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***Stochastic Dynamics of Discrete Curves and
Exclusion Processes.
Part 1: Hydrodynamic Limit of the ASEP System***

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Thème BIO



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Stochastic Dynamics of Discrete Curves and Exclusion Processes.

Part 1: Hydrodynamic Limit of the ASEP System

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Abstract: This report is the foreword of a series dedicated to stochastic deformations of curves. Problems are set in terms of exclusion processes, the ultimate goal being to derive hydrodynamic limits for these systems after proper scalings. In this study, solely the basic ASEP system on the torus is analyzed. The usual sequence of empirical measures, converges in probability to a deterministic measure, which is the unique weak solution of a Cauchy problem. The method presents some new features, letting hope for extensions to higher dimension. It relies on the analysis of a family of parabolic differential operators, involving variational calculus. Namely, the variables are the values of functions at given points, their number being possibly infinite.

Key-words: Exclusion process, hydrodynamic limit, martingale, Cauchy problem, weak solution, distribution, parabolic operator.

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Dynamique stochastique de courbes discrètes et processus d'exclusion. Partie 1: Sur la limite hydrodynamique du système ASEP

Résumé : Cette étude est la première pierre d'une suite de rapports consacrés aux déformations stochastiques de courbes. Les problèmes sont posés en termes de processus d'exclusion, le but final étant d'obtenir des équations hydrodynamiques pour ces systèmes, après changements d'échelle adéquats. Ici, nous n'analysons que le système ASEP sur le tore $\mathbb{Z}/N\mathbb{Z}$. La suite habituelle des mesures empiriques converge en probabilité, lorsque $N \rightarrow \infty$, vers une mesure déterministe, unique solution faible d'un problème de Cauchy. La méthode proposée présente quelques traits nouveaux, laissant espérer des généralisations à des dimensions supérieures. Elle s'appuie sur l'analyse d'une famille d'opérateurs paraboliques, avec calcul au sens des variations. De fait, les variables sont les valeurs prises par une fonction sur un ensemble de points, dont le nombre est possiblement infini.

Mots-clés : Processus d'exclusion, limite hydrodynamique, martingale, problème de Cauchy, solution faible, opérateur parabolique.

1 Preliminaries

Interplay between discrete and continuous description is a recurrent question in statistical physics, which in some cases can be answered quite rigorously via probabilistic methods. In the context of reaction-diffusion systems, this is tantamount to studying fluid or hydrodynamics limits. Number of approaches have been proposed, in particular in the framework of exclusion processes, see e.g. [12],[2] [15], [11] and references therein. As far as fluid limits are at stake, all these methods have in common to be limited to systems for which the stationary states are given in closed product forms, as far as hydrodynamic limits are concerned, or at least for which the invariant measure for finite N (the size of the system) is explicitly known. For instance, ASEP with open boundary can be described in terms of matrix product form (a sort of a non-commutative product form) and the continuous limits can be understood by means of brownian bridges (see [3]). We propose to adress this question from the following different point of view: starting from discrete sample paths subjected to stochastic deformations, the ultimate goal is to understand the nature of the limit curves when N increases to infinity. How do these curves evolve with time, and which limiting process do they represent as t goes to infinity (equilibrium curves)? Following [8] and [9], we will try to give some partial answers to these questions in a series of papers.

This first study is mainly dedicated to the ASEP model. The mathematical approach relies on the analysis of specific partial differential equations involving variational calculus. A usual sequence of empirical measures is shown to converge in probability to a deterministic measure, which is the unique weak solution of a Cauchy problem. Here variables are the values of some function at given points and their number becomes infinite. In our opinion, the method presents some new features, which let hope for extensions to higher dimension.

A future concern will be to establish a complete hierarchy of systems of hydrodynamic equations , whose steady state will help to describe non-Gibbs states.

2 Model definition

2.1 A stochastic clock model

The systems we will consider can typically be described as an oriented path embedded in a bidimensional manifold: N steps of equal size, each one being chosen among a discrete set of n possible orientations drawn from the set $\{2k\pi/n, k = 0 \dots n - 1\}$ of angles with some given origin. The stochastic dynamics which is applied consists in displacing one single point at a time without breaking the path, while keeping all links within the set of admissible orientations. In this operation two links are displaced. This constrains quite strongly the possible dynamical rules, which are given in terms of *reactions* between consecutive links.

We have

$$X^k X^l \xrightleftharpoons[\lambda^{lk}]{\lambda^{kl}} X^l X^k, \quad k \in [1, n], k \neq l.$$

2.2 Examples

(1) *The simple exclusion process*

The first elementary and most studied example is the simple exclusion process: this model, after mapping particles onto links, corresponds to a one-dimensional fluctuating interface. Here we have a binary alphabet and letting $X^1 = \tau$ and $X^2 = \bar{\tau}$, the set of reactions simply rewrites

$$\tau \bar{\tau} \xrightleftharpoons[\lambda^+]{\lambda^-} \bar{\tau} \tau,$$

where λ^\pm are the transition rates for the jump of a particle to the right or to the left.

(2) *The triangular lattice and the ABC model*

Here the evolution of the random walk is restricted to the triangular lattice. Each link (or step) of the walk is either 1, $e^{2i\pi/3}$ or $e^{4i\pi/3}$, and quite naturally will be said to be of type A, B or C, respectively. This corresponds to the so-called *ABC model*, since there is a coding by means of a 3-letter alphabet. The set of *transitions* (or

reactions) is given by



where there is a priori no symmetry, but we will impose *periodic boundary conditions* on the sample paths. This model was first introduced in [6] in the context of particles with exclusion, and for some cases corresponding to the reversibility of the process, a Gibbs form for the invariant measure was given in [7]

3 Hydrodynamics for a one-dimensional asymmetric exclusion process [ASEP]

As mentioned above, we aim at obtaining hydrodynamic equations for a class of exclusion models. The method, although relying on classical powerful tools (martingales, relative compactness of measures, functional analysis), has some new features which should hopefully prove fruitful in other contexts. The essence of the approach is in fact contained in the analysis of the popular ASEP model, presented below. We note the difficulty to find in the existing literature a complete study encompassing various special cases (symmetry, total asymmetry, etc). Some proofs will only be sketched, and the related results presented as claims or even conjectures.

Consider N sites labelled from 1 to N , forming a discrete closed curve in the plane, so that the numbering of sites is implicitly taken modulo N , i.e. on the discrete torus $\mathbf{G}^{(N)} \stackrel{\text{def}}{=} \mathbb{Z}/N\mathbb{Z}$. In higher dimension, say on the lattice \mathbb{Z}^k , the related set of sites would be drawn on the torus $(\mathbb{Z}/N\mathbb{Z})^k$.

We gather below some notational material valid throughout this section.

- \mathcal{R} stands for the real line. $\mathcal{C}^k[0,1]$ is the collection of all real-valued, k -continuously differentiable functions defined on the interval $[0,1]$, and \mathcal{M} is the space of all finite positive measures on the torus $\mathbf{G} \stackrel{\text{def}}{=} [0,1]$.

$\mathcal{C}_0^\infty(K)$ is the space of infinitely differentiable functions with compact support included in K .

- For \mathbf{S} an arbitrary metric space, $\mathcal{P}(\mathbf{S})$ is the set of probability measures $\mathcal{D}_{\mathbf{S}}[0, T]$ is the space of right continuous functions $z : [0, \infty] \rightarrow \mathbf{S}$ with left limits and $t \rightarrow z_t$.

- For $i = 1, \dots, N$, let $A_i^{(N)}(t)$ and $B_i^{(N)}(t)$ be binary random variables representing respectively a particule or a hole at site i , so that, owing to the exclusion constraint, $A_i^{(N)}(t) + B_i^{(N)}(t) = 1$, for all $1 \leq i \leq N$. Thus $\{\mathbf{A}^{(N)}(t) \stackrel{\text{def}}{=} (A_i^{(N)}(t), \dots, A_N^{(N)}(t)), t \geq 0\}$ is a Markov process.
- $\Omega^{(N)}$ will denote the generator of the Markov process $\mathbf{A}^{(N)}(t)$, and $\mathcal{F}_t^{(N)} = \sigma(\mathbf{A}^{(N)}(s), s \leq t)$ is the associated natural filtration.
- Our purpose is to analyze the sequence of empirical random measures

$$\mu_t^{(N)} = \frac{1}{N} \sum_{i \in \mathbf{G}^{(N)}} A_i^{(N)}(t) \delta_{\frac{i}{N}}, \quad (3.1)$$

when $N \rightarrow \infty$, after a convenient scaling of the parameters of the generator $\Omega^{(N)}$. The probability distribution associated with the path of the Markov process $\mu_t^{(N)}$, $t \in [0, T]$, for some fixed T , is simply denoted by $Q^{(N)}$.

As usual, one can embed $\mathbf{G}^{(N)}$ in \mathbf{G} , so that a point $i \in \mathbf{G}^{(N)}$ corresponds to the point i/N in \mathbf{G} . Hence, in view of (3.1), it is quite natural to let the sequence $Q^{(N)}$ be defined on a unique space $\mathcal{D}_{\mathcal{M}}[0, T]$, which becomes a polish space (i.e. complete and separable) via the usual Skorokod topology, as soon as \mathcal{M} is itself Polish (see e.g. [5], chapter 4). Without further comment, \mathcal{M} is assumed to be endowed with the vague product topology, as a consequence of the famous Banach-Alaoglo and Tychonoff theorems (see e.g. [13, 10]).

Let ϕ_a, ϕ_b be two arbitrary functions in $\mathbf{C}^2[0, 1]$ and define the real-valued positive measure

$$Z_t^{(N)}[\phi_a, \phi_b] \stackrel{\text{def}}{=} \exp \left[\frac{1}{N} \sum_{i \in \mathbf{G}^{(N)}} \phi_a \left(\frac{i}{N} \right) A_i^{(N)}(t) + \phi_b \left(\frac{i}{N} \right) B_i^{(N)}(t) \right], \quad (3.2)$$

which is a functional of ϕ_a, ϕ_b . For the sake of brevity, the explicit dependence of $A_i^{(N)}(t), B_i^{(N)}(t), Z_t^{(N)}[\phi_a, \phi_b]$ on N, t, ϕ , will be omitted wherever the meaning remains clear from the context: for instance, we often shall simply write A_i, B_i or $Z_t^{(N)}$. Also $Z^{(N)}$ stands for the process $\{Z_t^{(N)}, t \geq 0\}$.

A standard powerful method to prove the convergence (in a sense to be specified later) of the sequence of probability measures introduced in (3.1) consists first in showing its relative compactness, and then in verifying the coincidence of all possible limit points (see e.g. [11]). Moreover here it suffices to prove these two properties

for the sequence of projected measures defined on $\mathcal{D}_{\mathcal{R}}[0, T]$ and corresponding to the processes $\{Z_t^{(N)}[\phi_a, \phi_b], t \geq 0\}$, since the functions ϕ belong to $\mathbf{C}^2[0, 1]$.

Let us now introduce quantities which, as far as scaling is concerned, are crucial in order to obtain meaningful hydrodynamic equations.

$$\begin{cases} \lambda(N) \stackrel{\text{def}}{=} \frac{\lambda_{ab}(N) + \lambda_{ba}(N)}{2}, \\ \mu(N) \stackrel{\text{def}}{=} \lambda_{ab}(N) - \lambda_{ba}(N), \end{cases} \quad (3.3)$$

where the dependence of the rates on N is explicitly mentioned.

Theorem 3.1. *Let system (3.3) have a given asymptotic expansion of the form*

$$\begin{cases} \lambda(N) \stackrel{\text{def}}{=} \lambda N^2 + o(N^2), \\ \mu(N) \stackrel{\text{def}}{=} \mu N + o(N), \end{cases} \quad (3.4)$$

where λ and μ are fixed positive constants. [As for the scaling assumption (3.4), the random measure $\log Z_t^{(N)}$ is a functional of the underlying Markov process, in which the time has been speeded up by a factor N^2 and the space shrunk by N^{-1}]. Assume moreover the sequence of initial empirical measures $\log Z_0^{(N)}$, taken at time $t = 0$, converges in probability to some deterministic measure with a given density $\rho(x, 0)$, so that

$$\lim_{N \rightarrow \infty} \log Z_0^{(N)} = \int_0^1 [\rho(x, 0)\phi_a(x) + (1 - \rho(x, 0))\phi_b(x)] dx, \quad \text{in probability,} \quad (3.5)$$

for any pair of functions $\phi_a, \phi_b \in \mathcal{C}_0^\infty(K)$, where $K \in \mathcal{R}$ is a compact containing the interval $[0, 1]$.

Then, for every $t > 0$, the sequence of random measures $\mu_t^{(N)}$ converges in probability, as $N \rightarrow \infty$, to a deterministic measure having a density $(\rho(x, t))$ with respect to the Lebesgue measure, which is the unique weak solution of the Cauchy problem

$$\begin{aligned} \int_0^T \int_0^1 \left[\rho(x, t) \left(\frac{\partial \theta(x, t)}{\partial t} + \lambda \frac{\partial^2 \theta(x, t)}{\partial x^2} \right) - \mu \rho(x, t) (1 - \rho(x, t)) \frac{\partial \theta(x, t)}{\partial x} \right] dx dt \\ = \int_0^1 [\rho(x, T)\theta(x, T) - \rho(x, 0)\theta(x, 0)] dx, \end{aligned} \quad (3.6)$$

where (3.6) holds for any function $\theta \in \mathcal{C}_0^\infty([0, 1] \times [0, T])$.

If, moreover, one assumes the existence of $\frac{\partial^2 \rho(x, 0)}{dx^2}$, then (3.6) reduces to a classical Burger's equation

$$\frac{\partial \rho(x, t)}{\partial t} = \lambda \frac{\partial^2 \rho(x, t)}{dx^2} + \mu [1 - 2\rho(x, t)] \frac{\partial \rho(x, t)}{dx}.$$

Proof. The sketch of the proof is spread over three main subsections, referred to hereafter as **P1**, **P2** and **P3**.

P1 [Existence of limit points: sequential compactness] As usual in problems dealing with convergence of sequences of probability measures, our very starting point will be to establish the weak relative compactness of the set $\{\log Z_t^{(N)}, N \geq 1\}$. Some of the probabilistic arguments employed in this paragraph are in a way classical and can be found in good books, e.g. [15, 11], although for simpler models.

The process

$$U_t^{(N)} \stackrel{\text{def}}{=} Z_t^{(N)} - Z_0^{(N)} - \int_0^t \Omega^{(N)}[Z_s^{(N)}] ds \quad (3.7)$$

is a bounded $\{\mathcal{F}_t^{(N)}\}$ -martingale. Using the exponential form of $Z_t^{(N)}$ together with classical stochastic calculus (see e.g. [5], chap.3, page 93), it follows that

$$[V_t^{(N)}] \stackrel{\text{def}}{=} (U_t^{(N)})^2 - \int_0^t \left(\Omega^{(N)}[(Z_s^{(N)})^2] - 2Z_s^{(N)} \Omega^{(N)}[Z_s^{(N)}] \right) ds \quad (3.8)$$

is also a bounded real martingale.

From $A_i^{(N)}(t) + B_i^{(N)}(t) = 1, \forall 1 \leq i \leq N$, on sees that $Z_t^{(N)}$ is mainly a functional of the sole function $\psi_{xy} \stackrel{\text{def}}{=} \phi_x - \phi_y = -\psi_{yx}$, up to a constant uniformly bounded in N . Hence, setting

$$\begin{aligned} \Delta \psi_{xy} \left(\frac{i}{N} \right) &\stackrel{\text{def}}{=} \psi_{xy} \left(\frac{i+1}{N} \right) - \psi_{xy} \left(\frac{i}{N} \right), \\ \tilde{\lambda}_{xy}(i, N) &\stackrel{\text{def}}{=} \lambda_{xy}(N) \left[\exp \left(\frac{1}{N} \Delta \psi_{xy} \left(\frac{i}{N} \right) \right) - 1 \right], \quad xy = ab \text{ or } ba, \end{aligned}$$

we have

$$\Omega^{(N)}[Z_t^{(N)}] = L_t^{(N)} Z_t^{(N)}, \quad (3.9)$$

where

$$L_t^{(N)} = \sum_{i \in \mathbf{G}^{(N)}} \tilde{\lambda}_{ab}(i, N) A_i B_{i+1} + \tilde{\lambda}_{ba}(i, N) B_i A_{i+1}. \quad (3.10)$$

By using the exclusion property, a straightforward calculation in equation (3.10) allows to rewrite (3.8) in the form

$$[V_t^{(N)}] = (U_t^{(N)})^2 - \int_0^t (Z_s^{(N)})^2 R_s^{(N)} ds, \quad (3.11)$$

where the process $R_t^{(N)}$ is strictly positive and given by

$$R_t^{(N)} = \sum_{i \in \mathbf{G}^{(N)}} \frac{[\tilde{\lambda}_{ab}(i, N)]^2}{\lambda_{ab}(N)} A_i B_{i+1} + \frac{[\tilde{\lambda}_{ba}(i, N)]^2}{\lambda_{ba}(N)} B_i A_{i+1}.$$

The integral term in (3.11) is nothing else but the increasing process associated with Doob's decomposition of the submartingale $(U_t^{(N)})^2$.

The following estimates are crucial.

Lemma 3.2.

$$L_t^{(N)} = \mathcal{O}(1), \quad (3.12)$$

$$R_t^{(N)} = \mathcal{O}\left(\frac{1}{N}\right). \quad (3.13)$$

Proof. We will derive (3.12) by estimating the right-hand side member of equation (3.10).

Clearly, $\Delta\psi_{xy}\left(\frac{i}{N}\right) = \frac{1}{N}\psi'_{xy}\left(\frac{i}{N}\right) + \mathcal{O}\left(\frac{1}{N^2}\right)$, where ψ' denotes the derivative of ψ . Then, taking a second order expansion of the exponential function and using definitions (3.3) and (3.4), we can rewrite (3.10) as

$$\begin{aligned} L_t^{(N)} &= \frac{\mu(N)}{N} \sum_{i \in \mathbf{G}^{(N)}} \left[\frac{A_i + A_{i+1}}{2} - A_i A_{i+1} \right] \Delta\psi_{ab}\left(\frac{i}{N}\right) \\ &\quad + \frac{\lambda(N)}{N} \sum_{i \in \mathbf{G}^{(N)}} (A_i - A_{i+1}) \Delta\psi_{ab}\left(\frac{i}{N}\right) + \mathcal{O}\left(\frac{1}{N}\right). \end{aligned} \quad (3.14)$$

The first sum in (3.14) is uniformly bounded by a constant depending on ψ . Indeed, $|A_i| \leq 1$ and $\psi \in \mathbf{C}^2[0, 1]$, so that ψ' is of bounded variation.

As for the second sum coming in (3.14), we have

$$\sum_{i \in \mathbf{G}^{(N)}} (A_i - A_{i+1}) \Delta \psi_{ab} \left(\frac{i}{N} \right) = \sum_{i \in \mathbf{G}^{(N)}} A_{i+1} \left[\Delta \psi_{ab} \left(\frac{i+1}{N} \right) - \Delta \psi_{ab} \left(\frac{i}{N} \right) \right].$$

Then the discrete Laplacian

$$\Delta \psi_{ab} \left(\frac{i+1}{N} \right) - \Delta \psi_{ab} \left(\frac{i}{N} \right) \equiv \psi_{ab} \left(\frac{i+2}{N} \right) - 2\psi_{ab} \left(\frac{i+1}{N} \right) + \psi_{ab} \left(\frac{i}{N} \right)$$

admits of the simple form

$$\Delta \psi_{ab} \left(\frac{i+1}{N} \right) - \Delta \psi_{ab} \left(\frac{i}{N} \right) = \frac{1}{N^2} \psi''_{ab} \left(\frac{i}{N} \right) + \mathcal{O} \left(\frac{1}{N^2} \right), \quad (3.15)$$

where ψ'' denotes the second derivative of ψ .

By (3.4), $\lambda(N) = \lambda N^2 + o(N^2)$, so that (3.15) implies

$$\frac{\lambda(N)}{N} \sum_{i \in \mathbf{G}^{(N)}} (A_i - A_{i+1}) \Delta \psi_{ab} \left(\frac{i}{N} \right) = \sum_{i \in \mathbf{G}^{(N)}} \frac{\lambda A_{i+1}}{N} \psi''_{ab} \left(\frac{i}{N} \right) + o \left(\frac{1}{N} \right) = \mathcal{O}(1), \quad (3.16)$$

which concludes the proof of (3.12). The computation of $R_t^{(N)}$ leading to (3.13) can be obtained via similar arguments. \blacksquare

To show the relative compactness of the family $Z^{(N)}$, which here, by separability and completeness of the underlying spaces, is equivalent to tightness, we proceed as in [11] by means of the following useful criterion.

Proposition 3.3 (Aldous's tightness criterion, see [1]). *A sequence $\{X^{(N)}\}$ of random elements of $\mathcal{D}_{\mathcal{R}}[0, T]$ is tight (i.e. the distributions of the $\{X^{(N)}\}$ are tight) if the two following conditions hold:*

$$(i) \quad \lim_{a \rightarrow \infty} \limsup_N P[||X^{(N)}|| \geq a] = 0, \quad (3.17)$$

where $||X^{(N)}|| \stackrel{\text{def}}{=} \sup_{t \leq T} |X_t^{(N)}|$.

(ii) For each ϵ, η , there exist a δ_0 and an N_0 , such that, if $\delta \leq \delta_0$ and $N \geq N_0$, and if τ is an arbitrary stopping time with $\tau + \delta \leq T$, then

$$P[|X_{\tau+\delta}^{(N)} - X_{\tau}^{(N)}| \geq \epsilon] \leq \eta. \quad (3.18)$$

Note that condition (3.17) is always necessary for tightness. ■

We will now apply Lemma 3.2 to equations (3.7) and (3.11), the role of $X^{(N)}$ in Proposition 3.3 being played by $Z^{(N)}$.

Observe that, by the uniform boundedness of $Z_t^{(N)}$, condition (3.17) is immediately verified.

To check condition (3.18), rewrite (3.7) as

$$Z_{t+\delta}^{(N)} - Z_t^{(N)} = U_{t+\delta}^{(N)} - U_t^{(N)} + \int_t^{t+\delta} \Omega^{(N)}[Z_s^{(N)}] ds. \quad (3.19)$$

The integral term in (3.19) is bounded in modulus by $K\delta$ [where K is a constant uniformly bounded in N and ψ] and hence satisfies (3.18). We are left with the analysis of $U_t^{(N)}$. But, from (3.11), (3.13) and Doob's inequality for sub-martingales, we have

$$\begin{aligned} \mathbb{E}[(U_{t+\delta}^{(N)} - U_t^{(N)})^2] &= \mathbb{E}\left[\int_t^{t+\delta} (Z_s^{(N)})^2 R_s^{(N)} ds\right] \leq \frac{C}{N}, \\ P\left[\sup_{t \leq T} |U_t^{(N)}| \geq \epsilon\right] &\leq \frac{4}{\epsilon^2} \mathbb{E}\left[\int_0^t (Z_s^{(N)})^2 R_s^{(N)} ds\right] \leq \frac{4C}{N\epsilon^2}, \end{aligned} \quad (3.20)$$

where C is a positive constant depending only on ψ . Thus $U_t^{(N)} \rightarrow 0$ almost surely as $N \rightarrow \infty$. This last property together with assumption (3.5) yield (3.18) and the announced (weak) relative compactness of the sequence $Z_t^{(N)}$. Hence, the sequence of probability measures $Q^{(N)}$, defined on $\mathcal{D}_{\mathcal{M}}[0, T]$ and corresponding to the process $\mu_t^{(N)}$, is also relatively compact: this is a consequence of classical projection theorems (see for instance Theorem 16.27 in [10]). We are now in a position to state a further important property.

Let Q the limit point of some arbitrary subsequence $Q^{(n_k)}$, as $n_k \rightarrow \infty$, and $Z_t \stackrel{\text{def}}{=} \lim_{n_k \rightarrow \infty} Z_t^{(n_k)}$. Then the support of Q is a set of sample paths absolutely continuous

with respect to the Lebesgue measure. Indeed, the application $\mu_t \rightarrow \sup_{t \leq T} \log Z_t$ is continuous and we have the immediate bound

$$\sup_{t \leq T} \log Z_t \leq \int_0^1 [|\phi_a(x)| + |\phi_b(x)|] dx,$$

which holds for all $\psi_a, \psi_b \in \mathbf{C}^2[0, 1]$. Hence, by weak convergence, any limit point Z_t has the form

$$Z_t[\phi_a, \phi_b] = \exp \left[\int_0^1 [\rho(x, t)\phi_a(x) + (1 - \rho(x, t))\phi_b(x)] dx \right], \quad (3.21)$$

where $\rho(x, t)$ denotes the limit density (a priori random) of the sequence of empirical measures $\mu_t^{(m_k)}$ introduced in (3.1).

P2 [A functional integral operator to characterize limit points] This is somehow the Gordian knot of the problem. Relying on the above weak compactness property, our next result shows that any arbitrary limit point Q is concentrated on a set of trajectories which are weak solutions of a *functional integral equation* (IFE).

First, by (3.7), (3.9) and (3.10), we obtain at once

$$\begin{aligned} \frac{\partial(Z_t^{(N)} - U_t^{(N)})}{\partial t} = \\ N^2 \sum_{i \in \mathbf{G}^{(N)}} \tilde{\lambda}_{ab}(i, N) \frac{\partial^2 Z_t^{(N)}}{\partial \phi_a(\frac{i}{N}) \partial \phi_b(\frac{i+1}{N})} + \tilde{\lambda}_{ba}(i, N) \frac{\partial^2 Z_t^{(N)}}{\partial \phi_a(\frac{i+1}{N}) \partial \phi_b(\frac{i}{N})}. \end{aligned} \quad (3.22)$$

It is worth remarking that (3.22) should be written, strictly speaking, as a stochastic differential equation, which is well-defined since indeed all the underlying probability spaces emanate from a families of interacting Poisson processes.

Replacing for a while the quantities $\phi_a(\frac{i}{N})$ and $\phi_b(\frac{i}{N})$ by variables $x_i^{(N)}$ and $y_i^{(N)}$ respectively, (3.22) becomes

$$\frac{\partial(Z_t^{(N)} - U_t^{(N)})}{\partial t} = N^2 \sum_{i \in \mathbf{G}^{(N)}} \alpha_{xy}(i, N) \frac{\partial^2 Z_t^{(N)}}{\partial x_i^{(N)} \partial y_{i+1}^{(N)}} + \alpha_{yx}(i, N) \frac{\partial^2 Z_t^{(N)}}{\partial y_i^{(N)} \partial x_{i+1}^{(N)}}, \quad (3.23)$$

where we have put

$$\begin{aligned}\alpha_{xy}(i, N) &= \lambda_{ab}(N) \left[\exp\left(\frac{x_{i+1}^{(N)} - x_i^{(N)} + y_i^{(N)} - y_{i+1}^{(N)}}{N}\right) - 1 \right], \\ \alpha_{yx}(i, N) &= \lambda_{ba}(N) \left[\exp\left(\frac{y_{i+1}^{(N)} - y_i^{(N)} + x_i^{(N)} - x_{i+1}^{(N)}}{N}\right) - 1 \right].\end{aligned}$$

We shall rewrite (3.23) in the operator form

$$-\frac{\partial U_t^{(N)}}{\partial t} = \mathcal{L}_t^{(N)}[Z_t^{(N)}], \quad (3.24)$$

remarking in the present setting that, for each finite N , $\mathcal{L}^{(N)}$ acts on the function space $\mathcal{C}^p[-|\phi|, |\phi|]^{2N}$, where

$$|\phi| \stackrel{\text{def}}{=} \sup_{z \in [0,1]} (|\phi_a(z)|, |\phi_b(z)|), \quad (3.25)$$

and p is an arbitrary positive number, as $Z_t^{(N)}$ is analytic with respect to $\{\phi_a(\cdot), \phi_b(\cdot)\}$. The operator $\mathcal{L}_t^{(N)}$ is of parabolic type, but then in the wide sense, since here one can check the quadratic form usually associated with the second order derivative terms is non definite, see e.g. [4]).

The key point will be to show that any limit point $Z_t \stackrel{Law}{=} \lim_{n_k \rightarrow \infty} Z_t^{(n_k)}$ satisfies an IFE, obtained by studying the second order linear partial differential operators $\mathcal{L}_t^{(N)}$ along the sequence $n_k \rightarrow \infty$.

To carry out the analysis of the limit sum coming in (3.23) (which is a priori intricate), we propose a general approach, which aims at proving first that Z_t is a *weak solution* (or *distributional* in the sense of Schwartz) of a Cauchy type operator. The line of argument will be sketched below.

Beforehand, for the sake of shortness, it will be convenient to define the following cylinder sets, for $p = 1, 2 \dots$,

$$\mathcal{U}_t^p \stackrel{\text{def}}{=} [-|\phi|, |\phi|]^p \times [0, t], \quad \mathcal{U}^p \stackrel{\text{def}}{=} [-|\phi|, |\phi|]^p.$$

Introduce the operator $\tilde{\mathcal{L}}_t^{(N)}$, which is the adjoint of $\mathcal{L}_t^{(N)}$ in the Lagrange sense, so that, for every function $h \in \mathcal{C}_0^\infty(\mathcal{U}_t^{2N})$,

$$\begin{aligned} \tilde{\mathcal{L}}_t^{(N)}[h] &\stackrel{\text{def}}{=} \frac{\partial h}{\partial t} + N^2 \sum_{i \in \mathbf{G}^{(N)}} \frac{\partial^2 [\alpha_{xy}(i, N)h]}{\partial x_i^{(N)} \partial y_{i+1}^{(N)}} + \frac{\partial^2 [\alpha_{yx}(i, N)h]}{\partial y_i^{(N)} \partial x_{i+1}^{(N)}} \\ &\stackrel{\text{def}}{=} \frac{\partial h}{\partial t} + \mathcal{B}^{(N)}[h]. \end{aligned} \quad (3.26)$$

Definition 3.4 (see e.g. [14], Part 1, section III.5). *A function $g \in L_2$ is said to be a weak (or distributional) solution of the Cauchy problem $\mathcal{L}^{(N)}g = 0$ if, for all $h \in \mathcal{C}_0^\infty(\mathcal{U}_T^{2N})$,*

$$\int_{\mathcal{U}_T^{2N}} g \tilde{\mathcal{L}}_t^{(N)}[h] d\vec{u} dt = 0, \quad (3.27)$$

where in the integral \vec{u} denotes an arbitrary point in \mathcal{U}^{2N} .

Multiplying equation (3.23) by an arbitrary function $h \in \mathcal{C}_0^\infty(\mathcal{U}_T^{2N})$, for fixed T arbitrary positive, and then integrating twice by parts, we obtain, in agreement with (3.27),

$$\begin{aligned} \int_{\mathcal{U}_T^{2N}} \left[(Z_t^{(N)} - U_t^{(N)}) \frac{\partial h}{\partial t} + Z_t^{(N)} \mathcal{B}^{(N)}[h] \right] d\vec{u} dt = \\ \int_{\mathcal{U}^{2N}} [(Z_T^{(N)} - U_T^{(N)})h(\vec{u}, T) - Z_0^{(N)}h(\vec{u}, 0)] d\vec{u}. \end{aligned} \quad (3.28)$$

A brute force analysis of the adjoint operator could lead to a dead-end. A preliminary step will be to exploit carefully the estimates obtained in Lemma 3.2. This is the content of the next lemma.

Lemma 3.5. *The following partial differential equation holds.*

$$\begin{aligned} \frac{\partial(Z_t^{(N)} - U_t^{(N)})}{\partial t} = \sum_{i \in \mathbf{G}^{(N)}} \mu \psi'_{ab} \left(\frac{i}{N} \right) \left[\frac{1}{2} \left(\frac{\partial Z_t^{(N)}}{\partial x_i^{(N)}} + \frac{\partial Z_t^{(N)}}{\partial x_{i+1}^{(N)}} \right) - N \frac{\partial^2 Z_t^{(N)}}{\partial x_i^{(N)} \partial x_{i+1}^{(N)}} \right] \\ + \lambda \sum_{i \in \mathbf{G}^{(N)}} \psi''_{ab} \left(\frac{i}{N} \right) \frac{\partial Z_t^{(N)}}{\partial x_{i+1}^{(N)}} + \mathcal{O} \left(\frac{1}{N} \right), \end{aligned} \quad (3.29)$$

where the term $\mathcal{O}(\frac{1}{N})$ is in modulus uniformly bounded by $\frac{C}{N}$, C being a constant depending only on ψ, ψ' and ψ'' .

Proof. Immediate from equations (3.14) and (3.16). ■

Starting from Lemma 3.5, we will present the two global guidelines of a functional approach, called **G1** and **G2**. Basically, it relies on partial differential equations, whose variables are *functions taken at points of the torus*. We think this might well extend to larger dimensions, although this assertion could certainly be debated.

G1 Intermediate reduction to an almost sure convergence context. This can be achieved by means of the extended Skohorod coupling theorem (see Corollary 6.12 in [10]), which in brief says that, if a sequence of real random variables (ξ_k) is such that $\lim_{k \rightarrow \infty} f_k(\xi_k) = f(\xi)$ converges in distribution, then there exist a probability space \mathcal{V} and a new random sequence $\tilde{\xi}_k$, such that $\tilde{\xi}_k \stackrel{\mathcal{L}}{=} \xi_k$ and $\lim_{k \rightarrow \infty} f_k(\tilde{\xi}_k) = f(\xi)$, almost surely in \mathcal{V} , with $\tilde{\xi} \stackrel{\mathcal{L}}{=} \xi$. Here this theorem will be applied to the family $Z_t^{(n_k)}$, which thus gives rise a new sequence denoted by $Y_t^{(n_k)}$ in the sequel. This step is in no way obligatory, but just a matter of taste. Indeed, one could still keep on with weak convergence context and use Alexandrov's portmanteau theorem (see e.g. [5]) whenever needed.

G2 For each finite N , we can consider the quantities

$$\psi'_{ab}\left(\frac{i}{N}\right), \psi''_{ab}\left(\frac{i}{N}\right), \quad i = 1, \dots, N,$$

as *constant parameters*, while the $x_i^{(N)}$'s are *free variables*. This is clearly feasible, choosing for instance $\phi_a(\cdot), \phi_b(\cdot)$ in the class of polynomials of degree at least $3N$. Also, from now on, the functions ϕ_a and ϕ_b will be supposed to belong to $\mathcal{C}_0^\infty(K)$, for some compact $K \in \mathcal{R}$ containing the interval $[0, 1]$.

Then, according to **G1**, we rewrite (3.29) as

$$-\frac{\partial U_t^{(N)}}{\partial t} \stackrel{\text{def}}{=} \mathcal{A}_t^{(N)}[Y_t^{(N)}] + \mathcal{O}\left(\frac{1}{N}\right), \quad (3.30)$$

where $\mathcal{A}_t^{(N)}$ is viewed as an operator of parabolic type with *constant* coefficients and domain $\mathcal{C}_0^\infty(\mathcal{U}_T^{(N)})$.

$$\begin{aligned} \mathcal{A}_t^{(N)}[g] \stackrel{\text{def}}{=} & -\frac{\partial g}{\partial t} + \sum_{i \in \mathbf{G}^{(N)}} \mu \psi'_{ab}\left(\frac{i}{N}\right) \left[\frac{1}{2} \left(\frac{\partial g}{\partial x_i^{(N)}} + \frac{\partial g}{\partial x_{i+1}^{(N)}} \right) - N \frac{\partial^2 g}{\partial x_i^{(N)} \partial x_{i+1}^{(N)}} \right] \\ & + \lambda \sum_{i \in \mathbf{G}^{(N)}} \psi''_{ab}\left(\frac{i}{N}\right) \frac{\partial g}{\partial x_{i+1}^{(N)}}, \end{aligned}$$

remembering that $\psi_{ab} = \phi_a - \phi_b$. The term $\mathcal{O}\left(\frac{1}{N}\right)$ in (3.30) stands for an operator having a negligible range for $N \rightarrow \infty$.

Let $\tilde{\mathcal{A}}_t^{(N)}[h]$ denote the adjoint of $\mathcal{A}_t^{(N)}$. Then

$$\begin{aligned} \tilde{\mathcal{A}}_t^{(N)}[h] &= \frac{\partial h}{\partial t} - \sum_{i \in \mathbf{G}^{(N)}} \mu \psi'_{ab} \left(\frac{i}{N} \right) \left[\frac{1}{2} \left(\frac{\partial h}{\partial x_i^{(N)}} + \frac{\partial h}{\partial x_{i+1}^{(N)}} \right) + N \frac{\partial^2 h}{\partial x_i^{(N)} \partial x_{i+1}^{(N)}} \right] \\ &\quad - \lambda \sum_{i \in \mathbf{G}^{(N)}} \psi''_{ab} \left(\frac{i}{N} \right) \frac{\partial h}{\partial x_{i+1}^{(N)}}, \end{aligned} \quad (3.31)$$

and, for any $h^{(N)} \in \mathcal{C}_0^\infty(\mathcal{U}_T^{(N)})$, we have

$$\begin{aligned} \int_{\mathcal{U}^{(N)}} [(Y_T^{(N)} - U_T^{(N)})h^{(N)}(\vec{u}, T) - Y_0^{(N)}h^{(N)}(\vec{u}, 0)] \delta \vec{u} = \\ \int_{\mathcal{U}_t^{(N)}} (Y_t^{(N)} - U_t^{(N)}) \tilde{\mathcal{A}}_t^{(N)}[h^{(N)}] \delta \vec{u} dt + \mathcal{O}\left(\frac{1}{N}\right), \end{aligned} \quad (3.32)$$

where $\delta \vec{u}$ in (3.32) represents the differential volume element

$$\delta \vec{u} = dx_1^{(N)} dx_2^{(N)} \dots dx_N^{(N)} = \delta \phi_a \left(\frac{1}{N} \right) \delta \phi_a \left(\frac{2}{N} \right) \dots \delta \phi_a(1).$$

The next step is to make a suitable choice of the function h in (3.32) in order to extract a meaningful information on the limit operator, as $N \rightarrow \infty$. Keeping in mind that the random variables $Y_t^{(N)}$ are defined on the implicit probability space \mathcal{V} introduced in **G1**, we state the following result.

Lemma 3.6. [Claim1] *Let $Y_t = \lim_{n_k \rightarrow \infty} Y_t^{(n_k)}$ a.s., and let $W \in \mathcal{C}_0^\infty(K)$ be a fixed compact space. Then, for a class of test functions k properly chosen in a subset of $\mathcal{C}_0^\infty(W \times [0, T])$, we have*

$$\begin{aligned} \int_0^T dt \int Y_t[\phi(\cdot)] F_t[\phi(\cdot)] \delta \phi(\cdot) = \\ \int [k(\phi(\cdot), T) Y_T[\phi(\cdot)] - k(\phi(\cdot), 0) Y_0[\phi(\cdot)]] \delta \phi(\cdot), \end{aligned} \quad (3.33)$$

where

$$F_t[\phi(\cdot)] = \frac{\partial k(\phi(\cdot), t)}{\partial t} - \int_0^1 \left[\mu \frac{\partial^2 k(\phi(\cdot), t)}{\partial \phi^2(x)} \psi'(x) + [\mu \psi'(x) + \lambda \psi''(x)] \frac{\partial k(\phi(\cdot), t)}{\partial \phi(x)} \right] dx.$$

Moreover (3.33) yields the Cauchy problem posed in (3.6).

Proof. We only sketch the main lines of argument.

- The almost sure convergence of $Y_t^{(N)}$ and $U_t^{(N)}$, respectively to Y_t and 0 [by (3.20)], will yield (3.33) provided that in (3.32) the functions $h^{(N)}$ are properly chosen, to ensure the existence of the limit sums coming in (3.31), as $N \rightarrow \infty$.

Setting $\vec{x}^{(N)} \stackrel{\text{def}}{=} (x_1^{(N)}, x_2^{(N)}, \dots, x_N^{(N)})$, he reader can convince himself that it suffices to take in (3.32)

$$h^{(N)}\left(\frac{\vec{x}^{(N)}}{N}, t\right) = k(\vec{x}^{(N)}, t),$$

where $k \in \mathcal{C}_0^\infty(W \times [0, T])$, in which case convergent Riemann sums are obtained in (3.31).

- From Skohorod's coupling theorem, Y_t does satisfy an equation of the form (3.21). Hence, we can write the following functional derivatives (which are plainly of a Radon-Nykodym nature)

$$\begin{cases} \frac{\partial Y_t}{\partial \phi(\cdot)} = \rho(\cdot, t) Y_t, \\ \frac{\partial^2 Y_t}{\partial \phi^2(\cdot)} = \rho^2(\cdot, t) Y_t. \end{cases}$$

- To derive (3.6), one has to pick out k from a class of convolution test functions, depending on some parameter ϵ and properly converging in the space of Schwartz distributions.

■

P3 [Uniqueness] The problem of uniqueness of weak solutions of the Cauchy problem (3.6) for nonlinear parabolic equation is in fact already solved in the literature. We refer the reader for instance to [4] for a wide bibliography on the subject.

To conclude the analysis of Theorem 3.1, it suffices to switch back to $Z_t^{(N)}[\phi_a, \phi_b]$, which converges in distribution to $Z_t[\phi_a, \phi_b]$. Hence, the random measure $\mu_t^{(N)}$ converges in distribution to a deterministic measure, which is a peculiar situation implying also convergence in probability. ■

4 The n -species model

We will state a conjecture about hydrodynamic equations for the n -species model, briefly introduced in section 2.1, in the so-called *equidiffusion* case, precisely defined hereafter.

The n -species system is said to be *equidiffusive* whenever there exists a constant D , such that, for all pairs (k, l) ,

$$\lim_{N \rightarrow \infty} \frac{\lambda_{kl}(N)}{N^2} = D.$$

Letting

$$\alpha_{kl} \stackrel{\text{def}}{=} \lim_{N \rightarrow \infty} \log \frac{\lambda_{kl}(N)}{\lambda_{lk}(N)},$$

we assert that the following hydrodynamic system holds [**Claim2**].

$$\frac{\partial \rho_k}{\partial t} = D \left[\frac{\partial^2 \rho_k}{\partial x^2} + \frac{\partial}{\partial x} \left(\sum_{l \neq k} \alpha^{lk} \rho_k \rho_l \right) \right], \quad k = 1, \dots, n.$$

The idea is to apply the functional approach presented in this paper.

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