



## Zubov's method for interconnected systems

Fabian Wirth, Fabio Camilli, Lars Grüne

► **To cite this version:**

Fabian Wirth, Fabio Camilli, Lars Grüne. Zubov's method for interconnected systems. SADCO Kick off, Mar 2011, Paris, France. <inria-00585701>

**HAL Id: inria-00585701**

**<https://hal.inria.fr/inria-00585701>**

Submitted on 14 Apr 2011

**HAL** is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

# Zubov's method for interconnected systems

Fabian Wirth

Institute of Mathematics  
University of Würzburg

SADCO - Kick off meeting  
Paris, March, 1–2 2011.

joint work with:  
**Fabio Camilli (L'Aquila) and Lars Grüne (Bayreuth)**

## Zubov's Method

The domain of attraction

Zubov's equation

## Robust domains of attraction

Problem statement

A robust version of Zubov's theorem

Examples

## Interconnected Systems

ISS and Lyapunov functions

## Zubov's Method and Interconnected Systems



# The domain of attraction

Consider a nonlinear system

$$\begin{aligned}\dot{x} &= f(x) & (1) \\ x(0) &= x_0 \in \mathbb{R}^n,\end{aligned}$$

$f$  Lipschitz continuous,  $f(0) = 0$ .

Assume  $x^* = 0$  is **asymptotically stable**.



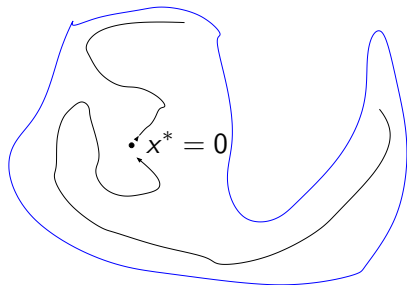
# The domain of attraction

Consider a nonlinear system

$$\begin{aligned} \dot{x} &= f(x) \\ x(0) &= x_0 \in \mathbb{R}^n, \end{aligned} \quad (1)$$

$f$  Lipschitz continuous,  $f(0) = 0$ .

Assume  $x^* = 0$  is **asymptotically stable**.



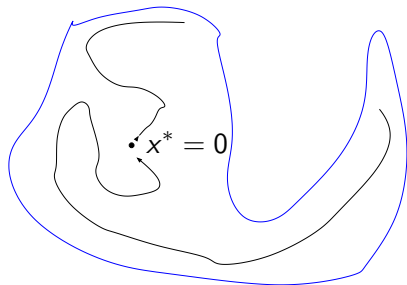
## The domain of attraction

Consider a nonlinear system

$$\begin{aligned}\dot{x} &= f(x) \\ x(0) &= x_0 \in \mathbb{R}^n,\end{aligned}\quad (1)$$

$f$  Lipschitz continuous,  $f(0) = 0$ .

Assume  $x^* = 0$  is **asymptotically stable**.



The **domain of attraction** of 0 is defined by

$$\mathcal{A}(0) := \{x \in \mathbb{R}^n \mid \varphi(t; x) \rightarrow 0, \text{ as } t \rightarrow \infty\}.$$

Here  $\varphi(\cdot; x)$  denotes the solution of (1).

## Zubov's result (1956)

$$\dot{x} = f(x) \quad (1)$$

$$f(0) = 0, \quad x^* = 0 \quad \text{is asymptotically stable.} \quad (2)$$

### Theorem

*A set  $A$  containing  $0$  in its interior is the domain of attraction of (1) if and only if*



## Zubov's result (1956)

$$\dot{x} = f(x) \quad (1)$$

$$f(0) = 0, \quad x^* = 0 \quad \text{is asymptotically stable.} \quad (2)$$

### Theorem

*A set  $A$  containing 0 in its interior is the domain of attraction of (1) if and only if there exist continuous functions  $V, h$  such that*





## Zubov's result (1956)

$$\dot{x} = f(x) \quad (1)$$

$$f(0) = 0, \quad x^* = 0 \quad \text{is asymptotically stable.} \quad (2)$$

### Theorem

A set  $A$  containing  $0$  in its interior is the domain of attraction of (1) if and only if there exist continuous functions  $V, h$  such that

- ▶  $V(0) = h(0) = 0,$   
 $0 < V(x) < 1$  for  $x \in A \setminus \{0\}, h > 0$  on  $\mathbb{R}^n \setminus \{0\}$



## Zubov's result (1956)

$$\dot{x} = f(x) \quad (1)$$

$$f(0) = 0, \quad x^* = 0 \quad \text{is asymptotically stable.} \quad (2)$$

### Theorem

A set  $A$  containing  $0$  in its interior is the domain of attraction of (1) if and only if there exist continuous functions  $V, h$  such that

- ▶  $V(0) = h(0) = 0,$   
 $0 < V(x) < 1$  for  $x \in A \setminus \{0\}, h > 0$  on  $\mathbb{R}^n \setminus \{0\}$
- ▶  $V(x_n) \rightarrow 1$  for  $x_n \rightarrow \partial A$  or  $\|x_n\| \rightarrow \infty,$



## Zubov's result (1956)

$$\dot{x} = f(x) \quad (1)$$

$$f(0) = 0, \quad x^* = 0 \quad \text{is asymptotically stable.} \quad (2)$$

### Theorem

A set  $A$  containing  $0$  in its interior is the domain of attraction of (1) if and only if there exist continuous functions  $V, h$  such that

- ▶  $V(0) = h(0) = 0,$   
 $0 < V(x) < 1$  for  $x \in A \setminus \{0\}, h > 0$  on  $\mathbb{R}^n \setminus \{0\}$
- ▶  $V(x_n) \rightarrow 1$  for  $x_n \rightarrow \partial A$  or  $\|x_n\| \rightarrow \infty,$

▶  $DV(x) \cdot f(x) = -h(x)(1 - V(x))\sqrt{1 + \|f(x)\|^2}$



## Robust domains of attraction

Consider systems

$$\dot{x}(t) = f(x(t), d(t)), \quad t \in \mathbb{R}$$

with a perturbation term  $d$ . We are interested in robust stability properties. In particular, the **robust domain of attraction**.

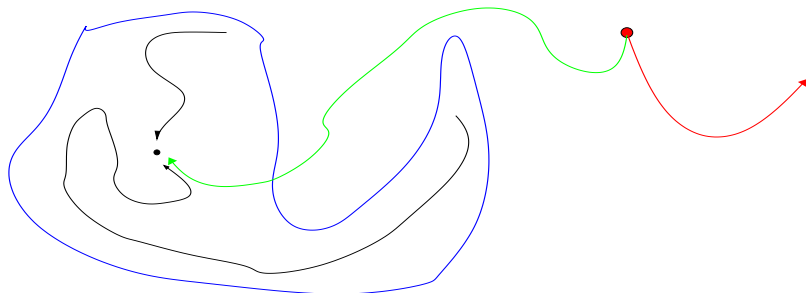


## Robust domains of attraction

Consider systems

$$\dot{x}(t) = f(x(t), d(t)), \quad t \in \mathbb{R}$$

with a perturbation term  $d$ . We are interested in robust stability properties. In particular, the **robust domain of attraction**.



# Robust domains of attraction

$$\dot{x}(t) = f(x(t), d(t)), \quad t \in \mathbb{R}$$

Assumptions:

- $f : \mathbb{R}^n \times D \rightarrow \mathbb{R}^n$  continuous, locally Lipschitz continuous in  $x$ , uniformly in  $d$
- $D \subset \mathbb{R}^m$  compact, convex,  $d(t) \in D$  a.e.



# Robust domains of attraction

$$\dot{x}(t) = f(x(t), d(t)), \quad t \in \mathbb{R}$$

Assumptions:

- $f : \mathbb{R}^n \times D \rightarrow \mathbb{R}^n$  continuous, locally Lipschitz continuous in  $x$ , uniformly in  $d$
- $D \subset \mathbb{R}^m$  compact, convex,  $d(t) \in D$  a.e.
- $f(0, d) = 0$  for all  $d \in D$
- $0$  is locally uniformly asymptotically stable

Notation:  $\mathcal{D} := \{d : \mathbb{R} \rightarrow D ; d \text{ Lebesgue measurable}\}$



# Robust domains of attraction

$$\dot{x}(t) = f(x(t), d(t)), \quad t \in \mathbb{R}$$

Assumptions:

- $f : \mathbb{R}^n \times D \rightarrow \mathbb{R}^n$  continuous, locally Lipschitz continuous in  $x$ , uniformly in  $d$
- $D \subset \mathbb{R}^m$  compact, convex,  $d(t) \in D$  a.e.
- $f(0, d) = 0$  for all  $d \in D$
- $0$  is locally uniformly asymptotically stable

Notation:  $\mathcal{D} := \{d : \mathbb{R} \rightarrow D ; d \text{ Lebesgue measurable}\}$

$$\mathcal{A}_D(0) := \{x \in \mathbb{R}^n \mid \phi(t; x, d) \rightarrow 0 \forall d \in \mathcal{D}\}$$





## A robust version of Zubov's theorem

**Theorem:**[Zubov's theorem for perturbed systems, SICON 2001]  
 Under suitable growth conditions on  $g$  there is a unique viscosity solution of

$$\begin{cases} \inf_{d \in D} \{-Dv(x)f(x, d) - (1 - v(x))g(x, d)\} = 0 \\ v(0) = 0 \end{cases}$$

The robust domain of attraction satisfies

$$\mathcal{A}_D(0) = v^{-1}([0, 1]).$$

# Example

$$\dot{x}_1 = -x_1 + x_2$$

$$\dot{x}_2 = 0.1x_1 - 2x_2 - x_1^2 - 0.1x_1^3$$

Fixed points:

$[0, 0]$ , unstable

$[-2.5505, -2.5505]$ , asymptotically stable

$[-7.4495, -7.4495]$ , asymptotically stable.



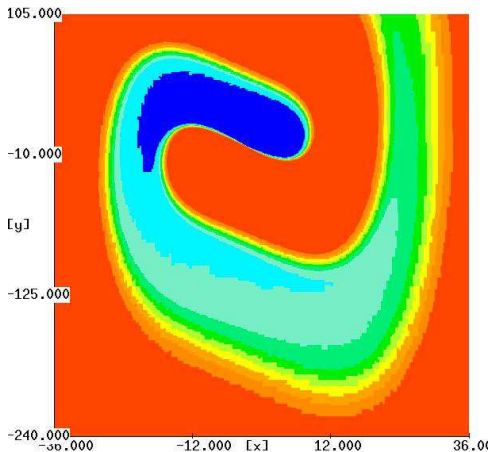
Examples

# Example

$$\dot{x}_1 = -x_1 + x_2$$

$$\dot{x}_2 = 0.1x_1 - 2x_2 - x_1^2 - (0.1 + d(t))x_1^3$$

$$D = \{0\}$$



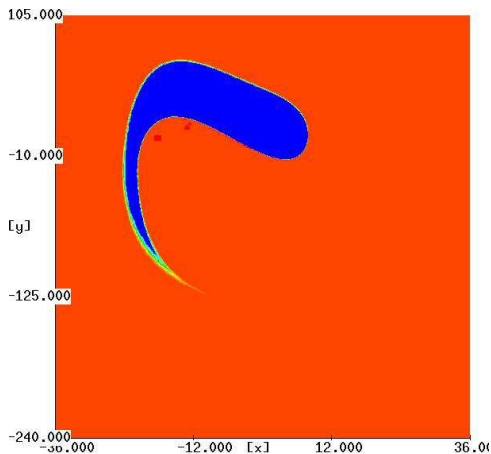
Examples

# Example

$$\dot{x}_1 = -x_1 + x_2$$

$$\dot{x}_2 = 0.1x_1 - 2x_2 - x_1^2 - (0.1 + d(t))x_1^3$$

$$D = [-0.02, 0.02]$$



# Drawbacks

- ▶ Solution of the PDE is obtained by discretisation of the state space.
- ▶ Curse of dimensionality: For systems of dimension greater than 4 the method is not really applicable.

# Drawbacks

- ▶ Solution of the PDE is obtained by discretisation of the state space.
- ▶ Curse of dimensionality: For systems of dimension greater than 4 the method is not really applicable.

## Idea:

View systems in larger dimension as interconnection of low-dimensional systems.

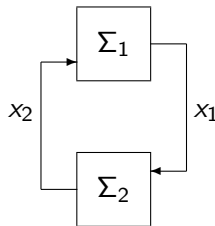
## Interconnection of two systems

Consider

$$\Sigma_1 : \dot{x}_1 = f_1(x_1, x_2)$$

$$\Sigma_2 : \dot{x}_2 = f_2(x_1, x_2)$$

$$f_i : \mathbb{R}^{N_1+N_2+N_u} \rightarrow \mathbb{R}^{N_i}$$



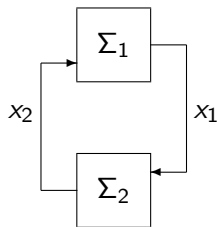
## Interconnection of two systems

Consider

$$\Sigma_1 : \dot{x}_1 = f_1(x_1, x_2)$$

$$\Sigma_2 : \dot{x}_2 = f_2(x_1, x_2)$$

$$f_i : \mathbb{R}^{N_1+N_2+N_u} \rightarrow \mathbb{R}^{N_i}$$



with two **Lyapunov functions** such that

$$V_1(x_1) > \gamma_{12}(V_2(x_2)) \quad \Rightarrow \quad \dot{V}_1 < -\alpha_1(\|x_1\|)$$

$$V_2(x_2) > \gamma_{21}(V_1(x_1)) \quad \Rightarrow \quad \dot{V}_2 < -\alpha_2(\|x_2\|)$$





# Input-to-state stability (ISS) — Lyapunov version



## Input-to-state stability (ISS) — Lyapunov version

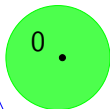
$$V > \gamma(\|u\|) \implies \dot{V} < 0$$



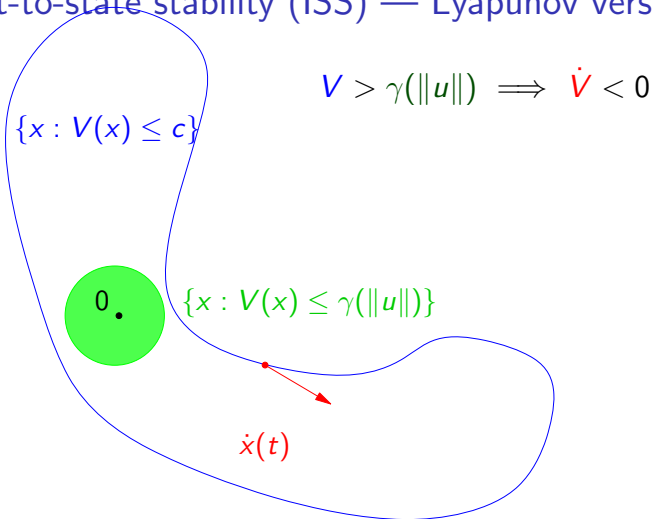
# Input-to-state stability (ISS) — Lyapunov version

$\{x : V(x) \leq c\}$

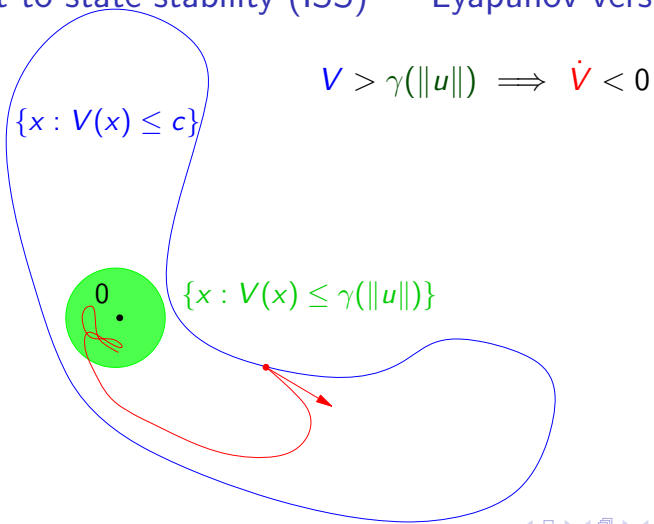
$$V > \gamma(\|u\|) \implies \dot{V} < 0$$



# Input-to-state stability (ISS) — Lyapunov version



# Input-to-state stability (ISS) — Lyapunov version



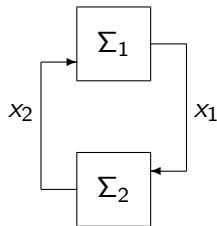
# Interconnection of two systems

Consider

$$\Sigma_1 : \dot{x}_1 = f_1(x_1, x_2)$$

$$\Sigma_2 : \dot{x}_2 = f_2(x_1, x_2)$$

$$f_i : \mathbb{R}^{N_1+N_2+N_u} \rightarrow \mathbb{R}^{N_i}$$



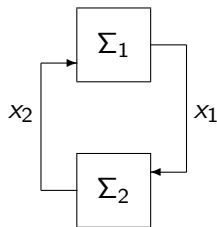
## Interconnection of two systems

Consider

$$\Sigma_1 : \dot{x}_1 = f_1(x_1, x_2)$$

$$\Sigma_2 : \dot{x}_2 = f_2(x_1, x_2)$$

$$f_i : \mathbb{R}^{N_1+N_2+N_u} \rightarrow \mathbb{R}^{N_i}$$



with two **Lyapunov functions** such that

$$V_1(x_1) > \gamma_{12}(V_2(x_2)) \Rightarrow \dot{V}_1 < -\alpha_1(\|x_1\|)$$

$$V_2(x_2) > \gamma_{21}(V_1(x_1)) \Rightarrow \dot{V}_2 < -\alpha_2(\|x_2\|)$$



## The ISS small gain theorem

### Theorem (Jiang, Mareels, Wang 1996)

If there exist  $\mathcal{K}_\infty$ -functions  $\rho_1, \rho_2$  such that

$$(\text{id} + \rho_1) \circ \gamma_{12} \circ (\text{id} + \rho_2) \circ \gamma_{21} < \text{id},$$

then

$$\dot{x} = f(x) = \begin{pmatrix} f_1(x_1, x_2) \\ f_2(x_1, x_2) \end{pmatrix}$$

with  $x = (x_1, x_2)^\top$  is asymptotically stable in  $(x_1^*, x_2^*) = (0, 0)$ .

See also [Jiang, Teel, Praly 1994] [Grüne 2002] and [Dashkovskiy, Rüffer, W. 2007, 2009].





# Goal

Can we compute ISS Lyapunov functions using a Zubov approach ?

## Zubov and ISS Lyapunov functions

Choose a gain  $\gamma \in \mathcal{K}_\infty$  and define

$$\begin{aligned} \tilde{f}_\gamma &: \mathbb{R}^n \times B(0, 1) \rightarrow \mathbb{R}^n \\ (x, d) &\mapsto f(x, \gamma(\|x\|)d) \end{aligned}$$

$$\dot{x} = f(x, \gamma(\|x\|)d) := \tilde{f}_\gamma(x, d), \quad (3)$$

### Proposition

Let  $\gamma \in \mathcal{K}_\infty$  be locally Lipschitz on  $(0, \infty)$ .

If  $V$  is a robust Lyapunov function for (3) it is an ISS Lyapunov function for

$$\dot{x} = f(x, d)$$

with Lyapunov gain  $\gamma^{-1}$ .



## Outline of procedure

- (i) For each of the subsystems  $i = 1, 2$  choose  $\gamma_i \in \mathcal{K}_\infty$  and compute the robust Lyapunov function  $v_i$ .



## Outline of procedure

- (i) For each of the subsystems  $i = 1, 2$  choose  $\gamma_i \in \mathcal{K}_\infty$  and compute the robust Lyapunov function  $v_i$ .
- (ii) For each  $v_{\gamma,i}$  compute bounds

$$\psi_{i,1}(\|x_i\|) \leq v_i(x_i) \leq \psi_{i,2}(\|x_i\|)$$

## Outline of procedure

- (i) For each of the subsystems  $i = 1, 2$  choose  $\gamma_i \in \mathcal{K}_\infty$  and compute the robust Lyapunov function  $v_i$ .
- (ii) For each  $v_{\gamma,i}$  compute bounds

$$\psi_{i,1}(\|x_i\|) \leq v_i(x_i) \leq \psi_{i,2}(\|x_i\|)$$

- (iii) The gain for each of the Lyapunov functions is then given by

$$\tilde{\gamma}_{ij} := \psi_{j,2} \circ \gamma_i^{-1} \circ \psi_{i,1}^{-1}.$$



## Outline of procedure

- (i) For each of the subsystems  $i = 1, 2$  choose  $\gamma_i \in \mathcal{K}_\infty$  and compute the robust Lyapunov function  $v_i$ .
- (ii) For each  $v_{\gamma,i}$  compute bounds

$$\psi_{i,1}(\|x_i\|) \leq v_i(x_i) \leq \psi_{i,2}(\|x_i\|)$$

- (iii) The gain for each of the Lyapunov functions is then given by

$$\tilde{\gamma}_{ij} := \psi_{j,2} \circ \gamma_i^{-1} \circ \psi_{i,1}^{-1}.$$

- (iv) Do the two gains  $\tilde{\gamma}_{12}, \tilde{\gamma}_{21}$  satisfy the small gain condition ?



## Outline of procedure

- (i) For each of the subsystems  $i = 1, 2$  choose  $\gamma_i \in \mathcal{K}_\infty$  and compute the robust Lyapunov function  $v_i$ .
- (ii) For each  $v_{\gamma,i}$  compute bounds

$$\psi_{i,1}(\|x_i\|) \leq v_i(x_i) \leq \psi_{i,2}(\|x_i\|)$$

- (iii) The gain for each of the Lyapunov functions is then given by

$$\tilde{\gamma}_{ij} := \psi_{j,2} \circ \gamma_i^{-1} \circ \psi_{i,1}^{-1}.$$

- (iv) Do the two gains  $\tilde{\gamma}_{12}, \tilde{\gamma}_{21}$  satisfy the small gain condition ?
- (v) If this is the case there is a constructive procedure to get a Lyapunov function for the interconnected system, (see Dashkovskiy, Rüffer, W. 2009).



## Outline of procedure

- (i) For each of the subsystems  $i = 1, 2$  choose  $\gamma_i \in \mathcal{K}_\infty$  and compute the robust Lyapunov function  $v_i$ .
- (ii) For each  $v_{\gamma,i}$  compute bounds

$$\psi_{i,1}(\|x_i\|) \leq v_i(x_i) \leq \psi_{i,2}(\|x_i\|)$$

- (iii) The gain for each of the Lyapunov functions is then given by

$$\tilde{\gamma}_{ij} := \psi_{j,2} \circ \gamma_i^{-1} \circ \psi_{i,1}^{-1}.$$

- (iv) Do the two gains  $\tilde{\gamma}_{12}, \tilde{\gamma}_{21}$  satisfy the small gain condition ?
- (v) If this is the case there is a constructive procedure to get a Lyapunov function for the interconnected system, (see Dashkovskiy, Rüffer, W. 2009).
- (vi) Use this function to estimate the domain of attraction.





## Conclusions

- ▶ An approach for the computation of lower estimates for the domain of attraction of interconnected systems has been presented.
- ▶ The idea still needs a lot of tuning:
  - ▶ which  $\gamma$  do you choose
  - ▶ is  $\gamma \in \mathcal{K}_\infty$  really necessary ? (Angeli and Astolfi, 2007) says clearly that this is not the case
  - ▶ Do state transformations help ?

