 2001] which provides an elegant expression for the integral of a symmetric q -linear form on a simplex. In Section 5.4, since the theorem makes use of nested sums, we provide identities for some of these nested sums. In Section 5.5, we compute the individual terms that make up the moments up to the fourth one. In Section 5.6, we provide the closed form solution of the first four moments. Finally, in Section 5.7, we propose a general algorithm to compute any moment.

5.1 Barycentric and Cartesian representations

There are affine maps to pass

- from barycentric to Cartesian coordinates:

$$\begin{aligned} m_{bc} : \mathbb{R}^n &\rightarrow \mathbb{R}^{n-1}, \\ x &\mapsto \check{x} = T\tilde{x} + v_n, \end{aligned} \quad (9)$$

where $\tilde{x} = (x_i)_{i=1,\dots,n-1}$, the simplex vertices v_i are expressed in Cartesian coordinates, i.e. $(n-1)$ -dimensional column vectors, and $T = [v_1 - v_n, \dots, v_{n-1} - v_n]$ is an $(n-1) \times (n-1)$ matrix.

- from Cartesian to barycentric coordinates:

$$\begin{aligned} m_{cb} : \mathbb{R}^{n-1} &\rightarrow \mathbb{R}^n, \\ \check{x} &\mapsto x = \begin{bmatrix} I_{n-1} \\ -1'_{n-1} \end{bmatrix} T^{-1}(\check{x} - v_n) + \begin{bmatrix} 0_{n-1} \\ 1 \end{bmatrix}, \end{aligned} \quad (10)$$

where 0_{n-1} and -1_{n-1} are the $(n-1)$ -dimensional column vectors of 0's and -1 's, respectively, I_{n-1} is the $(n-1) \times (n-1)$ identity matrix.

For individual asset returns $\mathbf{R} = (R_1, \dots, R_n)$, the return of portfolio x is then given by:

$$R'x = A\check{x} - Av_n + R_n, \quad (11)$$

where $A = R' \begin{bmatrix} I_{n-1} \\ -1'_{n-1} \end{bmatrix} T^{-1}$.

5.2 Moments

By definition, the moments of the portfolio returns distribution are given as follows, where $V(\cdot)$ denotes volume:

$$M_1 = \frac{1}{V(\Delta^{n-1})} \int_{\Delta^{n-1}} A\check{x} - Av_n + R_n d\check{x}, \quad (12)$$

$$M_2 = \frac{1}{V(\Delta^{n-1})} \int_{\Delta^{n-1}} (A\check{x} - Av_n + R_n - M_1)^2 d\check{x},$$

$$M_k = \frac{1}{V(\Delta^{n-1}) (\sqrt{M_2})^k} \int_{\Delta^{n-1}} (A\check{x} - Av_n + R_n - M_1)^k d\check{x}, \quad k \geq 3,$$

where the term $\frac{1}{V(\Delta^{n-1})}$ is normalizing the equations. Indeed, the distance between the vertices v_i is arbitrary, and so is the volume of Δ^{n-1} . An alternative is to choose the distance between the vertices v_i such that $V(\Delta^{n-1}) = 1$. Note that by construction we have $V(\Delta^{n-1}) = \int_{\Delta^{n-1}} 1 d\check{x}$.

5.3 Integrating over Δ^{n-1}

From [Lasserre and Avrachenkov, 2001], and slightly adapted to our notation, we have the following

Theorem 2. *Let v_1, \dots, v_n be the vertices of an $(n-1)$ -dimensional simplex Δ^{n-1} . Then, for a symmetric q -linear form $H : (\mathbb{R}^{n-1})^q \rightarrow \mathbb{R}$, we have*

$$\int_{\Delta^{n-1}} H(X, \dots, X) d\check{x} = \frac{V(\Delta^{n-1})}{\binom{n-1+q}{q}} \sum_{1 \leq i_1 \leq i_2 \leq \dots \leq i_q \leq n} H(v_{i_1}, v_{i_2}, \dots, v_{i_q}), \quad (13)$$

5.4 Nested sum identities

Since Theorem 2 makes use of nested sums, we shall employ the following identities:

Lemma 3. For $n \in \mathbf{N}$, it holds

$$2 \sum_{i=1}^n \sum_{j=i}^n x_i x_j = \left(\sum_{i=1}^n x_i \right)^2 + \sum_{i=1}^n x_i^2. \quad (14)$$

Proof. Straightforward.

Lemma 4. For $n \in \mathbf{N}$, it holds

$$(3!) \sum_{i=1}^n \sum_{j=i}^n \sum_{k=j}^n x_i x_j x_k = \left(\sum_{i=1}^n x_i \right)^3 + 3 \left(\sum_{i=1}^n x_i \right) \left(\sum_{i=1}^n x_i^2 \right) + 2 \sum_{i=1}^n x_i^3.$$

See proof in Annex A.

Lemma 5. For $n \in \mathbf{N}$, it holds

$$(4!) \sum_{i=1}^n \sum_{j=i}^n \sum_{k=j}^n \sum_{t=k}^n x_i x_j x_k x_t = \\ = \left(\sum_{i=1}^n x_i \right)^4 + 6 \left(\sum_{i=1}^n x_i \right)^2 \left(\sum_{i=1}^n x_i^2 \right) + 8 \left(\sum_{i=1}^n x_i \right) \left(\sum_{i=1}^n x_i^3 \right) + 6 \left(\sum_{i=1}^n x_i^4 \right) + 3 \left(\sum_{i=1}^n x_i^2 \right)^2.$$

See proof in Annex B.

5.5 Expression of moments' individual terms

First, let note that we have the following identity by construction:

Lemma 6. For $n \in \mathbf{N}$, vertices $(v_i)_{i=1}^n$, and matrix A as defined previously, it holds

$$\sum_{i=1}^n A v_i = A \sum_{i=1}^n v_i = 0. \quad (15)$$

As we shall see in Section 5.6, the moments can be expressed in terms of $\int_{\Delta^{n-1}} (A\check{x})^p d\check{x}$ with $p \in \mathbf{N}$. So, to compute the first four moments, we compute this term for $p \in \{1, 2, 3, 4\}$.

Lemma 7. For $n \in \mathbf{N}$, it holds

$$\int_{\Delta^{n-1}} A\check{x} d\check{x} = 0. \quad (16)$$

Proof. Apply Theorem 2, with $q = 1$ and $H(\check{x}_1) = A\check{x}_1$, then it suffices to recall Lemma 6.

Lemma 8. For $n \in \mathbf{N}$, it holds

$$\int_{\Delta^{n-1}} (A\check{x})^2 d\check{x} = \frac{V(\Delta^{n-1})}{n(n+1)} \sum_{i=1}^n (Av_i)^2. \quad (17)$$

Proof. Apply Theorem 2, with $q = 2$ and $H(\check{x}_1, \check{x}_2) = (A\check{x}_1)(A\check{x}_2)$, by replacing the nested sum in the theorem as in Lemma 3, then it suffices to recall Lemma 6.

Lemma 9. For $n \in \mathbf{N}$, it holds

$$\int_{\Delta^{n-1}} (A\check{x})^3 d\check{x} = \frac{2V(\Delta^{n-1})}{n(n+1)(n+2)} \sum_{i=1}^n (Av_i)^3. \quad (18)$$

Proof. Apply Theorem 2, with $q = 3$, and $H(\check{x}_1, \check{y}_2, \check{y}_3) = (A\check{x}_1)(A\check{x}_2)(A\check{x}_3)$, by replacing the nested sum in the theorem as in Lemma 4, then it suffices to recall Lemma 6.

Lemma 10. For $n \in \mathbf{N}$, it holds

$$\int_{\Delta^{n-1}} (A\check{x})^4 d\check{x} = \frac{V(\Delta^{n-1})}{n(n+1)(n+2)(n+3)} \left(6 \left(\sum_{i=1}^n (Av_i)^4 \right) + 3 \left(\sum_{i=1}^n (Av_i)^2 \right)^2 \right).$$

Proof. Apply Theorem 2, with $q = 4$, and $H(\check{x}_1, \check{y}_2, \check{y}_3, \check{y}_4) = (A\check{x}_1)(A\check{x}_2)(A\check{x}_3)(A\check{x}_4)$, replacing the nested sum in the theorem as in Lemma 5, then it suffices to recall Lemma 6.

5.6 Closed form expression of the first four moments

In this section, we derive the closed form expressions for the first four moments, reported in Theorems 12 to 17, respectively.

First, let note that by construction we have the identity:

Lemma 11. For $n \in \mathbf{N}$, $(R_i)_{i=1}^n$, $(v_i)_{i=1}^n$, and A as defined previously, it holds

$$R_i = Av_i - Av_n + R_n, \quad i \in \{1, \dots, n\}. \quad (19)$$

Next, we show that the first moment of the portfolio returns distribution is equal to the first moment of asset returns as stated in Theorem 12.

Theorem 12. In a market of n assets, $n \in \mathbf{N}$, whose returns are $\mathbf{R} = (R_i)_{i=1}^n$, the first moment of the portfolios' returns is

$$M_1 = \frac{1}{n} \sum_{i=1}^n R_i. \quad (20)$$

Proof. Develop M_1 in Equation 12 and simplify it using Lemma 7, then apply Lemma 11.

From Theorem 12 and Lemma 11, we get the identity:

Lemma 13. For $n \in \mathbf{N}$, $(R_i)_{i=1}^n$, $(v_i)_{i=1}^n$, A and M_1 as defined previously, it holds

$$M_1 = R_n - Av_n. \quad (21)$$

It follows that, by employing Lemma 13, M_2 and M_k simplify to

$$M_2 = \frac{1}{V(\Delta^{n-1})} \int_{\Delta^{n-1}} (A\check{x})^2 d\check{x}, \quad (22)$$

$$M_k = \frac{1}{V(\Delta^{n-1})(\sqrt{M_2})^k} \int_{\Delta^{n-1}} (A\check{x})^k d\check{x}, \quad k \geq 3. \quad (23)$$

From Lemma 11 and Lemma 13, we have

Lemma 14. For $n \in \mathbf{N}$, $(R_i)_{i=1}^n$, $(v_i)_{i=1}^n$, A and M_1 as defined previously, it holds

$$Av_i = R_i - M_1. \quad (24)$$

which is used to compute the second, third and fourth moments as stated in Theorems 15 to 17

Theorem 15. In a market of n assets, $n \in \mathbf{N}$, whose returns are $\mathbf{R} = (R_i)_{i=1}^n$, the second moment of the portfolios' returns is

$$M_2 = \frac{1}{n(n+1)} \sum_{i=1}^n (R_i - M_1)^2 = \frac{1}{n+1} \text{Var}(\mathbf{R}), \quad (25)$$

where $\text{Var}(\mathbf{R}) = \frac{1}{n} \sum_{i=1}^n (R_i - M_1)^2$ is the (biased) sample variance of the asset returns.

Proof. Replace $\int_{\Delta^{n-1}} (A\check{x})^2 d\check{x}$ in Equation (22) by the expression from Lemma 8, then apply Lemma 14.

Theorem 16. In a market of n assets, $n \in \mathbf{N}$, whose returns are $\mathbf{R} = (R_i)_{i=1}^n$, the third moment of the portfolios' returns is

$$M_3 = \frac{1}{M_2^{3/2}} \frac{2}{n(n+1)(n+2)} \sum_{i=1}^n (R_i - M_1)^3 = \frac{2\sqrt{n+1}}{n+2} \text{Skew}(\mathbf{R}), \quad (26)$$

where $Skew(\mathbf{R}) = \frac{1}{\text{var}(\mathbf{R})^{3/2}} \frac{1}{n} \sum_{i=1}^n (R_i - M_1)^3$ is the Fisher-Pearson coefficient of skewness of the asset returns.

Proof. By replacing $\int_{\Delta^{n-1}} (A\check{x})^3 d\check{x}$ in Equation (23) with the expression from Lemma 9, and applying Lemma 14, one obtains the result.

Theorem 17. *In a market of n assets, $n \in \mathbf{N}$, whose returns are $\mathbf{R} = (R_i)_{i=1}^n$, the fourth moment of the portfolios' returns is*

$$\begin{aligned} M_4 &= \frac{1}{M_2^2} \frac{1}{n(n+1)(n+2)(n+3)} \left(6 \sum_{i=1}^n (R_i - M_1)^4 + 3 \left(\sum_{i=1}^n (R_i - M_1)^2 \right)^2 \right) \\ &= \frac{3(n+1)}{(n+2)(n+3)} (2Kurt(\mathbf{R}) + n) \end{aligned} \quad (27)$$

where $Kurt(\mathbf{R}) = \frac{1}{\text{var}(\mathbf{R})^2} \frac{1}{n} \sum_{i=1}^n (R_i - M_1)^4$ is the Kurtosis of the asset returns.

Proof. By replacing $\int_{\Delta^{n-1}} (A\check{x})^4 d\check{x}$ in Equation (23) with the expression from Lemma 10, and applying Lemma 14, the claim is established.

To conclude this section, we find a direct mapping between the first four moments of the distribution of portfolio returns and those of the cross-sectional asset returns distribution.

5.7 General algorithm to compute the moments

We now wish to compute the k^{th} moment of the portfolios' returns, i.e., restating Equation (23), we compute

$$M_k = \frac{1}{V(\Delta^{n-1}) (\sqrt{M_2})^k} \int_{\Delta^{n-1}} (A\check{x})^k d\check{x}, \quad k \geq 3.$$

Now set $H(X_1, \dots, X_k) = \prod_{i=1}^k X_i$. It is a symmetric k -linear form, and we have

$$H(\underbrace{A\check{x}, \dots, A\check{x}}_{k \text{ times}}) = (A\check{x})^k.$$

Thus, following from Theorem 2, we obtain

$$\int_{\Delta^{n-1}} H(\underbrace{A\check{x}, \dots, A\check{x}}_{k \text{ times}}) d\check{x} = \frac{V(\Delta^{n-1})}{\binom{n-1+k}{k}} \sum_{1 \leq m_1 \leq m_2 \leq \dots \leq m_k \leq n} H(Av_{m_1}, Av_{m_2}, \dots, Av_{m_k}).$$

Let q_i be the number of occurrences of value i , $1 \leq i \leq n$. Then,

$$\int_{\Delta^{n-1}} (A\check{x})^k d\check{x} = \frac{V(\Delta^{n-1})}{\binom{n-1+k}{k}} \sum_{\sum_{i=1}^n q_i=k} \prod_{i=1}^n (Av_i)^{q_i}.$$

Now, we change the notation. Let $\lambda = (\lambda_1, \dots, \lambda_k)$ be a partition of k , and Λ_k the set of partitions of k . We denote by $l = (l_i)_{i=1}^d$ the d unique non-zero values in λ , $d \leq k$, and by $(p_i)_{i=1}^d$ the multiplicities of $(l_i)_{i=1}^d$. For instance, $\lambda = (2, 1, 1, 0)$ is a partition of $k = 4$, with $d = 2$, $l = (1, 2)$ and the associated multiplicities $p = (2, 1)$.

From [Macdonald, 1995, Eq. (2.14')], we have

$$\sum_{\sum_{i=1}^n q_i=k} \prod_{i=1}^n (Av_i)^{q_i} = \sum_{\lambda \in \Lambda_k} \frac{\prod_{i=1}^d \left(\sum_{j=1}^n (Av_j)^{l_i} \right)^{p_i}}{\prod_{i=1}^d p_i! l_i^{p_i}}.$$

Set Λ_k can be computed by Algorithm ZS1 in [Zoghbi and Stojmenovic, 1994], and is still tractable for large moments, as shown in Table 5.

k	1	5	10	20	30	40
$ \Lambda_k $	1	7	42	627	5604	37338

Table 5: Number of partitions $|\Lambda_k|$ for different values of k .

The computation is formally presented in Algorithm 3 below. As an illustration of the computation times, we compute the k^{th} order moments, $k = 5, 10, 15, 20$, for markets of 100, 1000 and 10,000 assets whose returns are randomly drawn. The computation is repeated 1000 times. We report in Table 6 the average computation time in seconds and its standard deviation.

Algorithm 3. *Let \mathbf{R} be the asset returns, N the number of assets, and k the moment order.*

1. Compute M_2 by Theorem 15
2. Compute Av as in Lemma 14
3. Compute Λ using Algorithm ZS1 in [Zoghbi and Stojmenovic, 1994]
4. Set $S = 0$

5. For each $\lambda \in \Lambda$:

(a) decompose λ in its d non-zero elements $(l_i)_{i=1}^d$ with multiplicities $(p_i)_{i=1}^d$

(b) $a = \prod_{i=1}^d p_i! l_i^{p_i}$

(c) $b = \prod_{i=1}^d \left(\sum_{j=1}^n (Av_j)^{l_i} \right)^{p_i}$

(d) $S = S + a/b$

6. Set $M_k = S / \left(\sqrt{M_2}^k \cdot \binom{n-1+k}{k} \right)$

Moment order: Nb of Assets	5	10	15	20
100	0.0006 (0.0021)	0.0024 (0.0003)	0.0100 (0.0005)	0.0398 (0.0005)
1000	0.0008 (0.0000)	0.0034 (0.0003)	0.0117 (0.0002)	0.0420 (0.0007)
10000	0.0020 (0.0001)	0.0053 (0.0000)	0.0145 (0.0011)	0.0506 (0.0028)

Table 6: Mean runtime in seconds, and standard deviation in parenthesis, of computing the moment of order k in markets of 100, 1000 and 10,000 assets. The assets returns are drawn randomly before each of the 1000 computations. The experiments were performed with Matlab© on a bi-xeon E2620 v3 under Windows©.

6 Concluding remarks and future work

In this paper, we reviewed different approaches to compute the PDF, CDF and moments of the distribution of portfolio returns, across portfolios and for the long-only strategy.

For the CDF, the computations improve upon existing work by providing exact results, allowing for equal asset returns, and handle a large number of assets, thus removing the need of Monte Carlo sampling for its estimation. These computations can be based on:

- the volume algorithm by [Varsi, 1973] which is fast and exact even for a large number of assets,
- the closed form expression of CDF, which is exact but numerically unstable for a large number of assets (> 20).

For the PDF, our methods are new, based on what follows:

- the algorithm by de Boor and Cox [de Boor, 1972, Cox, 1972], which is exact but too slow for a large number of assets (> 20) to be of practical use,
- the closed form expression of PDF, which is exact but numerically unstable for a large number of assets (> 20),
- the numerical derivation of the CDF using [Varsi, 1973], which only provides an estimate but is fast and applies to a large number of assets.

For the moments, the computations are new and can be based on

- closed form expressions up to the fourth-order moment,
- a new algorithm using Algorithm *ZS1* by [Zoghbi and Stojmenovic, 1994], for higher moments, which is fast and exact even for a large number of assets.

It should be noted that most of these computations can easily be vectorized, thus further extending their realm of applications.

These results have several statistical and econometric implications.

- The asset returns can be standardized cross-sectionally without altering the relative performance of portfolios. The series obtained are then robust to systemic heteroskedasticity.
- The closed form expressions of the first four moments show a direct mapping between the moments of the cross-sectional asset returns distribution and those of the distribution of portfolio returns.

In particular, the first moments are identical for both distributions. The second and third moments are proportional to each other, the factor depending on the number of assets. For the second moment, the factor is $\frac{1}{N+1}$ where N is the number of assets, implying that it might be more difficult to find a portfolio which performs significantly better than the equally weighted portfolio, when the number of assets increases.

The closed form expression of the fourth moment behaves differently with an extra positive term implying fatter tails in the distribution of portfolio returns than in the cross-sectional distribution of the asset returns. Its implications have to be further analyzed.

The relevance of computing high moments can be discussed. We believe that these moments should be useful in an alternative method recovering the PDF. Indeed, since the distribution is bounded, this problem is known as the Hausdorff moment problem, which has been addressed, see for instance [Mnatsakanov, 2008] and [Bréhard et al., 2019]. This approach has been inconclusive for the authors.

Future work can take several directions. On the theoretical side, it would be interesting to study the distribution of portfolio volatilities in order to better assess the dependency between portfolios returns and volatilities, which is done by sampling in [Calès et al., 2018] It would also be interesting to consider different investment sets, e.g. including short selling⁴ and leverage⁵.

In terms of applications, it should be noticed that the paper focuses on portfolio returns but the methodology can be applied to any linear combination of asset characteristics, e.g. by defining the portfolio dividend yield as the weighted sum of the asset dividend yields. The use of the score, i.e., the CDF, has already found applications in portfolio performance measures. These may be improved, for instance by considering the random nature of the asset returns. The PDF can be used to finely assess the distribution of portfolios with possible applications in portfolio diversification and turn-over analysis. The moments can find applications in the literature on return dispersion, see e.g. [Yu and Sharaiha, 2007], [Stivers and Sun, 2010], [Gorman et al., 2010], [Bhootra, 2011] and [Verousis and Voukelatos, 2018]. They can also find applications in the literature on noise trading, see e.g. [De Long et al., 1989].

⁴i.e. negative portfolio weights.

⁵i.e. sum of portfolio weights greater than one.

References

- [Ali, 1973] Ali, M. (1973). Content of the frustum of a simplex. *Pacific J. Math.*, 48(2):313–322.
- [Banerjee and Hung, 2011] Banerjee, A. and Hung, C.-H. (2011). Informed momentum trading versus uninformed “naive” investors strategies. *J. Banking & Finance*, 35(11):3077–3089.
- [Bhootra, 2011] Bhootra, A. (2011). Are momentum profits driven by the cross-sectional dispersion in expected stock returns? *J. Financial Markets*, 14(3):494–513.
- [Billio et al., 2011] Billio, M., Calès, L., and Guégan, D. (2011). A cross-sectional score for the relative performance of an allocation. *Intern. Review Appl. Financial Issues & Economics*, 3(4):700–710.
- [Boehmer et al., 1991] Boehmer, E., Masumeci, J., and Poulsen, A. B. (1991). Event-study methodology under conditions of event-induced variance. *J. Financial Economics*, 30(2):253–272.
- [Bréhard et al., 2019] Bréhard, F., Joldes, M., and Lasserre, J.-B. (2019). On moment problems with holonomic functions. In *Proc. International Symposium on Symbolic and Algebraic Computation, ISSAC 2019*, pages 66–73. ACM Press.
- [Calès, 2019] Calès, L. (2019). Erratum on: Volume of slices and sections of the simplex in closed form. Technical report, European Commission, Joint Research Centre.
- [Calès et al., 2018] Calès, L., Chalkis, A., Emiris, I. Z., and Fisikopoulos, V. (2018). Practical volume computation of structured convex bodies, and an application to modeling portfolio dependencies and financial crises. In Speckmann, B. and Tóth, C., editors, *Proc. Intern. Symp. Computational Geometry (SoCG)*, volume 99 of *Leibniz Intern. Proc. Informatics (LIPIcs)*, pages 19:1–19:15, Germany.
- [Cox, 1972] Cox, M. (1972). The numerical evaluation of b-splines. *IMA J. Applied Mathematics*, 10(2):134–149.
- [Curry and Schoenberg, 1966] Curry, H. B. and Schoenberg, I. J. (1966). On pólya frequency functions IV: The fundamental spline functions and their limits. *Journal d’Analyse Mathématique*, 7:71–107.

- [de Boor, 1972] de Boor, C. (1972). On calculating with b-splines. *J. Approximation Theory*, 6:50–62.
- [De Long et al., 1989] De Long, J. B., Shleifer, A., Summers, L. H., and Waldmann, R. J. (1989). The size and incidence of the losses from noise trading. *J. Finance*, 44(3):681–696.
- [Gorman et al., 2010] Gorman, L. R., Sapra, S. G., and Weigand, R. A. (2010). The cross-sectional dispersion of stock returns, alpha and the information ratio. *J. Investing*, 19(3):113–127.
- [Hallerbach et al., 2002] Hallerbach, W., Hundack, C., Pouchkarev, I., and Spronk, J. (2002). A broadband vision of the development of the dax over time. Technical Report ERS-2002-87-F&A, Erasmus University, Rotterdam, The Netherlands.
- [Hallerbach and Pouchkarev, 2005] Hallerbach, W. and Pouchkarev, I. (2005). A relative view on tracking error. Technical Report ERS-2005-063-F&A, Erasmus University, Rotterdam, The Netherlands.
- [Hallerbach and Pouchkarev, 2016] Hallerbach, W. and Pouchkarev, I. (2016). Active portfolio management with conditional tracking error. *Bankers, market and investors*, 143:18–25.
- [Lasserre and Avrachenkov, 2001] Lasserre, J. and Avrachenkov, K. (2001). The multi-dimensional version of $\int_a^b x^p dx$. *The American Mathematical Monthly*, 108(2):151–154.
- [Lasserre, 2015] Lasserre, J. B. (2015). Volume of slices and sections of the simplex in closed form. *Optimization Letters*, 9:1263–1269.
- [Macdonald, 1995] Macdonald, I. (1995). *Symmetric Functions and Hall Polynomials*. Oxford University Press, Oxford, 1st edition.
- [Mnatsakanov, 2008] Mnatsakanov, R. M. (2008). Hausdorff moment problem: Reconstruction of probability density functions. *Statistics & Probability Letters*, 78(13):1869 – 1877.
- [Pouchkarev, 2005] Pouchkarev, I. (2005). *Performance evaluation of constrained portfolios*. PhD thesis, Erasmus Research Institute of Management, The Netherlands.
- [Pouchkarev et al., 2004] Pouchkarev, I., Spronk, J., and Trinidad, J. (2004). Dynamics of the spanish stock market through a broadband view of the IBEX 35 index. *Estudios Econom. Aplicada*, 22(1):7–21.

- [Rubinstein and Melamed, 1998] Rubinstein, R. and Melamed, B. (1998). *Modern simulation and modeling*. Wiley, New York.
- [Stivers and Sun, 2010] Stivers, C. and Sun, L. (2010). Cross-sectional return dispersion and time variation in value and momentum premiums. *J. Financial and Quantitative Analysis*, 45(4):987–1014.
- [Varsi, 1973] Varsi, G. (1973). The multidimensional content of the frustum of the simplex. *Pacific J. Math.*, 46:303–314.
- [Verousis and Voukelatos, 2018] Verousis, T. and Voukelatos, N. (2018). Cross-sectional dispersion and expected returns. *Quantitative Finance*, 18(5):813–826.
- [Yu and Sharaiha, 2007] Yu, W. and Sharaiha, Y. M. (2007). Alpha budgeting cross-sectional dispersion decomposed. *J. Asset management*, 8(1):58–72.
- [Zoghbi and Stojmenovic, 1994] Zoghbi, A. and Stojmenovic, I. (1994). Fast algorithms for generating integer partitions. *Intern. J. Computer Mathematics*, 70:319–332.

A Proof of Lemma 4

Lemma 4 For $n \in \mathbb{N}$, it holds

$$6 \sum_{i=1}^n \sum_{j=i}^n \sum_{k=j}^n x_i x_j x_k = \left(\sum_{i=1}^n x_i \right)^3 + 3 \left(\sum_{i=1}^n x_i \right) \left(\sum_{i=1}^n x_i^2 \right) + 2 \sum_{i=1}^n x_i^3.$$

Proof. Let $S(n) = \sum_{i=1}^n \sum_{j=i}^n \sum_{k=j}^n x_i x_j x_k$. The cases $n = 0$ and $n = 1$ are easily verifiable. Let us assume that the theorem holds for $S(n), n \geq 1$. We shall prove it for $S(n+1)$. Clearly,

$$S(n+1) = S(n) + \sum_{i=1}^n \sum_{j=i}^n x_i x_j x_{n+1} + \sum_{i=1}^n x_i x_{n+1}^2 + x_{n+1}^3,$$

which, by inductive hypothesis, yields

$$6S(n+1) = \left(\sum_{i=1}^n x_i \right)^3 + 3 \left(\sum_{i=1}^n x_i \right) \left(\sum_{i=1}^n x_i^2 \right) + 2 \sum_{i=1}^n x_i^3 + \underbrace{6x_{n+1} \sum_{i=1}^n \sum_{j=i}^n x_i x_j + 6x_{n+1}^2 \sum_{i=1}^n x_i + 6x_{n+1}^3}_{\text{underlined}}.$$

The underlined term becomes

$$3x_{n+1} \left(2 \sum_{i=1}^n x_i^2 + 2 \sum_{i=1}^n \sum_{j>i}^n x_i x_j \right), \quad (28)$$

where the last index j is strictly larger than i . The overall sum is re-written as the sum of the following three terms, where we have underlined terms corresponding to sum (28):

$$\begin{aligned} & \left(\sum_{i=1}^n x_i \right)^3 + \underbrace{3x_{n+1} \left(\sum_{i=1}^n x_i \right)^2 + 3x_{n+1}^2 \sum_{i=1}^n x_i + x_{n+1}^3}_{\text{underlined}} = \left(\sum_{i=1}^n x_i + x_{n+1} \right)^3, \\ & 3 \left[\left(\sum_{i=1}^n x_i \right) \left(\sum_{i=1}^n x_i^2 \right) + \underbrace{x_{n+1} \sum_{i=1}^n x_i^2 + x_{n+1}^2 \sum_{i=1}^n x_i + x_{n+1}^3}_{\text{underlined}} \right] = \\ & = 3 \left(\sum_{i=1}^n x_i + x_{n+1} \right) \left(\sum_{i=1}^n x_i^2 + x_{n+1}^2 \right), \\ & \qquad \qquad \qquad 2 \sum_{i=1}^n x_i^3 + 2x_{n+1}^3, \end{aligned}$$

which correspond to the three sums of the original claim.

B Proof of Lemma 5

Lemma 5 For $n \in \mathbb{N}$, it holds

$$(4!) \sum_{i=1}^n \sum_{j=i}^n \sum_{k=j}^n \sum_{t=k}^n x_i x_j x_k x_t = \\ \left(\sum_{i=1}^n x_i \right)^4 + 6 \left(\sum_{i=1}^n x_i \right)^2 \left(\sum_{i=1}^n x_i^2 \right) + 8 \left(\sum_{i=1}^n x_i \right) \left(\sum_{i=1}^n x_i^3 \right) + 6 \left(\sum_{i=1}^n x_i^4 \right) + 3 \left(\sum_{i=1}^n x_i^2 \right)^2$$

Proof. Let $S(n) = \sum_{i=1}^n \sum_{j=i}^n \sum_{k=j}^n \sum_{t=k}^n x_i x_j x_k x_t$. The cases $n = 0$ and $n = 1$ are easily verifiable. Let us assume that the theorem holds for $S(n), n \geq 1$. We shall prove it for $S(n+1)$. Clearly,

$$S(n+1) = S(n) + \sum_{i=1}^n \sum_{j=i}^n \sum_{k=j}^n x_i x_j x_k x_{n+1} + \sum_{i=1}^n \sum_{j=i}^n x_i x_j x_{n+1}^2 + \sum_{i=1}^n x_i x_{n+1}^3 + x_{n+1}^4,$$

which, by the inductive hypothesis, yields:

$$24S(n+1) = \\ \left(\sum_{i=1}^n x_i \right)^4 + 6 \left(\sum_{i=1}^n x_i \right)^2 \left(\sum_{i=1}^n x_i^2 \right) + 8 \left(\sum_{i=1}^n x_i \right) \left(\sum_{i=1}^n x_i^3 \right) + 6 \left(\sum_{i=1}^n x_i^4 \right) + 3 \left(\sum_{i=1}^n x_i^2 \right)^2 \\ + 24x_{n+1} \sum_{i=1}^n \sum_{j=i}^n \sum_{k=j}^n x_i x_j x_k + 24x_{n+1}^2 \sum_{i=1}^n \sum_{j=i}^n x_i x_j + 24x_{n+1}^3 \sum_{i=1}^n x_i + 24x_{n+1}^4.$$

Let $A = x_{n+1}^3 \sum_{i=1}^n x_i$ and $B = x_{n+1}^4$. From Lemma 4, we have

$$24x_{n+1} \sum_{i=1}^n \sum_{j=i}^n \sum_{k=j}^n x_i x_j x_k = \\ = 4x_{n+1} \left(\left(\sum_{i=1}^n x_i \right)^3 + 3 \left(\sum_{i=1}^n x_i \right) \left(\sum_{i=1}^n x_i^2 \right) + 2 \sum_{i=1}^n x_i^3 \right) \\ = 4x_{n+1} \underbrace{\left(\sum_{i=1}^n x_i \right)^3}_{=C} + 12x_{n+1} \underbrace{\left(\sum_{i=1}^n x_i \right) \left(\sum_{i=1}^n x_i^2 \right)}_{=D} + 8x_{n+1} \underbrace{\sum_{i=1}^n x_i^3}_{=E}$$

And from Lemma 4, we have

$$\begin{aligned}
& 24x_{n+1}^2 \sum_{i=1}^n \sum_{j=i}^n x_i x_j = \\
& = 12x_{n+1}^2 \left(\left(\sum_{i=1}^n x_i \right)^2 + \sum_{i=1}^n x_i^2 \right) \\
& = \underbrace{12x_{n+1}^2 \left(\sum_{i=1}^n x_i \right)^2}_{=2F} + \underbrace{12x_{n+1}^2 \left(\sum_{i=1}^n x_i^2 \right)}_{=2G}.
\end{aligned}$$

The overall sum is rewritten using the sum of the following four terms:

$$\begin{aligned}
& \left(\sum_{i=1}^{n+1} x_i \right)^4 = \left(\sum_{i=1}^n x_i \right)^4 + \underbrace{4x_{n+1} \left(\sum_{i=1}^n x_i \right)^3}_{=C} + \underbrace{6x_{n+1}^2 \left(\sum_{i=1}^n x_i \right)^2}_{=F} + \underbrace{4x_{n+1}^3 \left(\sum_{i=1}^n x_i \right)}_{=4A} + \underbrace{x_{n+1}^4}_{=B}. \\
& 6 \left(\left(\sum_{i=1}^{n+1} x_i \right)^2 \left(\sum_{i=1}^{n+1} x_i^2 \right) \right) = 6 \left(\left(\left(\sum_{i=1}^n x_i \right)^2 + 2x_{n+1} \left(\sum_{i=1}^n x_i \right) + x_{n+1}^2 \right) \left(x_{n+1}^2 + \sum_{i=1}^n x_i^2 \right) \right) \\
& = 6 \left(\left(\sum_{i=1}^n x_i \right)^2 \left(\sum_{i=1}^n x_i^2 \right) + \underbrace{6x_{n+1}^2 \left(\sum_{i=1}^n x_i \right)^2}_{=F} + \underbrace{12x_{n+1}^3 \left(\sum_{i=1}^n x_i \right)}_{=12A} \right. \\
& \quad \left. + \underbrace{12x_{n+1} \left(\sum_{i=1}^n x_i \right) \left(\sum_{i=1}^n x_i^2 \right)}_{=D} + \underbrace{6x_{n+1}^4}_{=6B} + \underbrace{x_{n+1}^2 \left(\sum_{i=1}^n x_i^2 \right)}_{=G} \right). \\
& 8 \left(\sum_{i=1}^{n+1} x_i \right) \left(\sum_{i=1}^{n+1} x_i^3 \right) = 8 \left(\sum_{i=1}^n x_i \right) \left(\sum_{i=1}^n x_i^3 \right) + \underbrace{8x_{n+1} \left(\sum_{i=1}^n x_i^3 \right)}_{=E} + \underbrace{8x_{n+1}^3 \left(\sum_{i=1}^n x_i \right)}_{=8A} + \underbrace{8x_{n+1}^4}_{=8B}. \\
& 3 \left(\sum_{i=1}^{n+1} x_i^2 \right)^2 = 3 \left(\sum_{i=1}^n x_i^2 \right)^2 + \underbrace{6x_{n+1}^2 \left(\sum_{i=1}^n x_i^2 \right)}_{=G} + \underbrace{3x_{n+1}^4}_{=3B}.
\end{aligned}$$

$$6 \left(\sum_{i=1}^{n+1} x_i^4 \right) = 6 \left(\sum_{i=1}^n x_i^4 \right) + \underbrace{6x_{n+1}^4}_{=6B}.$$