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# Compiling Elementary Mathematical Functions into Finite Chemical Reaction Networks via a Polynomialization Algorithm for ODEs

Mathieu Hemery, François Fages, and Sylvain Soliman

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**Abstract.** The Turing completeness result for continuous chemical reaction networks (CRN) shows that any computable function over the real numbers can be computed by a CRN over a finite set of formal molecular species using at most bimolecular reactions with mass action law kinetics. The proof uses a previous result of Turing completeness for functions defined by polynomial ordinary differential equations (PODE), the dual-rail encoding of real variables by the difference of concentration between two molecular species, and a back-end quadratization transformation to restrict to elementary reactions with at most two reactants. In this paper, we present a polynomialization algorithm of quadratic time complexity to transform a system of elementary differential equations to PODE. This algorithm is used as a front-end transformation to compile any elementary mathematical function, either of time or of some input species, into a finite CRN. We illustrate the performance of our compiler on a benchmark of elementary functions relevant to CRN design problems in synthetic biology specified by mathematical functions. In particular, the abstract CRN obtained by compilation of the Hill function of order 5 is compared to the natural CRN structure of MAPK signalling networks.

## 1 Introduction

Chemical reaction networks (CRN) provide a standard formalism in chemistry and biology to describe, analyze, and also design complex molecular interaction networks. In the perspective of systems biology, they are a central tool to analyze the high-level functions of the cell in terms of their low-level molecular interactions. In the perspective of synthetic biology, they constitute a target programming language to implement in chemistry new functions in either living cells or artificial devices.

A CRN can be interpreted in a hierarchy of Boolean, discrete, stochastic and differential semantics [7,13] which is at the basis of a rich theory for the analysis of their dynamical properties [14,9,1], and more recently, of their computational power [7,6,11]. In particular, their interpretation by Ordinary Differential Equations (ODE) allows us to give a precise mathematical meaning to the notion of analog computation and high-level functions computed by cells [10,25,23], using the following definitions:

**Definition 1.** [11,16,26] A function  $f : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  is generated by a CRN on some species  $y$  with given initial concentrations for all species, if the ODE associated to the CRN has a unique solution verifying  $\forall t \geq 0 y(t) = f(t)$ .

That first definition states that a positive real function of one positive argument is *generated* by a CRN for some given initial concentration values, if the graph of that function is given by the temporal evolution of the concentration of one molecular species in that CRN.

**Definition 2.** [11,16] A function  $f : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  is computed by a CRN for some input species  $x$ , output species  $y$ , and initial concentrations given for all species apart from  $x$ , if for any input concentration value  $x(0)$  for  $x$ , the ODE initial value problem associated to the CRN has a unique solution satisfying<sup>1</sup>  $\lim_{t \rightarrow \infty} y(t) = f(x(0))$ .

The second definition states that the same function is *computed* by a CRN if for any input  $x \geq 0$ , and initialization of the CRN input species to value  $x$ , the CRN output species converges to the result  $f(x)$ . That definition for input/output functions computed by a CRN is used in [11] to show the Turing completeness of continuous CRNs in the sense that any computable function over the real numbers can be computed by a CRN over a finite set of formal molecular species using at most bimolecular reactions with mass action law kinetics. The proof uses a previous result of Turing completeness for functions defined by polynomial ordinary differential equation initial value problems (PIVP) [2], the dual-rail encoding of real variables by the difference of concentration between two molecular species [21,18], and a back-end quadratization transformation to restrict to elementary reactions with at most two reactants [5,19,3]. This proof gives rise to a pipeline, implemented in BIOCHAM-4<sup>2</sup>, to compile any computable real function presented by a PIVP into a finite CRN.

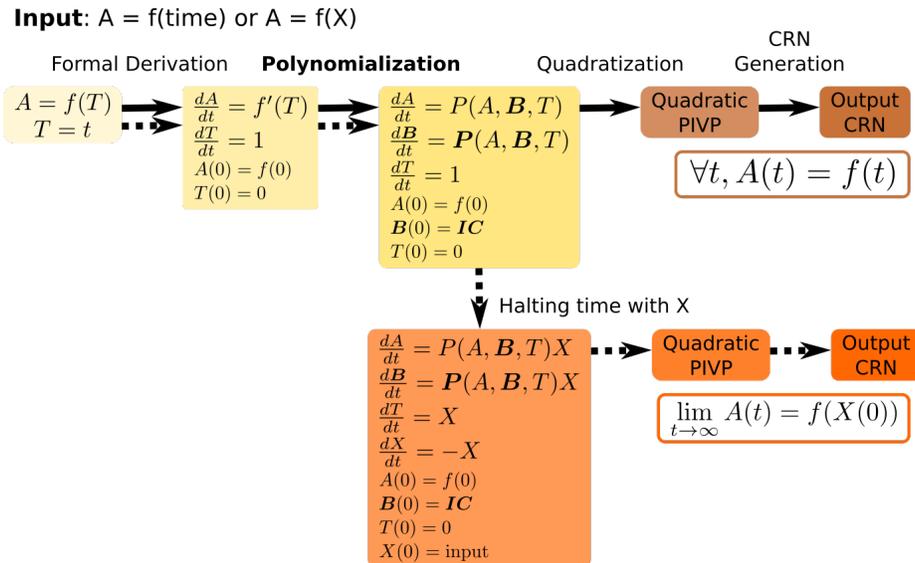
However in practice, it is not immediate to define a PIVP that generates or computes a desired function. In this article, we solve this problem for elementary functions over the reals, by adding to our compilation pipeline a front-end module to transform any elementary function to a PIVP which either generates or computes that function, as schematized in Fig. 1.

More precisely, we present a polynomialization algorithm to transform any Elementary ODE system (EODE), i.e. ODE system in explicit form made of elementary differential functions, to a polynomial one (PODE). This algorithm proceeds by introducing variables for computing the non-polynomial terms of the input, eliminating such terms from the ODE by rewriting, and obtaining the ODE for the new variables by formal derivation. The derivation steps may bring new non-polynomial terms requiring new variables. We show the termination of

<sup>1</sup> For the sake of simplicity of the definition given here, we omit the error control mechanism that requires one extra CRN species  $z$  verifying:

$$\forall t > 1 |y(t) - f(x(0))| \leq z(t), \forall t' > t z(t') < z(t) \text{ and } \lim_{t \rightarrow \infty} z(t) = 0.$$

<sup>2</sup> <http://lifeware.inria.fr/biocham/>. All experiments described in this paper are available at <https://lifeware.inria.fr/wiki/Main/Software#CMSB21>



**Fig. 1.** Polynomialization step in the complete pipeline for compiling a formally differentiable function  $f$  (termination is proved here for elementary functions) into a finite CRN, either a function of time (plain arrows) or an input/output function (dashed arrows):  $P$  and  $\mathbf{P}$  are polynomials, and  $\mathbf{B}$  denotes the set of species introduced by polynomialization given with initial conditions  $IC$ .

that algorithm, with quadratic time complexity, and that only a linear number of new variables, in terms of the size of the input expression, are actually needed.

Related work includes one method described in [24] to compute some polynomial abstractions of a non-polynomial system. That method progresses top-down from some set of possible functions given a priori, and progressively sieves them down to a polynomial system. This permits to choose the degree of the polynomial abstraction, but that method may fail if either the starting set of functions or the chosen degree are too small. On the other hand, our algorithm proceeds bottom-up, by introducing the functions when needed, with no choice a priori. A bottom-up approach closer to ours is also mentioned in [17] but for a very restricted grammar of functions while we develop here a general algorithm and prove its termination on the whole class of elementary mathematical functions. One can also cite the function `dpolyform` of Maple PDETools package which returns a PODE in implicit form for which the expression given as input is guaranteed to be a solution, but that does not provide a polynomial expression for the derivative of each variable, i.e. a PODE in explicit form, as required for our compilation pipeline.

The rest of the paper is organized as follows. In the next section, we describe the language of elementary function that are accepted as input of our compilation pipeline into CRN. In Sec. 3, we present a general polynomialization algo-

rithm for elementary ODEs, prove its termination, and show its quadratic time complexity. In Sec. 4 we describe the use of this algorithm as a front-end transformation in our compilation pipeline to compile any elementary mathematical function into a finite CRN. In Sec. 5 we evaluate this approach on a benchmark of elementary functions relevant to CRN design problems in synthetic biology used in [19]. In particular, we compare the CRN synthesized for the Hill function of order 5 to the structure of the natural MAPK signalling CRNs that have been shown to implement a similar input/output function [20]. Finally, we conclude on the results achieved and several perspectives for future work.

## 2 Input Language of Elementary Functions

### 2.1 Example

Let us consider the problem of synthesizing a CRN to *generate* the function of time:  $A(t) = \log(1+t^2)$  in the sense of Def. 1. The compilation method described in [11] takes as input a PIVP which admits that function as solution on variable  $A$ . Here, we want to automate the construction of such a PIVP.

The first step of our front-end transformation is schematized in Fig. 1, is to determine an ODE which admits that function of time as solution. For this, one can simply take the derivative of the equation with respect to time and set as initial condition the value for the desired function at 0, giving:

$$\frac{dA}{dt} = \frac{2t}{1+t^2} \quad A(0) = 1$$

Then we need to transform this ODE to a PODE. Our polynomialization algorithm will introduce a new variable  $B = \frac{1}{1+t^2}$ , and similarly compute its derivative and its initial value, as follows:

$$\frac{dB}{dt} = \frac{-2t}{(1+t^2)^2} = -2tB^2 \quad B(0) = 1$$

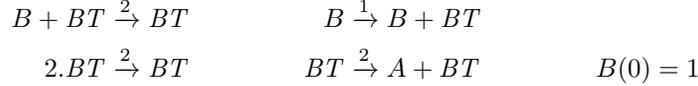
We also need to introduce a variable  $T$  for time with  $\frac{dT}{dt} = 1$  and  $T(0) = 0$ , giving the following PIVP:

$$\begin{array}{lll} \frac{dA}{dt} = 2.T.B & \frac{dB}{dt} = -2.T.B^2 & \frac{dT}{dt} = 1 \\ A(0) = 1 & B(0) = 1 & T(0) = 0 \end{array}$$

Note that the termination of those transformations is not obvious in general. It is proved in the next section. That PIVP of degree 3 can now be used as input of our previous compilation pipeline [11]. It is first transformed to a quadratic form [19], in this case by introducing one variable,  $BT = B.T$ , and removing the time  $T$ , giving the following quadratic PIVP:

$$\begin{array}{lll} \frac{dA}{dt} = 2.BT & \frac{dB}{dt} = -2.BT.B & \frac{d(BT)}{dt} = \frac{dB}{dt}.T + B\frac{dT}{dt} = -2.BT^2 + B \\ A(0) = 1 & B(0) = 1 & BT(0) = 0 \end{array}$$

One reaction with mass action law kinetics is then generated for each monomial of the ODE. Since in this example the reactions are well-formed and strict the system is positive (lemma 1 in [12]). There is thus no need to introduce dual-rail variables for negative values, and the generated elementary CRN (with rate constants written above the arrow) is:



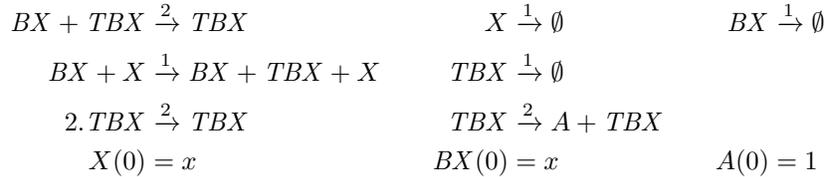
Now, it is worth noting that if we want to synthesize a CRN that *computes* (instead of generating) the function  $\log(1 + x^2)$  of some input  $x$  in the sense of Def. 2, the general method described in [22,11] consists in introducing a variable  $X$ , initialized to value  $x$ , multiplying the terms of the PIVP for generating the function, and following a decreasing exponential to halt the PIVP on the prescribed input. The previous PIVP of degree 3 thus becomes a PIVP of degree 4 by this transformation:

$$\begin{array}{llll}
\frac{dX}{dt} = -X & \frac{dA}{dt} = 2.T.B.X & \frac{dB}{dt} = -2.T.B^2.X & \frac{dT}{dt} = X \\
X(0) = x & A(0) = 1 & B(0) = 1 & T(0) = 0
\end{array}$$

The quadratization algorithm [19] now introduces new variables  $BX$  and  $TBX$  for the corresponding monomials, and removes variables  $T$  and  $B$ . This generates the following quadratic PIVP:

$$\begin{array}{ll}
\frac{dX}{dt} = -X & \frac{dBX}{dt} = \frac{dB}{dt}X + B\frac{dX}{dt} = -2.BX.TBX - BX \\
\frac{dA}{dt} = 2.TBX & \frac{dTBX}{dt} = BX.X - 2.TBX^2 - TBX \\
X(0) = x & BX(0) = x \quad A(0) = 1 \quad TBX(0) = 0
\end{array}$$

and finally the following elementary CRN which computes the  $\log(1 + x^2)$  function:



## 2.2 Elementary Functions as Compilation Pipeline Input Language

In mathematics, elementary functions refer to unary functions (over the reals in our case) that are defined as a sum, product or composition of finitely many polynomial, rational, trigonometric, hyperbolic, exponential functions and their

inverses. Most of these functions are defined on the real axis but a few exceptions are worth mentioning: the inverse of some function is restricted to the image of  $\mathbb{R}$  by the function (e.g.,  $\arccos$  is only defined on  $[-1, 1]$ ) and the exponentiation may be non-analytic in 0 and is thus considered elementary only on an open interval that does not include 0.

The set of elementary functions of  $x$  is formally defined as the least set of functions containing:

- Constants:  $2, \pi, e$ , etc.
- Polynomials of  $x$ :  $x + 1, x^2, x^3 - 42x$ , etc.
- Powers of  $x$ :  $\sqrt{x}, \sqrt[3]{x}, x^{-4}$ , etc.
- Exponential and logarithm functions:  $e^x, \ln x$
- Trigonometric functions:  $\sin x, \cos x, \tan x$ , etc.
- Inverse trigonometric functions:  $\arcsin x, \arccos x$ , etc.
- Hyperbolic functions:  $\sinh x, \cosh x$ , etc.
- Inverse hyperbolic functions:  $\operatorname{arsinh} x, \operatorname{arcosh} x$ , etc.

and closed by arithmetic operations (addition, subtraction, multiplication, division) and composition. Elementary functions are also closed by differentiation but not necessarily by integration. On the other hand hyper-geometric functions, Bessel functions, gamma, zeta functions, are examples of (computable) non-elementary functions.

### 3 Polynomialization Algorithm for Elementary ODEs

#### 3.1 Polynomialization Algorithm

The core of Alg. 1 for polynomializing an EODE system is the detection of the elements of the derivatives that are not polynomial and their introduction as new variables. Then symbolic derivation and syntactic substitution allow us to compute the derivatives of the new variables and to modify the system of equations accordingly.

It is worth noting that the list of substitutions has to be memorized along the way, therefore handling an algebraic-differential system during the execution of the algorithm, since they may reappear during the derivation step. This typically occurs when the derivation graph harbors a cycle like:  $\cos \rightarrow \sin \rightarrow \cos$  (Fig. 2).

Nevertheless, a particular treatment has to be applied to the case of non-integer or negative power as they form an infinite set and may thus produce infinite chains of derivations. This can be seen if we try to apply naively Alg. 1 on this simple example:

$$\frac{dA}{dt} = A^{0.4}$$

for which we introduce the new variable  $B = A^{0.4}$  with

$$\frac{dB}{dt} = 0.4A^{-0.6} \quad \frac{dA}{dt} = 0.4A^{-0.2}$$

---

**Algorithm 1** Polynomialization of an EODE system

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- 1: **Input:** A set of ODEs of the form  $\{x' = f_x(x, y, \dots), y' = f_y(x, y, \dots), \dots\}$ .
  - 2: **Output:** A set of PODEs where the initial variables  $x, y, \dots$  are still present and accept the same solutions.
  - 3: **Initialize**  $Transformations \leftarrow \emptyset$  and  $PolyODE \leftarrow \emptyset$
  - 4: **while** ODE is not empty **do**
  - 5:     take and remove  $Var' = Derivative$  from  $ODE$ ;
  - 6:      $NewDerivative \leftarrow$  apply  $Transformations$  to  $Derivative$ ;
  - 7:      $Terms \leftarrow$  set of maximal non-polynomial subterms of  $NewDerivative$ ;
  - 8:     **for all**  $Term$  in  $Terms$  **do**
  - 9:         add  $(Term \mapsto NewVar)$  to  $Transformations$ ;
  - 10:          $TermDerivative \leftarrow$  the symbolic derivative of  $Term$ ;
  - 11:         add  $(NewVar' = TermDerivative)$  to  $ODE$ ;
  - 12:      $PolyDerivative \leftarrow$  apply  $Transformations$  to  $Derivatives$ ;
  - 13:     add  $(Var' = PolyDerivative)$  to  $PolyODE$ ;
  - 14: **return**  $PolyODE$
- 

At this point, it is tempting to introduce  $C = A^{-0.2}$  but that would lead to an infinite loop, introducing more and more powers of  $A$ .

This can be easily avoided by introducing  $C = \frac{1}{A}$  instead, then:

$$\frac{dB}{dt} = 0.4B^2C$$
$$\frac{dC}{dt} = -\frac{1}{A^2} \quad \frac{dA}{dt} = -C^2B$$

There is therefore a specific treatment to do when introducing the new variable of an exponentiation in order to force the algorithm to use the inverse variable instead of an infinite sequence of variables. For this, when adding the new variable  $N = X^p$  to the system, we explicitly replace the expression  $X^{p-1}$  by  $N/X$  in the derivatives, thus making the use of  $1/X$  a natural consequence. Of course, this makes the final PODE non analytic in  $X = 0$ . This is linked to the fact that exponentiation apart from the polynomial case is actually not analytic in 0, and it is thus not surprising that computation fails if we reach a time where  $X = 0$ .

### 3.2 Interval of definition

Elementary functions are analytic upon open interval of their domain, but may suffer from non-analyticity on the boundary. For example exponentiation with a non integer coefficient may be extended by continuity in 0 but is not analytic here. During our polynomialization, this kind of behaviour may lead to the appearance of species that diverge on these points. This is important as it can be shown that only analytic functions can be generated by a PIVP.

In particular, the absolute value function over the reals is elementary as it can be expressed as the composition of a power and root of  $x : |x| = \sqrt{x^2}$ . But is not

analytic on 0. Hence, if we consider the EODE  $\frac{dx}{dt} = |x|$ , our polynomialization will introduce the variables  $y = |x|$  and  $z = \frac{1}{x}$ , to obtain the PODE:

$$\frac{dx}{dt} = y \quad \frac{dy}{dt} = y^2 \cdot z \quad \frac{dz}{dt} = -(z^2 \cdot y)$$

And when  $x$  approaches 0, the variable  $z$ , its inverse, will diverge.

The unicity of the solution of a PIVP is constrained by the initial conditions, but this unicity is not ensured when passing a non-analyticity. A consequence of this remark is that our compiled solution is defined from its initial condition ( $t = 0$ ) up to the first non-analyticity of the compiled function.

### 3.3 Termination

Before proving the termination of our algorithm for the input set of elementary functions over the reals, we can show a general lemma for any set  $F$  of formally differentiable, possibly multivariate, real functions. Let  $\bar{F}$  denote the closure of  $F \cup \mathbb{R}$  by addition and multiplication, that is the algebra of  $F$  over  $\mathbb{R}$ .

**Lemma 1.** *For any finite set  $F$  of formally differentiable functions over the reals such that  $\forall f \in F, f' \in \bar{F}$ , Alg. 1 terminates.*

*Proof.* In the **while** loop, since we detect all the non-polynomial parts of the derivatives in one pass, we are sure that the derivative at hand in each **while** step becomes polynomial. New variables may however be introduced in such a step, thus the only possibility of non-termination is to introduce an infinity of new variables.

The proof of termination proceeds by cases on the structure of the derivatives. Suppose we have an ODE on the set of variables  $\{X_i\}$  with  $i \in [1, n]$  and let us denote by  $d(X_i)$  the derivative of  $X_i$ . First, it is obvious that if  $d(X_i)$  is a single variable or a constant (numeric or parameter) then we have nothing to do. Similarly, for every expression composed by addition or multiplication of such terms, they are already polynomial.

If the new variable is a function of several variables (here 2):  $Y = f(X_j, X_k)$ , we have:

$$\frac{dY}{dt} = \frac{\partial f(X_j, X_k)}{\partial X_j} d(X_j) + \frac{\partial f(X_j, X_k)}{\partial X_k} d(X_k)$$

and as the addition is allowed in polynomial, we can consider separately the two derivatives. Thus, we can restrict ourselves to the case of functions of a single variable.

For a function of a single variable with no composition we have:

$$\frac{dy}{dt} = \frac{df(X_i)}{dt} = f'(X_i)d(X_i)$$

we have seen that  $d(X_i)$  is already polynomial but nothing ensures that  $f'$  is. However by definition of our set  $F$ ,  $f'(X_i)$  may be expressed with other function of  $X$  in the set  $F$ , all applied to  $X_i$ , since composition is not allowed in



Nevertheless, as explained above, the algorithm terminates also in this case since we express the derivative in the form:

$$f'(x) = \alpha x^{\alpha-1} = \alpha f(x) \frac{1}{x} \quad (1)$$

and the inverse function is in  $F$ , henceforth the case of exponentiation also terminates.

### 3.4 Complexity

To estimate the computational time complexity of Alg. 1, let us first determine a bound on the number of new variables introduced in the system.

**Proposition 1.** *Alg. 1 introduces at most a linear number of variables in the size of the input.*

*Proof.* For each elementary function  $f$ , represented in Fig. 2, we have to introduce recursively all the functions on which rely its derivative, in terms of the (directed) dependency graph, this is the reachable set starting from  $f$ . In this case the largest reachable set is of cardinal 3. More generally, let us call  $\ell$  the cardinal of the largest set of reachable nodes starting from a single node. Then, each elementary function that is not already polynomial introduces at most  $\ell$  variables.

Hence, we have to introduce at most  $\ell F$  variables where  $F$  is the number of functions used in the ODE. Of course,  $F$  is bounded by the size of the input.

**Proposition 2.** *Alg. 1 has a quadratic time complexity.*

*Proof.* To introduce a new variable, we have to first compute its derivative, and then substitute its expression in the remainder of the ODE. Both operations are linear in the size of the current system size, and we just have seen that this one will grow at most as a linear function of the input size, giving only a linear dependency. Thus, our algorithm is quadratic in the size of the input.

### 3.5 Remark on the Compilation of the Exponentiation

In the compilation of the exponentiation described in Sec. 3.1 we introduce two variables, but this raises an interesting question concerning the conditions under which a differential equation of the form:  $\frac{dA}{dt} = A^\alpha$  can be set in polynomial form by introducing only one variable. Indeed, if we introduce  $B = A^\beta$  we have:

$$\frac{dB}{dt} = \beta A^{\beta-1} \quad \frac{dA}{dt} = \beta A^{\alpha+\beta-1}$$

and to be polynomial we need to find four positive integers  $i, j, k, l$  such that:

$$\begin{aligned} \alpha &= i + j\beta \\ \alpha + \beta - 1 &= k + l\beta \end{aligned}$$

We thus need that  $\alpha$  be of the form:  $\alpha = \frac{j(k+1) + i(1-l)}{j+1-l}$

Clearly, only a fractional power can be reduced in one step. Now suppose that  $\alpha = \frac{p}{q}$  then we have by identifying numerator and denominator and setting  $l = 2$ :

$$j = q - 1 + l = q + 1 \quad \text{and} \quad k = \frac{p+i}{1+q} - 1$$

an equation that always admits solutions with  $i$  and  $k$  positive. For example  $\alpha = \frac{1}{3}$  may be solved with  $\beta = \frac{-2}{3}$  and  $i = 3, j = 4, k = 0, l = 2$ . But this uses a polynomial of order 7 which may impact negatively the final quadratization phase [19]. For these reasons, we chose to treat exponentiation by systematically introducing two variables.

## 4 CRN Compilation Pipeline for Elementary Functions

### 4.1 Detailed Example

To illustrate the behavior of our complete pipeline schematized in Fig. 1, let us consider the compilation of the Hill function  $H = \frac{x}{1+x}$  into a CRN that computes  $H(x)$  in the sense of Def. 2, i.e., such that the final concentration of species  $H$  gives the result  $\lim_{t \rightarrow \infty} H(t) = \frac{x}{1+x}$ .

The first step of the front-end transformation is to introduce a pseudo-time variable:  $T = t$  and replace the input  $X$  by  $T$  in the expression  $H = \frac{T}{1+T}$ , and then to compute the formal derivative of  $H$  to obtain the ODE:

$$\frac{dH}{dt} = \frac{1}{(1+T)^2} \quad \frac{dT}{dt} = 1$$

The second step is to polynomialize that ODE with Alg. 1. This is done by examining the right hand side of the derivative of  $H$  and introduce as new variable  $A = \frac{1}{(1+T)}$  which allows us to rewrite  $\frac{dH}{dt} = A^2$ . We also need to compute the derivative of this new variable:

$$\frac{dA}{dt} = -A^2, \quad A(0) = 1$$

This PIVP generates the time function  $H(t)$  in the sense of Def. 1.

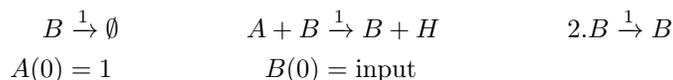
Now, we enter the compilation pipeline from PIVP described in [11]. To compute the function  $H(x)$  of input  $x$ , a new variable  $X$  that obeys a decreasing exponential is introduced and used to halt all other derivatives at time  $x$ :

$$\begin{aligned} \frac{dH}{dt} &= A^2 \cdot X & \frac{dX}{dt} &= -X \\ \frac{dA}{dt} &= -A^2 \cdot X & \frac{dT}{dt} &= X \\ H(0) &= 0 & X(0) &= x \\ A(0) &= 1 & T(0) &= 0 \end{aligned}$$

Then the quadratization step [19], introduces the new variable  $B = A.X$ . Interestingly, intermediary variables  $X$  and  $T$  are no longer used and removed. We finally get:

$$\begin{array}{lll} \frac{dH}{dt} = A.B & \frac{dB}{dt} = -B - B^2 & \frac{dA}{dt} = -A.B \\ H(0) = 0 & B(0) = x & A(0) = 1 \end{array}$$

And the compiled CRN is:



## 4.2 Implementation

Alg. 1 is implemented by rewriting formal expressions using a simple algebraic normal form and standard derivation rules.

The most computationally expensive step of our complete compilation pipeline in Fig. 1 is the quadratization of the intermediate PIVP to a PIVP of order at most 2. This step is necessary to restrict ourselves to elementary reactions with at most two reactants which are more amenable to real implementations with real enzymes. While the existence of a quadratic form for any PODE can be simply shown by introducing an exponential number of variables [5], the problem of minimizing the dimension of that quadratization is NP-hard [19]. In the implementation of BIOCHAM used in the next section, we use both the MAXSAT algorithm described in [19] (option `sat_species` below) and a heuristic algorithm (option `fastnSAT` below) to first obtain a subset of variables guaranteed to contain a quadratic solution, and then call the MAXSAT solver (RC2<sup>3</sup>) to minimize the dimension in that quadratization.

## 5 Evaluation

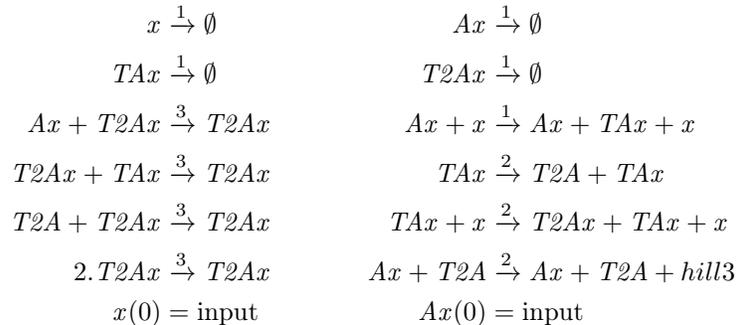
In this section, we consider the benchmark of functions already considered in [19] for quadratization problems. Table 1 gives some performance figures about the complete compilation pipeline in terms of total computation time and size of the synthesized CRNs, with the two options discussed above for quadratization. It is worth noting that those synthetic CRNs are not unique and that other CRNs could be synthesized for the same function, by making different choices in both our polynomialization and quadratization algorithms. Even when imposing optimality in the number of introduced variables, there may exist several optimal CRNs. For example, the two CRNs obtained for Hill4 compiled with the two options for quadratization are different but both have the same number of species and reactions (Table 1).

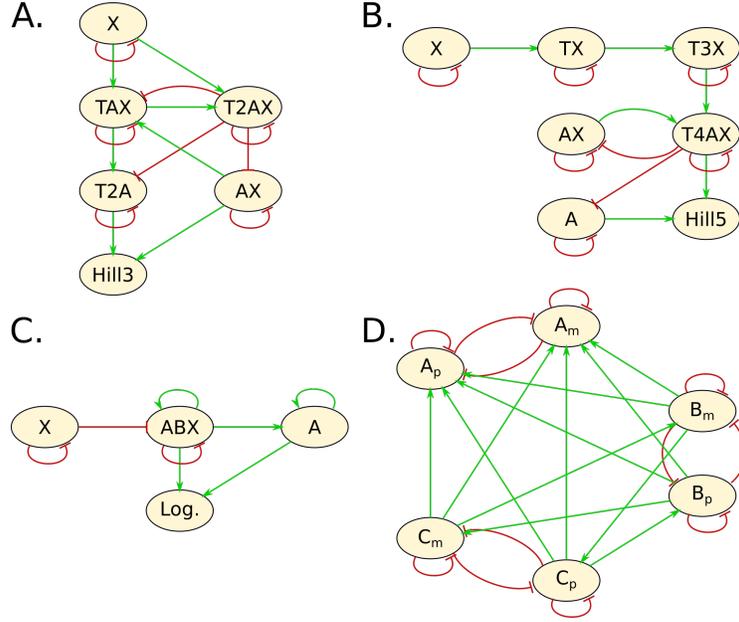
<sup>3</sup> <https://pysathq.github.io/docs/html/api/examples/rc2.html>

Function	fastnSAT			sat_species		
	time (ms)	number of species	number of reactions	time (ms)	number of species	number of reactions
Hill1	80	4	5	85	3	3
Hill2	90	6	10	82	5	8
Hill3	100	6	10	115	6	12
Hill4	100	7	13	162	7	13
Hill5	110	8	16	550	7	11
Hill10	160	13	31	timeout		
Hill20	380	23	61	timeout		
Logistic	80	3	5	85	3	5
Double exp.	80	3	4	85	3	4
Gaussian	85	3	4	85	3	4
Logit	95	4	7	100	4	6

**Table 1.** Performance results on the benchmark of CRN design problems of [19] in terms of total compilation time, and size of the synthesized CRN with two options for quadratization.

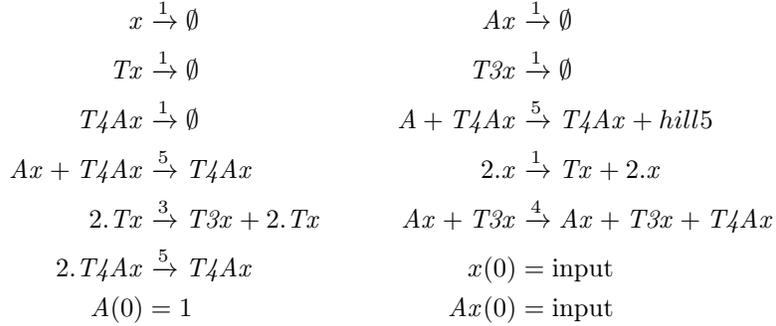
Let us examine the influence graphs of those synthetic CRNs since they provide a more compact abstract representation of the reaction graph [13]. Fig. 3 depicts the influence graphs between molecular species of the synthesized CRNs for the hill functions of order 3 (Fig. 3A.) and 5 (Fig. 3B.), the logistic function (Fig. 3C) and the square of the cosine function (Fig. 3). One can remark on those examples that the outputs of the synthesized CRN do not participate in any feedback reaction. This is however not necessarily the case of the CRNs synthesized by our pipeline, as shown for instance by the cosine function [11]. More precisely, the Hill3 CRN in Table 1 synthesized with the `sat_species` option is the following:





**Fig. 3.** Influence graphs of four of the synthetic CRNs of Table 1. **A.** and **B.** respectively implement the Hill function of order 3 and 5. **C.** corresponds to the logistic function and **D.** computes the square of the cosine of the time. In this last example, the output is only read on  $A_p$  but the presence of its negative part  $A_m$  is actually a crucial part of the computation despite having an essentially null concentration.

The Hill5 CRN in the table synthesized with the same option is:



From our computational point of view, the Hill5 CRN above is one synthetic analog of the natural MAPK CRN among others. Indeed, the natural MAPK signalling network has been shown in [20] to compute an ultrasensitive input/output function which is well approximated by a Hill function of order 4.9. Both the natural MAPK CRN and the synthetic Hill5 CRN thus compute a similar input/output function and it makes sense to try to compare their structure.

In term of size, the MAPK model of [20] comprises 22 species and 30 reactions, while the Hill5 CRN synthesized by our pipeline now uses only 7 formal molecular species and 11 elementary reactions. This shows a huge improvement with respect to our first results reported in [11] where several tens of reactions were synthesized for Hill functions. In term of topological structure, we have checked that there exists (several) subgraph epimorphisms [15] mapping the MAPK CRN to that Hill5 CRN, meaning that the MAPK CRN somehow contains the core structure of the synthetic Hill5 CRN in some non-trivial sense. The biological significance of those relationships is however still unclear, although one could expect to explain it in terms of robustness properties [4]. It is also worth noting that in the natural MAPK CRN structure, the input is a catalyst that is not consumed by the downward reactions, whereas in our CRN synthesis scheme, the input is generally consumed by the downward reactions. The MAPK network thus illustrates a case of online analog computation which is currently not treated by our theoretical framework.

## 6 Conclusion and Perspectives

We have presented an algorithm to transform any system of elementary ordinary differential equations to a polynomial ordinary differential equation system preserving the solutions of the original variables. This algorithm of quadratic time complexity introduces at most a linear number of new variables. This algorithm allows us to automatically compile any elementary mathematical function into a finite CRN, using a pipeline of transformations starting from the formal derivation of the elementary function to generate or compute, the polynomialization of the elementary ODE, and continuing with the previous pipeline of [11] for the dual-rail encoding of negative values of the PODE [18,21], the quadratization of the PODE [19], and the synthesis of elementary reactions for the quadratic ODEs [12].

The implementation in BIOCHAM-4 of this complete pipeline has been used to illustrate the CRNs synthesized for a variety of elementary mathematical functions used as specification. In particular, the CRN synthesized for the Hill function of order 5 provides a synthetic analog of the MAPK signalling network which has been shown to compute a similar ultrasensitive input/output function [20]. In this compilation process, the quadratization part is the most complex one since minimizing the dimension of the result is a NP-hard problem [19]. On the benchmark presented here, our maxSAT implementation is sufficient but we also use by default a heuristic algorithm that trades optimality for better performance. It should also be noted that a new algorithm has been recently proposed for the global optimization problem in [3].

This work may be improved in several directions. We might extend this approach to multivariate functions. This is not trivial as the trick of halting the time at the input value needs be generalized to several inputs.

Another important point is to investigate is the variety of different CRNs that can be synthesized by our pipeline. As pointed out earlier, there may be

several optimal solutions to the quadratization problem and there may similarly be several polynomializations of a given ODE introducing the same number of variables. Our pipeline make choices to deterministically propose one solution, but being able to explore the set of solutions and compare their properties with respect to metrics like robustness to initial conditions or reaction rates, or imposing some similarity requirement with a given biological solution would be interesting.

Furthermore, the comparison to the MAPK network also points to the interesting class of online computation which does not consume the inputs, whereas in our approach the input species are consumed, and the synthesized CRN would need to be reinitialized for another computation. This limitation is not a problem for one-shot CRN programs such as those designed for medical diagnosis applications [8], but synthesizing a CRN for computing an input/output function online appears to be a harder problem worthy of further theoretical investigation.

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