



Tutorial on Differential Games

Marc Quincampoix

► **To cite this version:**

Marc Quincampoix. Tutorial on Differential Games. SADCO Summer School 2011 - Optimal Control, Sep 2011, London, United Kingdom. inria-00630050

HAL Id: inria-00630050

<https://hal.inria.fr/inria-00630050>

Submitted on 7 Oct 2011

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

Differential Games III

Marc Quincampoix
Université de Bretagne Occidentale (Brest-France)
SADCO, London, September 2011

Contents

1. *I Introduction: A Pursuit Game and Isaacs Theory*
2. *II Strategies*
3. *III Dynamic Programming Principle*
4. *IV Existence of Value, Viscosity Solutions*
5. *► V Games on the space of measures, Incomplete information*
Joint Work P. Cardaliaguet , M.Q

The differential Game

$$\begin{cases} x'(t) = f(x(t), u(t), v(t)), & t \in [0, T] \\ u(t) \in U, v(t) \in V \end{cases} \quad (1)$$

where $f : \mathbb{R}^N \times U \times V \rightarrow \mathbb{R}^N$, U and V being the control sets of the players. To any initial condition $x(t_0) = x_0$ we associate $t \rightarrow X_t^{t_0, x_0, u, v}$ the solution to (1).

The first player—choosing u —wants to minimize a final cost of the form

$$g(x(T))$$

while the second player,—playing with v —wants to maximize it.

the state-space x_0 is only imperfectly known by the players : they only know that the initial position is randomly distributed under some fixed probability measure μ_0 . Both players are assumed to know this probability μ_0 , and have a perfect knowledge of the control of the other player.

So the "lack" of information is very specific :

- it is symmetric for both player
- it is only concerned with the current position of the game.

We denote by \mathcal{M} the Borel probability measures μ s.t.

$$\int_{\mathbb{R}^N} |x|^2 d\mu(x) < +\infty .$$

Assumptions

$$\left\{ \begin{array}{l} (i) \quad U \text{ and } V \text{ are compact subsets of some finite} \\ \quad \text{dimensional spaces} \\ (ii) \quad f : \mathbb{R}^N \times U \times V \rightarrow \mathbb{R}^N \text{ is continuous and} \\ \quad \text{Lipschitz continuous with respect to} \\ (iii) \quad \forall (x, u, v), |f(x, u, v)| \leq M \\ (iv) \quad g : \mathbb{R}^N \rightarrow \mathbb{R} \text{ is Lipschitz continuous and bounded} \end{array} \right. \quad (2)$$

$$\mathcal{U}(t_0) = \{u : [t_0, T] \rightarrow U, \text{ Lebesgue measurable}\}$$

$$\mathcal{V}(t_0) = \{v : [t_0, T] \rightarrow V, \text{ Lebesgue measurable}\}$$

Strategies

Definition 1 A *NAD strategy* is a map $\alpha : \mathcal{V}(t_0) \rightarrow \mathcal{U}(t_0)$ such that there is some $\tau > 0$ such that $\forall t$,

$\forall v_1, v_2 \in \mathcal{V}(t_0)$, $v_1 = v_2$ on $[t_0, t] \Rightarrow \alpha(v_1) = \alpha(v_2)$ on $[t_0, t + \tau]$.

$\mathcal{A}(t_0)$ is the set of such α . Symmetrically, $\mathcal{B}(t_0)$ is the set of *NAD strategies* $\beta : \mathcal{U}(t_0) \rightarrow \mathcal{V}(t_0)$ for the second player.

Lemma 2 $\forall (\alpha, \beta) \in \mathcal{A}(t_0) \times \mathcal{B}(t_0)$, $\exists!(u_0, v_0) \in \mathcal{U}(t_0) \times \mathcal{V}(t_0)$,

$$\alpha(v_0) = u_0 \text{ and } \beta(u_0) = v_0 .$$

$$X_t^{t_0, x, \alpha, \beta} := X_t^{t_0, x, u_0, v_0} \quad \forall t \in [t_0, T] .$$

Payoffs and Values

$g : \mathbb{R}^N \mapsto \mathbb{R}$ which is Lipschitz and bounded. For any $(t_0, \mu_0) \in [0, T) \times \mathcal{M}$ and for any $(u, v) \in \mathcal{U}(t_0) \times \mathcal{V}(t_0)$ we set

$$J(t_0, \mu_0, u, v) = \int_{\mathbb{R}^N} g \left(X_T^{t_0, x, u, v} \right) d\mu(x) .$$

For any pair of strategies $(\alpha, \beta) \in \mathcal{A}(t_0) \times \mathcal{B}(t_0)$, we define

$$J(t_0, \mu_0, \alpha, \beta) = J(t_0, \mu_0, u_0, v_0)$$

where $(u_0, v_0) \in \mathcal{U}(t_0) \times \mathcal{V}(t_0)$ is associated to (α, β) by the Lemma

Definition of the value functions:

$$V^+(t_0, \mu_0) = \inf_{\alpha \in \mathcal{A}(t_0)} \sup_{\beta \in \mathcal{B}(t_0)} J(t_0, \mu_0, \alpha, \beta)$$

and

$$V^-(t_0, \mu_0) = \sup_{\beta \in \mathcal{B}(t_0)} \inf_{\alpha \in \mathcal{A}(t_0)} J(t_0, \mu_0, \alpha, \beta) .$$

Obviously we have

$$V^-(t_0, \mu_0) \leq V^+(t_0, \mu_0) \quad \forall (t_0, \mu_0) \in [0, T] \times \mathcal{M} .$$

Remark

$$V^+(t_0, \mu_0) = \inf_{\alpha \in \mathcal{A}(t_0)} \sup_{v \in \mathcal{V}(t_0)} J(t_0, \mu_0, \alpha(v), v)$$

$$V^-(t_0, \mu_0) = \sup_{\beta \in \mathcal{B}(t_0)} \inf_{u \in \mathcal{U}(t_0)} J(t_0, \mu_0, u, \beta(u)) .$$

Preliminaries on Probability Measures

For $\mu \in \mathcal{M}$, we denote by $L^2_\mu(\mathbb{R}^N, \mathbb{R})$ (resp. $L^2_\mu(\mathbb{R}^N, \mathbb{R}^N)$) the set of μ -measurable maps $p : \mathbb{R}^N \rightarrow \mathbb{R}$ (resp. $p : \mathbb{R}^N \rightarrow \mathbb{R}^N$) such that $\|p\|_{L^2_\mu} := \int_{\mathbb{R}^N} |p|^2 d\mu < +\infty$

For $\mu \in \mathcal{M}$ and $\varphi : \mathbb{R}^N \rightarrow \mathbb{R}^N$ a Borel measurable with linear growth, $\varphi\#\mu$ is the push-forward of μ by φ ,

$$\varphi\#\mu(A) = \mu\left(\varphi^{-1}(A)\right) \quad \forall A \subset \mathbb{R}^N, \text{ Borel measurable}$$

or, equivalently, such that, $\forall f : \mathbb{R}^N \rightarrow \mathbb{R}$, Borel measurable and bounded,

$$\int_{\mathbb{R}^N} f d(\varphi\#\mu) = \int_{\mathbb{R}^N} f(\varphi(x)) d\mu(x) .$$

Wasserstein Distance **cf** book of Villani

$$\mathbf{d}(\mu, \nu) = \inf \left\{ \left(\int_{\mathbb{R}^{2N}} |x - y|^2 d\gamma \right)^{\frac{1}{2}} \right\} \quad (3)$$

where the infimum is taken over all the probability measures γ in \mathbb{R}^{2N} such that

$$\pi_1\#\gamma = \mu \quad \text{and} \quad \pi_2\#\gamma = \nu, \quad (4)$$

π_1 and π_2 being respectively the projections on the first and the second coordinates: $\pi_1(x, y) = x$ and $\pi_2(x, y) = y$. A measure γ satisfying (4) is an admissible transport plan from μ to ν . The optimal γ are called optimal plans.

Lemma 3 *If $h : \mathbb{R}^N \rightarrow \mathbb{R}$ is k -Lipschitz continuous, then*

$$\left| \int_{\mathbb{R}^N} h(x) d\mu(x) - \int_{\mathbb{R}^N} h(x) d\nu(x) \right| \leq k \mathbf{d}(\mu, \nu) \quad \forall \mu, \nu \in \mathcal{M}.$$

Lemma 4 *Let $\mu, \nu \in \mathcal{M}$ and γ be optimal for $\mathbf{d}(\mu, \nu)$. Then there exist $p \in L^2_\mu(\mathbb{R}^N, \mathbb{R}^N)$ and $q \in L^2_\nu(\mathbb{R}^N, \mathbb{R}^N)$ s. t.*

$$\int_{\mathbb{R}^N} \langle \varphi(x), p(x) \rangle d\mu(x) = \int_{\mathbb{R}^{2N}} \langle \varphi(x), x - y \rangle d\gamma(x) \quad (5)$$

$$\int_{\mathbb{R}^N} \langle \varphi(x), q(x) \rangle d\nu(x) = \int_{\mathbb{R}^{2N}} \langle \varphi(y), x - y \rangle d\gamma(x) \quad (6)$$

for any Borel measurable map $\varphi : \mathbb{R}^N \rightarrow \mathbb{R}^N$ with at most a linear growth.

proof Let γ be an optimal plan from μ to ν . Then

$$\begin{aligned}\int_{\mathbb{R}^N} h(x) d\mu(x) &= \int_{\mathbb{R}^{2N}} h(x) d\gamma(x, y) \\ &\leq \int_{\mathbb{R}^{2N}} h(y) d\gamma(x, y) + k \int_{\mathbb{R}^{2N}} |x - y| d\gamma(x, y) \\ &\leq \int_{\mathbb{R}^{2N}} h(y) d\nu(y) + k \mathbf{d}(\mu, \nu)\end{aligned}$$

□

proof We just show the existence of p , since the proof for q can be obtained in the same way. Let us consider the linear map Φ on $L^2_\mu(\mathbb{R}^N, \mathbb{R}^N)$ defined by

$$\Phi(\varphi) = \int_{\mathbb{R}^{2N}} \langle \varphi(x), x - y \rangle d\gamma(x)$$

Then

$$|\Phi(\varphi)| \leq \left(\int_{\mathbb{R}^{2N}} |\varphi(x)|^2 d\gamma(x) \right)^{\frac{1}{2}} \left(\int_{\mathbb{R}^{2N}} |x - y|^2 d\gamma(x) \right)^{\frac{1}{2}} \leq \mathbf{d}(\mu, \nu) \|\varphi\|_{L^2_\mu}$$

for any $\varphi \in L^2_\mu(\mathbb{R}^N, \mathbb{R}^N)$. Therefore Φ is bounded on $L^2_\mu(\mathbb{R}^N, \mathbb{R}^N)$ whence the existence of $p \in L^2_\mu(\mathbb{R}^N, \mathbb{R}^N)$ from Riesz Representation Theorem. \square

Regularity of the Values

Proposition 5 *The value functions V^+ and V^- are Lipschitz continuous.*

proof for V^+

We shall first prove that the values are Lipschitz continuous with respect to the second variable. Fix $t_0 \in [0, T]$, $\mu_0 \in \mathcal{M}$, $\nu_0 \in \mathcal{M}$ and $\varepsilon > 0$. There exists a nonanticipative strategy $\alpha_\varepsilon \in \mathcal{A}(t_0)$ such that

$$V^+(t_0, \nu_0) \leq \sup_{\beta \in \mathcal{B}(t_0)} J(t_0, \nu_0, \alpha_\varepsilon, \beta) \leq V^+(t_0, \nu_0) + \varepsilon.$$

Hence

$$\begin{aligned} & V^+(t_0, \mu_0) - V^+(t_0, \nu_0) \leq \\ & \varepsilon + \sup_{\beta \in \mathcal{B}(t_0)} J(t_0, \mu_0, \alpha_\varepsilon, \beta) - \sup_{\beta \in \mathcal{B}(t_0)} J(t_0, \nu_0, \alpha_\varepsilon, \beta) \\ & \leq 2\varepsilon + J(t_0, \mu_0, \alpha_\varepsilon, \beta_\varepsilon) - J(t_0, \nu_0, \alpha_\varepsilon, \beta_\varepsilon) \end{aligned}$$

where $\beta_\varepsilon \in \mathcal{B}(t_0)$ is such that

$$\sup_{\beta \in \mathcal{B}(t_0)} J(t_0, \mu_0, \alpha_\varepsilon, \beta) - \varepsilon \leq J(t_0, \mu_0, \alpha_\varepsilon, \beta_\varepsilon) \leq \sup_{\beta \in \mathcal{B}(t_0)} J(t_0, \mu_0, \alpha_\varepsilon, \beta).$$

Thus

$$\begin{aligned} V^+(t_0, \mu_0) - V^+(t_0, \nu_0) &\leq \\ 2\varepsilon + \int_{\mathbb{R}^N} g \left(X_T^{t_0, x, \alpha_\varepsilon, \beta_\varepsilon} \right) d\mu_0(x) - \int_{\mathbb{R}^N} g \left(X_T^{t_0, x, \alpha_\varepsilon, \beta_\varepsilon} \right) d\nu_0(x) \\ &\leq k^2 e^{kT} d(\mu_0, \nu_0) + 2\varepsilon \end{aligned}$$

thanks to Lemma 3 and because $x \mapsto X_T^{t_0, x, u, v}$ is $k^2 e^{kT}$ Lipschitz.

Consider now $0 < t_0 < s_0 < T$ and the strategy α_ε . Let $u_0 \in \mathcal{U}(t_0)$ and $v_0 \in \mathcal{V}(t_0)$ two given control. We define the

nonanticipative strategy $\alpha_1 \in A(s_0)$ as follows

$$\forall v \in \mathcal{V}(s_0), \alpha_1(v) := \alpha_\varepsilon(v_1)$$

where $v_1(t) = v_0(t)$ if $t \in [t_0, s_0)$ and $v_1(t) = v(t)$ if $t \in [s_0, T]$.

$$\begin{aligned} & V^+(s_0, \mu_0) - V^+(t_0, \mu_0) \\ & \leq \varepsilon + \sup_{\beta \in \mathcal{B}(s_0)} J(s_0, \mu_0, \alpha_1, \beta) - \sup_{\beta \in \mathcal{B}(t_0)} J(t_0, \mu_0, \alpha_\varepsilon, \beta) \\ & \leq 2\varepsilon + J(s_0, \mu_0, \alpha_1, \beta_\varepsilon) - J(t_0, \mu_0, \alpha_\varepsilon, \beta_1) \end{aligned}$$

where $\beta_\varepsilon \in \mathcal{B}(s_0)$ is such that

$$\sup_{\beta \in \mathcal{B}(s_0)} J(s_0, \mu_0, \alpha_1, \beta) - \varepsilon \leq J(s_0, \mu_0, \alpha_1, \beta_\varepsilon) \leq \sup_{\beta \in \mathcal{B}(s_0)} J(s_0, \mu_0, \alpha_1, \beta)$$

and $\beta_1 \in \mathcal{B}(t_0)$ is defined as follows:

$\forall u \in \mathcal{U}(t_0), \beta_1(u)(t) = v_0(t)$ if $t \in [t_0, s_0)$ and $\beta_1(u)|_{[s_0, T]} = \beta_\varepsilon(u|_{[s_0, T]})$. Hence

$$\begin{aligned}
& V^+(s_0, \mu_0) - V^+(t_0, \mu_0) \\
\leq & 2\varepsilon + \int_{\mathbb{R}^N} g \left(X_T^{s_0, x, \alpha_1, \beta_\varepsilon} \right) d\mu_0(x) - \int_{\mathbb{R}^N} g \left(X_T^{t_0, x, \alpha_\varepsilon, \beta_1} \right) d\mu_0(x) \\
= & 2\varepsilon + \int_{\mathbb{R}^N} g \left(X_T^{s_0, x, \alpha_1, \beta_\varepsilon} \right) - g \left(X_T^{s_0, X_{s_0}^{t_0, x, \alpha_1, v_0}, \alpha_1, \beta_\varepsilon} \right) d\mu_0(x)
\end{aligned}$$

by noticing that

$$X_T^{t_0, x, \alpha_\varepsilon, \beta_1} = X_T^{s_0, X_{s_0}^{t_0, x, \alpha_1, v_0}, \alpha_1, \beta_\varepsilon}.$$

Consequently

$$V^+(s_0, \mu_0) - V^+(t_0, \mu_0) \leq 2\varepsilon + Mk^2 e^{kT} (t_0 - s_0),$$

using the fact that $|x - X_{s_0}^{t_0, x, \alpha_1, v_0}| \leq M(t_0 - s_0)$ □

Dynamic Programming

Proposition 6 [*Dynamic programming*] *Let* $(t_0, t_1, \mu_0) \in [0, T) \times [0, T] \times \mathcal{M}$ *be fixed with* $t_0 < t_1$. *Then*

$$V^+(t_0, \mu_0) = \inf_{\alpha \in \mathcal{A}(t_0)} \sup_{\beta \in \mathcal{B}(t_0)} V^+ \left(t_1, X_{t_1}^{t_0, \cdot, \alpha, \beta} \# \mu_0 \right)$$

and

$$V^-(t_0, \mu_0) = \sup_{\beta \in \mathcal{B}(t_0)} \inf_{\alpha \in \mathcal{A}(t_0)} V^- \left(t_1, X_{t_1}^{t_0, \cdot, \alpha, \beta} \# \mu_0 \right)$$

proof We only prove the dynamic programming for

$$V^-(t_0, \mu_0) = \sup_{\beta \in \mathcal{B}(t_0)} \inf_{u \in \mathcal{U}(t_0)} J(t_0, \mu_0, u, \beta(u)) .$$

$V^-(t_0, \mu_0) = W(t_0, t_1, \mu_0)$ where we set

$$W(t_0, t_1, \mu_0) = \sup_{\beta \in \mathcal{B}(t_0)} \inf_{u \in \mathcal{U}(t_0)} V^- \left(t_1, X_{t_1}^{t_0, \cdot, u, \beta} \# \mu_0 \right)$$

Let us prove first that $V^-(t_0, \mu_0) \leq W(t_0, t_1, \mu_0)$. Fix $\beta_0 \in \mathcal{B}(t_0)$ and $u_0 \in \mathcal{U}(t_0)$. Define $\beta_1 \in \mathcal{B}(t_1)$ as follows

$$\forall u \in \mathcal{U}(t_1), \beta_1(u) := \beta_0(u_1)$$

where $u_1(t) = u_0(t)$ if $t \in [t_0, t_1)$ and $u_1(t) = u(t)$ if $t \in [s_0, T]$.

Clearly β_1 is nonanticipative such that

$$\forall t \in [t_1, T], X_t^{t_0, x, u, \beta_0(u)} = X_t^{t_1, X_{t_1}^{t_0, x, u_0, \beta_0(u_0)}, u, \beta_1(u)}.$$

Hence for any $u \in \mathcal{U}(t_1)$,

$$\begin{aligned} & J(t_1, X_{t_1}^{t_0, \cdot, u_0, \beta_0(u_0)} \# \mu_0, u, \beta_1) = \\ &= \int_{\mathbb{R}^N} g \left(X_T^{t_1, x, u, \beta_1} \right) d(X_{t_1}^{t_0, \cdot, u_0, \beta_0(u_0)} \# \mu_0)(x) = \\ & \int_{\mathbb{R}^N} g \left(X_T^{t_0, x, u_1, \beta_0(u_1)} \right) d\mu_0(x) \end{aligned}$$

So

$$\inf_{u \in \mathcal{U}(t_1)} J(t_1, X_{t_1}^{t_0, \cdot, u_0, \beta_0(u_0)} \# \mu_0, u, \beta_1) =$$

v

$$\inf_{u \in \mathcal{U}(t_0) \text{ with } u|_{[t_0, t_1]} = u_0|_{[t_0, t_1]}} J(t_0, \mu_0, u, \beta_0).$$

Hence

$$V^-(t_1, X_{t_1}^{t_0, \cdot, u_0, \beta_0(u_0)}) \geq \inf_{u \in \mathcal{U}(t_0) \text{ with } u|_{[t_0, t_1]} = u_0|_{[t_0, t_1]}} J(t_0, \mu_0, u, \beta_0).$$

Consequently, u_0 and β_0 being arbitrary, we have $V^-(t_0, \mu_0) \leq W(t_0, t_1, \mu_0)$.

Let us prove the reverse inequality

$$V^-(t_0, \mu_0) \geq W(t_0, t_1, \mu_0) := \sup_{\beta \in \mathcal{B}(t_0)} \inf_{u \in \mathcal{U}(t_0)} V^-\left(t_1, X_{t_1}^{t_0, \cdot, u, \beta} \# \mu_0\right)$$

Fix $\varepsilon > 0$. For any $\mu \in \mathcal{M}$ there exists some $\beta_\mu \in \mathcal{B}(t_1)$ such that

$$\inf_{u \in \mathcal{U}(t_1)} J(t_1, \mu, u, \beta_\mu) \geq V^-(t_1, \mu) - \varepsilon.$$

Fix $\beta_0 \in \mathcal{U}(t_0)$. Define $\beta_0 \in \mathcal{B}(t_0)$ as follows: for any $u \in \mathcal{U}(t_0)$ we have

$$\beta(u)|_{[t_0, t_1]} = \beta_0(u)|_{[t_0, t_1]}, \quad \beta(u)|_{[t_1, T]} = \beta_{\mu_1}(u|_{[t_1, T]}),$$

where $\mu_1 = X_{t_1}^{t_0, \cdot, u, \beta_0} \# \mu_0$. Hence for any $u \in \mathcal{U}(t_0)$ we obtain

$$J(t_0, \mu_0, u, \beta(u)) = J(t_1, \mu_1, u|_{[t_1, T]}, \beta_{\mu_1}(u|_{[t_1, T]})) \geq V^-(t_1, \mu_1) - \varepsilon.$$

Hence

$$V^-(t_0, \mu_0) \geq \inf_{u \in \mathcal{U}(t_0)} J(t_0, \mu_0, u, \beta(u)) \geq \inf_{u \in \mathcal{U}(t_0)} V^-(t_1, X_{t_1}^{t_0, \cdot, u, \beta_0} \# \mu_0) - \varepsilon.$$

We obtained the wished conclusion passing to the supremum in β_0 because ε is arbitrary. \square

Hamilton Jacobi Isaacs Equation

$$w_t + \mathcal{H}(\mu, Dw) = 0 \tag{7}$$

where $\mathcal{H} = \mathcal{H}(\mu, p)$ is an Hamiltonian defined for any $\mu \in \mathcal{M}$ and $p \in L^2_\mu(\mathbb{R}^N, \mathbb{R}^N)$.

Definition 7 (Sub- and super-differential) *Let $w : [0, T] \times \mathcal{M} \rightarrow \mathbb{R}$ be a function, $(t_0, \mu_0) \in (0, T) \times \mathcal{M}$ and let $\delta > 0$. $(p_t, p_\mu) \in \mathbb{R} \times L_\mu^2(\mathbb{R}^N, \mathbb{R}^N)$ belongs to the δ -super-differential $D_\delta^+ w(t_0, \mu_0)$ to w at (t_0, μ_0) if, $\forall \varphi \in \mathcal{C}_b(\mathbb{R}^N, \mathbb{R}^N)$,*

$$\limsup_{\|\varphi\|_{L_\mu^2} \rightarrow 0, t \rightarrow t_0} [w(t, (\text{id}_{\mathbb{R}^N} + \varphi) \# \mu_0) - w(t_0, \mu_0) - p_t(t - t_0)$$

$$- \int_{\mathbb{R}^N} \langle \varphi(x), p_\mu(x) \rangle d\mu_0(x)] \frac{1}{\|\varphi\|_{L_\mu^2} + |t - t_0|} \leq \delta$$

A pair $(p_t, p_\mu) \in \mathbb{R} \times L_\mu^2(\mathbb{R}^N, \mathbb{R}^N)$ belongs to the δ -sub-differential $D_\delta^- w(t_0, \mu_0)$ to w at (t_0, μ_0) if $(-p_t, -p_\mu)$ belongs to the δ -super-differential to $-w$ at (t_0, μ_0) .

Solutions of Hamilton-Jacobi equation

Definition 8 *We say that a map $w : [0, T] \times \mathcal{M} \rightarrow \mathbb{R}$ is a sub-solution of the HJ equation (7) if w is upper semi-continuous and if, for any $(t_0, \mu_0) \in (0, T) \times \mathcal{M}$, for any $(p_t, p_\mu) \in D_\delta^+ w(t_0, \mu_0)$, we have for any $\delta > 0$,*

$$p_t + \mathcal{H}(\mu_0, p_\mu) \geq -C\delta \quad (8)$$

where $C > 0$ is a constant which depends only of \mathcal{H} .

In a similar way, w is a super-solution of the HJ equation (7) if w is lower semicontinuous and if, for any $(t_0, \mu_0) \in (0, T) \times \mathcal{M}$, for any $(p_t, p_\mu) \in D_\delta^- w(t_0, \mu_0)$, we have

$$p_t + \mathcal{H}(\mu_0, p_\mu) \leq C\delta . \quad (9)$$

Values and HJI Equations

$$\mathcal{H}^+(\mu, p) = \inf_{u \in U} \sup_{v \in V} \int_{\mathbb{R}^N} \langle f(x, u, v), p(x) \rangle d\mu(x)$$

$$\mathcal{H}^-(\mu, p) = \sup_{v \in V} \inf_{u \in U} \int_{\mathbb{R}^N} \langle f(x, u, v), p(x) \rangle d\mu(x) .$$

Lemma 9 *Let $\mu, \nu \in \mathcal{M}$, γ be an optimal plan from μ to ν , and $p \in L^2_\mu$ and $q \in L^2_\nu$ be defined by (5) and (6) respectively. Then, for $\mathcal{H} = \mathcal{H}^+$ or $\mathcal{H} = \mathcal{H}^-$*

$$|\mathcal{H}(\mu, p) - \mathcal{H}(\nu, q)| \leq k(\mathbf{d}(\mu, \nu))^2 ,$$

$$\forall \varphi, \int_{\mathbb{R}^N} \langle \varphi(x), p(x) \rangle d\mu(x) = \int_{\mathbb{R}^{2N}} \langle \varphi(x), x - y \rangle d\gamma(x)$$

proof for \mathcal{H}^-

$$\begin{aligned} \mathcal{H}^-(\mu, p) &= \sup_v \inf_u \int_{\mathbb{R}^N} \langle f(x, u, v), p(x) \rangle d\mu(x) \\ &= \sup_v \inf_u \int_{\mathbb{R}^{2N}} \langle f(x, u, v), x - y \rangle d\gamma(x, y) \\ &\leq \sup_v \inf_u \int_{\mathbb{R}^{2N}} \langle f(y, u, v), x - y \rangle d\gamma(x, y) \\ &\quad + k \int_{\mathbb{R}^{2N}} |x - y|^2 d\gamma(x, y) \\ &\leq \sup_v \inf_u \int_{\mathbb{R}^N} \langle f(y, u, v), q(y) \rangle d\nu(y) \\ &\quad + k \mathbf{d}^2(\mu, \nu) \\ &\leq \mathcal{H}^-(\nu, q) + k \mathbf{d}^2(\mu, \nu) \end{aligned}$$

□

Proposition 10 *The upper value function V^+ is a solution to HJI with $\mathcal{H} := \mathcal{H}^+$ while the lower value function V^- is a solution to HJI with $\mathcal{H} := \mathcal{H}^-$.*

proof of V^+ is a subsolution

Fix $(t_0, \mu_0) \in (0, T) \times \mathcal{M}$, $\delta > 0$ and $(p_t, p_\mu) \in D_\delta^+ V^+(t_0, \mu_0)$.

We will prove that

$$p_t + \mathcal{H}(\mu_0, p_\mu) \geq -\delta \quad (10)$$

Consider $t \in (t_0, T)$. **For any** $\alpha \in \mathcal{A}(t_0)$ and $\beta \in \mathcal{B}(t_0)$ **define** $\varphi_{\alpha, \beta} \in \mathcal{C}_b(\mathbb{R}^N, \mathbb{R}^N)$ **such that**

$$(\text{id}_{\mathbb{R}^N} + \varphi_{\alpha, \beta})(x) = X_t^{t_0, x, \alpha, \beta} = x + \int_{t_0}^t f(x(s), u(s), v(s)) ds,$$

where (u, v) **is associated with** (α, β) **and** $x(s) = X_s^{t_0, x, \alpha, \beta}$.

$$\begin{aligned}
& V^+(t, X_t^{t_0, \cdot, \alpha, v} \# \mu_0) - V^+(t_0, \mu_0) - p_t(t - t_0) \\
& - \int_{\mathbb{R}^N} < \int_{t_0}^t f(X_s^{t_0, x, \alpha, \beta}, u(s), v(s)) ds, p_\mu(x) > d\mu(x) \quad (11) \\
& \leq (\|\varphi_{\alpha, \beta}\|_{L_\mu^2} + |t - t_0|)(\varepsilon(t, \varphi_{\alpha, \beta}) + \delta)
\end{aligned}$$

where $\varepsilon(t, \varphi_{\alpha, \beta}) \rightarrow 0$ as $t \rightarrow t_0$ and $\varphi_{\alpha, \beta} \rightarrow 0$ in L_μ^2 . Passing to the sup on v and inf on α , we obtain by DDP

$$\begin{aligned}
0 \leq & \inf_{\alpha \in \mathcal{A}(t_0)} \sup_{v \in \mathcal{V}(t_0)} \left[\int_{\mathbb{R}^N} < \int_{t_0}^t f(X_s^{t_0, x, \alpha(v), v}, \alpha(v)(s), v(s)) ds, p_\mu(x) > d\mu \right. \\
& \left. + p_t(t - t_0) + (\|\varphi_{\alpha(v), v}\|_{L_\mu^2} + |t - t_0|)(\delta + \varepsilon(t, \varphi_{\alpha, \beta})) \right]
\end{aligned}$$

for $\|\varphi_{\alpha(v), v}\|_{L_\mu^2} + |t - t_0|$ small enough.

For t close enough to t_0 we obtain

$$0 \leq \inf_{u \in U} \sup_{v \in \mathcal{V}(t_0)} \left[\int_{\mathbb{R}^N} < \int_{t_0}^t f(x, u, v(s)) ds, p_\mu(x) > d\mu(x) \right. \\ \left. + p_t(t - t_0) + (\|\varphi_{u,v}\|_{L_\mu^2} + |t - t_0|)(\delta + \varepsilon(t, \varphi_{u,v})) \right]$$

when we restrict the infimum to nonanticipative strategies α which has constant control values. Hence

$$0 \leq \inf_{u \in U} \sup_{v \in V} \left[(t - t_0) \int_{\mathbb{R}^N} < f(x, u, v) ds, p_\mu(x) > d\mu(x) \right. \\ \left. + p_t(t - t_0) + (\|\varphi_{u,v}\|_{L_\mu^2} + |t - t_0|)(\delta + \varepsilon(t, \varphi_{u,v})) \right]$$

Dividing this inequality by $t - t_0$ and letting $t \rightarrow t_0^+$ gives, since $\|\varphi_{u,v}\|_{L_\mu^2} = O(t - t_0)$,

$$p_t + \mathcal{H}(\mu_0, p_\mu) \geq -(1 + M)\delta .$$

Comparison Principle for HJI

$$w_t + \mathcal{H}(\mu, Dw) = 0$$

Assumptions on \mathcal{H}

- $p \in L^2_\mu(\mathbb{R}^N, \mathbb{R}^N) \mapsto \mathcal{H}(\mu, \cdot)$ is positively homogeneous.
- for any $\mu, \nu \in \mathcal{M}$, if γ is the optimal plan from μ to ν , and $p \in L^2_\mu$ and $q \in L^2_\nu$ are defined by (5) and (6) respectively,

$$|\mathcal{H}(\mu, p) - \mathcal{H}(\nu, q)| \leq k(\mathbf{d}(\mu, \nu))^2. \quad (12)$$

$$\forall \varphi, \int_{\mathbb{R}^N} \langle \varphi(x), p(x) \rangle d\mu(x) = \int_{\mathbb{R}^{2N}} \langle \varphi(x), x - y \rangle d\gamma(x)$$

$$\forall \varphi, \int_{\mathbb{R}^N} \langle \varphi(x), q(x) \rangle d\nu(x) = \int_{\mathbb{R}^{2N}} \langle \varphi(y), x - y \rangle d\gamma(x)$$

Comparison principle for HJI

Theorem 11 *Let w_1 be a bounded and Lipschitz continuous subsolution and w_2 be a bounded and Lipschitz continuous supersolution to (7). Then*

$$\inf_{[0,T] \times \mathcal{M}} (w_2 - w_1) = \inf_{\mathcal{M}} w_2(T, \cdot) - w_1(T, \cdot) .$$

Proof of Comparison Principle

$$A = \inf_{\mu \in \mathcal{M}} w_2(T, \mu) - w_1(T, \mu) .$$

Since \mathcal{H} is independant of w , $w_1 - A$ is still a subsolution.
So we suppose without loss of generality that $A = 0$.

By Contradiction

$$-\xi := \inf_{\mu \in \mathcal{M}, t \in [0, T]} w_2(t, \mu) - w_1(t, \mu) < 0 .$$

And choose $(t_0, \mu_0) \in [0, T] \times \mathcal{M}$ such that

$$(w_2 - w_1)(t_0, \mu_0) < -\xi/2. \tag{13}$$

Let $C > 0$ such that $\forall \delta > 0$

$$\forall (p_t, p_\mu) \in D_\delta^+ w_1(t_0, \mu_0), p_t + \mathcal{H}(\mu_0, p_\mu) \geq -C\delta$$

$$\forall (p_t, p_\mu) \in D_\delta^- w_2(t_0, \mu_0) p_t + \mathcal{H}(\mu_0, p_\mu) \leq C\delta .$$

Fix $\varepsilon > 0$, $\eta > 0$ and $\delta > 0$ sufficiently small such that

$$\xi > 2\eta T + \frac{k^2\varepsilon}{2} \quad \text{and} \quad 2C\delta + 2k(\delta + k)^2\varepsilon < \eta . \quad (14)$$

We consider the following continuous function defined on $([0, T] \times \mathcal{M})^2$:

$$\Phi(s, \mu, t, \nu) = -w_1(s, \mu) + w_2(t, \nu) + \frac{1}{\varepsilon} (\mathbf{d}^2(\mu, \nu) + (t - s)^2) - \eta s .$$

Define

$$(\bar{\mu}, \bar{\nu}, \bar{s}, \bar{t}) \in \text{Arg} \min_{[0, T] \times \mathcal{M}} \Phi$$

From Ekeland Variational Principle that $\exists(\bar{\mu}, \bar{\nu}, \bar{s}, \bar{t}) \in \mathcal{M}^2 \times [0, T]^2$ such that for any $(s, \mu, t, \nu) \in ([0, T] \times \mathcal{M})^2$

$$\left\{ \begin{array}{l} i) \quad \Phi(\bar{s}, \bar{\mu}, \bar{t}, \bar{\nu}) \leq \Phi(t_0, \mu_0, t_0, \mu_0) \\ ii) \quad \Phi(\bar{s}, \bar{\mu}, \bar{t}, \bar{\nu}) \leq \Phi(s, \mu, t, \nu) \\ \quad \quad + \delta([\mathbf{d}^2(\mu, \bar{\mu}) + |s - \bar{s}|^2]^{\frac{1}{2}} + [\mathbf{d}^2(\nu, \bar{\nu}) + |t - \bar{t}|^2]^{\frac{1}{2}}) \end{array} \right. \quad (15)$$

CLAIM 1 $\rho^2 := \mathbf{d}^2(\bar{\mu}, \bar{\nu}) + |\bar{s} - \bar{t}|^2 \leq (k + \delta)^2 \varepsilon^2$ **Indeed,**

$$\Phi(\bar{s}, \bar{\mu}, \bar{t}, \bar{\nu}) \leq \Phi(\bar{s}, \bar{\mu}, \bar{s}, \bar{\mu}) + \delta[\mathbf{d}^2(\bar{\nu}, \bar{\nu}) + |\bar{s} - \bar{t}|^2]^{\frac{1}{2}}$$

Since w_2 is k -Lipschitz continuous,

$$\begin{aligned} \delta\rho + w_2(\bar{s}, \bar{\mu}) - w_1(\bar{s}, \bar{\mu}) - \eta\bar{s} &\geq w_2(\bar{t}, \bar{\nu}) - w_1(\bar{s}, \bar{\mu}) + \frac{1}{\varepsilon}\rho^2 - \eta\bar{s} \\ &\geq w_2(\bar{s}, \bar{\mu}) - w_1(\bar{s}, \bar{\mu}) - k\rho + \frac{1}{\varepsilon}\rho^2 - \eta\bar{s} \end{aligned}$$

Hence $\rho \leq (k + \delta)\varepsilon$,

Assume $\bar{s}, \bar{t} \in (0, T)$. Let γ be the optimal transport plan between $\bar{\mu}$ and $\bar{\nu}$ and $p \in L^2(\bar{\mu})$ and $q \in L^2(\bar{\nu})$ associated.

CLAIM 2

$$\left(\frac{2}{\varepsilon}(\bar{s} - \bar{t}) - \eta, \frac{2}{\varepsilon}p \right) \in D_{\delta}^+ w_1(\bar{s}, \bar{\mu}), \quad \left(\frac{2}{\varepsilon}(\bar{s} - \bar{t}), \frac{2}{\varepsilon}q \right) \in D_{\delta}^- w_2(\bar{t}, \bar{\nu}),$$

From (15)-ii), we have for any (s, μ) ,

$$\Phi(\bar{s}, \bar{\mu}, \bar{t}, \bar{\nu}) \leq \Phi(s, \mu, \bar{t}, \bar{\nu}) + \delta[\mathbf{d}^2(\mu, \bar{\mu}) + |s - \bar{s}|^2]^{\frac{1}{2}}.$$

$$\begin{aligned} w_1(s, \mu) &\leq w_1(\bar{s}, \bar{\mu}) + \frac{1}{\varepsilon}(\mathbf{d}^2(\mu, \bar{\nu}) - \mathbf{d}^2(\bar{\mu}, \bar{\nu}) + (s - \bar{t})^2 - (\bar{s} - \bar{t})^2) \\ &\quad + \delta[\mathbf{d}^2(\mu, \bar{\mu}) + |s - \bar{s}|^2]^{\frac{1}{2}} + \eta(\bar{s} - s) \end{aligned} \tag{16}$$

We will replace μ by $(\text{id}_{\mathbb{R}^N} + \varphi)\# \bar{\mu}$ with $\varphi \in \mathcal{C}_b(\mathbb{R}^N, \mathbb{R}^N)$

Estimation

Observe $\gamma' = (\text{id}_{\mathbb{R}^N} + \varphi, \text{id}_{\mathbb{R}^N})\#\gamma$ is an admissible transport plan from $(\text{id}_{\mathbb{R}^N} + \varphi)\#\bar{\mu}$ to $\bar{\nu}$. Hence

$$\begin{aligned} \mathbf{d}^2((\text{id}_{\mathbb{R}^N} + \varphi)\#\bar{\mu}, \bar{\nu}) - \mathbf{d}^2(\bar{\mu}, \bar{\nu}) &\leq \\ \int_{\mathbb{R}^{2N}} |x - y|^2 d\gamma'(x, y) - \int_{\mathbb{R}^{2N}} |x - y|^2 d\gamma(x, y) & \\ = \int_{\mathbb{R}^{2N}} (|x + \varphi(x) - y|^2 - |x - y|^2) d\gamma(x, y) & \\ = \int_{\mathbb{R}^{2N}} (2 \langle x - y, \varphi(x) \rangle + |\varphi(x)|^2) d\gamma(x, y) & \\ = \int_{\mathbb{R}^N} \langle 2p(x), \varphi(x) \rangle d\bar{\mu}(x) + \|\varphi\|_{L^2_{\bar{\mu}}}^2 \quad (\text{from the def. of } p) & \end{aligned}$$

$$\begin{aligned} w_1(s, (\text{id}_{\mathbb{R}^N} + \varphi)\#\bar{\mu}) &\leq w_1(\bar{s}, \bar{\mu}) + \frac{1}{\varepsilon} \int_{\mathbb{R}^N} \langle 2p(x), \varphi(x) \rangle d\bar{\mu}(x) + \|\varphi\|_{L^2_{\bar{\mu}}}^2 \\ &+ \frac{1}{\varepsilon} (s - \bar{s}) [(s - \bar{s}) + 2(\bar{s} - \bar{t})] + \delta [\mathbf{d}^2(\mu, \bar{\mu}) + |s - \bar{s}|^2]^{\frac{1}{2}} + \eta(\bar{s} - s) \end{aligned}$$

So

$$\begin{aligned} & w_1(s, (\text{id}_{\mathbb{R}^N} + \varphi)\#\bar{\mu}) - w_1(\bar{s}, \bar{\mu}) - (s - \bar{s})\left[\frac{2}{\varepsilon}(\bar{s} - \bar{t}) - \eta\right] \\ & - \frac{1}{\varepsilon} \int_{\mathbb{R}^N} \langle 2p(x), \varphi(x) \rangle d\bar{\mu}(x) + \|\varphi\|_{L^2_{\bar{\mu}}}^2 \leq \\ & + \frac{1}{\varepsilon}(s - \bar{s})^2 + \delta[\mathbf{d}^2(\mu, \bar{\mu}) + |s - \bar{s}|^2]^{\frac{1}{2}} \end{aligned}$$

Hence

$$\left(\frac{2}{\varepsilon}(\bar{s} - \bar{t}) - \eta, \frac{2}{\varepsilon}p \right) \in D_{\delta}^+ w_1(\bar{s}, \bar{\mu})$$

which the claim 2.

By Claim 2, because w_1 sub solution, w_2 supersolution

$$\frac{2}{\varepsilon}(\bar{s} - \bar{t}) - \eta + \mathcal{H}\left(\bar{\mu}, \frac{2}{\varepsilon}p\right) \geq -C\delta .$$

$$\frac{2}{\varepsilon}(\bar{s} - \bar{t}) + \mathcal{H}\left(\bar{\mu}, \frac{2}{\varepsilon}q\right) \leq C\delta .$$

Subtracting we obtain $\mathcal{H}(\bar{\nu}, q) - \mathcal{H}(\bar{\mu}, p) \leq 2C\delta - \eta$.

But from the assumption on \mathcal{H} we have $\mathcal{H}(\bar{\nu}, q) - \mathcal{H}(\bar{\mu}, p) \geq -k\mathbf{d}^2(\bar{\mu}, \bar{\nu})$. So

$$-k(k + \delta)^2\varepsilon \leq 2C\delta - \eta ,$$

a contradiction with (14).

We have to check that \bar{s} and \bar{t} cannot be equal to 0 or T . Let us assume for instance that $\bar{s} = T$. We first note that

$$\Phi(t_0, \mu_0, t_0, \mu_0) = w_2(t_0, \mu_0) - w_1(t_0, \mu_0) - \eta t_0 \leq -\xi/2$$

From (Ekeland), i), we have

$$\Phi(\bar{s}, \bar{\mu}, \bar{t}, \bar{\nu}) \leq \Phi(t_0, \mu_0, t_0, \mu_0) \leq -\xi/2 .$$

Since $\bar{s} = T$ and w_2 is k -Lipschitz continuous, we get (setting as before $\rho := [\mathbf{d}^2(\bar{\nu}, \bar{\nu}) + |\bar{s} - \bar{t}|^2]^{\frac{1}{2}}$)

$$\begin{aligned} -\xi/2 &\geq w_2(\bar{t}, \bar{\nu}) - w_1(T, \bar{\mu}) + \frac{1}{\varepsilon}\rho^2 - \eta T \\ &\geq w_2(T, \bar{\mu}) - w_1(T, \bar{\mu}) - k\rho + \frac{1}{\varepsilon}\rho^2 - \eta T \\ &\geq -k\rho + \frac{1}{\varepsilon}\rho^2 - \eta T , \end{aligned}$$

A contradiction with the choices of $\eta, \delta, \varepsilon$ and the estimation of ρ .

To show that $\bar{s} \neq 0$ and $\bar{t} \neq 0$, it is enough to use the standard fact that w_1 and w_2 are respectively sub- and supersolutions up to $t = 0$,

Lemma 12 *If w is a subsolution (resp. a supersolution) of (7) on the time interval $(0, T)$, then w is also a subsolution (resp. a supersolution) on $[0, T)$.*

□

Uniqueness Result for HJI

Corollary 13 *There exists at most one lipschitz continuous solution of (7) satisfying*

$$w(T, \mu) = \int_{\mathbb{R}^N} g(x) d\mu(x) , \forall \mu \in \mathcal{M}.$$

Existence of A value

Theorem 14 *We suppose the following Isaacs condition:*

$$\mathcal{H}^+ = \mathcal{H}^-.$$

Then the game has a value. Namely:

$$V^+(t, \mu) = V^-(t, \mu) \quad \forall (t, \mu) \in [0, T] \times \mathcal{M}.$$

Furthermore $V^+ = V^-$ is the unique solution of the Hamilton-Jacobi equation (7) with $\mathcal{H} = \mathcal{H}^+ = \mathcal{H}^-$.

Thank You for your Attention
