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Asymmetrical Wireless Communications*

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Extending INET Framework for Directional and Asymmetrical Wireless Communications

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Abstract: This paper reports our work on extending the *OMNeT++ INET* Framework with a directional radio model, putting a special emphasis on the implementation of asymmetrical communications. We first analyze the original *INET* radio model, focusing on its design and components. Then we discuss the modifications that have been done to support directional communications. Our preliminary results show that the new model is flexible enough to allow the user to provide any antenna pattern shape, with only an additional reasonable computational cost.

Key-words: OMNeT++, INET Framework, Directional Radios, Asymmetrical communication

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Extending INET Framework for Directional and Asymmetrical Wireless Communications

Résumé : Ce rapport présente nos travaux pour étendre le cadre de simulations de réseau *INET* (basé sur OMNET++) en lui ajoutant un modèle de radios directionnelles. Nous mettons ici l'accent particulièrement sur l'implémentation de communications asymétriques. Dans un premier temps, nous analysons la conception et les composants du modèle actuel de radio d'*INET*. Dans un second temps, nous en proposons des modifications qui permettent des communications directionnelles. Nos résultats préliminaires montrent que cette nouvelle extension est assez flexible : elle permet à l'utilisateur, au prix d'un nombre limité de calculs supplémentaires, de modifier n'importe quelle forme de rayonnement de l'antenne.

Mots-clés : Réseaux sans fil, Handover, Simulation, Connectivité sur la route, OMNeT++

1 Introduction

Mobile Ad-hoc Networks (MANETs) are receiving more attention in the last few years. In many cases, the behavior of these networks depends on the performance of the radio communications in various directions around the emitters or receivers. This performance may be uniform in all directions, when using omni-directional antennas, or non-uniform, when using directional antennas. In the latter case, the antennas have a preferential direction of radiation, and a pattern of secondary emissions, at lower levels of radiation, in other directions. Thanks to such directional antennas, the network coverage can be increased and, at the same time, the use of less number of antennas becomes possible, hence reducing the interference effects.

Since simulation tools are commonly used to design and evaluate the performance of such radio networks, simulation models of directional antennas are needed. Unfortunately, only a few simulation tools offer the ability to model directional antennas, such as OPNET [opn00], GloMoSim [glo98], NS-2 [ns2], or QualNet [qua]. Indeed, modeling directional antennas is more complicated than modeling the omni-directional ones, because emitted or received power depends on the direction and a specific attenuation pattern that depends on the antenna. These patterns often consist of a main lobe in the direction of the antenna, and possibly some side and back lobes. The latter ones have a much lower amplification gain, but still cannot be neglected, in particular for the interferences calculation. In most of the simulators mentioned above, an antenna's radiation pattern is described in a configuration file built by using mapping techniques. The gain values of the antenna are given for different points in space to determine the gain in all directions. However, there are some simulators that model the antenna using other techniques than mapping. In [HGT⁺08], Hardwick et al. use statistics to estimate the main and side lobes values for size and position, while in [GH09], Gharavi and Bin propose a 2D model, consisting of a "pie-wedge" pattern shape with circular constant gain for side and back lobes. In [KKY07], Kucuk et al. build a model of a smart antenna on top of *OMNeT++*'s *Mobility Framework* for sensor networks applications, focusing on the performance evaluation, on the number of nodes, the traffic and the energy consumption.

In this paper, we report on our work on extending the *OMNeT++ INET* Framework for supporting directional wireless communications. We propose a *DirectionalRadio* module based on Gharavi and Bin's model [GH09], which allows the implementation of several antenna patterns. These patterns are defined by means of plugins that calculate the directional gain of the antenna in a two dimensional plane. Additionally, we present the modifications made to the *INET* radio model in order to incorporate asymmetrical communications to support directional communications. We verify the correctness of the implementation by comparing the antenna patterns observed in simulations against the expected theoretical patterns. We also evaluate our proposed radio model from the computational point of view by providing quantitative data of the impact of including asymmetrical communications in the overall execution time.

The paper is organized as follows: In Section 2, the current *INET* implementation and features are analyzed. Section 3 depicts our proposed extension to the *INET* radio model for the directional antenna representation. Section 4 presents the model implementation, its main features, parameters and limi-

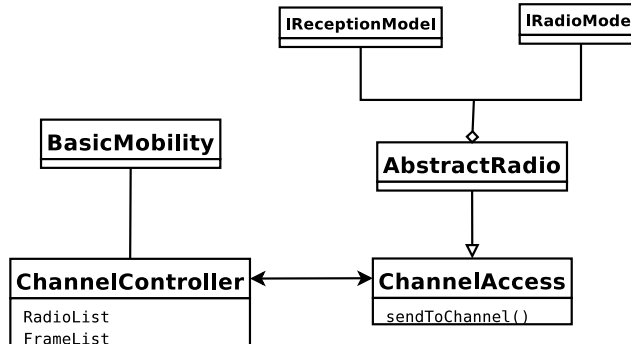


Figure 1: INET’s radio model components.

tations. Section 5 provides a model evaluation by examining various antenna patterns under two well defined scenarios. Finally, Section 6 summarizes the proposed model, our main contributions and further works towards the improvement of the *INET*’s radio model.

2 Status of INET Model

INET is an extensible network modeling framework that consists of a set of modules, built on top of the *OMNeT++* simulator. It includes sub-models for several high-level protocols, such as Applications, IPv4, IPv6, SCTP, TCP, UDP, and wired and wireless physical layers. The initial design of the *INET*’s radio model integrates an abstraction of the channel, called the *ChannelController*, with a *ChannelAccess* interface, which allows the *AbstractRadio* to interact with the radio channel. Radios are built on-top of this *ChannelAccess*. Also, a *Mobility* component is provided, giving nodes (with radio devices inside) the ability to move on the simulation playground. Fig. 1 is a class diagram of *INET*’s radio model components.

The *ChannelController* is an abstraction of the radio channels. Its main roles are: being aware of all communications (packets in the air on each channel) that are happening; registering all the simulated physical radios and their positions; and determining which radios are “connected”, meaning which hosts are able to communicate. This latter operation defines a connectivity graph, built by using the Maximum Interference Distance to determine whether or not a radio is able to “hear” another radio, based on the Free Space propagation (Path Loss) defined by a set of identical radio parameters for all radios.

The *ChannelAccess* is an interface that provides the services needed to send an airframe by the channel. This interface is the cornerstone for implementing any radio. It is important to note that *ChannelAccess* interacts with the *ChannelController*, both being responsible for providing the required information to the radio in order to decide if an airframe is correctly received or transmitted.

The *AbstractRadio* is an extension of the *ChannelAccess* module. It provides a generic radio functionality, through a *RadioModel* interface, which is responsible for deciding if a packet is correctly received, based on the noise measures. It also includes a *ReceptionModel* interface, in charge of calculating the airframe’s reception power, using a propagation loss model. There are two propagation

models already implemented: the classical *Free Space Pathloss* and the *Two-ray* with ground reflection.

Hosts (or nodes) contain one (or several) radio modules and one of the available *Mobility* modules (circular, linear, random, etc.).

The *ChannelController* keeps the important information needed for the *AbstractRadio*. Therefore, the *ChannelAccess* must provide means for the radio to access that information, since it is the entity that connects both sides. Moreover, as mentioned above, the *ChannelController* must build the connectivity graph (or hosts neighbors list), that indicates with which nodes communications can occur. This graph varies only in response to a mobility event, which implies that the module that triggers the graph's update is the *BasicMobility*, through the *ChannelController*. In the current version of *INET*, the communications follow a symmetrical model: For a pair of hosts $h1$ and $h2$, $h2$ is considered the neighbor of $h1$ if it is within its maximum interference distance, which, reciprocally, always implies that $h1$ is neighbor of $h2$ (the *ChannelController* uses the same maximum transmission power for all radios, when calculating their maximum interference distance).

Currently¹, there are several *INET* branches that introduce improvements in different ways. In particular, the branch supporting multiple radios assigns a neighbors list to each host's radio instead of to a single list to the host. Therefore, each host has as many lists as radios. This change implies that the responsibility for building and updating the connectivity graph is transferred from the host to the radios of the host when a mobility event occurs.

3 Extensions to INET's Radio Model

In this section, we introduce our proposed extension to *INET*'s radio model to support directional wireless communications. We start with some technical concepts, followed by the description of our proposed extension. Then, we present an extended module for the *INET* model, that supports directional and omni-directional communications. Notice that the problem of asymmetrical communications addressed hereafter is deeper studied in Section 4.

3.1 Concepts

Antenna patterns are commonly used when studying propagation of radio signals in the space. The *antenna pattern* [Bal05] is a polar chart that describes the dependence of the radiation power (usually in relative decibels, dB) and the direction of communication in 360°. For omni-directional antennas, the theoretical pattern is a circle. For directional antennas, it is an irregular shape, having in general a principal or main lobe and side/back lobes. For directional patterns, the main lobe corresponds to the region where the largest amount of power is radiated, and can be characterized by its maximum gain and its *Beam Width*, corresponding to the beam wideness, often defined by a 3dB-threshold [Car01] that delimits it. Side/back lobes regions can also be distinguished, where smaller amounts of power are radiated (generally seen as losses) with no preferential direction. These losses are often characterized by their maximum gain. In order to quantify the signal propagation, the *Link Budget* [Rap02] equation is used.

¹as of November 2009.

This equation corresponds to an account of the transmission power, antennas gains and losses. The main contributions are the transmission power, antennas gains and free space propagation loss.

3.2 Proposed Extension for the Radio Model

Our proposed extension to the *INET*'s radio model allows representation of any antenna pattern, and specifically, to represent any gain function when calculating the *Link Budget* for a wireless communication. Our extension separates the *Link Budget* into two phases: the calculation of the antenna's gain in a pluggable external module, and the calculation of the effective reception power on the receiving end. In this model, the transmission and reception gain patterns are assumed to be identical, due to the Reciprocity theorem [Kra88]. This helps to apply the same procedure for the gain calculation, both for transmitting and receiving an airframe. In more detail, the external pluggable module is an abstraction of an antenna pattern, that gives the gain value in the direction of two-nodes communication. Our proposed extension uses this external module to calculate the *Link Budget* when determining the *effective transmission power* of an airframe. For two wireless hosts, the communication angle can be calculated from the transmitter's and receiver's coordinates, and consequently, the antenna gain in that direction can be determined. The *effective transmission power* is obtained by adding this gain and the nominal antenna transmission power. A similar calculation is performed to determine the *effective reception power*, but using the received power (i.e. the difference between the effective transmission power and the path loss) instead of the nominal transmission power. More formally, for omni-directional communications, the simplified *Link Budget* expression is as follows:

$$P_{rx} = P_{tx} - PL \quad (1)$$

when considering the antenna gains for directional communication, the expression becomes as:

$$P_{rx} = P_{tx} + G_{tx} - PL + G_{rx} \quad (2)$$

where P_{tx} is the nominal transmission power, G_{tx} is the transmitter gain, G_{rx} is the receiver gain, PL is the path loss and P_{rx} is the effective received power.

The advantages of separating the antenna gain from the *Link Budget* is the flexibility introduced by the externalization of the antenna gain calculation, allowing us to implement any antenna pattern without changing the radio functionalities. Directional and omni-directional antenna patterns can be implemented by describing the antenna gain with mathematical curves, as well as by mapping techniques. We used a simplified *Link Budget* expression that only considers the antenna gains and propagation losses, as expressed in Equation 2, while losses due to cables, connectors, or any other type of losses are not considered.

We use the previous described extensions to implement four directional antenna patterns, based on the "pie-wedge" model described by Gharavi et al. in [GH09]. The radiation pattern is represented by two main components: a main lobe and side/back lobes. We used different mathematical curves (folium, cardioid, circle and rose) to analytically define the main lobe's gain function

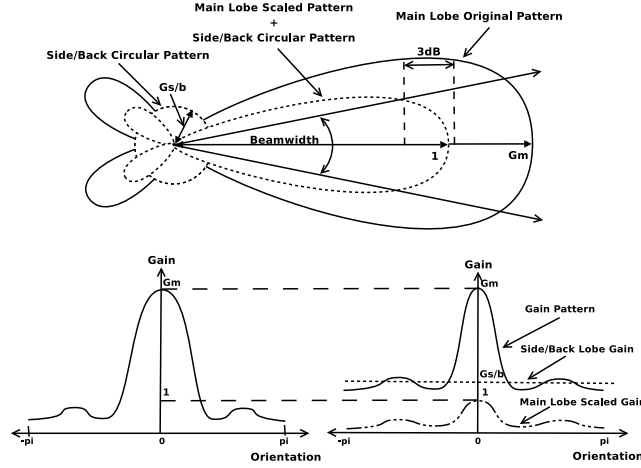


Figure 2: Example of antenna pattern and the scaled antenna pattern.

in every direction (from 0° to 360°); and a circle with an unity-gain (omni-directional communication) to represent the side/back lobes. Then, while the gain of the main lobe varies according to the mathematical formula evaluated in different points, defined by the transmission/reception angle, the gain of the side/back lobes remains constant. For practical reasons, we scale the original analytical curve that defines the main lobe gain pattern, in order to obtain a curve with a maximum gain of G_m in the main beam direction. Also, the side/back lobes are represented by a circular unity-gain pattern, which multiplied by the side/back lobes gain, gives the circular pattern with radius $G_{s/b}$. Fig. 2 depicts the original and the scaled analytical curves used by the proposed directional radio, where we observe the gain function before and after the scaling. Note that the maximum gain remains the same, but now the gain function corresponds to the maximum between the main lobe scaled gain and the side/back lobes circle. This means that within the area defined by the 3dB-threshold, the main lobe gain dominates, while within the rest of the space, the gain value alternates between the main lobe scaled curve and the the side/back lobes circle.

4 Model Implementation

In this Section, we describe the implementation of our proposed directional radio module. This implementation can be separated into two different parts: i) the modifications that have to be made to current *INET* version when implementing asymmetrical communications; and, ii) the changes made to incorporate directional communications, including four different antenna patterns and the proposed *Link Budget* calculation presented in the previous section.

4.1 Asymmetrical Communications

Our *INET* branch extends the multiple radios branch to support asymmetrical communications, where radios no longer are assumed to have the same antenna pattern and transmission power. It also allows the user to select one of the implemented antenna patterns, or create a new one. This improvement forces to change the way the neighbor lists are calculated and updated, since the premise *if you hear me, I can hear you*, is not always true [KNG⁺04] when considering asymmetrical communications.

The first step to implement asymmetrical communications on the current *INET* radio model, is to relieve the *ChannelController* of the responsibility of calculating the maximum interference distance. According to an asymmetrical radio model, radios may have different coverages (in range and in shape). Thus, this task should be assigned to the radio itself, implementing it at the *AbstractRadio* level. Consequently, the *ChannelAccess* interface would rely on the *ChannelController* to build the neighbors list, but now using a method provided by the radio to determine when a node is under its radio coverage. This method, called *isInCoverageArea*, relies on the *ReceptionModel* to determine the maximum interference distance, according to the antenna's radiation shape, and also to the radio signal propagation model.

Regarding the connectivity graph determination, the event that triggers an update in our implementation is not only a mobility event, but a mobility event or a transmission request, since the neighbor list of any node **must** be updated when transmitting a packet, and so, be faithful with the radio signals that each node receives. Additionally, this update is now related to all nodes (and radios) in the simulation, and not only to the node that has changed its position. These modifications have a detrimental impact on the overall execution time. Firstly, the neighbor discovery algorithm has now a complexity of $O(n^2m)$, n being the number of hosts, and m the number of radios per host; and secondly, this algorithm is executed more often. Preliminary results shown that the computational cost is higher enough to make the model not attractive to users when using this algorithm of "brute force" to update the neighbor lists. So, we developed an alternative algorithm that exploits the locality of nodes to calculate their neighbors lists and supports different coverage ranges. In Section 5.2, we analyze the computational cost of both algorithms in terms of the execution time. The next section presents the proposed algorithm for the neighbor list calculation.

4.2 NeighborsGraph Algorithm

In the previous section, we showed the need for an efficient algorithm to overcome the increase of the model's execution time when using asymmetrical communications. This algorithm should exploit the locality of nodes, since when a single node moves, let's say node N_1 , the neighbors lists that must be updated are only those that change due to N_1 's movement, meaning the inclusion or the exclusion of N_1 as a neighbor. Updating a node that is far away from N_1 is useless, in terms of the propagation model and noise levels. This leads to our *selective neighbor list update algorithm*.

This algorithm uses a data structure, similar to a sparse matrix, but keeping the positions of nodes (in fact, radio positions) and a coverage area (Figure 3). This area, C_s , is the square box that contains the real coverage area C_r . The

boxed coverage area C_s is defined by the maximum interference distance given a propagation model, when the received power is equal to the noise level. In the case of the Pathloss model, this distance depends on the transmitter power, carrier frequency and Pathloss coefficient. This distance defines C_s , which is used by the algorithm to compute the neighbors list within this region. Afterwards, a refinement of this list can be made by using the *isInCoverageArea* method of each radio to get the real neighbors list (nodes within C_r). It is worth to notice that the *isInCoverageArea* method is now applied to a reduced set of nodes, instead of all nodes in the simulation. Additionally, the neighbor list calculation returns the list of nodes to be updated as a consequence of N_1 's displacement. For all those nodes, their neighbor lists are tagged as invalid, forcing them to be updated when the node wants to transmit a packet. The algorithm determines

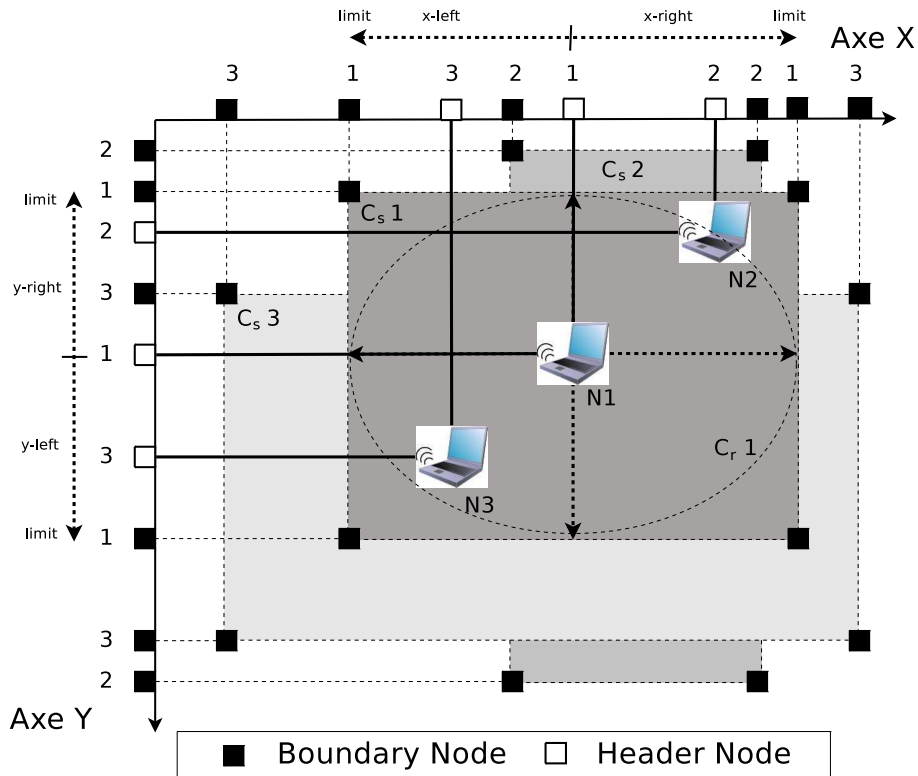


Figure 3: NeighborsGraph data structure

the neighbor list for a node N_1 by exploring the sparse matrix axes on each direction: **x-left**, **y-right**, **x-right** and **y-left**; finding the *header nodes* within the region C_s . It also determines the updated list by finding the *boundary nodes* that are traversed by N_1 . Each node's position (header and boundary nodes) is updated every time the node moves in a $O(\log(n))$ operation, since the matrix axes are red-black trees [GS78]. A formal pseudo-code for the proposed algorithm is shown in Algorithm 1.

The function $pos(node, axe)$ returns the position of the node on the given axe; $boundary(node, direction)$ returns the C_s boundary limit in the given direction; and $owner(node)$ returns the reference to the host/radio of the node.

Input: node n , empty neighbors and toUpdate lists
Output: updated neighbors list and toUpdate list

```

1 begin
2   directions  $\leftarrow$  { x-left,y-right,x-right,y-left }
3   foreach direction in directions do
4     axe  $\leftarrow$  axe of direction
5     limit  $\leftarrow$  pos( $n$ ,axe) + boundary( $n$ ,direction)
6     current  $\leftarrow$  header node of  $n$  on axe
7     while pos(current,axe) not reach limit do
8       n'  $\leftarrow$  owner(current)
9       if type(current) = header node then
10        p  $\leftarrow$  pos(n',in the contrary axe)
11        if inRange( $n$ , p) then
12          | add n' to neighbors
13        end
14      end
15      if type(current) = boundary node then
16        b1  $\leftarrow$  inRange(n',pos( $n$ ,axe))
17        b2  $\leftarrow$  inRange(n',prevpos( $n$ ,axe))
18        if b1  $\neq$  b2 then
19          | add n' to toUpdate
20        end
21      end
22      current  $\leftarrow$  next node in direction
23    end
24  end
25  remove from neighbors repeated nodes
26  remove from toUpdate repeated nodes
27 end

```

Algorithm 1: The NeighborsGraph Algorithm.

As Figure 3 shows, each host has a header node, referencing the host position on each axe, and four boundary nodes, referencing the limits of the region C_s . All these nodes have a direct reference to their host/radio module. Finally, the function $inRange(node, position)$ returns whether the given position is within the C_s region, or not. As we already mentioned, after the execution of this algorithm, the real coverage of each radio inside the node n is evaluated for each neighbor host, in order to determine the real neighbors list. All neighbor lists belonging to a host contained in the *toUpdate* list are invalidated, thus, forcing them to be updated when the host sends a packet to the channel.

The complexity of this algorithm may be higher than the brute force update algorithm on a single host, since it visits each node at least two times (x and y directions). But, we improve the performance by doing this operation only for the nodes affected when a certain node moves, instead of updating the neighbor list of all nodes in the simulation. Performance evaluation results are given in Section 5.2.

4.3 DirectionalRadio Module

Based on the proposed extension of *INET*'s radio model, we created the *DirectionalRadio* module, which complements the current radio implementation with new functionality. In order to make this module flexible enough to allow several antenna patterns, an *AntennaPattern* interface has been added. This interface contains the specific operations of a directional antenna and enables the implementation of new antenna patterns, without interfering with existing basic radio operations.

As stated in Section 3, the main lobe curve is scaled to 1 (i.e. its maximum value is G_m), according to the main lobe width as specified in the configuration file. For a given direction of communication, the gain is given by the higher value between the main lobe's and the side/back lobes' gain.

We provide four antenna patterns, which use known mathematical curves: *CircularPattern*, *CardioidPattern*, *FoliumPattern* and *RosePattern*. These antenna patterns are customizable by changing the settings in the configuration file.

There are some parameters common to all patterns, proper to directional antennas: the *beamWidth*, the angular distance that indicates the main lobe width, in degrees; the *mainLobeGain*, the maximum gain of the main lobe, measured in dB; the *sideLobeGain*, the maximum gain of the side/back lobes, in dBi; the *mainLobeOrientation*, which indicates the direction at which the main lobe is pointing, in degrees; the *dBThreshold*, the threshold value that defines the main lobe area, in dB; and the *patternType*, the selected antenna pattern shape, specified by its name. There are also some specific parameters to each case. For example, if using the *CircularPattern*, the radio r must be set, or the a and b parameters for the *FoliumPattern*.

5 Model Evaluation

We evaluated two aspects of our proposed directional radio module implementation: its correctness and its computational cost. The correctness of the model implementation is evaluated by comparing our simulation results with similar ones found in the literature. The computational cost is estimated by measuring the execution time of the same simulation model with three different scenarios: a symmetrical model scenario, an asymmetrical model scenario with full update of neighbors, and an asymmetrical model scenario with the neighbors-graph algorithm to compute and update the neighbors.

5.1 Correctness of the Proposed DirectionalRadio Module

We designed two simulations to validate and evaluate the correctness of our implementation of the *DirectionalRadio* module. The first one is intended to obtain and analyze the simulated antenna pattern. The second is intended to compare the performance of omni-directional and directional communications.

5.1.1 Obtaining an Antenna Pattern

This simulation has two objectives: to exhibit the antenna pattern, and to verify how it changes according to the transmitter-receiver distance and the path

loss effect. The pattern obtained through the simulation is expected to match the settings given in the configuration file. The simulated scenario consists of one directional AP with the main lobe oriented at 90° , and 10 omni-directional hosts following a circular path with different radiuses surrounding the AP. The simulation begins with all hosts aligned at 0° and separated by 10 meters each, and ends when all hosts are back to their initial position after a complete revolution around the AP. For each host, each *Beacon's Received Power* is logged to assess whether the beacon was correctly received, or not.

The *FoliumPattern* antenna was selected for this simulation. The radio parameters set for this simulation are shown below as an excerpt from the configuration file.

```
# Antenna Pattern Parameters
**.ap1.wlan.radio.transmitterPower = 40.0mW
**.ap1.wlan.radio.beamWidth = 40deg
**.ap1.wlan.radio.mainLobeGain = 15dB
**.ap1.wlan.radio.sideLobeGain = -5dBi
**.ap1.wlan.radio.mainLobeOrientation = 90deg
**.ap1.wlan.radio.dBThreshold = 3dB

# Folium Pattern
**.ap1.wlan.radio.patternType = "FoliumPattern"
**.ap1.wlan.radio.FoliumPattern.a = 1
**.ap1.wlan.radio.FoliumPattern.b = 3
```

Fig. 4 shows the observed antenna pattern for different distances between transmitter and receiver. The angular axis corresponds to the angle between the AP and the hosts, while the radial axis corresponds to the received power in milliwatts (mW).

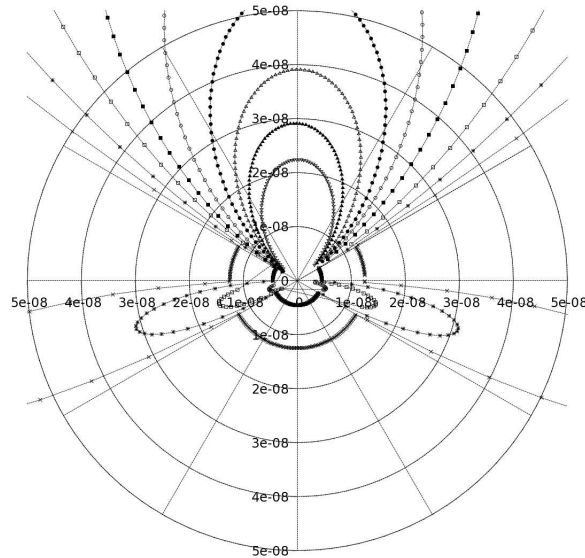


Figure 4: Observed folium pattern at different distances transmitter/receiver obtained from the simulation.

We successfully verified that the antenna pattern matches with the set folium curve and its orientation. Regarding the side/back lobes, we can observe how the gain value alternates between the folium curve and the circle, depending on what

is the higher value, as described in the implementation section. We can observe that the received power varies according to the distance between transmitter and receiver due to the path loss effect. Following one radial direction, the difference between two consecutive level curves corresponds to the path loss when the radio signal travels 10 meters.

5.1.2 Omni-directional vs. Directional Communications

The goal of the second simulation is to evaluate our *DirectionalRadio* by comparing the network throughput when using omni-directional and directional antennas. For this purpose, we build a mesh network simulation, with 10 nodes containing 2 bridged radio interfaces, and 2 client hosts with a single radio interface. In this scenario, the radio parameters for the hosts are chosen such that directional antennas are able to “hear” up to 5 antennas placed in their same direction of orientation, even when they are supposed to communicate only with their immediate neighbors. We determined that using a network with 10 hosts is enough to create strong interference between antennas and to clearly observe the behavior of communications. All antennas in the simulation have the same maximum transmission range, and the radio interfaces are configured as shown in Fig. 5, using the same channel. In this scenario, a TCP stream is transmitted first time from *client1* to *client2* through the mesh network, using omni-directional antennas (1st case) and then, a second time using directional antennas (2nd case); network throughput was monitored during the experiment.

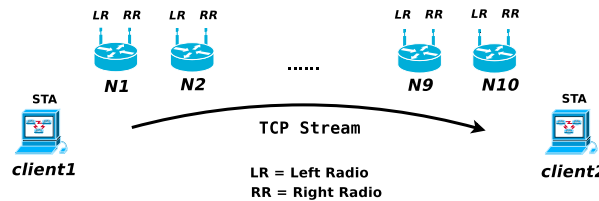


Figure 5: Second evaluation scenario. Mesh network with multiple radio interfaces nodes.

Fig. 6 presents a comparison of the network throughput for the two cases described above. In the 1st case, we observe that the network throughput is about half of the theoretical one, which is consistent with previously obtained results [MIKR07]. In Fig. 7(a) we can see that the number of collisions using omni-directional nodes is constant for all radios, while for directional antennas (Fig. 7(b)) the number varies depending on the node’s position. This is because the coverage range for directional antennas is set to be greater, thus allowing two distant antennas to “hear” each other. The left radio of N8, for instance, is able to hear from N2 to N7, leading to a greater number of collisions when receiving. The packet loss, however, is reduced when using directional antennas, as shown in Fig. 8(b), compared to the case that uses omni-directional antennas (Fig. 8(a)).

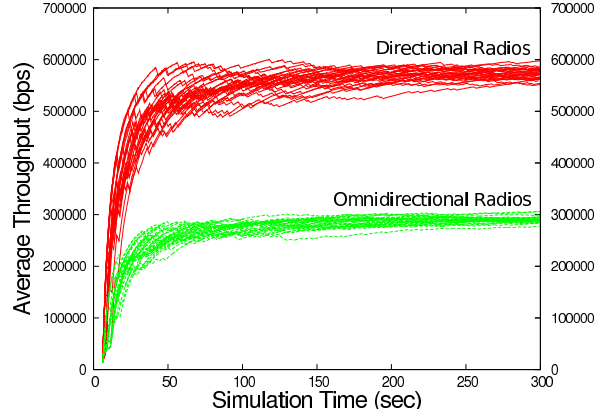
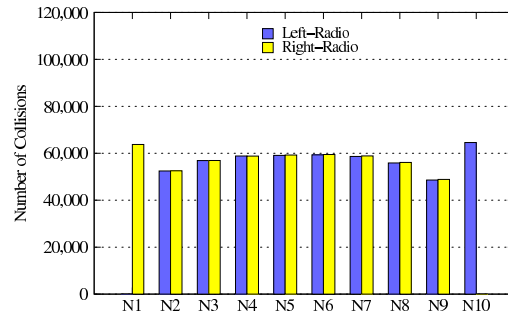
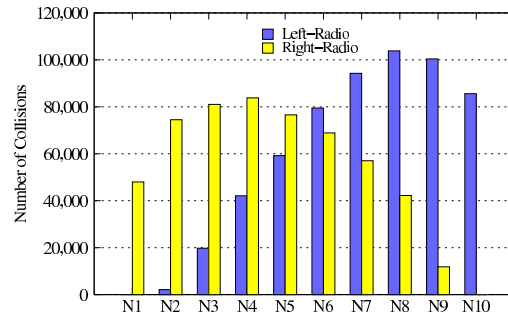


Figure 6: Comparison of TCP throughput for the 1st and 2nd case for 30 repetitions of the simulation.



(a) Omnidirectional radios



(b) Directional radios

Figure 7: Comparison for packet collisions for the 1st and 2nd case.

5.2 Computational cost Analysis

The introduction of asymmetrical communications generates an increase in the execution time of the neighbors discovery procedure, since it can not be assumed reciprocity when building (or updating) the neighbor list. However, the computational cost can be partially decreased if a more refined algorithm is used. In order to evaluate the performance of each algorithm, we compare the simulation time for the same scenario when using: the current neighbor discovery procedure

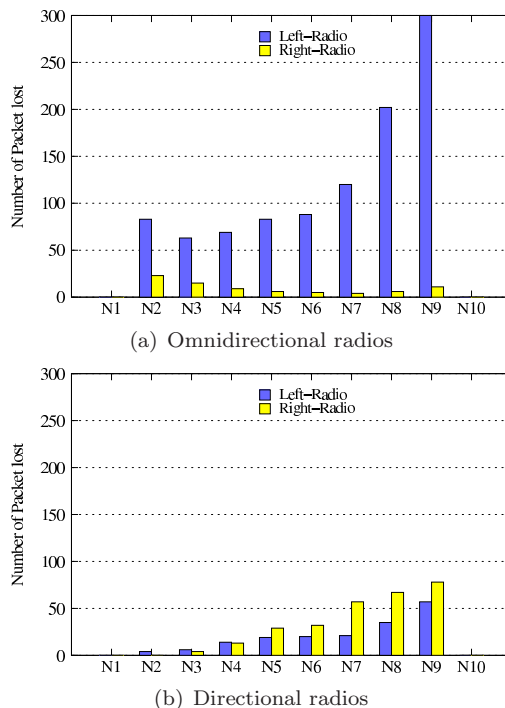


Figure 8: Comparison for packet losses for the 1st and 2nd case.

described in Section 2 for a symmetrical model (Procedure 1); the “brute force” neighbors discovery procedure for the asymmetrical model described in Section 4.1 (Procedure 2); and the *NeighborsGraph Algorithm* described in Section 4.2 (Procedure 3).

The simulation scenario consists of 100 hosts, randomly moving at different speeds (up to 40 Km/h). There are 4 access points belonging to the same network, located in a 2×2 grid, covering all the simulation playground and connected to a server via wired links. All radios in simulation (APs and hosts) have the same radio parameters. The hosts are expected to associate to the network performing handover when passing from one AP’s coverage area to another’s. All along the simulation, hosts are sending ICMP traffic (ping) to the server. The simulation time was set to 500 seconds and 10 repetitions for each model were ran, logging the real execution time for each case. The hardware used to simulate this scenario was a Dell Precision T3400 (Intel(R) Core(TM)2 Duo CPU E6550 @ 2.33GHz, 2Gb RAM running Fedora 11).

Figure 9 shows the execution time for the Procedures 1, 2 and 3, respectively. We can observe that using Procedure 2 increases $\approx 500\%$ the computation time compared with Procedure 1, while the increase is close to a 50% when using Procedure 3. A comparison of means [MR06] among the procedures shows that, while the difference between Procedure 1 and Procedure 2 is always large, the difference between Procedure 1 and Procedure 3 always remains about 50%.

We realize that Procedure 1 takes advantage from the assumption of symmetry of communications when determining the nodes to be updated, having a very good performance in execution time. Contrarily, when asymmetrical

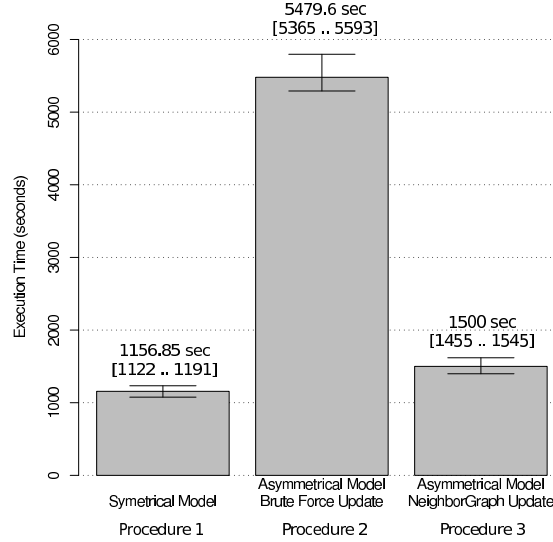


Figure 9: Execution time for Symmetrical and Asymmetrical model with different neighbors list update algorithms.

communications are used, the neighbors list must be updated much more often to honor the SNR and noise calculation and this is done for all nodes when a host moves or transmits an airframe. Thus, the execution time is increased dramatically. Nevertheless, our proposed algorithm to calculate the neighbors overcomes this impact, reducing the increase in execution time reasonably when using an asymmetrical communications radio model.

Extending these results to larger simulations, we estimate that the execution time of our proposed algorithm will be always higher than the execution time when symmetrical communications are used. However, further experimentation has shown that this difference is always around 50%. As we stated in Section 4.2, the execution time of the neighbors graph algorithm is expected to be higher since each neighbor node is visited at least twice (axe-x and axe-y). But, a possible alternative to overcome this overhead could be to perform this exploration in a parallel way (exploiting the multi-core architectures). Whether or not the execution time of the neighbors graph algorithm could be improved, it will never be better than the algorithm for symmetrical communications, since the assumption of symmetry gives the best case when all radio coverages are equal. On the contrary, our algorithm ensures a good approximation of the optimal case when calculating the neighbors lists for a node, not only when radios coverages are equal, but also in cases where radios coverages are different in shape and size.

6 Conclusions

In this work, we presented an extension of the *OMNeT++*'s *INET* Framework for directional and asymmetrical wireless communications. This new extension is based on the existing *INET* multi-radio branch and introduces the following contributions: an asymmetrical Radio Model to support directional antenna

patterns; a *NeighborsGraph* Algorithm to speed up the neighbor nodes update computation; and an implementation of a Directional Radio module with four antenna patterns. The included antenna patterns use mathematical curves to represent the gain pattern in a pie-wedge directional radiation model.

Although the proposed model still has several simplifications, we demonstrated through simulations that the results obtained agree with the results found in the literature when using directional radios in mesh networks.

Furthermore, despite the increase in execution time could be potentially high when using asymmetrical communications, we showed it is possible to reasonably reduce it by using our *NeighborsGraph* algorithm.

In this work, we also identified open issues, such as the accuracy of antenna gain in the plane, or the use of multi-core architectures to speed-up the construction/update of the neighbors list. First, antenna gain can be described through a set of points by using *mapping techniques*; and second, the use of *threading* to explore on each axe direction when using the *NeighborsGraph* algorithm.

Finally, we consider that our contributions are a first attempt to provide an asymmetrical communications support within the *OMNeT++/INET* Framework.

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