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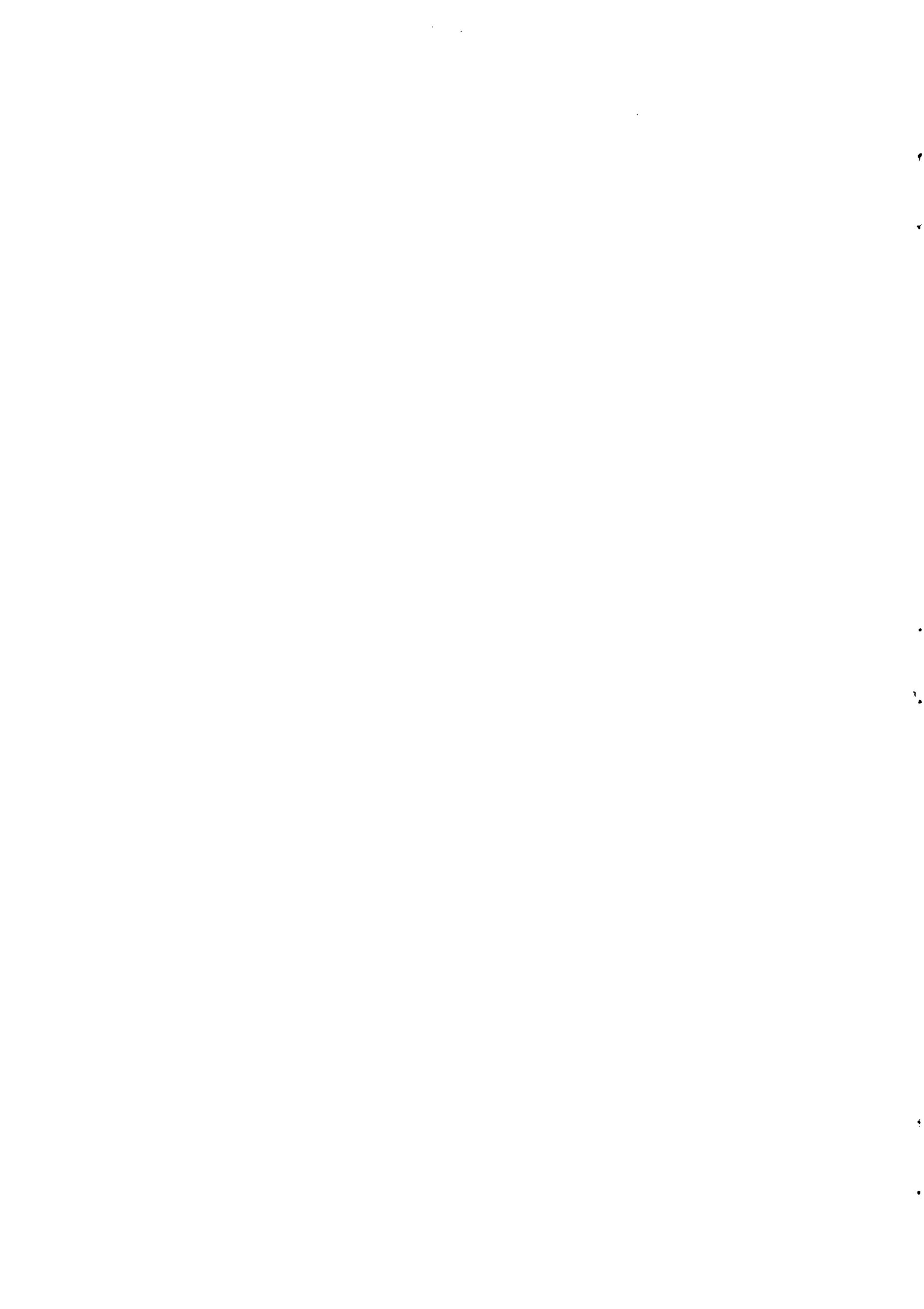
AN INEQUALITY INVOLVING NONNEGATIVE MATRICES AND INCREASING FUNCTIONS

Jean-Luc GOUZÉ

Octobre 1990



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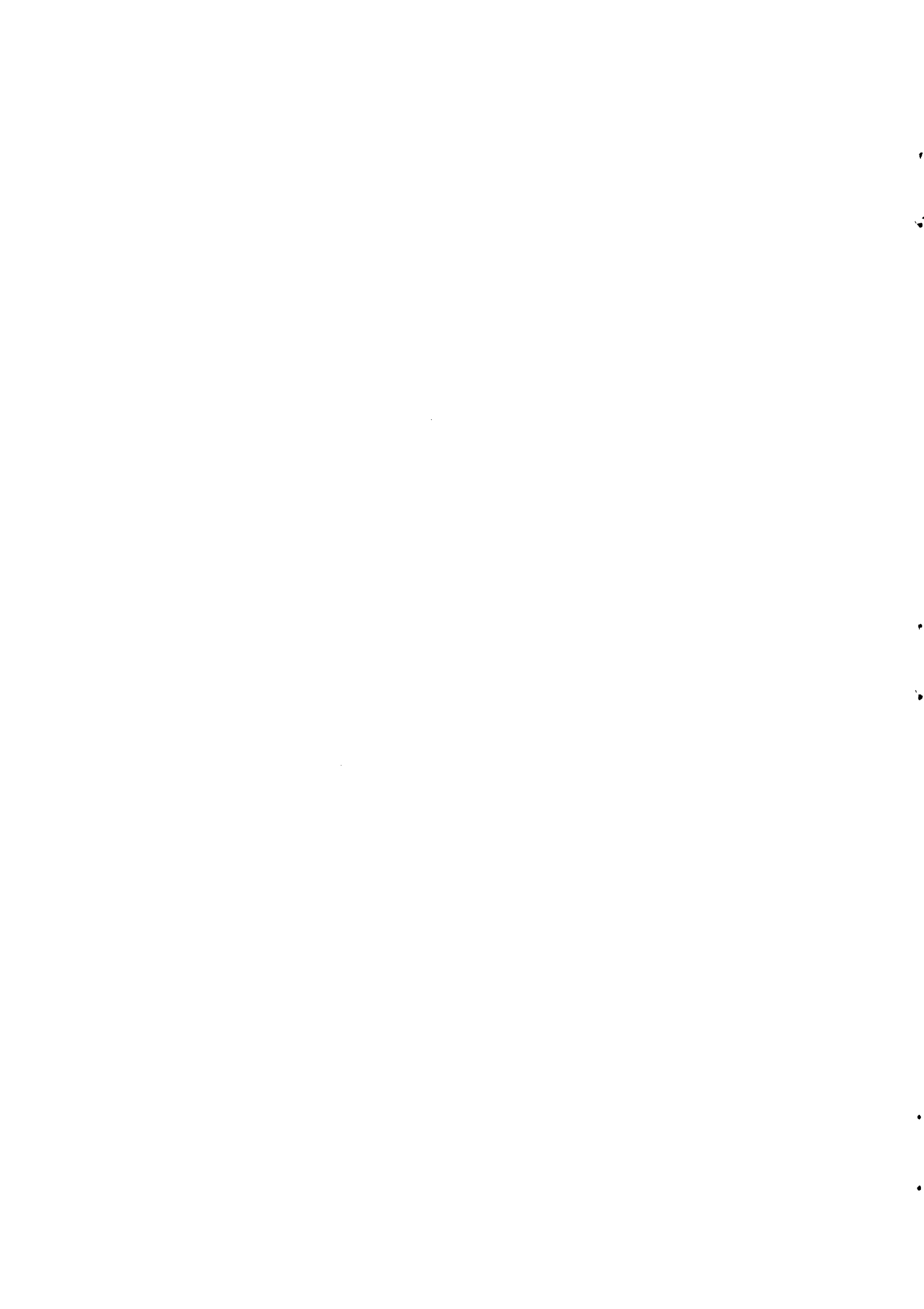
An inequality involving nonnegative matrices and increasing functions

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Abstract. Let $\tilde{f}(x)$ denote the vector $(f(x_1), \dots, f(x_n))^t$; if A is a doubly stochastic matrix and f a strictly increasing function, we demonstrate that $x^t A \tilde{f}(x) - x^t \tilde{f}(x) \leq 0$ for all vector x ; this inequality has applications in the study of non-linear differential systems.

Une inégalité “entropique” entre matrices positives et fonctions monotones

Résumé : Notons par $\tilde{f}(x)$ le vecteur $(f(x_1), \dots, f(x_n))^t$; si A est une matrice positive doublement stochastique et si f est une fonction réelle strictement croissante, nous démontrons que $x^t A \tilde{f}(x) - x^t \tilde{f}(x) \leq 0$ pour tout x ; cette inégalité a des applications pour la construction de fonctions de Lyapounov pour des systèmes différentiels non linéaires.



1 Introduction and main result

We want here to prove an inequality involving nonnegative matrices (particularly stochastic and doubly stochastic matrices) and strictly increasing functions. This inequality is by itself interesting, and can also be used to construct Lyapunov functions for non-linear differential n -dimensional systems, and consequently to prove convergence towards equilibria. For some particular cases, this inequality has been proved in the framework of probabilistic problems ([5]) or of convergence of chemical differential systems ([3]); it can be interpreted as the increasing character of something looking like entropy (cf. [6]).

We first state the result; let f a real function of a real variable, defined in some real subset D , and strictly increasing. If x is a vector in \mathbf{R}^n , we denote by $\tilde{f}(x)$ the vector $(f(x_1), \dots, f(x_n))^t$. If A is a real $(n \times n)$ matrix, the non-oriented graph of A is partitioned into p connected classes, corresponding to p submatrices A_i . A is called doubly stochastic if it is a nonnegative matrix verifying $A\mathbf{1} = \mathbf{1}$ and $A^t\mathbf{1} = \mathbf{1}$ ($\mathbf{1}$ is the vector with all the components equal to 1). (cf. [1]).

Theorem 1.1 *Let A a doubly stochastic matrix and*

$$\phi_A(x) = x^t A \tilde{f}(x) - x^t \tilde{f}(x)$$

Then

- $\phi_A(x) \leq 0$ for all $x \in D^n$
- $\phi_A(x) = 0 \Leftrightarrow x = \sum_{i=1}^p \lambda_i \mathbf{1}_i$
where $\mathbf{1}_i$ is the vector having the components corresponding to the vertices of the graph of A_i equal to 1, and the others equal to 0, and the λ_i are real.

We remark that $\phi_A(x) = x^t (A - I) \tilde{f}(x)$, and that $M = A - I$ is a singular off-diagonal nonnegative matrix such that $M\mathbf{1} = 0$, $M^t\mathbf{1} = 0$ (cf. [1]). We deduce the following corollary:

Corollary 1 *Let M a singular off-diagonal nonnegative matrix such that $M\mathbf{1} = 0$, $M^t\mathbf{1} = 0$ and*

$$\phi'_M(x) = x^t M \tilde{f}(x)$$

Then

- $\phi'_M(x) \leq 0$ for all $x \in D^n$
- $\phi'_M(x) = 0 \Leftrightarrow x = \sum_{i=1}^p \lambda_i \mathbf{1}_i$
 where $\mathbf{1}_i$ is the vector having the components corresponding to the vertices of the graph of M ; equal to 1, and the others equal to 0, and the λ_i are real.

To prove this corollary, we choose $\alpha > 0$ such that $M + \alpha I$ is a nonnegative matrix; then $\frac{1}{\alpha}M + I$ is a doubly stochastic matrix and we can apply the theorem to obtain the result.

It is now easy to deduce a new corollary that extend the application of the theorem; if k is a vector with each component non equal to zero, we denote by x/k the vector $(x_1/k_1, \dots, x_n/k_n)$, and by $(\text{diag } k)$ the diagonal matrix with diagonal k .

Corollary 2 *Let B a nonnegative matrix verifying $B\mathbf{1} = \mathbf{1}$ and $B^t k = k$ with $k > 0$ (that is $k_i > 0$ for all i). Let:*

$$\phi''_B(x) = x^t B \tilde{f}(x/k) - x^t \tilde{f}(x/k)$$

Then

- $\phi''_B(x) \leq 0$ for all $(x/k) \in D^n$
- $\phi''_B(x) = 0 \Leftrightarrow x/k = \sum_{i=1}^p \lambda_i \mathbf{1}_i$
 where $\mathbf{1}_i$ is the vector having the components corresponding to the vertices of the graph of B ; equal to 1, and the others equal to 0, and the λ_i are real.

Indeed, if we let $z = x/k$, it is easy to see that $\phi''_B(x) = \phi'_{(\text{diag } k)(B-I)}(z)$ and we can apply the corollary to $M = (\text{diag } k)(B - I)$.

Let us remark that if B is a stochastic matrix ($B\mathbf{1} = \mathbf{1}$) without transitory states, it implies ([1]) the existence of $k > 0$ such that $B^t k = k$.

We now demonstrate the inequality before giving applications.

2 Demonstration of the inequality:

We first prove the theorem when A is a permutation matrix. The problem is therefore to study:

$$\phi_P(x) = x^t P \tilde{f}(x) - x^t \tilde{f}(x)$$

where P is a $n \times n$ permutation matrix. We can, in a unique way, decompose P :

$$P = \sum_{i=1}^p P_i^0 \quad (1)$$

where P_i^0 is a cycle of length l_i (with $1 \leq l_i \leq n$), that is to say a cyclic permutation on l_i elements, and the null application for the other elements. Of course:

$$\sum_{i=1}^p l_i = n$$

and there is no intersection between the p classes. This is equivalent to say that the (non-oriented) graph is made of p disconnected classes, each one being a cycle with matrix P_i^0 . The problem is now reduced to study:

$$\phi_{P_i}(y) = y^t P_i \bar{f}(y) - y^t \bar{f}(y)$$

where P_i is a cycle on l_i elements and y a vector of dimension l_i . Without any restriction, we can always suppose that the cycle is:

$$y_1 \rightarrow y_2 \rightarrow \dots \rightarrow y_{l_i} \rightarrow y_1$$

We can now demonstrate (cf. [3]):

Lemma 1

$$\phi_{P_i}(y) \leq 0 \text{ for all } y$$

and (λ being a real)

$$\phi_{P_i}(y) = 0 \Leftrightarrow y = \lambda \mathbf{1}$$

Proof:

$$\phi_{P_i}(y) = \sum_{j=1}^{l_i} (y_j f(y_{j+1}) - y_j f(y_j))$$

where by convention $y_{l_i+1} = y_1$. We prove the lemma by induction on l_i ; if $l_i = 1$, the result is trivial; if $l_i = 2$, then :

$$\phi_{P_i}(y) = (y_1 - y_2)(f(y_2) - f(y_1))$$

and the result is true because $f(x)$ is a strictly increasing function. We suppose that the result is true for $l_i - 1$; we can also suppose without any restriction of the problem that $y_{l_i} \geq y_j$ ($j = 1, \dots, l_i - 1$). Then:

$$\begin{aligned} \phi_{P_i}(y) &= [y_1 f(y_2) - y_1 f(y_1) + \dots + y_{l_i-1} f(y_1) - y_{l_i-1} f(y_{l_i-1})] \\ &\quad + (y_{l_i-1} - y_{l_i})(f(y_{l_i}) - f(y_1)) \end{aligned}$$

The first part of the right member is nonpositive because of the induction hypothesis, and the second part because f is strictly increasing. If $\phi(y)$ is zero, then $y_1 = y_2 = \dots = y_{i,-1}$ because of the induction hypothesis, and moreover $y_{i,-1} = y_i$, or $y_1 = y_i$, so finally $y = \lambda \mathbf{1}$.

It is now a simple matter to obtain the result for ϕ_P :

Lemma 2

$$\phi_P(y) \leq 0 \text{ for all } y \in D^n$$

and $(\lambda_i \text{ being real})$

$$\phi_P(y) = 0 \Leftrightarrow y = \sum_{i=1}^p \lambda_i \mathbf{1}_i$$

where $\mathbf{1}_i$ is a vector having the components corresponding to the vertices of the graph of P_i^0 equal to 1, and the others equal to 0.

Indeed, it is enough to apply the preceding lemma to each cycle of the permutation by using (1).

Take now a doubly stochastic matrix A ; by a theorem of Birkhoff (cf. [1]), we know that A is a convex combination of permutation matrices; we deduce that $\phi_A(y)$ is a convex combination of $\phi_P(y)$, and therefore nonpositive.

If $\phi_A(y)$ is zero, consider a connected class A_c of the graph of A ; then ϕ_{A_c} is also zero; A_c has a convex decomposition into permutations P , and each $\phi_P(y)$ must be zero; moreover, the graphs of these permutations realise a (non-disjoint) covering of the graph of A_c , and therefore we must have equality for all components belonging to A_c . The theorem is therefore demonstrated.

3 Applications

- We can first make explicit the function f to obtain useful inequalities. If we take $f(x) = x$, we obtain, by using the corollary 1, the result that $(B - I)\text{diag } k + \text{diag } k(B^t - I)$ is semidefinite negative if B is a stochastic matrix; this result is simple to obtain directly ([1]).

Take now $f(x) = e^x$; we obtain:

$$x^t B e^{x/k} - x^t e^{x/k} \leq 0$$

in particular $x^t M e^x \leq 0$ for all singular off-diagonal nonnegative matrix M such that $M\mathbf{1} = 0$ and $M^t\mathbf{1} = 0$.

Let us take now $f(p) = \ln p$, ($p > 0$), we obtain:

$$p^t(B - I)(\ln p - \ln k) \leq 0 \quad (2)$$

for all $p > 0$ (cf. [5]).

- The main interest of this inequality for dynamical systems is to enable one to construct Lyapunov functions or auxiliary functions that decrease along the trajectories of the system (cf. [4]). Take the differential n -dimensional non-linear system:

$$\dot{y} = M \tilde{f}(y)$$

where M is a matrix verifying the hypotheses of the corollary 2 and f is C^1 (and always strictly increasing). Then the norm function $V(y) = \|y\|^2$ is decreasing along the trajectories because its derivative with respect to time is $2\phi'_M(y)$, and this expression cancels if and only if y is an equilibrium for the differential system. We deduce that all the trajectories of the system are bounded and converge towards the set of equilibria. For example, the inequality (2) has been used in [3] (in a concealed way) to show convergence to equilibrium of chemical systems. It is also possible to use this inequality (2) to obtain results of convergence for Lotka-Volterra differential systems in population dynamics ([2]).

- Take $f(p) = \ln p$ for $p > 0$. The inequality given by the theorem is :

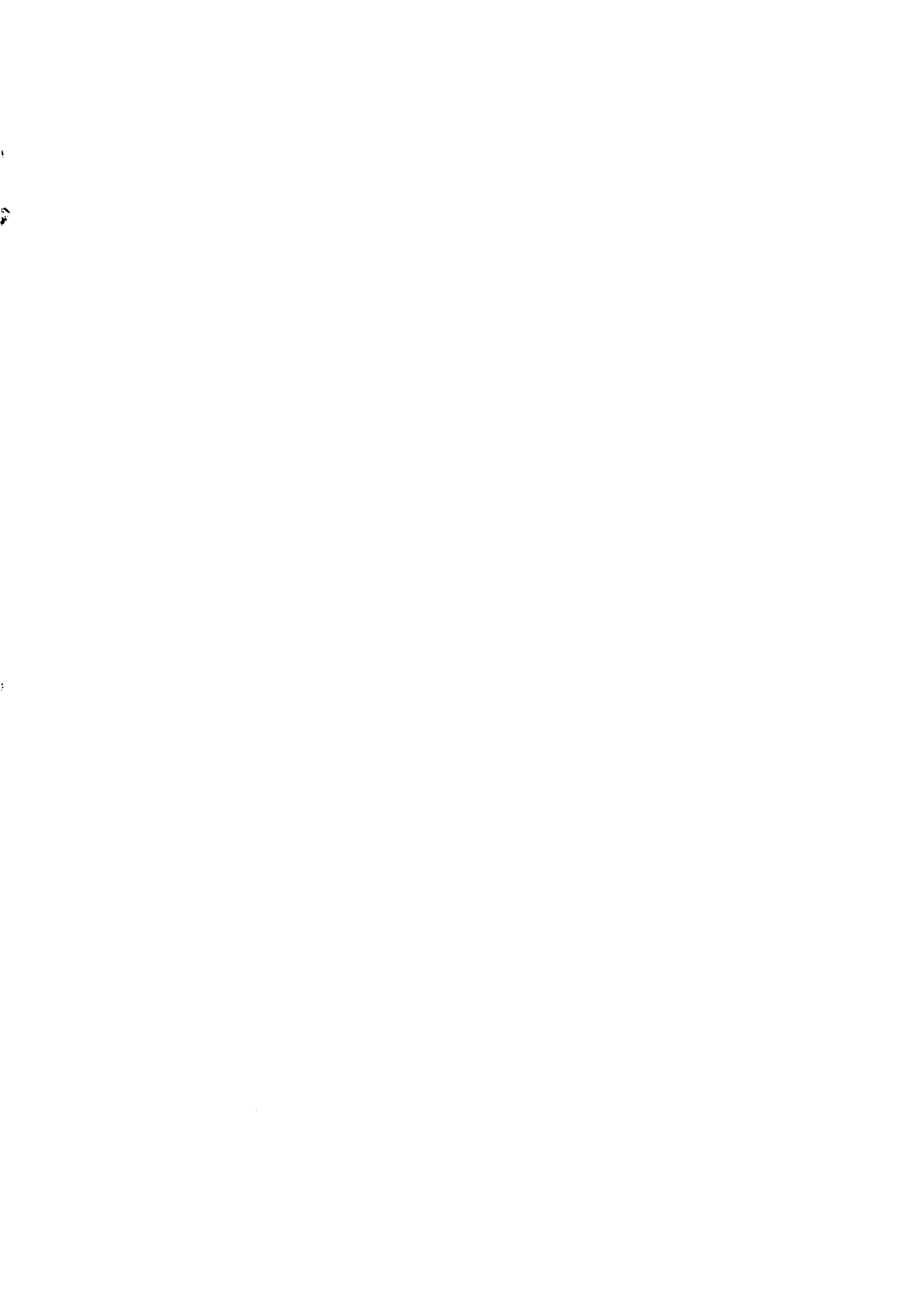
$$p^t A \ln p - p^t \ln p \leq 0$$

If the p_i are a probability distribution for a discrete finite system, the entropy of such a system is $-p^t \ln p$ ([6]). It seems to us that one could see the preceding inequality as an "entropic inequality" saying that something that looks like entropy always increases when the system is equitably mixed.

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