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# Conditions for some non stationary random walks in the quarter plane to be singular or of genus 0 

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#### Abstract

We analyze the kernel $K(x, y, t)$ of the basic functional equation associated with the tri-variate counting generating function (CGF) of walks in the quarter plane. In this short paper, taking $t \in] 0,1\left[\right.$, we provide the conditions on the step set $\left\{p_{i, j}\right\}$ to decide whether the walks are singular or regular, as defined in [3, Section 2.3]. These conditions are independent of $t \in] 0,1[$ and given in terms of step set configurations. We also give the configurations for the kernel to be of genus 0 . All these conditions are very similar to the case $t=1$ considered in [3]. Our results extend the work [2], which considers only very special situations, namely when $t \in] 0,1[$ is a transcendental number and the $p_{i, j}^{\prime} s$ are rational.


## 1 Introduction and notation

Enumeration of planar lattice walks has become a classical topic in combinatorics. For a given set $\mathcal{S}$ of allowed jumps (or steps), it is a matter of counting the number of paths starting from some point and ending at some arbitrary point in a given time, and possibly restricted to some regions of the plane.

It will be convenient to denote by $\mathcal{S}$ the set of admissible small steps, included in the set of the eight nearest neighbors, so that

$$
\mathcal{S} \subset\{-1,0,1\}^{2} \backslash\{(0,0)\}
$$

Let $f(i, j, k)$ denote the probability for a walk in $\mathbb{Z}_{+}^{2}$ of reaching the point

[^0]$(i, j)$ after $k$ steps, starting from $(0,0)$. Then the corresponding CGF
\[

$$
\begin{equation*}
F(x, y, t)=\sum_{i, j, k \geqslant 0} f(i, j, k) x^{i} y^{j} t^{k} \tag{1.1}
\end{equation*}
$$

\]

satisfies the functional equation (see [1] for details)

$$
\begin{equation*}
K(x, y, t) F(x, y, t)=K(x, 0, t) F(x, 0, t)+K(0, y, t) F(0, y, t)+l(x, y, t) \tag{1.2}
\end{equation*}
$$

where

$$
\left\{\begin{array}{l}
K(x, y, t)=x y[t S(x, y)-1]  \tag{1.3}\\
S(s, y)=\sum_{(i, j) \in \mathcal{S}} p_{i, j} x^{i} y^{j} \\
l(x, y, t)=-t p_{-1,-1} F(0,0, t)-x y
\end{array}\right.
$$

We assume $\sum_{(i, j)} p_{i, j} \in \mathcal{S}=1$, which does not restrict the generality, so that $F(x, y, t)$ is sought to be convergent in the region $|x| \leq 1,|y| \leq 1,|t| \leq 1$. Usually, for fixed $t$, the algebraic curve corresponding to

$$
\begin{equation*}
\left\{(x, y) \in \mathbb{C}^{2}: K(x, y, t)=0\right\} \tag{1.4}
\end{equation*}
$$

has genus 0 or 1 . But this is is no more true when the kernel $K(x, y, t)$ may be factorized in $\mathbb{C}[x, y]$, in which case the walk is called singular according to the definition (see [3]).

Following the notation in [3], we define the triple $a(x), b(x), c(x)$, [resp. $\widetilde{a}(y), \widetilde{b}(y), \widetilde{c}(y)]$ from 1.3 by

$$
\begin{align*}
K(x, y, t) & =x y\left(t \sum p_{i j} x^{i} y^{j}-1\right)  \tag{1.5}\\
& \stackrel{\text { def }}{=} t\left[a(x) y^{2}+b(x, t) y+c(x)\right] \stackrel{\text { def }}{=} t\left[\widetilde{a}(y) x^{2}+\widetilde{b}(y, t) x+\widetilde{c}(y)\right] \tag{1.6}
\end{align*}
$$

with

$$
\left\{\begin{array}{l}
a(x)=\sum_{i=0}^{2} p_{i-1,1} x^{i},  \tag{1.7}\\
b(x, t)=p_{-1,0}+\left(p_{0,0}-1 / t\right) x+p_{1,0} x^{2}, \\
c(x)=\sum_{i=0}^{2} p_{i-1,-1} x^{i},
\end{array}\right.
$$

and similar equations for $\widetilde{a}(y), \widetilde{b}(y), \widetilde{c}(y)$.
Let us introduce the discriminant of 1.6 , always viewed as a polynomial in $x$

$$
\begin{equation*}
D(x, t) \stackrel{\text { def }}{=} b^{2}(x, t)-4 a(x) c(x) \tag{1.8}
\end{equation*}
$$

Then it will be convenient to write

$$
\begin{equation*}
D(x, t)=\sum_{i=0}^{4} d_{i}(t) x^{i} \tag{1.9}
\end{equation*}
$$

where, by using (1.7),

$$
\begin{cases}d_{0}(t) & =p_{-1,0}^{2}-4 p_{-1,1} p_{-1,-1},  \tag{1.10}\\ d_{1}(t) & =2\left[p_{-1,0}\left(p_{0,0}-1 / t\right)-2\left(p_{-1,1} p_{0,-1}+p_{0,1} p_{-1,-1}\right)\right], \\ d_{2}(t) & =\left(p_{0,0}-1 / t\right)^{2}+2 p_{1,0} p_{-1,0}-4\left(p_{1,1} p_{-1,-1}+p_{1,-1} p_{-1,1}+p_{0,1} p_{0,-1}\right), \\ d_{3}(t) & =2 p_{1,0}\left(p_{0,0}-1 / t\right)-4\left(p_{1,1} p_{0,-1}+p_{0,1} p_{1,-1}\right), \\ d_{4}(t) & =p_{1,0}^{2}-4 p_{1,1} p_{1,-1},\end{cases}
$$

noting that $d_{0}$ and $d_{4}$ are in fact independant of $t$. It is immediate to check that $d_{2}(t)$ is always strictly positive. Hence, the degree of $D(x, t)$ in $x$ is always $\geqslant 2$.

We shall need the following simple notion of positivity for an arbitrary polynomial.

Definition 1.1. A polynomial $p(x)$ is said to be positive (resp. negative) to mean that its coefficients are all real positive (resp. negative) and not simultaneously 0 .

## 2 The roots of the discriminant $\mathrm{D}(\mathrm{x}, \mathrm{t})$

The main result of this section resides in he following theorem.

Theorem 2.1. For all $t \in] 0,1], D(x, t)$ has 4 real roots, exactly two of them being inside the unit disk, and double roots can occur only at $x=0$ or $x=\infty$.

Proof. For all $x$ satisfying $a(x) c(x) \geq 0$, we introduce

$$
\begin{equation*}
\phi_{1}(x, t) \stackrel{\text { def }}{=} b(x, t)+2 \sqrt{a(x) c(x)}, \quad \phi_{2}(x, t) \stackrel{\text { def }}{=} b(x, t)-2 \sqrt{a(x) c(x)}, \tag{2.1}
\end{equation*}
$$

whence, according to (1.8),

$$
D(x, t)=\phi_{1}(x, t) \phi_{2}(x, t) .
$$

Keeping in mind that $a(x)$ and $c(x)$ are positive (see Definition 1.1), they have no positive real roots. Our goal is to distribute the 4 roots of $D(x, t)$ between $\phi_{1}$ and $\phi_{2}$.

The roots of $\phi_{1}(x, t)$ and $\phi_{2}(x, t)$. The next inequalities are immediate

$$
\begin{equation*}
\phi_{2}(1, t) \leqslant \phi_{1}(1, t) \leqslant 1-1 / t<0, \quad \phi_{1}(0, t) \geqslant 0 . \tag{2.2}
\end{equation*}
$$

Let $\xi_{0}$ denote the largest real root of $a(x) c(x)$, when it exists. Then $\xi_{0} \leqslant 0$ and $\phi_{1}\left(\xi_{0}, t\right)=\phi_{2}\left(\xi_{0}, t\right)=b\left(\xi_{0}, t\right) \geqslant 0$. Consequently, $\phi_{1}(x, t)$ and $\phi_{2}(x, t)$ each have a root on $] \xi_{0}, 1\left[\right.$. On the other hand, if $\xi_{0} \leqslant-1$, then $a(x) c(x) \geqslant 0$ for $x \in[-1,1]$ and

$$
\phi_{1}(-1, t) \geqslant \phi_{2}(-1, t)>0,
$$

which, in tandem with (2.2), proves indeed that $\phi_{2}(x, t)$ has always a root on ] $-1,1\left[\right.$. This conclusion still holds when $\xi_{0}$ does not exist, since then $a(x) c(x)$ is positive and $\phi_{1}(x, t), \phi_{2}(x, t)$ are real $\forall x \in \mathbb{R}$.

So, when degree of $D(x, t)=2$, there are two real roots inside the unit disk, harmoniously distributed between $\phi_{1}(x, t)$ and $\phi_{2}(x, t)$.
In addition, we note that, when degree of $D(x, t) \geqslant 3$,

$$
\begin{equation*}
\lim _{x \rightarrow+\infty} \phi_{1}(x, t)=+\infty, \tag{2.3}
\end{equation*}
$$

in which case $\phi_{1}(x, t)$ has a root on $] 1, \infty[$ and a root on $[0,1[$.
Degree of $\mathrm{D}(\mathrm{x}, \mathrm{t})=\mathbf{3}$, i.e., $\mathrm{d}_{\mathbf{4}}(\mathrm{t})=\mathrm{p}_{1,0}^{2}-4 \mathrm{p}_{1,1} \mathrm{p}_{1,-\mathbf{1}}=\mathbf{0}$. Then two roots of $D(x, t)$ come from $\phi_{1}(x, t)$, and the third one from $\phi_{2}(x, t)$.

Degree of $\mathbf{D}(\mathbf{x}, \mathbf{t})=\mathbf{4}$, i.e. $\quad \mathbf{d}_{\mathbf{4}}(\mathbf{t}) \neq \mathbf{0}$. Letting $|x| \rightarrow \infty$, there are two possibilities.
(i) $d_{4}(t)>0$. Then $\lim _{x \rightarrow \infty} \phi_{2}(x, t)=+\infty$, and $\phi_{2}(x, t)$ has a positive real root on $] 1,+\infty[$.
(ii) $d_{4}(t)<0$. Let $\xi_{1}$ denote the smallest finite real root of $a(x) c(x)$, when it exists. Then

$$
\left.a(x) c(x \geqslant 0, \forall x \in]-\infty, \xi_{1}\right], \phi_{2}\left(\xi_{1}, t\right)=b\left(\xi_{1}, t\right)>0,
$$

and, since $\lim _{x \rightarrow-\infty} \phi_{2}(x, t)=-\infty$, it follows that $\phi_{2}(x, t)$ has a negative real root on ] $-\infty, \xi_{1}$ [. If $\xi_{1}$ does not exist, then $\phi_{2}(x, t)$ has a root on ] $-\infty,-1$ ].
In conclusion, the distribution of the roots of $D(x, t)$ between $\phi_{1}(x, t)$ and $\phi_{2}(x, t)$ implies that a double root exists if, and only if,

$$
\begin{equation*}
\phi_{1}(x, t)=\phi_{2}(x, t)=0 \Longleftrightarrow b(x, t)=a(x) c(x)=0 . \tag{2.4}
\end{equation*}
$$

But the roots of $b(x, t)$ are real positive, while those of $a(x)$ and $c(x)$ have negative real parts. Hence (2.4) can only take place if $x=0$ or $x=\infty$. The proof of the theorem is terminated.

## 3 Classification of the singular random walks

Definition 3.1. A random walk is called singular (see [3]) if the associated polynomial $K(x, y, t)$ is either reducible or of degree 1 in at least one of the variables.

We establish a useful lemma, which is of an algebraic nature and gives conditions for the factorization of the kernel $K(x, y, t)$.

Lemma 3.2. Let $\mathcal{A}[x]$ be the algebra of polynomials in $x$ with coefficients in an arbitrary field $\mathcal{A}$ containing the rational numbers $\mathbb{Q}$. For given a, $b, c, p \in \mathcal{A}[x]$ satisfying

$$
\begin{equation*}
b^{2}-4 a c=k p^{2}, \tag{3.1}
\end{equation*}
$$

there exist $\alpha, \beta, f_{1}, f_{2} \in \mathcal{B}[x]$, such that

$$
\begin{equation*}
a y^{2}+b y+c=\left(f_{1} y-\alpha\right)\left(f_{2} y-\beta\right), \tag{3.2}
\end{equation*}
$$

where $\mathcal{B} \stackrel{\text { def }}{=} \mathcal{A}+\sqrt{k}$ denotes the field $\mathcal{A}$ to which is added the element $\sqrt{k}$ ). In addition, the relation (3.1) is necessary to have the factorization (3.2).

Proof. Let $Z_{1}, Z_{2}$ be the roots of

$$
\begin{equation*}
Z^{2}+b Z+a c=0, \tag{3.3}
\end{equation*}
$$

so that, with an obvious notation,

$$
Z_{1,2}=-\frac{b}{2} \pm \frac{p}{2} \sqrt{k} .
$$

In $\mathcal{B}[x]$, let $f_{1}$ be the greatest common divisor (g.c.d) of $Z_{1}$ and $a$, so that

$$
Z_{1}=\beta f_{1} \quad \text { and } a=f_{1} f_{2},
$$

where $\beta$ and $f_{2}$ are relatively prime. Then, from $Z_{1} Z_{2}=a c$, we get $\beta Z_{2}=c f_{2}$. Hence, the g.c.d. of $\beta$ and $f_{2}$ being the unit element, $f_{2}$ divides $Z_{2}$ and we shall put $Z_{2}=\alpha f_{2}$.

Setting for a while $Z=a y$, the announced factorization (3.2) follows directly from the chain of equalities

$$
\begin{equation*}
Z^{2}+b Z+a c=\left(Z-Z_{1}\right)\left(Z-Z_{2}\right)=\left(a y-\beta f_{1}\right)\left(a y-\alpha f_{2}\right)=a\left(f_{2} y-\beta\right)\left(f_{1} y-\alpha\right) \tag{3.4}
\end{equation*}
$$

together with the identity

$$
Z^{2}+b Z+a c=a\left(a y^{2}+b y+c\right) .
$$

As for the necessity of (3.1) to have 3.2), we therefore assume

$$
a y^{2}+b y+c=\left(f_{1} y-\alpha\right)\left(f_{2} y-\beta\right) .
$$

Letting $Z_{1} \stackrel{\text { def }}{=} \alpha f_{2}, Z_{2} \stackrel{\text { def }}{=} \beta f_{1}$, one sees that $Z_{1}, Z_{2}$ are the respective roots of (3.3), which both belong to $\in \mathcal{B}[x]$ and satisfy

$$
\begin{equation*}
\left(Z_{1}-Z_{2}\right)^{2}=\left(Z_{1}+Z_{2}\right)^{2}-4 Z_{1} Z_{2}=b^{2}-4 a c . \tag{3.5}
\end{equation*}
$$

On the other hand, as part of the hypothesis, we can set $Z_{i} \xlongequal{\text { def }} u_{i}+v_{i} \sqrt{k} \in \mathcal{B}[x]$, for $i=1,2$, where $u_{i}, v_{i} \in \mathcal{A}[x]$. Then, using the fact that $a, b, c$ belong to $\mathcal{A}[x]$, together with the relations

$$
\alpha f_{2}+\beta f_{1}=-b, \quad \text { and } \quad \alpha \beta f_{1} f_{2}=a c,
$$

we get immediately

$$
u_{1}=u_{2}=-b / 2, \quad v_{1}+v_{2}=0,
$$

Hence

$$
\left(Z_{1}-Z_{2}\right)^{2}=\left[2 v_{1} \sqrt{k}\right]^{2}=4 k v^{2},
$$

which, comparing with (3.5), yields exactly (3.1).
The proof of the lemma is terminated.
Lemma 3.3. In Lemma 3.2, take $\mathcal{A}=\mathbb{C}$, the field of complex numbers. Then, among all the possible factorizations of the form (3.2), one can always choose a real one over $\mathbb{R}[x, y]$.

Proof. Equation (3.1) shows that $D(x, t)$ has solely double roots, which by Theorem 2.1 happens only for $x=0$ and $x=\infty$, so that $k=d_{2}(t)$ and $p=x$. Since $\left.d_{2}(t)\right)$ is always positive for $\left.\left.t \in\right] 0,1\right]$, the roots $Z_{1,2}$ of equation (3.3) have the form

$$
Z_{1,2}=\frac{-b \pm \sqrt{d_{2}(t)} x}{2} .
$$

They clearly have real coefficients, and so do $f_{1}, f_{2}, \alpha, \beta$ which are highlighted in Lemma 3.2 in a constructive way (or algorithmic so to speak).

The classification of the family of random walks under study is given by the next theorem.

Theorem 3.4. For $t \in] 0,1]$ and $p_{i, j} \in[0,1], p_{0,0} \neq 1$, the random walk is singular if, and only if, one of the following conditions holds:
(i) There exists $(i, j) \in \mathbb{Z}^{2},|i| \leqslant 1,|j| \leqslant 1$, such that only $p_{i j}$ and $p_{-i,-j}$ are different from 0 (see figure 3.1a and the three cases obtained by rotation);

$a$

b

c

$d$

$e$

Fig. 3.1: Singular random walks.
(ii) There exists $i,|i|=1$, such that for any $j,|j| \leqslant 1, p_{i j}=0$ (see figure 3.1b, c);
(iii) There exists $j,|j|=1$, such that for any $i,|i| \leqslant 1, p_{i j}=0$ (see figure $3.1 d, e$ ).

Proof. Let us first eliminate three simple situations.
Case $\mathbf{a} \equiv \mathbf{0}$. Then $p_{1,1}=p_{0,1}=p_{-1,1}=0$. The kernel is of degree 1 in $y$ and this corresponds to the walks of type $e$ in figure 3.1 and

$$
K(x, y, t)=t(b y+c) .
$$

Case $\mathbf{c} \equiv \mathbf{0}$. Then $p_{1,-1}=p_{0,-1}=p_{-1,-1}=0$, giving the walks of type $d$ in figure 3.1 and

$$
K(x, y, t)=t y(a y+b) .
$$

By exchanging the variables $x$ and $y$, and writing the kernel as a polynomial in $x$ with coefficients $\widetilde{a}, \widetilde{b}, \widetilde{c}$ (see (1.5), the cases $\widetilde{a} \equiv 0$ or $\widetilde{c} \equiv 0$ depict the walks of respective types $c$ and $b$ in figure (3.1).

From now on, we shall assume $a c \not \equiv 0$.
Case $\mathbf{K}(\mathbf{x}, \mathbf{y}, \mathbf{t})=\mathbf{u}(\mathbf{x}, \mathbf{t}) \mathbf{v}(\mathbf{x}, \mathbf{y}, \mathbf{t})$. Here $u$ (resp. $v$ ) stands for a polynomial in $x$ (resp. $(x, y)$. It is immediate to see that the degree of $u(x, t)$ in $x$ is 1 . But this means that $a, b, c$ have a common real root in $x$, which can occur only at $x=0$. Indeed, by $\sqrt{1.7}$ ), it appears that $b(x, t)$ has always two positive real roots, while the roots of $a$ and $c$ cannot be positive. Thus the only possibility is $p_{-1,1}=p_{-1,0}=p_{-1,-1}=0$, or equivalently $\widetilde{c} \equiv 0$, which corresponds to the walks of type $b$ in figure (3.1). Hence,

$$
\widetilde{c}(y) \equiv 0 \Longleftrightarrow K(x, y, t)=t x[x \widetilde{a}(y)+\widetilde{b}(y, t)] .
$$

Similarly, by exchanging the roles of $x$ and $y$, we obtain the walks of type $d$ in figure (3.1). In particular,

$$
c(x) \equiv 0 \Longleftrightarrow K(x, y, t)=\operatorname{ty}[y a(x)+b(x, t)] .
$$

Under Definition 3.1, all singular random walks satisfy 3.2 together with the system

$$
\begin{align*}
\alpha f_{2}+\beta f_{1} & =-b  \tag{3.6}\\
f_{1} f_{2} & =a  \tag{3.7}\\
\alpha \beta & =c \tag{3.8}
\end{align*}
$$

where $\alpha, \beta, f_{1}, f_{2}$ are polynomials of degree at most 2 in $x$, with real coefficients by Lemma 3.3, noting that in the course of the proof we omit the variables $(x, t)$ for the sake of readability.

When $a$ and $c$ are positive (see Definition 1.1), (3.7) and (3.8) imply that $\left(f_{1}, f_{2}\right)$ are both either positive or negative, and likwise for $(\alpha, \beta)$. This is true because $a$ and $c$ are of degree at most 2 , and we shall choose $\left(f_{1}, f_{2}\right)$ positive.

Recalling that $b \equiv b(x, t)=p_{-1,0}+\left(p_{0,0}-1 / t\right) x+p_{1,0} x^{2}$, the identity (3.6) leads to consider two different situations.
(i) $p_{1,0}+p_{-1,0} \neq 0$. Here it is impossible to satisfy (3.6) for $\left.\left.t \in\right] 0,1\right]$, since the three coefficients of the polynomial $b$ do not have the same sign.
(ii) $p_{1,0}=p_{-1,0}=0$. Then (3.6) can hold only if $(\alpha, \beta)$ are positive and if $\left(\alpha f_{2}, \beta f_{1}\right)$ are proportional to $x$. Upon combining (3.7)-(3.8), we obtain

$$
\left(\alpha f_{2}\right)\left(\beta f_{1}\right)=a c=K x^{2}
$$

where $K$ is a constant. Thus the coefficients of $x^{4}, x^{3}, x, x^{0}$ of the polynomial $a(x) c(x)$ must cancel out, yielding from 1.7) the respective equations

$$
\left\{\begin{array}{l}
p_{1,1} p_{1,-1}=0  \tag{3.9}\\
p_{1,1} p_{0,-1}+p_{1,-1} p_{0,1}=0 \\
p_{0,1} p_{-1,-1}+p_{-1,1} p_{0,-1}=0 \\
p_{-1,1} p_{0,-1}=0
\end{array}\right.
$$

Now it is easy to check that the puzzle-like system (3.9) generates exactly the 4 following random walks:

$$
\begin{cases}p_{1,-1}=p_{0,-1}=p_{-1,1}=p_{0,1}=0, & \text { figure (3.1, a) }  \tag{3.10}\\ p_{1,1}=p_{0,1}=p_{-1,-1}=p_{0,-1}=0, & \text { figure (3.1, a) rotated by } 90^{\circ} ; \\ p_{1,1}=p_{1,-1}=p_{-1,-1}=p_{-1,1}=0, & \text { figure (3.1, a) rotated by } 45^{\circ} ; \\ p_{1,1}=p_{0,1}=p_{-1,1}=p_{0,-1}=0, & \text { sub-case of figure } 3.1, e)\end{cases}
$$

By exchanging the roles of $x$ and $y$, we also obtain the singular walk where only $p_{1,0}$ and $p_{-1,0}$ are different from zero.

The proof of the theorem is terminated.

Remark 3.5. When $p_{0,0}=0$, one verifies easily that Theorem 3.4 holds in fact for all $t \in] 0,+\infty[$.

## 4 Kernel of genus 0

It is wellknown that, for all non-singular random walks, the Riemann surface $\mathbf{S}$ defined by the algebraic curve (1.4) has genus 0 or 1 . Morever, the genus of $\mathbf{S}$ is 0 if, and only if, the discriminant $D(x, t)$ defined in (1.8) has a multiple zero in $x$, possibly infinite.

For the sake of completeness, we also introduce the branch points $x_{i}$ (resp. $y_{i}$ ), $i=1, \ldots, 4$, of the algebraic function $Y(x, t)$ satisfying $K(x, Y(x, t), t)=0$ [resp. $X(y, t)$ satisfying $K(X(y, t), y, t)=0]$. These branch points depend on $t$.

In the book [3, Section 2.3], the classification in the so-called stationary case $t=1$ has been dealt with in great detail. The proof was heavily using the principle of continuity of the roots with respect to the parameters $p_{i, j}$, thus reducing the analysis to the case of the so-called simple random walk, i.e. when only $p_{1,0}, p_{0,1}, p_{-1,0}, p_{0,-1}$ are different from 0 . Indeed, for $\left.t \in\right] 0,1[$, exactly the same arguments hold. Nonetheless, we present hereafter a selfcontained proof. The following theorem holds.

Theorem 4.1. For all non singular random walks and for all $t \in] 0,1[$, the algebraic curve defined by $K(x, y, t)=0$ has genus 0 if, and only if, $D(x, t)$ has a double root at $x=0$ or $x=\infty$. That corresponds to the following pictures.
$X$-plane $\quad Y$-plane

1. $\left\{\begin{array}{l}x_{1}=x_{2}=0 \\ y_{3}=y_{4}=\infty .\end{array}\right.$

$X$-plane
2. $\left\{\begin{array}{l}y_{1}=y_{2}=0 \\ x_{3}=x_{4}=\infty .\end{array}\right.$

$X$-plane
3. $\left\{\begin{array}{l}x_{3}=x_{4}=\infty \\ y_{3}=y_{4}=\infty .\end{array}\right.$


$Y$-plane

$Y$-plane


$$
\text { 4. }\left\{\begin{array}{l}
x_{1}=x_{2}=0 \\
y_{1}=y_{2}=0 .
\end{array}\right.
$$

In other words, multiple roots of $D(x, t)$ can occur only in either of the two following situations:
(a) $x=0$, in which case $d_{0}(t)=d_{1}(t)=0 ;$
(b) $x=\infty$, in which case $d_{3}(t)=d_{4}(t)=0$.

Proof. Let us recall that, since $d_{2}(t)>0$, the degree of $D(x, t)$ with respect to $x$ is always $\geqslant 2$. From the outset, we shall solve the case where this degree is exactly 2 .

Degree of $\mathbf{D}(\mathbf{x}, \mathbf{t})=\mathbf{2}$. This means that $D(x, t$ has a double root at $x=\infty$, whence $d_{3}(t)=d_{4}(t)=0$ and the genus of the kernel is 0 for all non singular random walks. Then, by using 1.10 and remarking that $d_{3}(t) \leqslant 0$, we get the system

$$
\begin{equation*}
p_{1,0}=p_{1,1} p_{0,-1}=p_{0,1} p_{1,-1}=p_{1,1} p_{1,-1}=0 \tag{4.1}
\end{equation*}
$$

It is now easy to check that the set of relations 4.1), without taking into account the singular random walk $p_{1,0}=p_{1,1}=p_{1,-1}=0$, is tantamount to the pictures 2. and 3.

Degree of $\mathbf{D}(\mathbf{x}, \mathbf{t}) \geqslant \mathbf{3}$. We have proved in Theorem 2.1 that a double root can only occur at $x=0$. Then $d_{0}(t)=d_{1}(t)=0$, whence by using 1.10

$$
p_{-1,0}=p_{-1,1} p_{0,-1}=p_{0,1} p_{-1,-1}=p_{-1,1} p_{-1,-1}=0
$$

which corresponds to the pictures 1. and 4.
The proof of the theorem is terminated.

Remark 4.2. When $D(x, t)$ has a double root both at $x=0$ and $x=\infty$, we know from Lemma 3.2 that a factorization of the form $(3.2$ holds, and the walk is singular. On the other hand, it is worth noting that, for all $t \in] 0,1[$, the discriminant $D(x, t)$ can never have double root at $x=1$. This case can occur for $t=1$ and corresponds random walks having zero drift vectors (see [3, Section 2.3]).

Remark 4.3. The approach proposed in this paper applies verbatim to functional equations pertaining to the transient distribution of two-dimensional Markov processes, such as those encountered in queueing systems (see e.g., [3, Section 8.4]).

## References

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